

# Lecture 10: Geometric Modeling and Visualization

## Integrals & Integral Equations: Molecular Energetics & Forces

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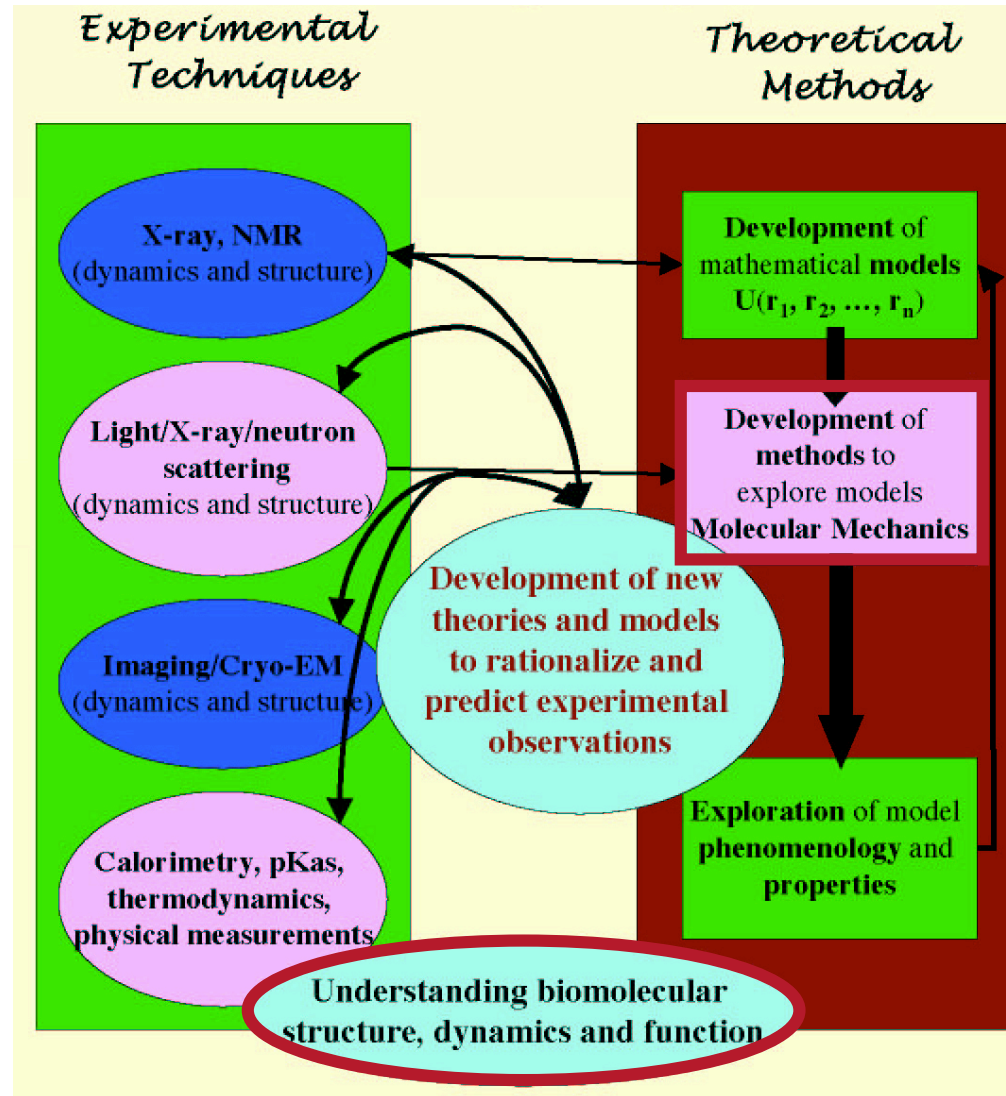


Center for Computational Visualization  
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University of Texas at Austin

November 2007

# Molecular Mechanics and Modeling



Courtesy Charlie Brooks, TSRI



# Biological Time scale

Bond vibrations	1 fs	( $10^{-15}$ s)
Sugar repuckering	1 ps	( $10^{-12}$ s)
<del>DNA bending</del>	<del>1 ns</del>	<del>(<math>10^{-9}</math> s)</del>
Domain movement	1 ms	( $10^{-6}$ s)
Base pair opening	1 ms	( $10^{-3}$ s)
Transcription	2.5 ms / nucleotide	
Protein synthesis	6.5 ms / amino acid	
Protein folding	~ 10 s	
RNA lifetime	~ 300 s	



# Biological energy scale

Chemical bonds	C-H	105	kcal.mol <sup>-1</sup>
		C=C	172
Ionic hydration	Na <sup>+</sup>	-93	
		Ca <sup>2+</sup>	-373
Hydrogen bonds	O...H	-5	( <i>in vacuum</i> )
Protein folding		~ 2-10	( <i>in solution</i> )
Protein-DNA binding		~ 5-20	
(~200 Å <sup>2</sup> contact)			

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Courtesy David Case, TSRI



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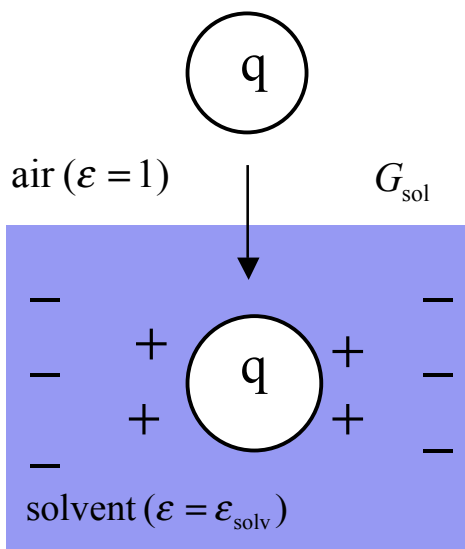
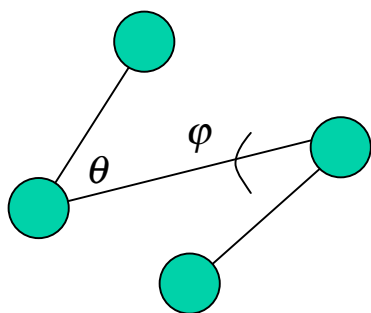


# Free Energy of a Macromolecule in Solvent

Total free energy :  $G = E_{MM} + G_{sol} - TS$

$$E = E_b + E_\theta + E_\varphi + E_{vdw} + E_{elec}$$

$$G_{sol} = G_{cav} + G_{vdw} + G_{pol}$$

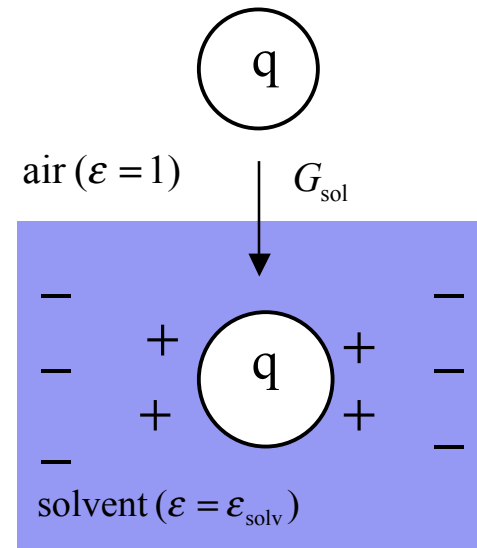
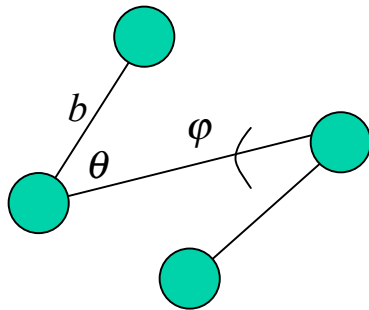


# Free Energy of a Single Molecule in Solvent

Total free energy :  $G = E_{MM} + G_{sol} - TS$

$$E_{MM} = \underbrace{E_b + E_\theta + E_\varphi}_{\text{bonded}} + \underbrace{E_{vdw} + E_{elec}}_{\text{non-bonded}}$$

$$G_{sol} = G_{cav} + G_{vdw} + G_{pol}$$



# Free Energy of a Single Molecule in Solvent

• bonded

$$E_b = \sum_b k_b (r_b - r_b^0)^2 \quad r, r_0 : \text{covalent bond and minima}$$

$$E_\theta = \sum_a k_a (\theta_a - \theta_a^0)^2 \quad \theta, \theta_0 : \text{valence angle and minima}$$

$$E_\varphi = \sum_t k_t (1 + \cos n(\varphi_t - \varphi_t^0)) \quad \varphi, \varphi_0 : \text{torsion and minima}$$

• non-bonded

$$E_{vdw} = \sum_{i < j} \frac{C_{ij}}{r_{ij}^{12}} - \frac{D_{ij}}{r_{ij}^6} \quad C, D : \text{Lennard-Jones parameters}$$

$$r_{ij} : \text{distance between atoms}$$

$$E_{elec} = \sum_{i < j} \frac{q_i q_j}{r_{ij}} \quad q : \text{atomic charge}$$

•  $G_{cav} + G_{vdw} = \gamma S \quad \gamma, S : \text{surface tension and surface area}$



# Binding Energy of Macromolecules

In structure based drug design, binding of a drug (ligand) to a receptor (protein/nucleic acid), usually causes the ligand to either **enhance** or **inhibit** the activity of the receptor.

Binding energy:

$$\Delta G_{\text{bind}} = G_{\text{protein+ligand}} - (G_{\text{protein}} + G_{\text{ligand}})$$

Variation of binding energy:

$$\Delta\Delta G_{\text{bind}} = \Delta G_{\text{bind}}^{\text{wildtype}} - \Delta G_{\text{bind}}^{\text{mutant}}$$



receptor  
protein

ligand



# How to Compute $G_{\text{pol}}$ ?

$$G_{\text{pol}} = \frac{1}{2} \int [\phi_{\text{solvent}}(\mathbf{r}) - \phi_{\text{air}}(\mathbf{r})] \rho(\mathbf{r}) dV$$

## ■ Poisson-Boltzmann (PB) Theory

$$-\nabla \cdot [\epsilon(\mathbf{r}) \nabla \phi(\mathbf{r})] = 4\pi\rho(\mathbf{r}) + 4\pi\lambda(\mathbf{r}) \sum_{j=1}^{\infty} c_j^{\infty} q_j \exp(-q_j \phi(\mathbf{r}) / k_B T)$$

finite difference, finite element

$\epsilon$	dielectric constant
$\phi$	electrostatic potential
$\rho$	solute charge density
$\lambda$	ion accessibility parameter
$c_j^{\infty}$	ion bulk concentration
$q_j$	ion charge
$k_B$	Boltzmann's constant
$T$	temperature

## ■ Generalized Born (GB) Theory

- Born formula (Born 1920)

generalized Born formula (Still 1990)

- methods to compute the Born radii:

• pairwise summation : fast but not easy for force calculation

• analytic, nFFT, and higher order quadrature [\[Bajaj, Zhao 2006\]](#)

$$R_i^{-1} = \frac{1}{4\pi} \int_{\Gamma} \frac{(\mathbf{r} - \mathbf{x}_i) \cdot \mathbf{n}(\mathbf{r})}{|\mathbf{r} - \mathbf{x}_i|^4} dS$$



# GB Theory

Born formula: (single ion)

$$G_{\text{pol}} = -\left(1 - \frac{1}{\epsilon}\right) \frac{q^2}{2a}$$

$\epsilon$  dielectric constant  
 $a$  atomic radius  
 $q$  atomic charge

Generalized Born formula: (molecule)

$$G_{\text{pol}} = -\frac{\tau}{2} \sum_{ij} \frac{q_i q_j}{\left[ r_{ij}^2 + R_i R_j \exp\left(-\frac{r_{ij}^2}{4R_i R_j}\right) \right]^{\frac{1}{2}}}$$

$$\tau = 1 - \frac{1}{\epsilon_{\text{solv}}} \quad r_{ij} : \text{distance between atom } i \text{ and } j$$

$q_i$  : charge of atom  $i$

$R_i$  : effective Born radius of atom  $i$

W. C. Still et al., JACS (1990), 112, 6127-6129





# Calculation of Born Radius

A single charge  $q_i$  located at the center of atom  $i$  in the molecule.

$$G_{\text{pol}} = -\frac{\tau}{2} \frac{q_i^2}{R_i} \quad (\text{by GB})$$

On the other hand, by approximating the electric field as the Coulombic field,

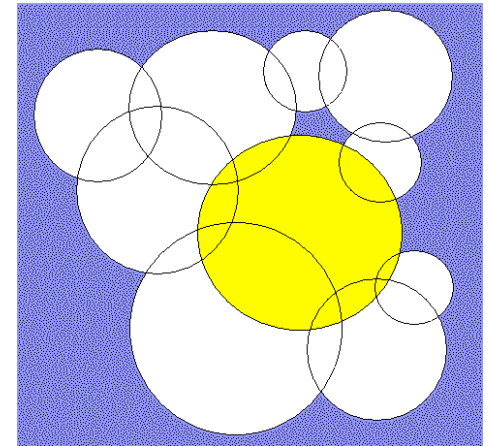
$$G_{\text{pol}} = -\frac{1}{8\pi} \tau \int_{\text{ex}} \frac{q_i^2}{|\mathbf{r} - \mathbf{x}_i|^4} dV$$

Therefore 
$$R_i^{-1} = \frac{1}{4\pi} \int_{\text{ex}} \frac{1}{|\mathbf{r} - \mathbf{x}_i|^4} dV$$

via Gauss'  
Divergence Thm

$$R_i^{-1} = \frac{1}{4\pi} \int_{\Gamma} \frac{(\mathbf{r} - \mathbf{x}_i) \cdot \mathbf{n}(\mathbf{r})}{|\mathbf{r} - \mathbf{x}_i|^4} dS$$

$\Gamma$  : molecular surface



ex: exterior of the molecule



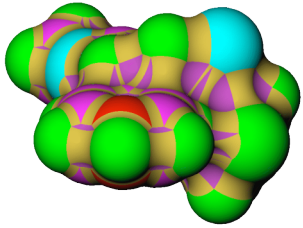
# Fast Computation of Born Radii

$$R_i^{-1} = \frac{1}{4\pi} \int_{\Gamma} \frac{(\mathbf{r} - \mathbf{x}_i) \cdot \mathbf{n}(\mathbf{r})}{|\mathbf{r} - \mathbf{x}_i|^4} dS \approx \frac{1}{4\pi} \sum_{k=1}^N w_k \frac{(\mathbf{r}_k - \mathbf{x}_i) \cdot \mathbf{n}(\mathbf{r}_k)}{|\mathbf{r}_k - \mathbf{x}_i|^4}, \quad \mathbf{r}_k \in \Gamma$$

Algorithm:

1. Generate a model for the molecular surface  $\Gamma$ .
2. Cubature: choose  $w_k$  and  $\mathbf{r}_k$  properly so that higher order accuracy can be obtained for small  $N$ .
3. Fast summation to evaluate  $R_i$ ,  $i = 1, \dots, M$ .





# Convex/Concave Spherical Patches

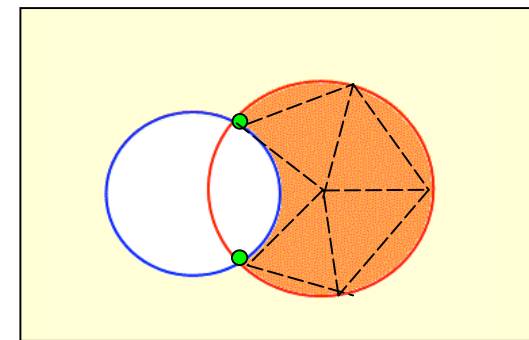
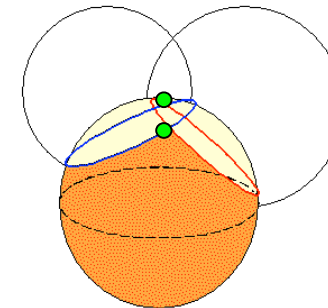
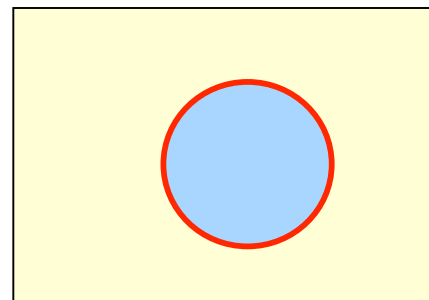
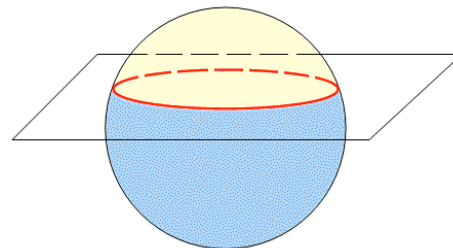
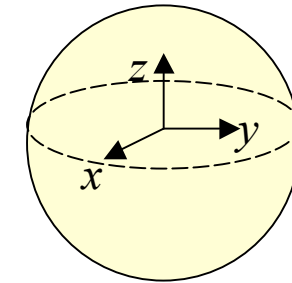
The rational map  $\mathbf{g} : (u, v) \rightarrow (x, y, z)$

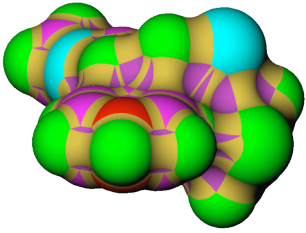
$$x = \frac{2ru}{u^2 + v^2 + 1}$$

$$y = \frac{2rv}{u^2 + v^2 + 1}$$

$$z = \frac{r(u^2 + v^2 - 1)}{u^2 + v^2 + 1}$$

( $r = 1$ , for unit sphere)





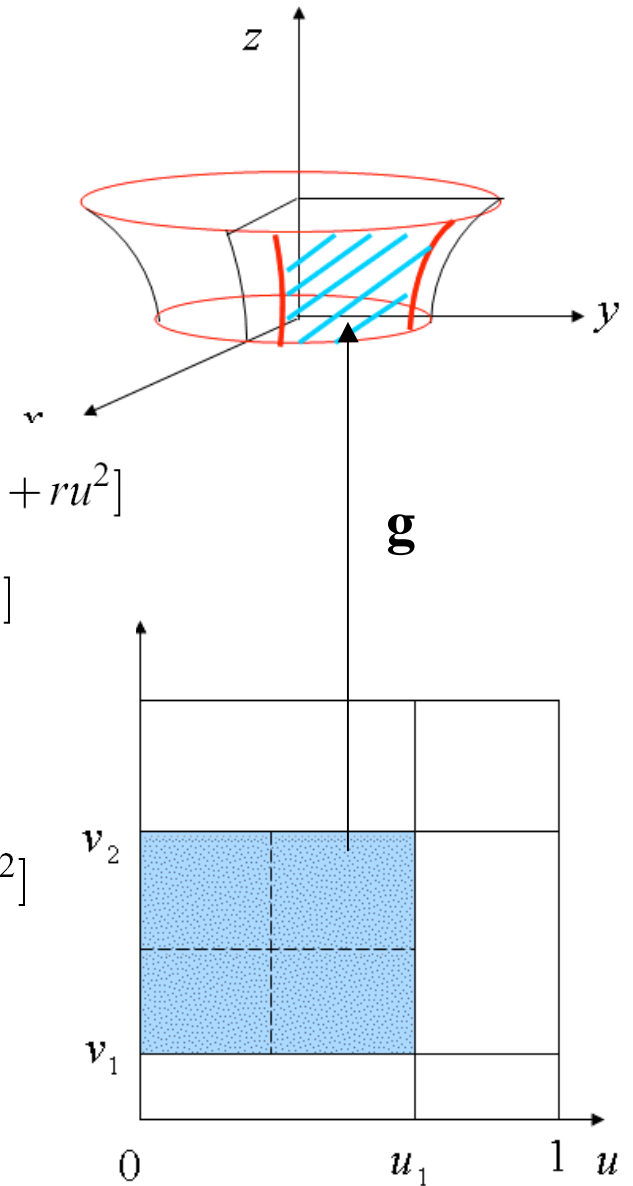
# Toroidal Patches

$$\mathbf{g} : (u, v) \rightarrow (x, y, z)$$

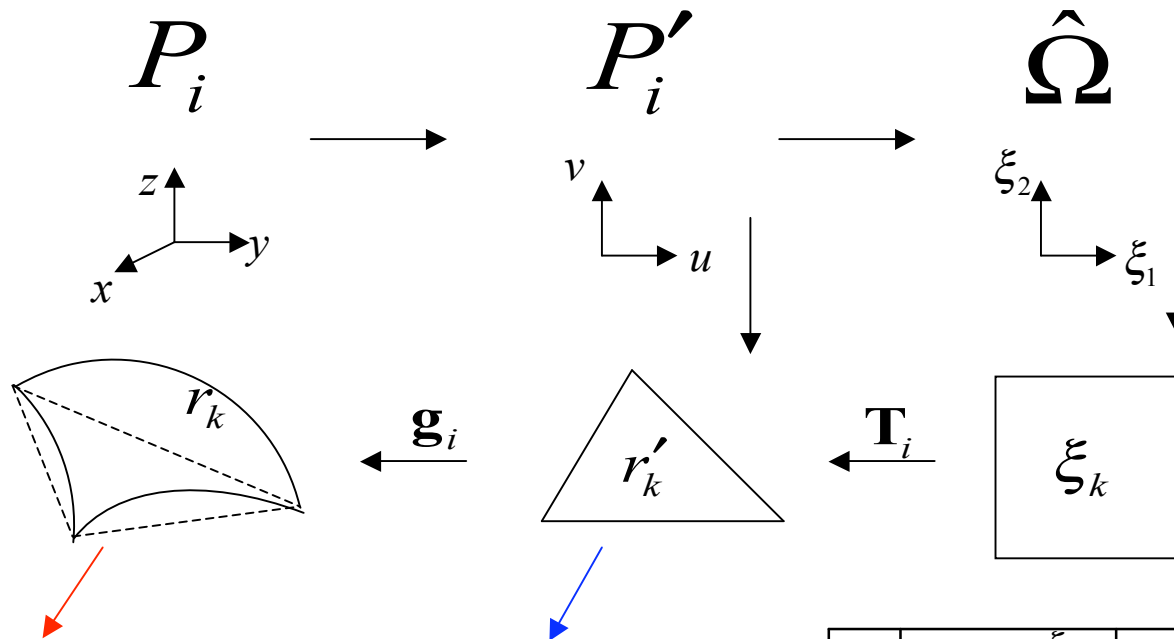
For  $x \geq 0, y \geq 0, z \geq 0$

$$\left\{ \begin{array}{l} x = \frac{1}{\Sigma} [(1-v)^2 + \sqrt{2}v(1-v)] [a[(1-u)^2 + \sqrt{2}u(1-u) + u^2] + ru^2] \\ y = \frac{1}{\Sigma} [v^2 + \sqrt{2}v(1-v)] [a[(1-u)^2 + \sqrt{2}u(1-u) + u^2] + ru^2] \\ z = \frac{r[u^2 + \sqrt{2}u(1-u)]}{(1-u)^2 + \sqrt{2}u(1-u) + u^2} \\ \Sigma = [(1-u)^2 + \sqrt{2}u(1-u) + u^2] [(1-v)^2 + \sqrt{2}v(1-v) + v^2] \end{array} \right.$$

where  $u \in [0,1], v \in [0,1]$



# Cubature over LR Molecular Surface



$$r_k = \mathbf{g}_i(\mathbf{T}_i(\xi_k))$$

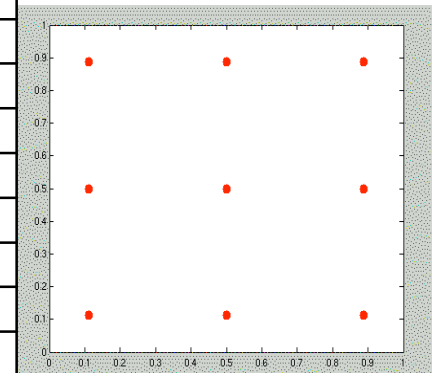
$$w_k = |J(\mathbf{g}_i)J(\mathbf{T}_i)| \hat{w}_k$$

$$r'_k = \mathbf{T}_i(\xi_k)$$

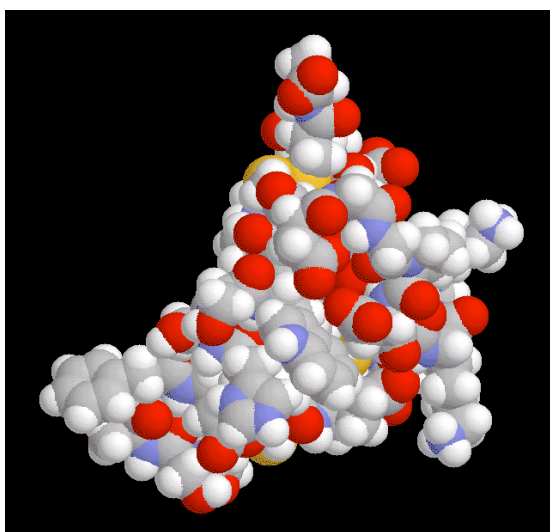
$$w'_k = |J(\mathbf{T}_i)| \hat{w}_k$$

$$\int_{P_i} f(\mathbf{r}) dS \approx \sum_k |J(\mathbf{g}_i)J(\mathbf{T}_i)| \hat{w}_k f(\mathbf{g}_i(\mathbf{T}_i(\xi_k)))$$

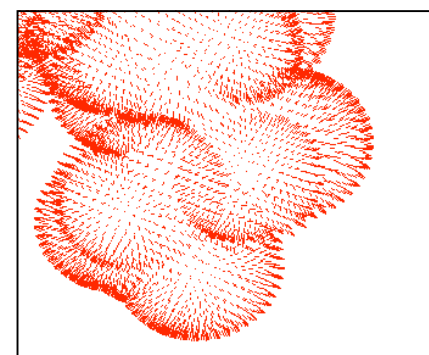
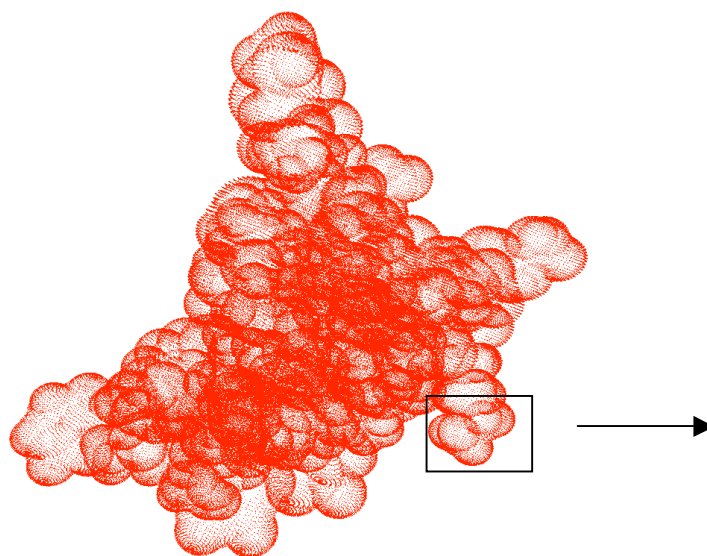
	Nodes $\xi_k$	Weights $\hat{w}_k$
1	(0.1127, 0.1127)	0.3087
2	(0.5, 0.1127)	0.4939
3	(0.8873, 0.1127)	0.3087
4	(0.1127, 0.5)	0.4939
5	(0.5, 0.5)	0.7901
6	(0.8873, 0.5)	0.4939
7	(0.1127, 0.8873)	0.3087
8	(0.5, 0.8873)	0.4939
9	(0.8873, 0.8873)	0.3087



# Cubature Sampling



1AJJ, 514 atoms



(50x25)





# Fast Fourier Summation

After we find the weights  $w_k$  and the nodes  $\mathbf{r}_k$  by sampling over the LR surface or the analytic surface, we apply error-bounded fast Fourier summation methods to evaluate

$$R_i^{-1} = \frac{1}{4\pi} \sum_{k=1}^N w_k \frac{(\mathbf{r}_k - \mathbf{x}_i) \cdot \mathbf{n}(\mathbf{r}_k)}{|\mathbf{r}_k - \mathbf{x}_i|^4} \quad i = 1, \dots, M$$



# Force Calculation

The electrostatic force acting on atom  $\alpha$  which is part of the forces driving Molecular dynamics is

$$\mathbf{F}_\alpha^{\text{elec}} = -\frac{\partial G_{\text{pol}}}{\partial \mathbf{x}_\alpha}$$

$$\frac{\partial G_{\text{pol}}}{\partial \mathbf{x}_\alpha} = \sum_i \sum_{j \neq i} \frac{\partial G_{\text{pol}}}{\partial r_{ij}} \frac{\partial r_{ij}}{\partial \mathbf{x}_\alpha} + \sum_i \frac{\partial G_{\text{pol}}}{\partial R_i} \frac{\partial R_i}{\partial \mathbf{x}_\alpha}$$

$$R_i^{-1} = \frac{1}{4\pi} \int_{\text{ex}} \frac{1}{|\mathbf{r} - \mathbf{x}_i|^4} dV \quad , \text{ or } \quad R_i^{-1} = \frac{1}{4\pi} \int_{\Gamma} \frac{(\mathbf{r} - \mathbf{x}_i) \cdot \mathbf{n}(\mathbf{r})}{|\mathbf{r} - \mathbf{x}_i|^4} dS$$

The integration domain depends on  $\mathbf{x}_\alpha$  .



# Volumetric Analytic Density Function

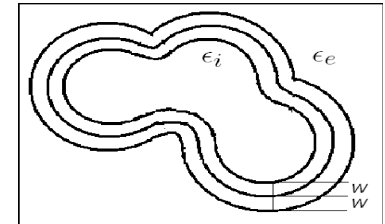
Introduce a differentiable molecular volumetric density function  $\rho(\mathbf{r})$  such that

$$\int_{\text{ex}} \frac{1}{|\mathbf{r} - \mathbf{x}_i|^4} dV \approx \int_{\mathbb{R}^3} \frac{1 - \rho(\mathbf{r})}{|\mathbf{r} - \mathbf{x}_i|^4} dV$$

For atom  $i$ , define  $\rho_i(x) = \begin{cases} 1 & x \leq a_i - w \\ \frac{1}{4w^3} (x - (a_i - w))^3 - \frac{3}{4w^2} (x - (a_i - w))^2 + 1 & a_i - w < x < a_i + w \\ 0 & x \geq a_i + w \end{cases}$

where  $x = \|\mathbf{r} - \mathbf{x}_i\|$

Then define  $\rho(\mathbf{r}) = \sum_i \rho_i - \sum_{i < j} \rho_i \rho_j + \sum_{i < j < k} \rho_i \rho_j \rho_k - \sum_{i < j < k < l} \rho_i \rho_j \rho_k \rho_l$



Molecular Skin

Let  $\bar{\rho} = 1 - \rho$ , then

$$R_i^{-1} \approx \frac{1}{4\pi} \int_{\mathbb{R}^3} \frac{\bar{\rho}(\mathbf{r}, \{\mathbf{x}_j\})}{|\mathbf{r} - \mathbf{x}_i|^4} dV$$



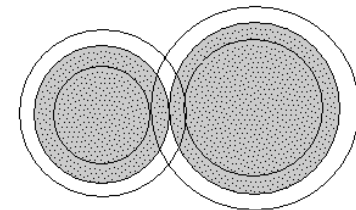
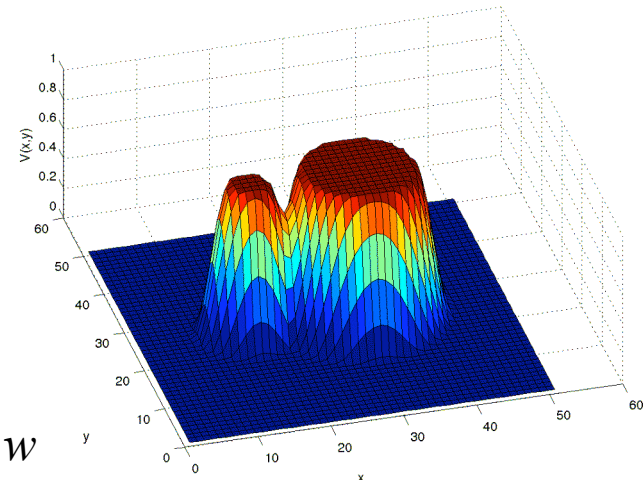
# How to define the analytic volume function?

Im, Lee and Brooks (2003):

$$V(\mathbf{r}) = 1 - H(\mathbf{r})$$

where  $H(\mathbf{r}) = \prod_j H_j(|\mathbf{r} - \mathbf{x}_j|)$

$$H_j(x) = \begin{cases} 0, & x \leq a_j - w \\ \frac{1}{2} + \frac{3}{4w}(x - a_j) - \frac{1}{4w^3}(x - a_j)^3, & a_j - w < x < a_j + w \\ 1, & x \geq a_j + w \end{cases}$$



- $\mathbf{x}$  : distance between the spatial point and center of atom  $j$
- $2w$ : smoothing length (less than 1 Å)
- $a_j$  : the van der Waals radius of atom  $j$

In such a model,  $V(\mathbf{r}) \in C^1$



# Force Calculation

$$-\frac{1}{R_i^2} \frac{\partial R_i}{\partial \mathbf{x}_\alpha} = \frac{1}{4\pi} \int_{\mathbb{R}^3} \frac{\partial}{\partial \mathbf{x}_\alpha} \frac{\bar{\rho}(\mathbf{r}, \{\mathbf{x}_j\})}{|\mathbf{r} - \mathbf{x}_i|^4} dV$$

$$\frac{\partial R_i}{\partial \mathbf{x}_\alpha} = -\frac{R_i^2}{4\pi} \left( \int_{\mathbb{R}^3} \frac{\frac{\partial}{\partial \mathbf{x}_\alpha} \bar{\rho}(\mathbf{r}, \{\mathbf{x}_j\})}{|\mathbf{r} - \mathbf{x}_i|^4} dV + \int_{\text{ex}} \frac{\partial}{\partial \mathbf{x}_\alpha} \frac{1}{|\mathbf{r} - \mathbf{x}_i|^4} dV \right)$$

$$\parallel$$

$$-4\mathbf{x}_i^3 \int_{\Gamma} \frac{(\mathbf{r} - \mathbf{x}_i) \cdot \mathbf{n}(\mathbf{r})}{|\mathbf{r} - \mathbf{x}_i|^6} dS$$

$$\frac{\partial}{\partial \mathbf{x}_\alpha} \bar{\rho} = -\frac{\partial}{\partial \mathbf{x}_\alpha} \tilde{\rho} = \frac{\partial \rho_\alpha}{\partial \mathbf{x}_\alpha} \left( 1 - \sum_j \rho_j + \sum_{j<k} \rho_j \rho_k - \sum_{j<k<l} \rho_j \rho_k \rho_l \right)$$

Molecular surface

Since  $\frac{\partial \rho_\alpha}{\partial \mathbf{x}_\alpha} \neq 0$  only if  $a_\alpha - w < |\mathbf{r} - \mathbf{x}_\alpha| < a_\alpha + w$

Molecular skin

$$\int_{\mathbb{R}^3} \frac{\frac{\partial}{\partial \mathbf{x}_\alpha} \bar{\rho}(\mathbf{r}, \{\mathbf{x}_j\})}{|\mathbf{r} - \mathbf{x}_i|^4} dV = \int_{|\mathbf{r} - \mathbf{x}_\alpha| = a_\alpha - w}^{|\mathbf{r} - \mathbf{x}_\alpha| = a_\alpha + w} \frac{\frac{\partial \rho_\alpha}{\partial \mathbf{x}_\alpha} \left( 1 - \sum_j \rho_j + \sum_{j<k} \rho_j \rho_k - \sum_{j<k<l} \rho_j \rho_k \rho_l \right)}{|\mathbf{r} - \mathbf{x}_i|^4} dV$$



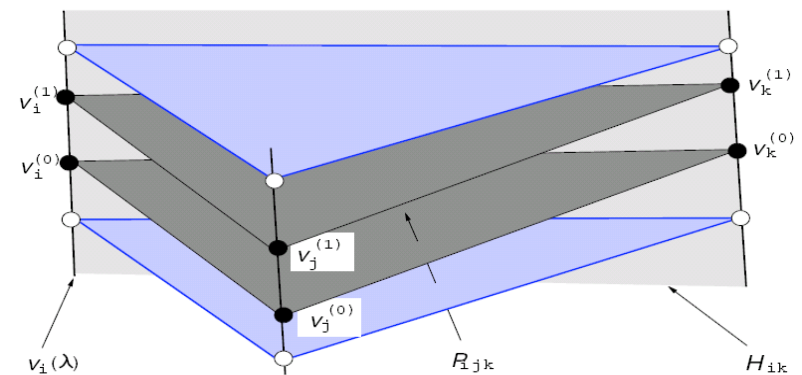
# Force Calculation - Integration over A-shells

- Triangulate the molecular surface with attached normal at each vertex.
- For each triangle, along the normal direction at the vertices, construct prism A-shells:

$$P_{ijk}(I) = \{p := b_1 v_i(\lambda) + b_2 v_j(\lambda) + b_3 v_k(\lambda), b_1 + b_2 + b_3 = 1, \lambda \in I\}$$

where  $I$  is a specified interval

- For a  $\lambda$  sampling, we obtain  $\{\lambda_l\}$   
For each  $\lambda_l$ ,  
 $\{v_i(\lambda_l), v_j(\lambda_l), v_k(\lambda_l)\}$  is a  
parametric A-patch



Bajaj and Xu, CAGD (2002), 89-112



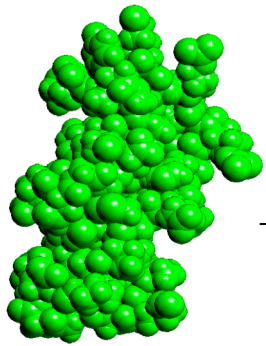
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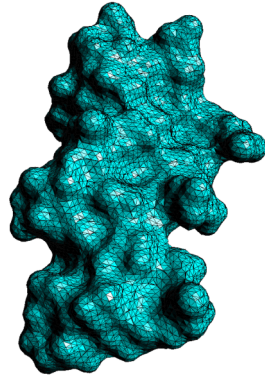
November 2007



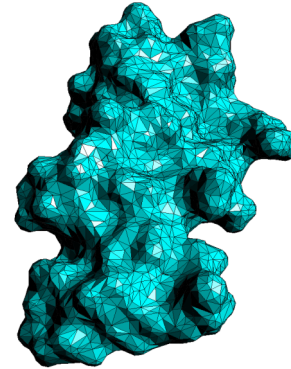
# Continuum Approximation via A-Spline



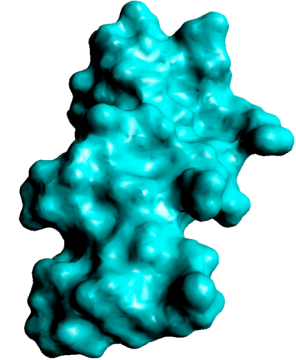
atomic/quasi-atomic structure



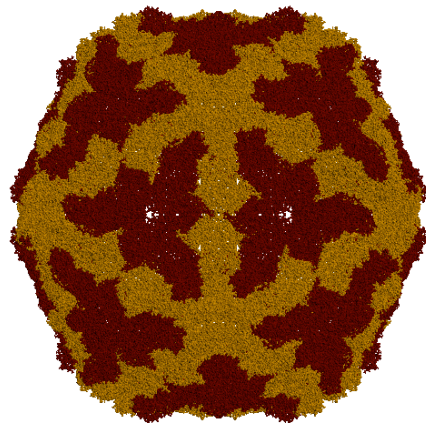
molecular surface triangulation



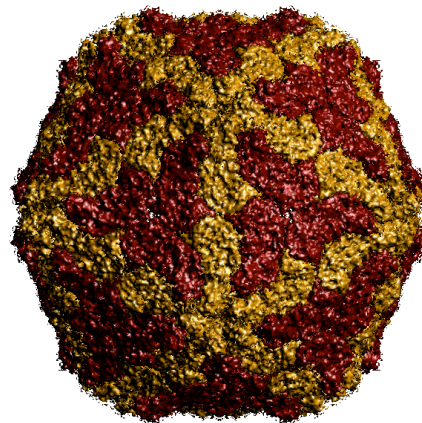
coarse mesh



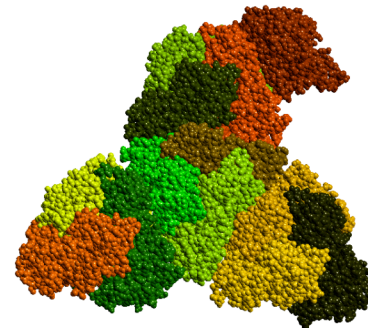
A-Spline



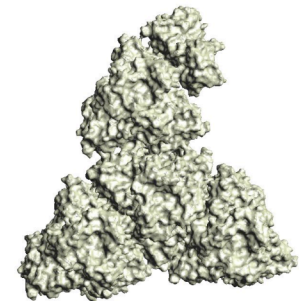
atomic structure of P3



A-Spline



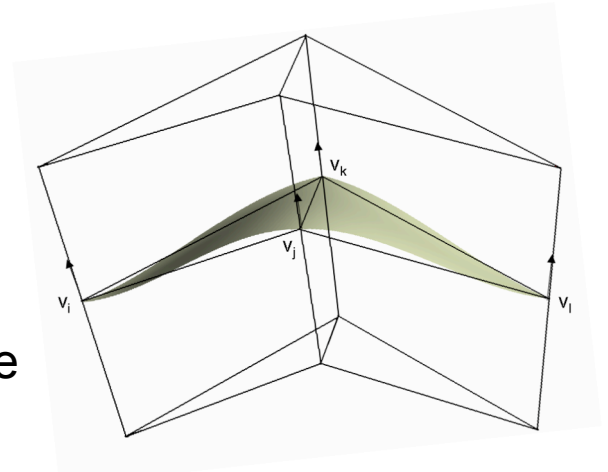
atomic structure asymmetric subunit P8



A-Spline



# A-Spline



## A-Spline model:

$S := \{\mathbf{p}(b_1, b_2, b_3, \lambda) : F(b_1, b_2, b_3, \lambda) = 0, \mathbf{p} \in D_{ijk}\}$  where

- $D_{ijk} = \{\mathbf{p}(b_1, b_2, b_3, \lambda) : \mathbf{p} = b_1 \mathbf{v}_i(\lambda) + b_2 \mathbf{v}_j(\lambda) + b_3 \mathbf{v}_k(\lambda), \lambda \in I_{ijk}\}$

- $I_{ijk}$  is an interval containing 0

- $$F(b_1, b_2, b_3, \lambda) = \sum_{i+j+k=n} b_{ijk}(\lambda) B_{ijk}^n(b_1, b_2, b_3)$$

- $$B_{ijk}^n(b_1, b_2, b_3) = \frac{n!}{i!j!k!} b_1^i b_2^j b_3^k$$

- $n > 2$  so that  $S$  is smooth. We consider the case  $n=3$ .  $b_{ijk}(\lambda)$  are determined so that  $C^1$  continuity is obtained across the patch boundaries.



# Parametrization for FEM/BEM

To evaluate  $\int_{\Gamma} f(\mathbf{x}) dS = \sum_j \int_{\Gamma_j} f(\mathbf{x}) dS$ , where  $\Gamma_j$  is the  $j$ th surface element

$$\int_{\Gamma_i} f(\mathbf{x}) dS = \int_{\sigma_i} f(x(b_1, b_2), y(b_1, b_2), z(b_1, b_2)) \sqrt{EG - F^2} db_1 db_2$$

where

$$E = \left(\frac{\partial x}{\partial b_1}\right)^2 + \left(\frac{\partial y}{\partial b_1}\right)^2 + \left(\frac{\partial z}{\partial b_1}\right)^2$$

$$F = \frac{\partial x}{\partial b_1} \frac{\partial x}{\partial b_2} + \frac{\partial y}{\partial b_1} \frac{\partial y}{\partial b_2} + \frac{\partial z}{\partial b_1} \frac{\partial z}{\partial b_2}$$

$$G = \left(\frac{\partial x}{\partial b_2}\right)^2 + \left(\frac{\partial y}{\partial b_2}\right)^2 + \left(\frac{\partial z}{\partial b_2}\right)^2$$

Apply the quadrature over the planar triangle,

$$\int_{\sigma_i} f(b_1, b_2) \sqrt{EG - F^2} db_1 db_2 \approx \sum_{k=1}^n W_k f(b_1^k, b_2^k) \sqrt{EG - F^2} |_{b_1^k, b_2^k}$$



# Force Calculation

- The method to compute the surface integral is as same as the electrostatic solvation energy calculation.
- For volume integral in the force calculation, cubature over a spherical shell needs to be generated and fast summation method can be applied to evaluate the numerical cubature.
- For symmetric structures, both the surface integral and the volume integral can be sped up by doing the sampling over a single subunit and applying transformations for other subunits.



# Error Estimation (I)

$$|I(\mathbf{x}_i) - \tilde{I}(\mathbf{x}_i)| \leq |I(\mathbf{x}_i) - I_1(\mathbf{x}_i)| + |I_1(\mathbf{x}_i) - I_2(\mathbf{x}_i)| + |I_2(\mathbf{x}_i) - \tilde{I}(\mathbf{x}_i)|$$

↑            ↑             $\underbrace{\hspace{2cm}}$              $\underbrace{\hspace{2cm}}$              $\underbrace{\hspace{2cm}}$

exact    computed    quadrature    Fourier series    NFFT  
value    value    error    truncation error    error



# Error Estimation (II)

## A) NFFT error

$$|I_2(\mathbf{x}_i) - \tilde{I}(\mathbf{x}_i)| \leq E_f(\mathbf{x}_i) + E_t(\mathbf{x}_i)$$

$$\|E_f\|_\infty \leq \|\hat{f}\|_1 \max_{\hat{\mathbf{u}} \in I_n} \sum_{r \in \mathbf{Z}^3 \setminus \{0\}} |\hat{\phi}(\hat{\mathbf{u}} + nr) / \hat{\phi}(\hat{\mathbf{u}})|$$

$$\|E_t\|_\infty \leq \|\hat{f}\|_1 n^{-3} \left( \max_{\hat{\mathbf{u}} \in I_n} |\hat{\phi}(\hat{\mathbf{u}})|^{-1} \right) \sum_{\mathbf{l} \in I_{\sigma n}} |\phi(\mathbf{x} - \frac{\mathbf{l}}{\sigma n}) - \psi(\mathbf{x} - \frac{\mathbf{l}}{\sigma n})|$$

where  $\|\hat{f}\|_1 = \sum_{\hat{\mathbf{u}} \in I_n} |\hat{f}_{\hat{\mathbf{u}}}|$

Steidl, ACM (1998), 337-352





# Error Estimation (III)

## B) Cubature error

By Peano's theorem, the Gaussian Cubature error for  $f \in C^{2m}$  is

$$E_m(f) = \left| \int_a^b f(x) dx - \sum_{k=1}^m w_k f(x_k) \right| = \frac{(b-a)^{2m+1} (m!)^4}{(2m+1)[(2m)!]^3} |f^{(2m)}(\xi)|$$

For 2D quad patches:

$$E_{m_1 m_2}(f) = \left| \int_{a_1}^{b_1} \int_{a_2}^{b_2} f(x, y) dy dx - \sum_{i=1}^{m_1} \sum_{j=1}^{m_2} A_i B_j f(x_i, y_j) \right| \leq (b_2 - a_2) E_{m_1} + (b_1 - a_1) E_{m_2}$$

Let  $m_1 = m_2 = m$ ,  $N_P$  be the number of patches,  $M = \max \left\{ \left\| \frac{\partial^{2m} h}{\partial u^{2m}} \right\|_{\infty}, \left\| \frac{\partial^{2m} h}{\partial v^{2m}} \right\|_{\infty} \right\}$

$$h(u, v) = f(\mathbf{g}(u, v)) |J(\mathbf{g})|$$

$$|I(\mathbf{x}_i) - I_1(\mathbf{x}_i)| \leq N_P \frac{(u_2 - u_1)(v_2 - v_1)(m!)^4}{(2m+1)[(2m)!]^3} M (h_u^{2m} + h_v^{2m})$$

Bajaj, Zhao (2006)



# Error Estimation (IV)

## C) Fourier series truncation error

$$R_n = I_1(\mathbf{x}) - I_2(\mathbf{x}) = \sum_{\mathbf{u} \in I_\infty \setminus I_n} b_{\mathbf{u}} e^{2\pi i \mathbf{u} \cdot \mathbf{x}}$$

In one dimension,

$$|R_n| \leq \sum_{\omega=n+1}^{\infty} (|b_\omega| + |b_{-\omega}|), \text{ where } b_\omega = \int_{-\frac{1}{2}}^{\frac{1}{2}} K(x) e^{-2\pi i \omega x} dx$$

If  $K \in C^{2m}$ ,  $m \geq 1$ , by successive integration by parts,

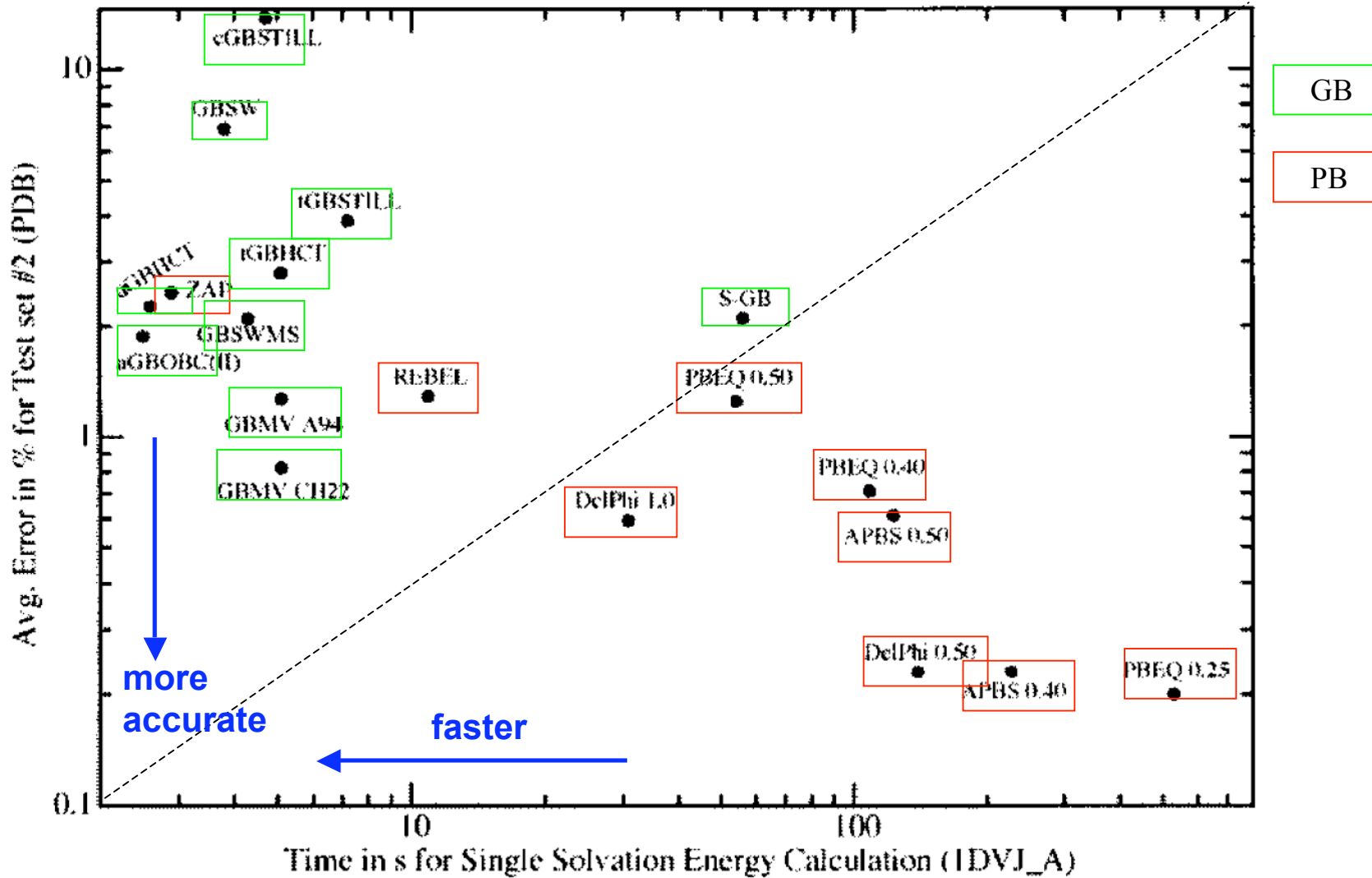
$$|b_\omega| \leq \left(\frac{1}{2\pi\omega}\right)^{2m} \int_{-\frac{1}{2}}^{\frac{1}{2}} |K^{(2m)}(x)| dx = \left(\frac{1}{2\pi\omega}\right)^{2m} \mu_{2m}$$

$$|R_n| \leq \frac{2\mu_{2m}}{(2\pi)^{2m}} \sum_{\omega=n+1}^{\infty} \frac{1}{\omega^{2m}} \leq \frac{2\mu_{2m}}{(2\pi)^{2m}} \int_n^{\infty} \frac{1}{\omega^{2m}} d\omega = \frac{2\mu_{2m}}{(2\pi)^{2m} (2m-1)n^{2m-1}}$$

Bajaj, Siddahanavalli (2005)



# GB versus PB



# Generalized Born Energetics

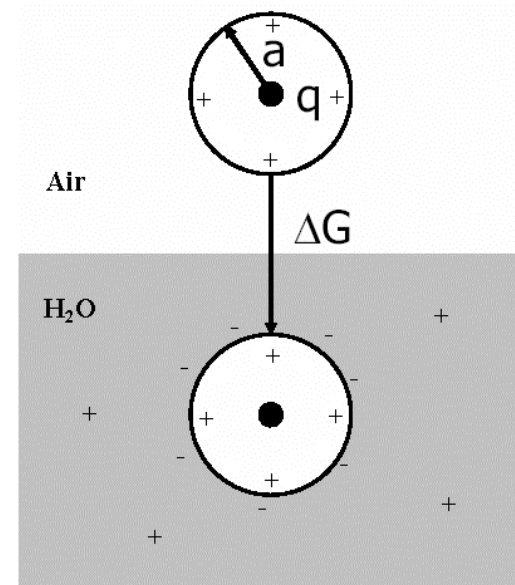
<b>Name</b>	<b>Year</b>	<b>Authors</b>	<b>Program</b>	<b>Calculation of Born radii</b>	<b>CFA Corr.</b>	<b>Dielectric Boundary</b>
GB GB/SA	1990	Still, Tempczyk, Hawley, Hendrickson	Macromodel	FDPB	Yes	Molecular surface
GB	1995	Hawkins, Cramer, Truhlar	Amber, Tinker	Pairwise descreening	No	Overlapping spheres
ACE	1996/ 2001	Schaefer, Karplus	CHARMM	Pairwise sum of atomic volumes	No	Overlapping Gaussians
GB	1997	Qiu, Shenkin, Hollinger, Still	Macromodel, Tinker	Pairwise sum of atomic volumes	No	Overlapping spheres
S-GB	1998	Ghosh, Rapp, Friesner	Impact	Surface integral formulation	Yes	Overlapping spheres
GB1	1999	Dominy, Brooks	CHARMM	Pairwise sum of atomic volumes	No	Overlapping spheres
GBMV	2002/ 2003	Lee, Salsbury, Feig, Brooks	CHARMM	Numerical integration	Yes	Molecular surface
GBSW	2003	Im, Lee, Brooks	CHARMM	Numerical integration	Yes	Overlapping spheres + smooth boundary
AGB	2004	Gallicchio, Levy	Impact	Pairwise descreening	No	Overlapping spheres
GB	2004	Onufriev, Case	Amber	Pairwise descreening, radius rescaling	No	Molecular surface



The solvation energy consists of three components:

- solute-solvent cavity formation
- solute-solvent hydrophobicity (van der Waals interaction)
- solute-solvent electrostatic polarization

$$G_{sol} = G_{cav} + G_{vdw} + G_{pol}$$



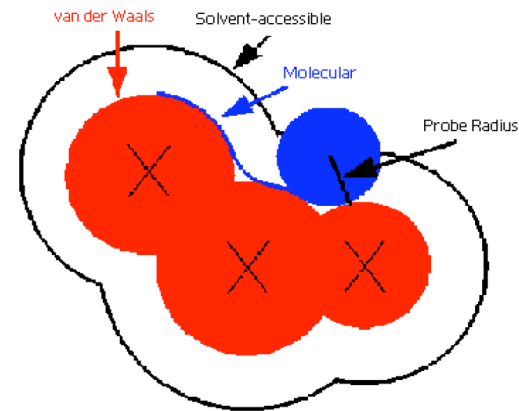
$$G_{sol} = G_{cav} + G_{vdw} + G_{pol}$$

- $G_{cav} + G_{vdw} = \sum_k \sigma_k SA_k$

$\sigma_k$  : empirical parameter

(7.2 cal/(mol Å<sup>2</sup>), *still et al, 1990*)

$SA_k$ : solvent-accessible surface area



- $G_{pol}$  : Poisson theory  
or generalized Born (GB) theory

Given an accurate calculation of the Born radii, GB energy can reproduce Poisson energy within 1% error. (Lee et al, 2002)



## Poisson theory

### Model:

Solvent: high-dielectric continuum, e.g. water  $\epsilon = 81.5$  (14<sup>0</sup>C)

Solute: a macromolecule of lower dielectric embedding charges

The electrostatic potential  $\phi$  in such a system is

$$-\nabla \cdot [\epsilon(\mathbf{r}) \nabla \phi(\mathbf{r})] = 4\pi \rho(\mathbf{r}) \quad (\text{Poisson equation})$$

$\rho(r)$ : charge density at the position  $r$

$$\epsilon(r) = \begin{cases} \epsilon_{in} & \text{if } r \text{ is in the molecule interior} \\ \epsilon_{ex} & \text{if } r \text{ is in the exterior} \end{cases}$$



For gas phase (air),  $\varepsilon_{ex} = 1 \Rightarrow \phi = \phi_{vac}(\mathbf{r})$

For solvent phase,  $\varepsilon_{ex} = \varepsilon_{solvent} \Rightarrow \phi = \phi_{sol}(\mathbf{r})$

} finite difference or  
boundary element method  
(expensive calculation!)

The electrostatic energy is equivalent to the work required to assemble a charge distribution, so

$$G = \frac{1}{2} \int \rho(\mathbf{r})\phi(\mathbf{r}) dV$$

The electrostatic component of the solvation energy is

$$G_{pol} = \frac{1}{2} \int (\phi_{sol}(\mathbf{r}) - \phi_{vac}(\mathbf{r}))\rho(\mathbf{r}) dV$$



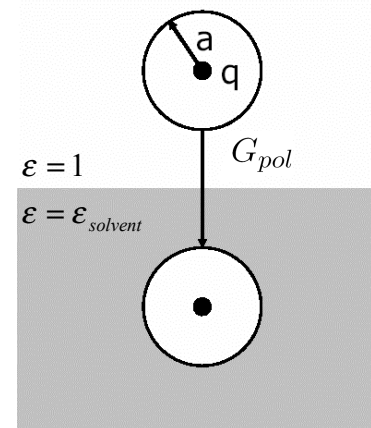


## Generalized Born theory

**Simple case:** one ion of radius  $a$  and charge  $q$

The electrostatic solvation energy is

$$G_{pol} = \frac{q^2}{2a} \left( \frac{1}{\epsilon_{solvent}} - 1 \right) \quad (\text{Born formula})$$



**General case:** A molecule consists of atoms of radii  $a_1 \dots a_N$  with charges  $q_1 \dots q_N$ , and  $r_{ij}$  is the distance between atom  $i$  and  $j$ , the electrostatic solvation energy is

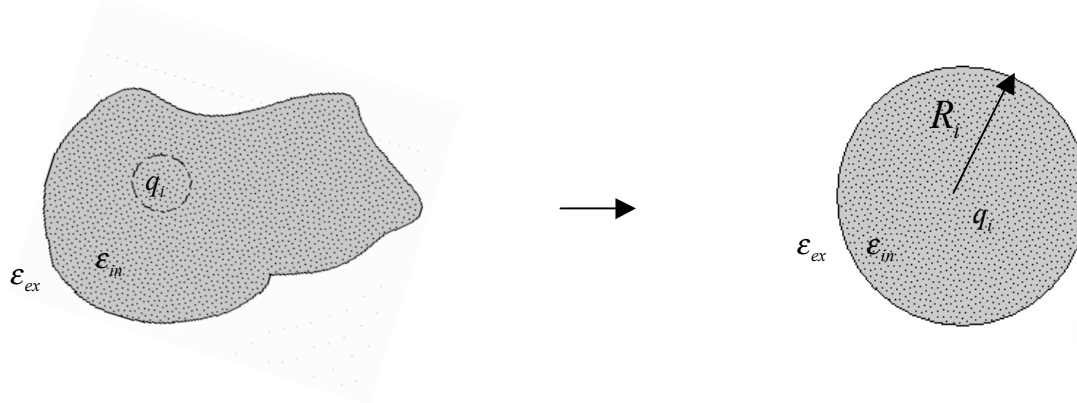
$$G_{pol} = \frac{1}{2} \left( \frac{1}{\epsilon_{solvent}} - 1 \right) \sum_{i,j} \frac{q_i q_j}{\left[ r_{ij}^2 + R_i R_j \exp\left(-\frac{r_{ij}^2}{4R_i R_j}\right) \right]^{\frac{1}{2}}}$$

$R_i$ : Born radius of atom  $i$

(Still et al, 1990)



## Born radius



The Born radius is chosen in this way: we assume that there is a single charge  $q_i$  located at the center of atom  $i$  in the molecule. We solve the Poisson equation for this system. If we let it be equivalent to another system where there is a sphere of radius  $R_i$  with charge  $q_i$  at its center, then  $R_i$  is the effective Born radius of atom  $i$ . So

$$\frac{1}{2} q_i (\phi_{sol} - \phi_{vac}) = \frac{q_i^2}{2R_i} \left( \frac{1}{\epsilon_{solvent}} - 1 \right)$$

Not practical !



A practical approach to compute  $R_i$  : (Donald Bashford et al, 2000)

In classical electrostatics the work required to assemble a continuous charge distribution is

$$W = \frac{1}{2} \int \rho(\mathbf{r})\phi(\mathbf{r}) dV$$

From Poisson equation, we know that

$$\rho = \frac{\epsilon}{4\pi} \nabla \cdot \mathbf{E}$$

So

$$W = \frac{1}{8\pi} \int \epsilon\phi\nabla \cdot \mathbf{E} dV$$

Because of the fact that  $\nabla \cdot (\mathbf{E}\phi) = \phi\nabla \cdot \mathbf{E} + \mathbf{E} \cdot \nabla\phi$  and  $\nabla\phi = -\mathbf{E}$  therefore

$$W = \frac{1}{8\pi} \left[ \int \epsilon\nabla \cdot (\mathbf{E}\phi) dV + \int \epsilon\mathbf{E} \cdot \mathbf{E} dV \right]$$



$$W = \frac{1}{8\pi} \left[ \int \varepsilon \nabla \cdot (\mathbf{E}\phi) dV + \int \varepsilon \mathbf{E} \cdot \mathbf{E} dV \right]$$

Apply Gauss' theorem:  $\int_V (\nabla \cdot \mathbf{F}) dV = \int_{\partial V} \mathbf{F} \cdot d\mathbf{S}$

$$W = \frac{1}{8\pi} \left[ \oint_S \varepsilon \mathbf{E}\phi d\mathbf{S} + \int_V \varepsilon \mathbf{E} \cdot \mathbf{E} dV \right]$$

Assume the solute is embedded in an infinite water dielectric. The electric field at far distance from the charge distribution looks like the field of a point charge, so

$$E \sim \frac{1}{r^2} \quad \phi \sim \frac{1}{r} \quad S \sim r^2 \quad \oint_S \varepsilon \mathbf{E}\phi d\mathbf{S} \sim \frac{1}{r}$$

As  $r \rightarrow \infty$

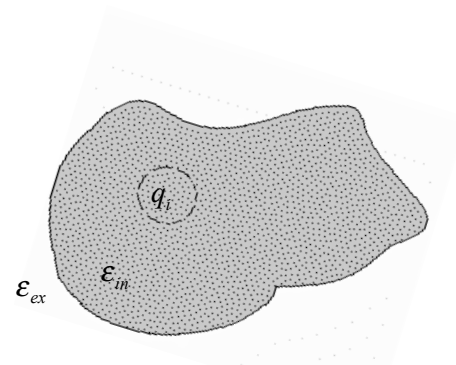
$$W = \frac{1}{8\pi} \int \varepsilon \mathbf{E} \cdot \mathbf{E} dV$$

The electric field due to charge  $q_i$  (lying on the origin) is

$$\mathbf{E}_i = \frac{q_i \mathbf{r}}{\varepsilon r^3} \quad (\text{Coulombic electric field})$$



The electrostatic energy of the system :

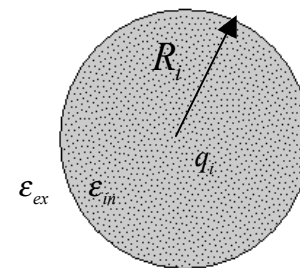


$$G_i = \frac{1}{8\pi} \int \epsilon \mathbf{E} \cdot \mathbf{E} dV \approx \frac{1}{8\pi} \int_{in} \frac{q_i^2}{r^4 \epsilon_{in}} dV + \frac{1}{8\pi} \int_{ex} \frac{q_i^2}{r^4 \epsilon_{ex}} dV$$

The electrostatic solvation energy of this system is

$$G_{pol}^i = G_{i,solvent} - G_{i,air} = \frac{1}{8\pi} \left( \frac{1}{\epsilon_{solvent}} - 1 \right) \int_{ex} \frac{q_i^2}{r^4} dV$$

The electrostatic solvation energy of the system:



$$G_{pol}^i = \frac{q_i^2}{2R_i} \left( \frac{1}{\epsilon_{solvent}} - 1 \right)$$



$$\frac{1}{8\pi} \left( \frac{1}{\epsilon_{solvent}} - 1 \right) \int_{ex} \frac{q_i^2}{r^4} dV = \frac{q_i^2}{2R_i} \left( \frac{1}{\epsilon_{solvent}} - 1 \right)$$

⇒

$$\begin{aligned} R_i^{-1} &= \frac{1}{4\pi} \int_{ex} \frac{1}{r^4} dV \\ &= \frac{1}{4\pi} \left( \int_{V, r > a_i} \frac{1}{r^4} dV - \int_{in, r > a_i} \frac{1}{r^4} dV \right) \quad (\int dV = \iint r^2 dr d\Omega) \\ &= a_i^{-1} - \frac{1}{4\pi} \int_{in, r > a_i} \frac{1}{r^4} dV \end{aligned}$$

A sphere of radius  $a_i$  (the van der Waals radius of atom  $i$ ) is excluded from the integration domain to avoid singularity at 0.



# Electrostatic Solvation Energy

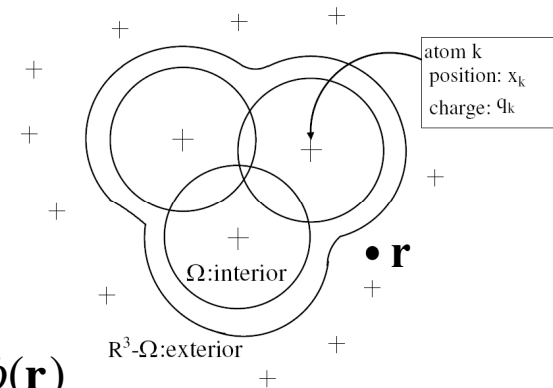
- $$G_{\text{pol}} = \frac{1}{2} \int [\phi_{\text{solvent}}(\mathbf{r}) - \phi_{\text{air}}(\mathbf{r})] \rho(\mathbf{r}) dV$$

Poisson-Boltzmann (PB) theory:

$$\nabla \cdot [\epsilon(\mathbf{r}) \nabla \phi(\mathbf{r})] = \rho_c(\mathbf{r}) + \rho_b(\mathbf{r})$$

$$\rho_c(\mathbf{r}) = -4\pi \sum_{k=1}^M q_k \delta(\mathbf{r} - \mathbf{x}_k), \quad \rho_b(\mathbf{r}) = \kappa^2(\mathbf{r}) \left( \frac{k_B T}{e_c} \right) \sinh\left( \frac{e_c \phi(\mathbf{r})}{k_B T} \right)$$

where



$\epsilon(\mathbf{r})$	dielectric coefficient at $\mathbf{r}$	$q_k$	charge of atom k
$\mathbf{x}_k$	position of charge point $q_k$ (center of atom k)	$M$	the number of point charge
$\kappa(\mathbf{r}) = \sqrt{\frac{8\pi e_c^2 I(\mathbf{r})}{k_B T}}$	modified Debye-Huckel parameter	$e_c$	charge of an electron
$k_B$	Boltzmann's constant	$T$	absolute temperature
$I(\mathbf{r}) = \frac{1}{2} \sum_i c_i z_i^2$	ionic strengths at $\mathbf{r}$	$c_i, z_i$	concentration and charge of $i^{\text{th}}$ ionic species



# Electrostatic Solvation Energy

## PB theory: (cont.)

After we solve the PB equations, we could calculate the reaction field energy

$$G_{rf}(\kappa, \epsilon_e) = \frac{1}{2} \sum_{k=1}^M \phi(\mathbf{x}_k) q_k$$

and the electrostatic solvation energy

$$G_{pol}(\kappa, \epsilon_e) = G_{rf}(\kappa, \epsilon_e) - G_{rf}(0, 1)$$





# Linear Poisson-Boltzmann Equation

The LPB equation is formally correct when  $q_i\phi(r)/kT \ll 1$

$$\nabla(\epsilon(\vec{X})\nabla\phi(\vec{X})) = \rho_c(\vec{X}) + \rho_b^L(\vec{X})$$

Where  $\rho_b^L(x)$  is the first term of Taylor expansion of  $\rho_b(x)$

$$\begin{aligned}\rho_b(x) &= \frac{k_B T}{e_c} \sinh\left(\frac{e_c \phi(\vec{X})}{k_B T}\right) \\ &= \phi(\vec{X}) + \frac{k_B T}{e_c} \left( \frac{1}{3!} \left(\frac{e_c \phi(\vec{X})}{k_B T}\right)^3 + \frac{1}{5!} \left(\frac{e_c \phi(\vec{X})}{k_B T}\right)^5 + \dots \right)\end{aligned}$$



# Boundary Element Solution to LPBE

The boundary element representation of the solution:

$$\begin{aligned}\nabla(\epsilon(\mathbf{x})\nabla\phi(\mathbf{x})) &= -4\pi \sum_{k=1}^{n_c} q_k \delta(\mathbf{x} - \mathbf{x}_k) & \mathbf{x} \in \Omega \\ \nabla(\epsilon(\mathbf{x})\nabla\phi(\mathbf{x})) &= \kappa^2\phi(\mathbf{x}) & \mathbf{x} \in R^3 \setminus \Omega\end{aligned}$$

The interface continuous condition on the boundary  $\Gamma$  of  $\Omega$

$$\begin{aligned}\phi(\vec{\mathbf{X}}) &= \phi_1(\vec{\mathbf{X}}) = \phi_2(\vec{\mathbf{X}}) & \mathbf{x} \in \Gamma \\ \frac{\partial\phi}{\partial n_x}(\vec{\mathbf{X}}) &= \frac{\partial\phi_1}{\partial n_x}(\vec{\mathbf{X}}) = \frac{\epsilon_e}{\epsilon_i} \frac{\partial\phi_2}{\partial n_x}(\vec{\mathbf{X}}) & \mathbf{x} \in \Gamma\end{aligned}$$



# Nonderivative Boundary Integral Equations

Apply Green's second identity to the above equations

$$\int_{\Omega} (\phi \nabla^2 \psi - \psi \nabla^2 \phi) \cdot d\Omega = \int_{\Gamma} (\phi \nabla \psi - \psi \nabla \phi) \cdot d\Gamma$$

We can get the boundary integral equations:

$$\frac{1}{2} \phi(x) + \int_{\Gamma} \frac{1}{4\pi} \left( \frac{\partial}{\partial n_y} \frac{1}{|x-y|} \phi(y) - \frac{1}{|x-y|} \frac{\partial \phi(y)}{\partial n_y} \right) d\Gamma = \sum_{k=1}^{n_c} \frac{q_k}{4\pi \epsilon_j |x-x_k|}$$

$$\frac{1}{2} \phi(x) + \int_{\Gamma} \frac{1}{4\pi} \left( \frac{\epsilon_e}{\epsilon_j} \frac{e^{-\kappa|x-y|}}{|x-y|} \frac{\partial \phi(y)}{\partial n_y} - \frac{\partial}{\partial n_y} \frac{e^{-\kappa|x-y|}}{|x-y|} \phi(y) \right) d\Gamma = 0$$



# Derivative Boundary Integral Equations

Let  $G_0(x, y) = \frac{1}{4\pi|x-y|}$  and  $G_\kappa(x, y) = \frac{e^{-\kappa|x-y|}}{4\pi|x-y|}$

Then

$$\frac{1}{2}\left(1 + \frac{\epsilon_e}{\epsilon_i}\right)\phi(x) + \int_\Gamma \left(\frac{\partial G_0(x, y)}{\partial n_y} - \frac{\partial G_\kappa(x, y)}{\partial n_y}\right)\phi(y) d\Gamma - \int_\Gamma (G_0(x, y) - G_\kappa(x, y)) \frac{\partial \phi(y)}{\partial n_y} d\Gamma = \sum_{k=1}^{n_c} \frac{q_k}{\epsilon_i} G_0(x, x_k)$$

$$\frac{1}{2}\left(1 + \frac{\epsilon_i}{\epsilon_e}\right)\frac{\partial \phi(x)}{\partial n_x} + \int_\Gamma \left(\frac{\partial^2 G_0(x, y)}{\partial n_x \partial n_y} - \frac{\epsilon_e}{\epsilon_i} \frac{\partial^2 G_\kappa(x, y)}{\partial n_x \partial n_y}\right)\phi(y) d\Gamma - \int_\Gamma \left(\frac{\partial G_0(x, y)}{\partial n_x} - \frac{\epsilon_i}{\epsilon_e} \frac{\partial G_\kappa(x, y)}{\partial n_x}\right) \frac{\partial \phi(y)}{\partial n_y} = \sum_{k=1}^{n_c} \frac{q_k}{\epsilon_i} \frac{\partial G_0(x, x_k)}{\partial n_x}$$



# Numerical Treatment of Boundary Integral Equations using A-Spline

The numerical treatment of the boundary integral equations of the LPBE:

$$\begin{aligned} & \frac{1}{2} \left( 1 + \frac{\epsilon_e}{\epsilon_j} \right) \phi(X) \\ &= \sum_{e=1}^E \frac{\partial \phi}{\partial n}(X_e) \sum_k W_{kf} J(b_1^k, b_2^k) (G_0(x, b_1^k, b_2^k) - G_{\kappa}(x, b_1^k, b_2^k)) \\ & - \sum_{e=1}^E \phi(X_e) \sum_k W_{kf} J(b_1^k, b_2^k) \left( \frac{\partial G_0}{\partial n}(x, b_1^k, b_2^k) - \frac{\partial G_{\kappa}}{\partial n}(x, b_1^k, b_2^k) \right) \\ & + \sum_{k=1}^{n_c} \frac{q_k}{\epsilon_j} G_0(x, X_k) \end{aligned}$$

where

$X_e$ : center of the eth element

$E$ : number of elements

$X$ : collocation point



# Numerical Treatment of Boundary Integral Equations using A-Spline

Since  $y = \sum_{i=1}^3 b_i v_i(\lambda)$ , we have

$$G_0(x, y) = \frac{1}{4\pi|x - \sum_{i=1}^3 b_i v_i(\lambda)|} \quad G_\kappa(x, y) = \frac{e^{-\kappa|x - \sum_{i=1}^3 b_i v_i(\lambda)|}}{4\pi|x - \sum_{i=1}^3 b_i v_i(\lambda)|}$$

$$\frac{\partial G_0(x, y)}{\partial n_y} = \frac{-(x - \sum_{i=1}^3 b_i v_i(\lambda)) \cdot n_y(\lambda)}{4\pi|x - \sum_{i=1}^3 b_i v_i(\lambda)|^3}$$

$$\frac{\partial G_\kappa(x, y)}{\partial n_y} = \frac{-e^{-\kappa|x - \sum_{i=1}^3 b_i v_i(\lambda)|} (1 + \kappa|x - \sum_{i=1}^3 b_i v_i(\lambda)|) (x - \sum_{i=1}^3 b_i v_i(\lambda)) \cdot n_y}{4\pi|x - \sum_{i=1}^3 b_i v_i(\lambda)|^3}$$



# Numerical Treatment of Boundary Integral Equations using A-Spline

The boundary integral equations become

$$\begin{aligned} \frac{1}{2}\left(1 + \frac{\epsilon_e}{\epsilon_j}\right)\phi(\mathbf{x}) &= \sum_{e=1}^E \frac{\partial\phi}{\partial n}(\mathbf{x}_e) \sum_k W_{kf} J(b_1^k, b_2^k) \frac{1 - e^{-\kappa|\mathbf{x} - \sum b_i v_i(\lambda)|}}{4\pi|\mathbf{x} - \sum b_i v_i(\lambda)|} \\ &\quad - \sum_{e=1}^E \phi(\mathbf{x}_e) \sum_k \left( W_{kf} J(b_1^k, b_2^k) \right. \\ &\quad \times \left. \frac{(-1 + (1.0 + \kappa|\mathbf{x} - \sum b_i v_i(\lambda)|)e^{-\kappa|\mathbf{x} - \sum b_i v_i(\lambda)|})(\mathbf{x} - \sum b_i v_i(\lambda)) \cdot \mathbf{n}_y(\lambda)}{4\pi|\mathbf{x} - \sum b_i v_i(\lambda)|^3} \right) \\ &\quad + \sum_{k=1}^{n_c} \frac{q_k}{\epsilon_j} \frac{1}{4\pi|\mathbf{x} - \mathbf{x}_k|} \end{aligned}$$

where

$$\mathbf{n}_y(\lambda) = \nabla F = T^{-1} \left( \frac{\partial F}{\partial b_1}, \frac{\partial F}{\partial b_2}, \frac{\partial F}{\partial \lambda} \right)^T$$



# Boundary Element Solver to LPBE

The linear system of LPBE boundary element solver are

$$\frac{1}{2}\left(1 + \frac{\epsilon_e}{\epsilon_j}\right)\phi_j = \sum_{e=1}^E \frac{\partial \phi^e}{\partial n} A_j^e + \sum_{e=1}^E \phi^e B_j^e + \sum_{k=1}^{n_c} q_k G_0(x_j, x_k)$$

$$\frac{1}{2}\left(1 + \frac{\epsilon_j}{\epsilon_e}\right)\frac{\partial \phi_j}{\partial n} = \sum_{e=1}^E \frac{\partial \phi^e}{\partial n} D_j^e + \sum_{e=1}^E \phi^e C_j^e + \sum_{k=1}^{n_c} q_k \frac{\partial G_0}{\partial n}(x_j, x_k)$$

where

$$A_i^e = \sum_k W_{kf} J(b_1^k, b_2^k) (G_0(x, b_1^k, b_2^k) - G_{\kappa}(x, b_1^k, b_2^k))$$

$$B_i^e = \sum_k W_{kf} J(b_1^k, b_2^k) \left( \frac{\partial G_0}{\partial n_i}(x, b_1^k, b_2^k) - \frac{\epsilon_e}{\epsilon_j} \frac{\partial G_{\kappa}}{\partial n}(x, b_1^k, b_2^k) \right)$$

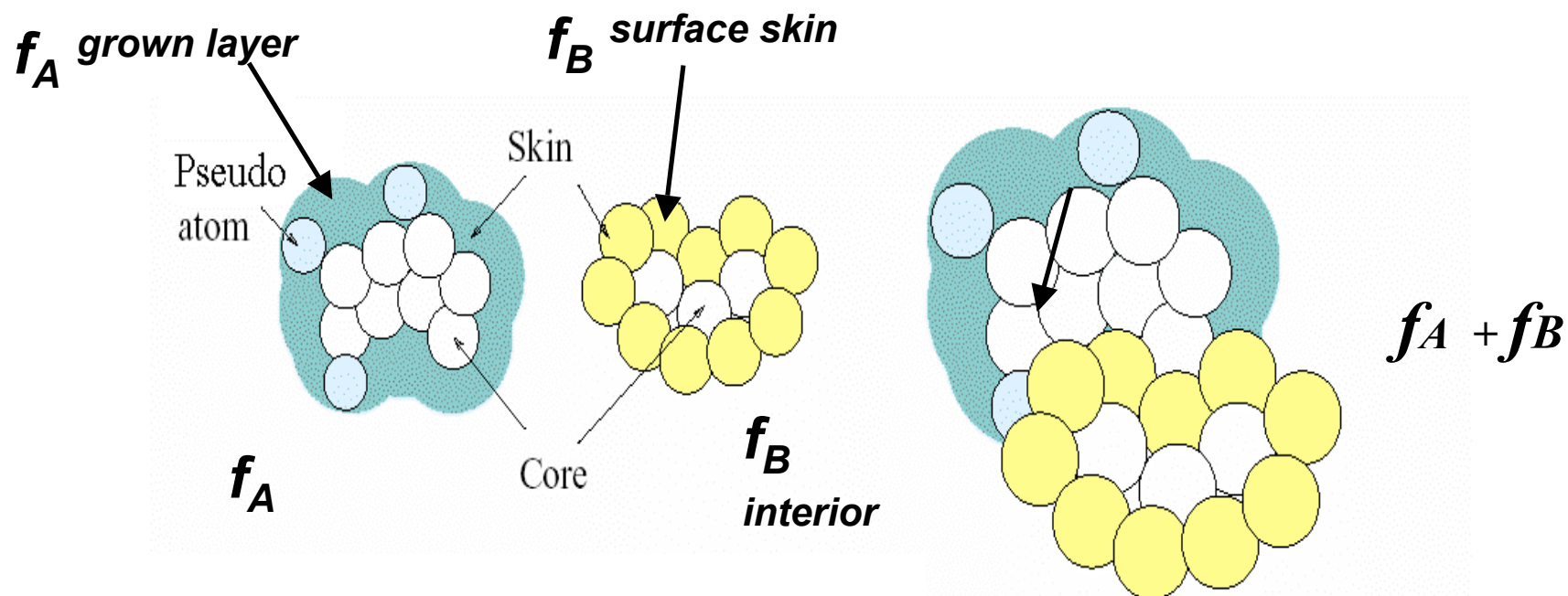
$$C_i^e = \sum_k W_{kf} J(b_1^k, b_2^k) \left( \frac{\partial^2 G_0}{\partial n_i \partial n}(x, b_1^k, b_2^k) - \frac{\partial^2 G_{\kappa}}{\partial n_i \partial n}(x, b_1^k, b_2^k) \right)$$

$$D_i^e = \sum_k W_{kf} J(b_1^k, b_2^k) \left( \frac{\partial G_0}{\partial n_i}(x, b_1^k, b_2^k) - \frac{\epsilon_j}{\epsilon_e} \frac{\partial G_{\kappa}}{\partial n_i}(x, b_1^k, b_2^k) \right)$$





## F<sup>3</sup> Dock: Fast Flexible Fourier Docking



- **$f_A$  grown layer:** Sampled SAS with pseudo atom centers

- **$f_A$ :** Atom centers of the protein

- **$f_B$  surface skin:** Surface atoms

- **$f_B$  interior:** Atoms of B which are not surface atoms



## Affinity based Scoring I

- Summation of Weighted Gaussians with following coefficients:

Region	Function	Coeff. weights
$f_A^{grown\ layer}$	positive real	1
$f_A$	positive imaginary	2i
$f_B^{surface\ skin}$	positive real	1
$f_B^{interior\ atoms}$	positive imaginary	2i

- Affinity:

- $(f_A, f_B^{interior\ atoms})$  overlap: **pos imag. \* pos imag. = (-)ve real**
- $(f_A^{grown\ layer}, f_B^{surface\ skin})$  overlap: **pos real \* pos real = pos real**
- $(f_A, f_B^{surface\ skin})$  &&  $(f_A^{grown\ layer}, f_B^{interior\ atoms})$  overlap: **ignore**
- Maximal values indicate regions of high skin overlaps and low interior clashes, and therefore highly plausible docking sites.



# Affinity based Scoring II

$$f_1(\vec{x}) = F_A^{grown\ layer}(\vec{x}) + F_A(\vec{x}) = F_A^{Re}(\vec{x}) + F_A^{Im}(\vec{x})$$

$$f_2(\vec{x}) = F_B^{surface\ skin}(\vec{x}) + F_B^{interior\ atoms}(\vec{x}) = F_B^{Re}(\vec{x}) + F_B^{Im}(\vec{x})$$

- The score of the overlap of two functions, one shifted by  $\mathbf{x}$  is given by the integral of their product.

$$s(\vec{x}) = \int_{\vec{y} \in R^3} f_1(\vec{y}) f_2(\vec{x} - \vec{y}) d\vec{y}$$

- If we rotate the second function by  $\mathbf{R}$ , we get the overlap score to be:

$$s(\vec{x}) = \int_{\vec{y} \in R^3} f_1(\vec{y}) (\Delta_R(f_2))(\vec{x} - \vec{y}) d\vec{y}$$

Location of the maximum score, over all  $\mathbf{R}$  and  $\mathbf{x}$  is recorded as a potential docking position.

$$pos = arg\ max_{[\vec{x}, R]} \int_{\vec{y} \in R^3} f_1(\vec{y}) (\Delta_R(f_2))(\vec{x} - \vec{y}) d\vec{y}, \quad \forall [\vec{x}, R]$$



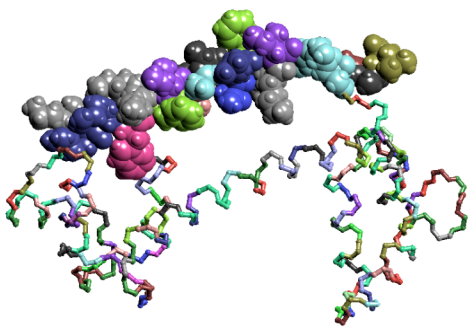
## F<sup>3</sup> Dock: results

Calmodulin (1CLL.PDB) with a peptide (myosin light chain kinase)

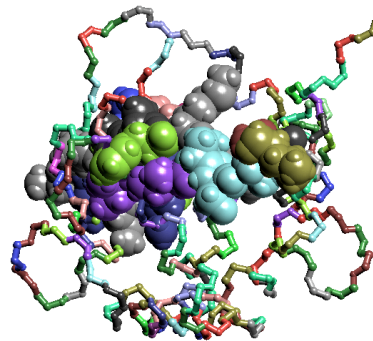
148, 36 residues

98 conformation samplings to keep <2Å difference.

Used 32<sup>3</sup> Fourier coefficients



Open pos: 6.2769



Closed pos: 9.8430

The docking position is in the list of the top 10% of all combinations checked



## More Reading

- Molecular modelling: Principles and applications, A.R. Leach 2001, Prentice-Hall
- Molecular modeling and simulation: An interdisciplinary guide, T. Schlick 2003, Springer-Verlag
- Understanding molecular simulation: From algorithms to applications, D. Frenkel, B. Smit 1998 Academic Press
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## Further Reading: GB Theory

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# Protein-protein docking

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- **Hashing based scheme:**  
Daniel Fischer, Raquel Norel, Ruth Nussinov, and Haim J. Wolfson.  
*3-d docking of protein molecules.*  
In CPM '93: Proceedings of the 4<sup>th</sup> Annual Symposium on Combinatorial Pattern Matching, pages 20–34,  
London, UK, 1993. Springer-Verlag.
- **FFT grid based:**  
Ephraim Katchalski-Katzir, Isaac Shariv, Miriam Eisenstein, Asher A. Friesem, Claude Aflalo, and Ilya A. Vakser.  
*Molecular surface recognition: determination of geometric fit between proteins and their ligands by correlation techniques.*  
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- **ZDock:** (same algorithm as above)  
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*An initial-stage proteindocking algorithm.*  
Proteins: Structure, Function, and Genetics, Special Issue: CAPRI - Critical Assessment of PRedicted Interactions . Issue edited by Jol Janin, 52(1):80–87, May 2003.
- **Harmonics based algorithms:**  
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- **Hex:**  
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## Further Reading: Virtual Screening

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