# Complexity Theory 

Eric Price<br>UT Austin

## CS 331, Spring 2020 Coronavirus Edition

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- If OLD is hard, and you could solve OLD by solving NEW, then NEW must be hard as well.


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## Formal(ish) Definitions

## Definition (Language)

A "problem" is also referred to as a "language" $L \subseteq\{0,1\}^{*}$ consisting of YES inputs. An input $x \in\{0,1\}^{*}$ is "YES" if, and only if, $x \in L$.

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$P \subseteq N P: \mathcal{V}(x, p):=\mathcal{A}(x)$.

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- Then "is $x \in L$ " is the same as $\exists p: \overline{\mathcal{V}}(x, p)=1$
- Which is just CircuitSAT on $\overline{\mathcal{V}}(x, \cdot)$
- So we just need to transform the Turing machine into an equivalent circuit of polynomial size.


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## Reducing Turing machine to SAT by unrolling across time

## Variables

$L_{i, j}:=$ Machine at tape position $j$ at time $i$
$Q_{i, j}:=$ Machine in state $j$ at time $i$
$T_{i, j, k}:=$ Tape at position $j$ at time $i$ has value $k$

- Polynomial time, states, values $\Longrightarrow$ polynomially many vars.


## Transition rules

If $L_{i, j} \cap T_{i, j, k} \cap Q_{i, \ell}$ then machine moves based on reading $k$ in state $\ell$ :

$$
\begin{aligned}
L_{i+1, t} & =1 \text { if } t=g(k, \ell) \text { else } 0 & & \text { Move left/right } \\
Q_{i+1, t} & =1 \text { if } t=f(k, \ell) \text { else } 0 & & \text { Change state } \\
T_{i+1, j, t} & =1 \text { if } t=h(k, \ell) \text { else } 0 & & \text { Write new char. }
\end{aligned}
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Example: $g(k, \ell)=\ell+1$ if, when reading $k$ in state $\ell$, you move right.

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- Q for NP verifier: does there exist an initial input (= tape state) such that output is YES?


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- Such that $x$ is YES for $A$ if, and only if, $x^{\prime}$ is YES for $B$.


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(1) Transform an arbitrary instance $x$ of $A$ into a very specific instance $y$ of $B$ (of polynomial size).

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- Hence if $y$ is YES, $x$ must be YES.
(4) To prove NP-completeness: show $B \in N P$ by showing that arbitrary instances of $B$ have certificates.


## Karp's 21 NP-complete problems

- Every NP problem reduces to Circuit-SAT
- Circuit-SAT reduces to SAT
- SAT reduces to 3-SAT
- 3-SAT reduces to independent set
- Independent set reduces to vertex cover
* Vertex cover reduces to directed Hamiltonian cycle
$\star$ Directed Hamiltonian cycle reduces to undirected hamiltonian cycle
- 3-SAT reduces to graph coloring
- Chromatic number reduces to exact cover
$\star$ Exact cover reduces to subset sum.


## Subset Sum is NP-hard

## Definition (Subset Sum)

Given $a_{1}, a_{2}, \ldots, a_{n}>0$-each represented with poly $(n)$ bits-and a number $T$, does there exist $S \subseteq[n]$ such that

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- For any vertex cover $S$ of size $k$,

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\sum_{v \in S} a_{v}=k 4^{|E|}+\sum_{e} 4^{e} \cdot \begin{cases}1 & \text { if }|e \cap S|=1 \\ 2 & \text { if }|e \cap S|=2\end{cases}
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- Hence $T=k 4^{|E|}+22222222222{ }_{4}$ is possible.


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- Certificate for $y$ is a set of $S_{V}$ and $S_{E}$ with

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\sum_{v \in S_{V}} a_{v}+\sum_{e \in S_{E}} b_{e}=T=k 4^{|E|}+\sum_{e} 2 \cdot 4^{e}
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## Recipe for Karp reductions to prove NP-hardness

(1) Transform an arbitrary instance $x$ of $A$ into a very specific instance $y$ of $B$ (of polynomial size).

- $b_{e}=000100000_{4}$, with a 1 at position $e$.
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- Exactly $k$ of the $a_{u}$ picked so $4^{|E|}$ term matches.
- Hence $S_{V}$ is a vertex cover.


## Some very similar NP-complete problems

Given a graph $G=(V, E)$
Definition (Max independent set)
Does there exist a set $S \subseteq V$ of size $\geq k$ such that, for all $(u, v) \in E$, at most 1 of $u \in S$ and $v \in S$ ?

Definition (Max clique)
Does there exist a set $S \subseteq V$ of size $\geq k$ such that, for all $(u, v) \in S$, $(u, v) \in E$ ?

Definition (Min vertex cover)
Does there exist a set $S \subseteq V$ of size $\leq k$ such that, for all $(u, v) \in E$, at least 1 of $u \in S$ and $v \in S$ ?

## From here: preview of next class

- P: Polynomial time
- NP: Nondeterministic polynomial time
- BPP: Probabilistic polynomial time, failure probability at most $1 / 3$.
- PP: failure probability $<1 / 2$.
- BQP: Probabilistic quantum polynomial time, failure probability at most 1/3.
- PSPACE: Polynomial space
- EXPTIME: Exponential time


## Relations of complexity classes

## $P \subseteq N P \subseteq P S P A C E \subseteq E X P T I M E \subseteq N E X P T I M E \subseteq E X P S P A C E \subseteq \ldots$

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- Most people expect: $P=B P P$, everything else $\subsetneq$.
- Don't know NP compared to BPP or BQP (or even if one is inside the other).


## Prototypical examples

- P: evaluate a function
- Given a circuit $f$ and input $x$, what is $f(x)$ ?
- NP: solve a puzzle
- SAT: given $f$, determine if $\exists x: f(x)=1$ ?
- Given a puzzle, find the solution
- Easy to verify once the solution is found.
- PSPACE: solve a 2-player game
- TQBF: $\exists x_{1} \forall x_{2} \exists x_{3} \cdots \forall x_{n}: f(x)=1$
- Think chess: do I have a move, so no matter what you do, I can find a move, so no matter, etc., etc., I end up winning?
- Caveat: requires the puzzle/game to only have a polynomial number of moves.
- Puzzles/games with exponentially many moves may be harder.
- Go: actually EXPTIME-complete to solve a position.
- Zelda: actually PSPACE-complete to solve a level.

