Outline CS376 Computer Vision Wed, April 20, 2011

## Part-based and local feature models for generic object recognition

- Bag of words (no geometry)
  - o Local feature correspondence kernel for discriminative learning with local features
    - Pyramid match: descriptors, spatial
    - Example results
- Implicit shape model (star graph for spatial model)
  - o Training process
  - o Detection (testing) process
- Constellation model (fully connected graph for spatial model)
  - Model definition
  - o Example learned models
- Comparison of the two spatial models

Recap of basic recognition models covered in last couple weeks

## Motion estimation in video

- Motion field definition, examples
- Motion estimation techniques: dense vs. feature-based
- Optical flow
  - o Constraints (brightness constancy and small motion) and optical flow equations
  - The aperture problem
  - Adding the spatial coherency constraint, solving for flow vectors
  - o When is it solvable?
- Motion vs. stereo