Should Future Variability Modeling Languages Express Constraints in OCL?

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ABSTRACT

Since the mid-2000s, *Propositional Logic* (PL) has been the de facto language to express constraints in *Feature Models* (FMs) of *Software Product Line* (SPLs). PL was adequate because product configurations were formed by binary decisions including or not including features in a product. Inspired by both prior research and practical systems (*eg.*, SPLs that use KConfig), future FMs must go beyond PL and admit numerical (and maybe even text) variables and their constraints.

The *Object Constraint Language* (\mathbb{OCL}) is a general-purpose declarative constraint language for *Model Driven Engineering* (\mathbb{MDE}), which admits virtually any kind of variable and constraint in metamodels. We should expect future \mathbb{FMs} to be examples of \mathbb{MDE} metamodels. This raises a basic question: Should \mathbb{OCL} be used to express constraints of future variability modeling language(s)?

In this talk, I outline the pros and cons for doing so.

ACM Reference Format:

Don Batory. 2019. Should Future Variability Modeling Languages Express Constraints in OCL?. In 23rd International Systems and Software Product Line Conference - Volume B (SPLC '19), September 9–13, 2019, Paris, France. ACM, New York, NY, USA, 1 page. https://doi.org/10.1145/3307630.3342406

1 INTRODUCTION

I am no fan of the *Object Constraint Language* (\mathbb{OCL}) and never have been. I find it inelegant and bloated. Using Eclipse \mathbb{OCL} years ago, I recall different \mathbb{OCL} implementations did not agree on syntax and covered the \mathbb{OCL} standard (at that time) with varying fidelity. (Note: The current 2.0 standard is a behemoth 262 page document [5]!) I tried to teach \mathbb{OCL} to my undergrads, and that was an unpleasant experience for both me and my students. \mathbb{OCL} and related tools were simply too complicated. As mentioned in [1], Eclipse tools:

- Were unappealing—they were difficult to use even for simple applications.
- (2) Fostered a medieval mentality in students to use incantations to solve problems. Point here, click that, something happens. From a student's perspective, this is gibberish. Although I could tell them what was happening, this mode of interaction left a vacuum where a deep understanding should reside.

SPLC '19, September 9–13, 2019, Paris, France

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https://doi.org/10.1145/3307630.3342406

(3) Have a steep entry cost to use, teach, and learn – too high for my comfort (and I suspect my student's as well).

I'm not alone with these opinions [2].

From a distance, I have also watched various attempts to generalize *Feature Models* (FMs) to address next generation *Software Product Line* (SPL) concerns – such as admitting replicated features, features with attributes, numerical features, and expressing constraints. I recoiled at the complexity of these attempts, and the use of \mathbb{OCL} as the language to express constraints.

I do not profess to know what future SPL Variability Modeling Languages will be and how constraints in such languages will be expressed. But I do believe the answer will be guided by:

- Simplicity! PL was chosen for classical FM constraints because it was a simple mathematical standard. I'm not sure there is a formal grammar (language) to which all classical FM tools agree, but it is hard to screw-up writing PL constraints. Next-generation FM constraints should be equally straightforward to write.
- Don't Invent, Reuse! Do we really need a new constraint language for future FMs? Clearly we need more than PL. But are we good enough as language engineers to create a new constraint language without making a complete mess of it? Shouldn't we reuse existing languages or sub-languages of existing languages? Our expertise is in SPLs, not in language engineering. If you want an example of (IMO) a failed custom constraint language, it is OCL. Re-read the 2nd sentence of this Introduction.
- Circularity Avoidance! Generalizing beyond hierarchical relationships of classical FMs, we're not far away from UML class diagrams [4] and Model Driven Engineering *metamodels* [3] which are class diagrams + constraints. And constraints for class diagrams beg the use of OCL.

In this talk, I offer and demonstrate a way out of this circular conundrum. My solution does *not* eliminate all problems, but it does diminish key problems about \mathbb{OCL} standards, \mathbb{OCL} tooling, reducing the need for yet-another-language, minimizing long-term tool maintenance, and keeping constraint languages both familiar and simple to \mathbb{SPL} programmers, practitioners, and researchers.

Acknowledgments. Batory is supported by NSF grant CCF1212683. **REFERENCES**

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ACM ISBN 978-1-4503-6668-7/19/09...\$15.00