

Reflection and Light Source Models

Illumination: Energy physics...

- Radiance: the flux of light energy in a given direction
- Geometry/Visibility: how light energy falls upon a surface
- BRDF: the interaction function of a surface point with light
- Energy Balance Equation: the local balance of energy in a scene

Approximation: Hacks for interaction at a point...

- Ambient: approximating the global energy
- Lambertian: approximating the diffuse interaction
- Phong: approximating the specular interaction

Reflection VS. Illumination

Light: An electromagnetic *energy flux* that has

- intensity (power per unit area)
- direction of propagation

Reflection: A *local lighting model* that relates

- the properties of a surface at a point
- the incoming direction and energy at the point
- the outgoing direction and energy at the point

BRDF: *bidirectional reflectance distribution function*

- the function that embodies the surface properties

Illumination: A global lighting model that computes

- overall light distribution in an environment
 - from the reflection models
 - from the shape and location of all objects
 - from the shape and location of all light sources

Shading: A local interpolation technique used to

- reduce the cost of computing reflection
- shade polygons “nicely”

Energy of Illumination

Radiance: Electromagnetic *energy flux*, the amount of energy traveling

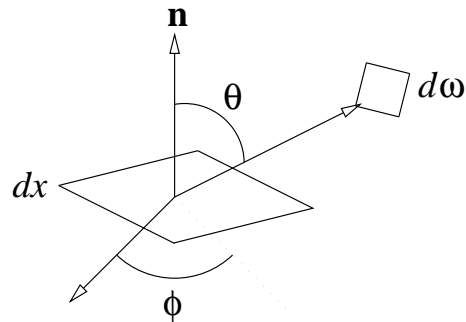
- at some point x
- in a specified direction θ, ϕ
- per unit time
- per unit area perpendicular to the direction
- per unit solid angle
- for a specified wavelength λ
- denoted by $L(x, \theta, \phi, \lambda)$

Spectral Properties: Total energy flux comes from flux at each wavelength

- $$L(x, \theta, \phi) = \int_{\lambda_{\min}}^{\lambda_{\max}} L(x, \theta, \phi, \lambda) d\lambda$$

Picture: For the indicated situation $L(x, \theta, \phi) dx \cos \theta d\omega dt$ is

- energy radiated through differential solid angle $d\omega = \sin \theta d\theta d\phi$
- through/from differential area dx
- not perpendicular to direction (projected area is $dx \cos \theta$)
- during differential unit time dt



Power: Energy per unit time (as in the picture)

- $L(x, \theta, \phi) dx \cos \theta d\omega$

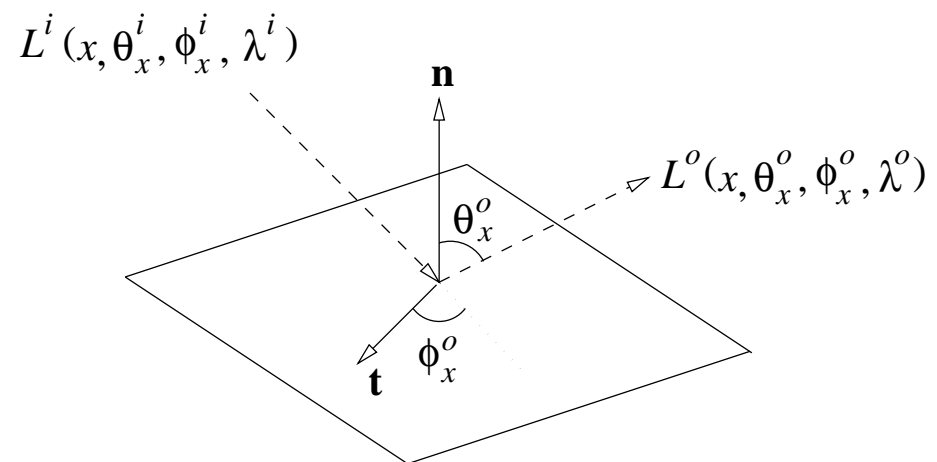
Radiosity: Total power leaving a surface point per unit area

- $\int_{\Omega} L(x, \theta, \phi) \cos \theta d\omega = \int_0^{\frac{\pi}{2}} \int_0^{2\pi} L(x, \theta, \phi) \cos \theta \sin \phi d\phi d\theta$
(integral is over the hemisphere above the surface point)

Bidirectional Reflectance Distribution Function:

- is a surface property at a point
- relates energy in to and energy out
- depends on incoming and outgoing directions
- varies from wavelength to wavelength
- Definition: Ratio
 - of radiance in the outgoing direction
 - to radiant flux density for the incoming direction

$$\rho_{bd}(x, \theta_i, \phi_i, \lambda_i, \theta_o, \phi_o, \lambda_o) = \frac{L^o(x, \theta_x^o, \phi_x^o, \lambda^o)}{L^i(x, \theta_x^i, \phi_x^i, \lambda^i) \cos \theta_x^i d\omega_x^i}$$



Energy Balance Equation

$$L^o(x, \theta_x^o, \phi_x^o, \lambda^o) = L^e(x, \theta_x^o, \phi_x^o, \lambda^o) + \int_0^{\frac{\pi}{2}} \int_0^{2\pi} \int_{\lambda_{\min}}^{\lambda_{\max}} \rho_{bd}(x, \theta_x^i, \phi_x^i, \lambda^i, \theta_x^o, \phi_x^o, \lambda^o) \cos(\theta_x^i) L^i(x, \theta_x^i, \phi_x^i, \lambda^i) d\lambda^i \sin(\phi_x^i) d\phi_x^i d\theta_x^i$$

- $L^o(x, \theta_x^o, \phi_x^o, \lambda^o)$ is the radiance
 - at wavelength λ^o
 - leaving point x
 - in direction θ_x^o, ϕ_x^o
- $L^e(x, \theta_x^o, \phi_x^o, \lambda^o)$ is the radiance emitted by the surface from the point
- $L^i(x, \theta_x^i, \phi_x^i, \lambda^i)$ is the incident radiance impinging on the point
- $\rho_{bd}(x, \theta_x^i, \phi_x^i, \lambda^i, \theta_x^o, \phi_x^o, \lambda^o)$ is the BRDF at the point

- describes the surface's interaction with light at the point
- the integration is over the hemisphere above the point

Fast and Dirty Approximations

Rough Approximations:

- Use *red*, *green*, and *blue* instead of full spectrum
 - Roughly follows the eye's sensitivity
 - Forego such complex surface behavior as metals
- Use finite number of point light sources instead of full hemisphere
 - Integration changes to summation
 - Forego such effects as soft shadows and color bleeding
- BRDF behaves independently on each color
 - Treat red, green, and blue as three separate computations
 - Forego such effects as iridescence and refraction
- BRDF split into three approximate effects
 - Ambient: constant, nondirectional, background light
 - Diffuse: light reflected uniformly in all directions
 - Specular: light of higher intensity in mirror-reflection direction

- Energy flux L replaced by simple “intensity” I
 - No pretense of being physically true

Approximate Intensity Equation: (single light source)

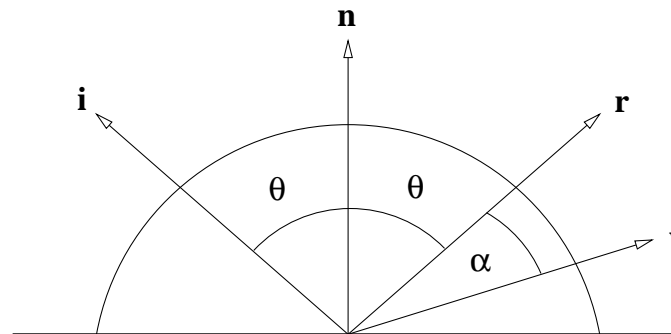
$$I_{\lambda}^o = I_{\lambda}^e + k_{\lambda}^a I_{\lambda}^a + k_{\lambda}^d I_{\lambda}^l \cos(\theta^l) + k_{\lambda}^s I_{\lambda}^l W(\theta^l) S(\alpha^l)$$

- λ stands for each of *red, green, blue*
- I_{λ}^l is the intensity of the light source (modified for distance)
- $\cos(\theta^l)$ accounts for the projected cross-sectional area of the incoming light
- the k are between 0 and 1 and represent absorption factors
- $W(\theta^l)$ accounts for any highlight effects that depend on the incoming direction
 - use $\cos(\theta^l)$ if there is nothing special
- α^l is the mirror reflection angle for the light
 - the angle between the view direction and the mirror reflection direction
- $S(\alpha^l)$ accounts for highlights in the mirror reflection direction
- the superscripts e, a, d, s stand for *emitted, ambient, diffuse, specular* respectively
- sum over each light l if there are more than one

Lambertian Reflection Model

Diffuse Geometry:

- \mathbf{l} is the *unit vector* in the direction of the illumination (light source)
- \mathbf{n} is the *unit vector* normal to the surface
- \mathbf{r} is the *unit vector* in the mirror reflection direction
- \mathbf{v} is the *unit vector* in the direction of the eyepoint



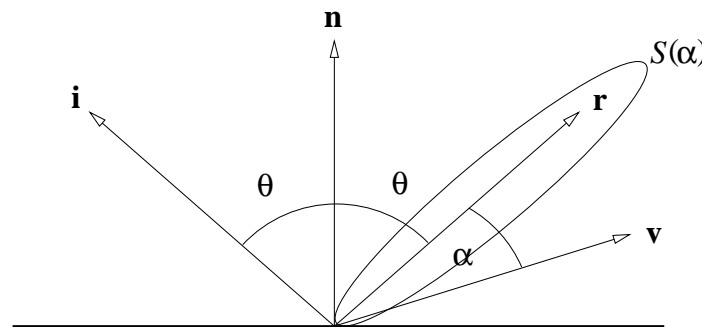
Formulas:

- $\cos(\theta) = \mathbf{n} \cdot \mathbf{l}$
- \mathbf{r} and α are not needed

Phong Reflection Model

Specular Geometry (Phong Model):

- \mathbf{l} is the *unit vector* in the direction of the illumination (light source)
- \mathbf{n} is the *unit vector* normal to the surface
- \mathbf{r} is the *unit vector* in the mirror reflection direction
- \mathbf{v} is the *unit vector* in the direction of the eyepoint



Formulas:

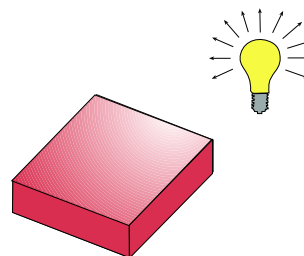
- $\cos(\theta) = \mathbf{n} \cdot \mathbf{l}$

- $\mathbf{r} = 2(\mathbf{l} \cdot \mathbf{n})\mathbf{n} - \mathbf{l}$
- $\cos(\alpha) = \mathbf{r} \cdot \mathbf{v}$
- $S(\alpha) = \cos(\alpha)^{n_s}$

Point Light Sources

Point Light Sources:

- Point light sources has a **position** P_i and an **intensity** I_i
- Light energy is radiated equally in all directions



Positional Light

Distance Attenuation:

- Physically, need $1/r^2$ attenuation since light energy spreads out spherically
- This is too harsh, point light sources are rare in the real world

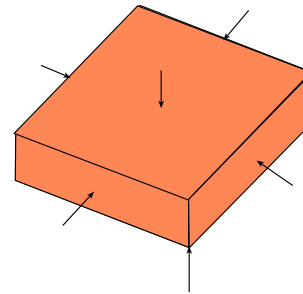
- Use modified attenuation factor:

$$a(r) = \frac{1}{\alpha_0 + \alpha_1 r + \alpha_2 r^2}$$

- This **simulates** the attenuation of an *area light source*
- Only use attenuation from light source to surface, **not** from surface to pixel
- Pixel is **area**, not point, so foreshortening cancels attenuation

Ambient Lighting:

- True global illumination difficult and expensive to calculate
- Often use constant low level lighting everywhere to fake global illumination: I_{λ}^a
- Each surface may reflect “ambient” lighting differently: k_{λ}^a
- Usually, $k_{\lambda}^a = k_{\lambda}^d$



Ambient Light

Lambertian Lighting:

at point x with ℓ point light sources at points p_i is now:

$$\begin{aligned} d_i &= |p_i - x|, \\ a(d_i) &= \frac{1}{\alpha_{0i} + \alpha_{1i}d_i + \alpha_{2i}d_i^2}, \\ \mathbf{l}_i &= (p_i - x)/d_i, \\ I_\lambda^o &= k_\lambda^a I_\lambda^a + k_\lambda^d \sum_{i=1}^{\ell} a(d_i) I_\lambda^i |\mathbf{l}_i \cdot \mathbf{n}| \end{aligned}$$

Specular Lighting Similarly: For example,

$$\begin{aligned} \mathbf{r}_i &= 2\mathbf{n}(\mathbf{n} \cdot \mathbf{l}_i) - \mathbf{l}_i \\ I_\lambda^o &= k_\lambda^a I_\lambda^a + k_\lambda^d \sum_{i=1}^{\ell} a(d_i) I_\lambda^i |\mathbf{l}_i \cdot \mathbf{n}| (k_\lambda^d + k_\lambda^s |\mathbf{r}_i \cdot \mathbf{v}|^{n_s}) \end{aligned}$$

- Sometimes we see the Phong model stated with the half-vector \mathbf{h} :

- $\mathbf{h} = (\mathbf{l} + \mathbf{v})$ normalized
- Angle between \mathbf{n} and \mathbf{h} is twice that between \mathbf{r} and \mathbf{v} if coplanar
- Use $|\mathbf{h} \cdot \mathbf{n}|^{n_s}$
- Not exactly the equivalent of using reflection vector \mathbf{r}
- Avoids recomputation of \mathbf{v}

Reading Assignment and News

Chapter 10 pages 477 - 520, of Recommended Text.

Please also track the News section of the Course Web Pages for the most recent Announcements related to this course.

(<http://www.cs.utexas.edu/users/bajaj/graphics23/cs354/>)