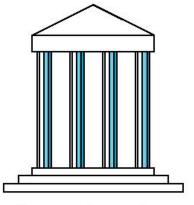
Supplement to Lecture 8

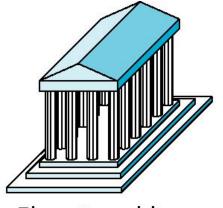
Viewing/Projections in OpenGL

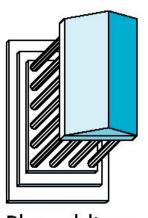


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Classical Projections



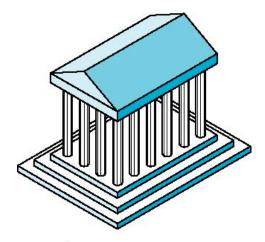


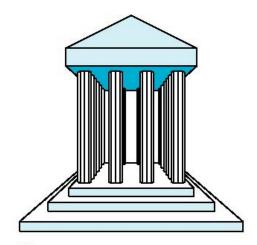


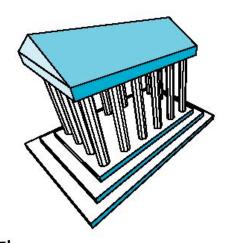
Front elevation

Elevation oblique

Plan oblique







Isometric

One-point perspective

Three-point perspective



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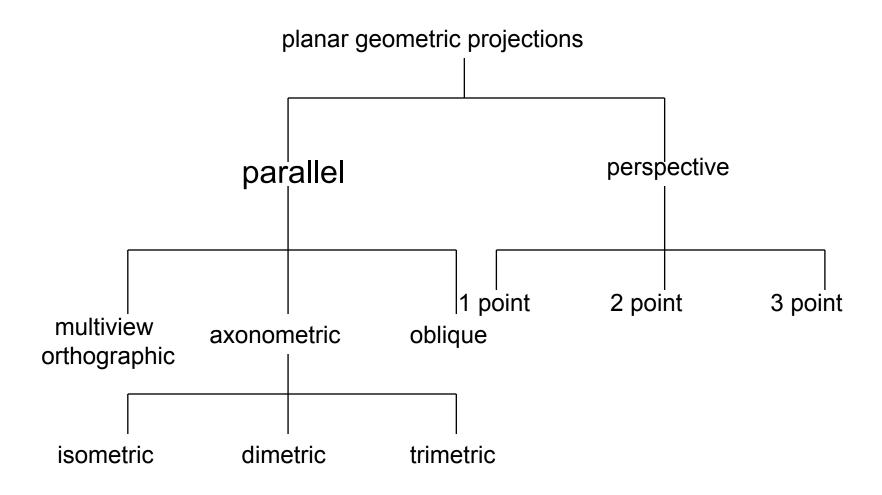
Perspective vs Parallel

- Computer graphics treats all projections the same and implements them with a single pipeline
- Classical viewing developed different techniques for drawing each type of projection
- Fundamental distinction is between parallel and perspective viewing even though mathematically parallel viewing is the limit of perspective viewing



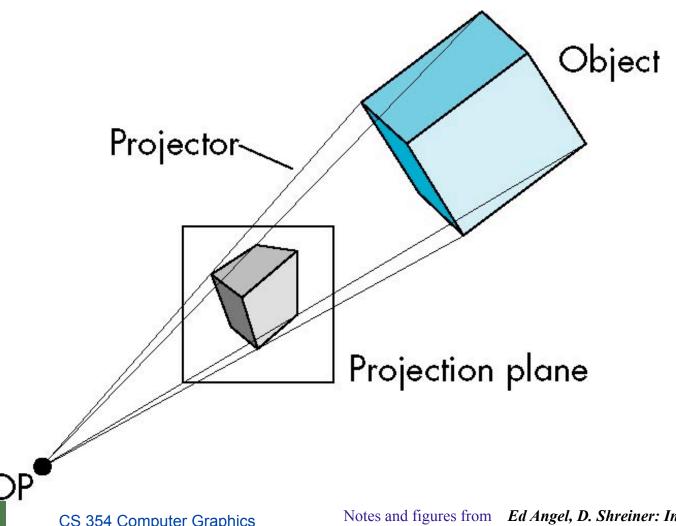
http://www.cs.utexas.edu/~bajai/

Taxonomy of Planar Projections





Perspective Projection

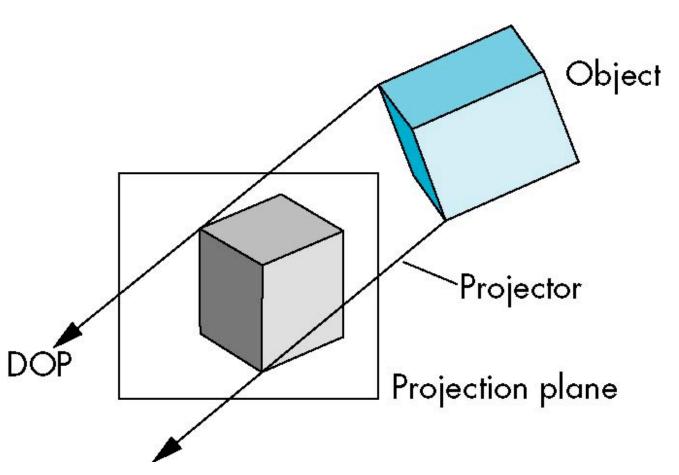


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Parallel Projection





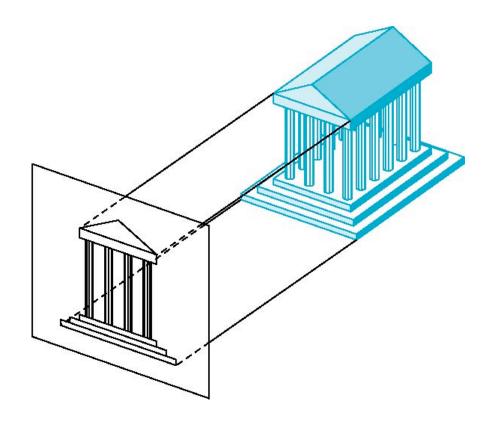
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Orthographic Projection

Projectors are orthogonal to projection surface

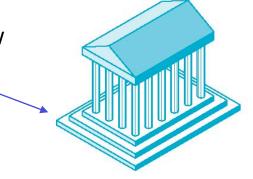




Multiview Orthographic Projection

- Projection plane parallel to principal face
- Usually form front, top, side views

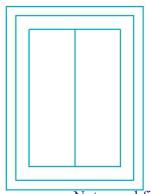
isometric (not multiview orthographic view)

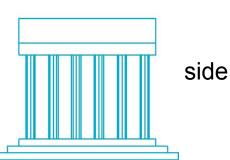




in CAD and architecture, we often display three multiviews plus isometric

top







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Plus & Minus

- Preserves both distances and angles
 - Shapes preserved
 - Can be used for measurements
 - Building plans
 - Manuals
- Cannot see what object really looks like because many surfaces hidden from view
 - Often we add the isometric

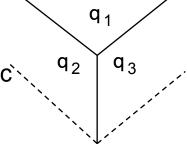


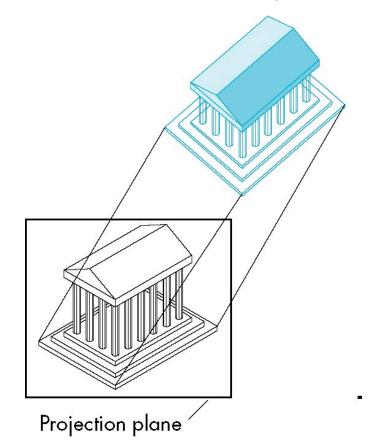
Axonometric Projections (AP)

Allow projection plane to move relative to object

classify by how many angles of a corner of a projected cube are the same

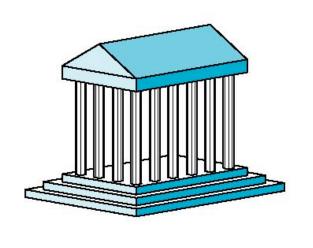
none: trimetric two: dimetric three: isometric



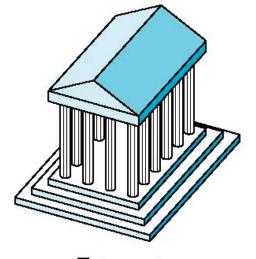




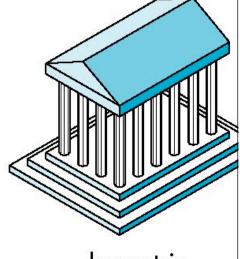
Types of AP







Trimetric



Isometric



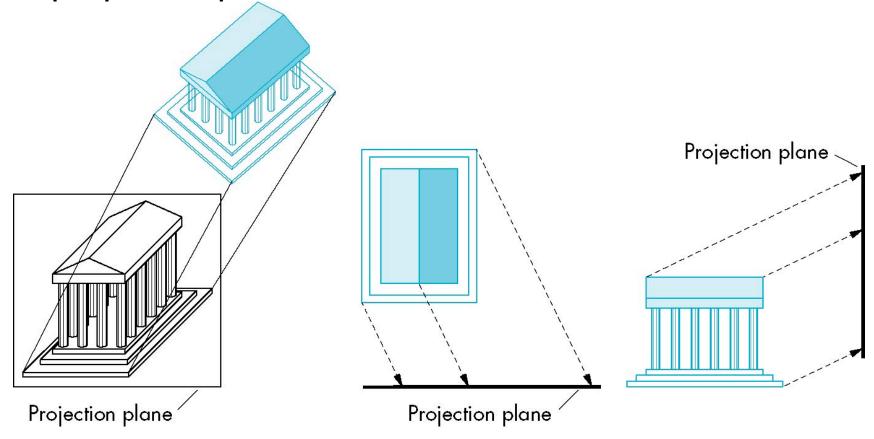
Plus & Minus

- Lines are scaled (foreshortened) but can find scaling factors
- Lines preserved but angles are not
 - Projection of a circle in a plane not parallel to the projection plane is an ellipse
- Can see three principal faces of a box-like object
- Some optical illusions possible
 - Parallel lines appear to diverge
- Does not look real because far objects are scaled the same as near objects
- Used in CAD applications



Oblique Projection

Arbitrary relationship between projectors and projection plane



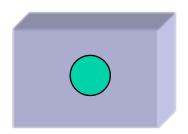


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Plus & Minus

- Can pick the angles to emphasize a particular face
 - Architecture: plan oblique, elevation oblique
- Angles in faces parallel to projection plane are preserved while we can still see "around" side

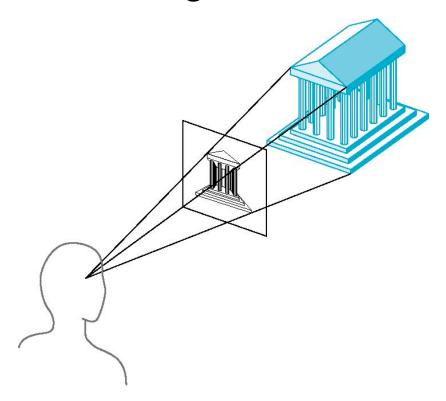


 In physical world, cannot create with simple camera; possible with bellows camera or special lens (architectural)



Perspective Projections

Projectors coverge at center of projection

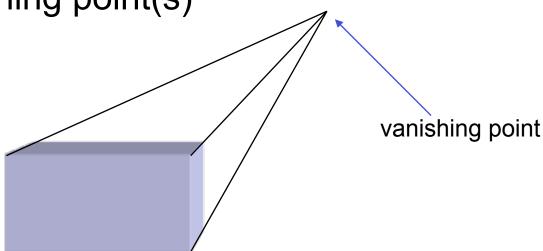




Vanishing Points

 Parallel lines (not parallel to the projection plan) on the object converge at a single point in the projection (the *vanishing point*)

 Drawing simple perspectives by hand uses these vanishing point(s)





Three Point Perspective

- No principal face parallel to projection plane
- Three vanishing points for cube





Two Point Perspective

- On principal direction parallel to projection plane
- Two vanishing points for cube





One Point Perspective

- One principal face parallel to projection plane
- One vanishing point for cube





Plus & Minus

- Objects further from viewer are projected smaller than the same sized objects closer to the viewer (diminution)
 - Looks realistic
- Equal distances along a line are not projected into equal distances (nonuniform foreshortening)
- Angles preserved only in planes parallel to the projection plane
- More difficult to construct by hand than parallel projections (but not more difficult by computer)



Computer Viewing in OpenGL

- There are three aspects of the viewing process, all of which are implemented in the pipeline,
 - Positioning the camera
 - Setting the model-view matrix
 - Selecting a lens
 - Setting the projection matrix
 - Clipping
 - Setting the view volume



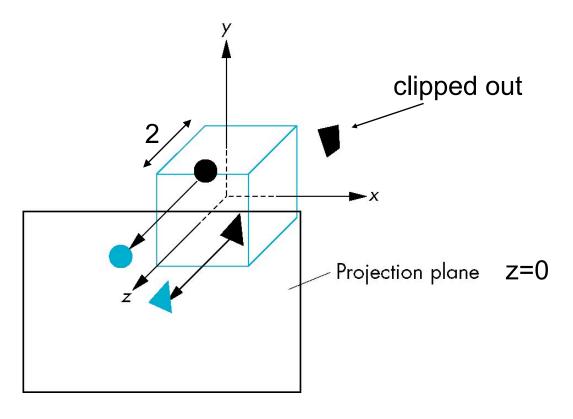
OpenGL camera

- In OpenGL, initially the object and camera frames are the same
 - Default model-view matrix is an identity
- The camera is located at origin and points in the negative z direction
- OpenGL also specifies a default view volume that is a cube with sides of length 2 centered at the origin
 - Default projection matrix is an identity



Default Projection

Default projection is orthogonal





Moving Camera Frame

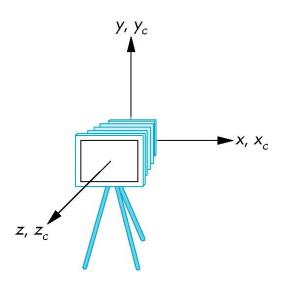
- If we want to visualize object with both positive and negative z values we can either
 - Move the camera in the positive z direction
 - Translate the camera frame
 - Move the objects in the negative z direction
 - Translate the world frame
- Both of these views are equivalent and are determined by the model-view matrix
 - Want a translation (glTranslatef(0.0,0.0,-d);)
 - -d > 0



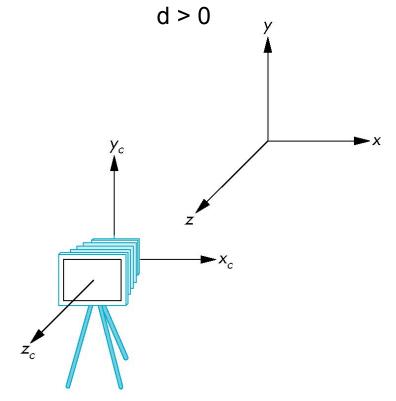
Moving Camera Back from Origin

frames after translation by -d

default frames



(a)





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(b)

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Moving Camera

We can move the camera to any desired position by a sequence of rotations and translations

- Example: side view
 - Rotate the camera
 - Move it away from origin
 - Model-view matrix C = TR



OpenGL code

 Remember that last transformation specified is first to be applied

```
glMatrixMode(GL_MODELVIEW)
glLoadIdentity();
glTranslatef(0.0, 0.0, -d);
glRotatef(90.0, 0.0, 1.0, 0.0);
```



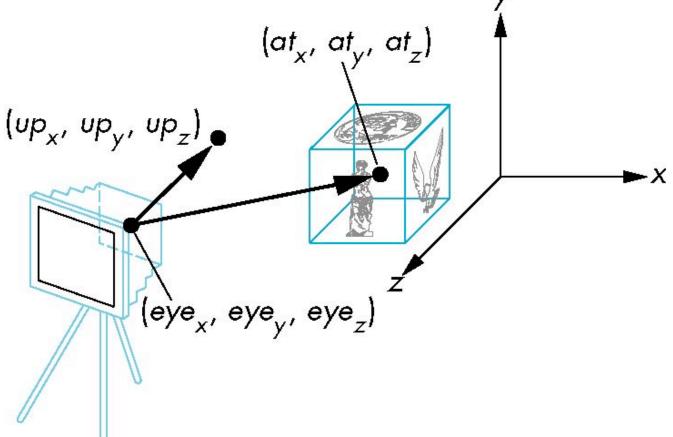
The LookAt Function

- The GLU library contains the function gluLookAt to form the required modelview matrix through a simple interface
- Note the need for setting an up direction
- Still need to initialize
 - Can concatenate with modeling transformations
- Example: isometric view of cube aligned with axes

```
glMatrixMode(GL_MODELVIEW):
glLoadIdentity();
gluLookAt(1.0, 1.0, 1.0, 0.0, 0.0, 0.0, 0., 1.0. 0.0);
```



gluLookAt





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Other Viewing API's

- The LookAt function is only one possible API for positioning the camera
- Others include
 - View reference point, view plane normal, view up (PHIGS, GKS-3D)
 - Yaw, pitch, roll
 - Elevation, azimuth, twist
 - Direction angles



Projections and Normalization

- The default projection in the eye (camera) frame is orthogonal
- For points within the default view volume

$$x_p = x$$

 $y_p = y$
 $z_p = 0$

- Most graphics systems use view normalization
 - All other views are converted to the default view by transformations that determine the projection matrix
 - Allows use of the same pipeline for all views



4x4 ModelView Matrix

default orthographic projection

$$x_p = x$$

$$y_p = y$$

$$z_p = 0$$

$$w_p = 1$$

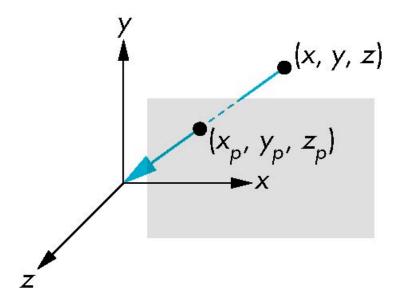
$$\mathbf{m} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

In practice, we can let M = I and set the z term to zero later



Simple Perspective

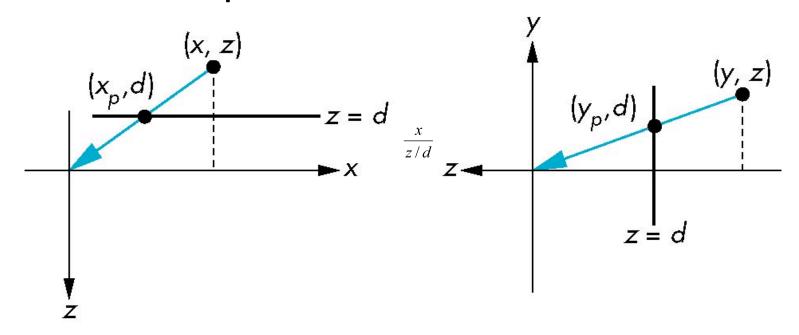
- Center of projection at the origin
- Projection plane z = d, d < 0





Perspective Equations

Consider top and side views



$$x_{\rm p} = \frac{x}{z/d}$$

$$y_{\rm p} = \frac{y}{z/d}$$

$$z_{\rm p} = d$$



4x4 ModelView Matrix

consider
$$\mathbf{q} = \mathbf{M}\mathbf{p}$$
 where $\mathbf{M} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1/d & 0 \end{bmatrix}$

$$\mathbf{p} = \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

$$\mathbf{q} = \mathbf{M} \mathbf{p} = \begin{bmatrix} x \\ y \\ z \\ z/d \end{bmatrix}$$



Perspective Division

- However w = 1, so we must divide by w to return from homogeneous coordinates
- This perspective division yields

$$x_{\rm p} = \frac{x}{z/d}$$
 $y_{\rm p} = \frac{y}{z/d}$ $z_{\rm p} = d$

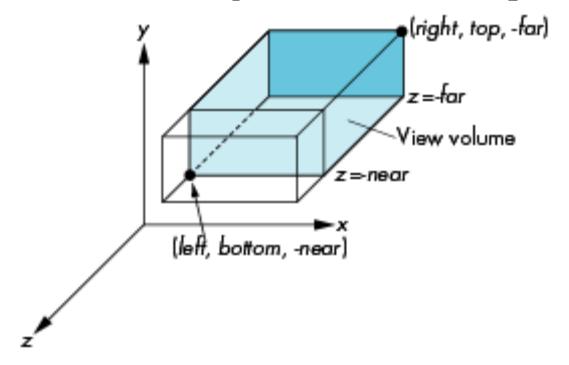
the desired perspective equations

 We will consider the corresponding clipping volume with the OpenGL functions



OpenGL Orthogonal Viewing

glOrtho(left,right,bottom,top,near,far)

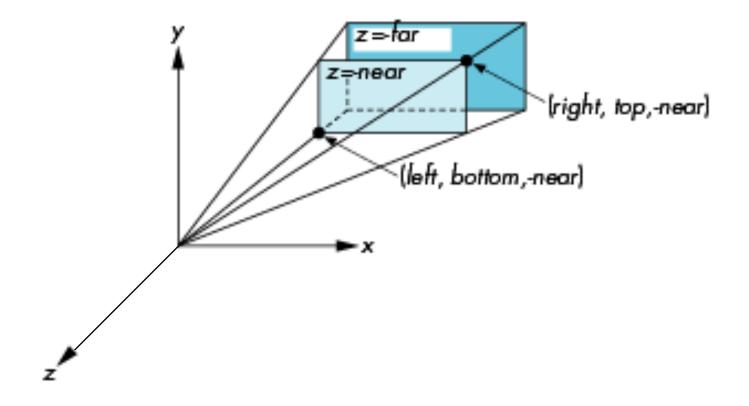


near and far measured from camera



OpenGL Perspective

glFrustum(left,right,bottom,top,near,far)





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Using Field of View

- With glfrustum it is often difficult to get the desired view
- •gluPerpective(fovy, aspect, near, far) often provides a better interface

