CS429: Computer Organization and Architecture
Storage Technologies

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Random-Access Memory (RAM)

- Key Features
  - RAM is packaged as a chip
  - The basic storage unit is a cell (one bit per cell)
  - Multiple RAM chips form a memory.
- Static RAM (SRAM)
  - Each cell stores a bit with a 6-transistor circuit.
  - Retains value indefinitely, as long as kept powered (volatile).
  - Relatively insensitive to disturbances such as electrical noise.
  - Faster but more expensive than DRAM.
- Dynamic RAM (DRAM)
  - Each cell stores a bit with a capacitor and transistor.
  - Value must be refreshed every 10–100 ms (volatile).
  - Sensitive to disturbances, slower and cheaper than SRAM

Random-Access Memory (RAM) (2)

- Flash RAM (what's in your ipod and cell phone)
  - Each cell stores 1 or more bits on a "floating-gate" capacitor
  - Keeps state even when power is off (non-volatile).
  - As cheap as DRAM, but much slower

RAM Summary

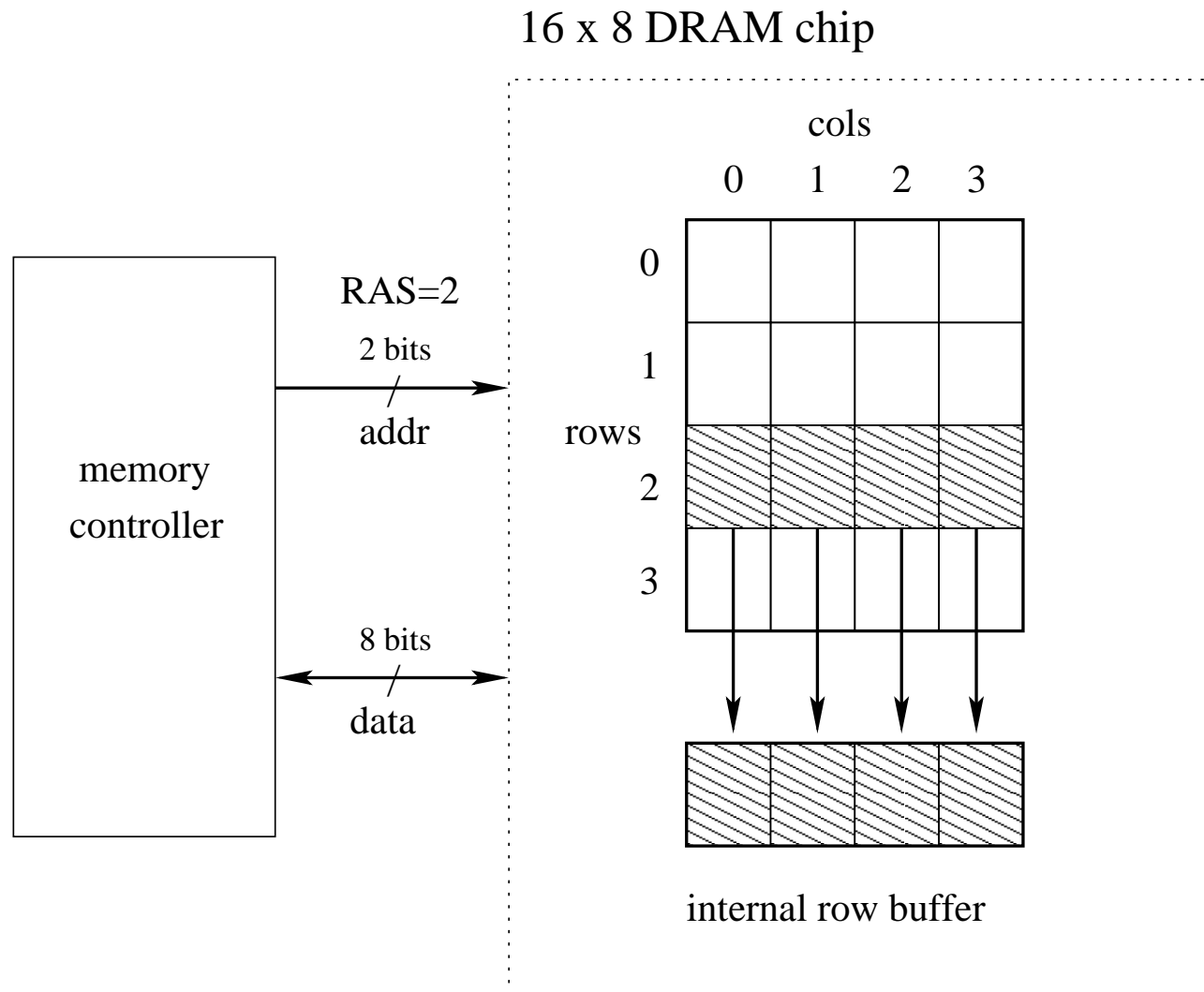| Type	Trans. per bit	Access time	Persist?	Sensitive	Cost	Applications
SRAM	6	1X	No	No	100X	cache memory
DRAM	1	10X	No	Yes	1X	main memory
Flash	1/2–1	10000X	Yes	No	1X	disk substitute

Conventional DRAM Organization

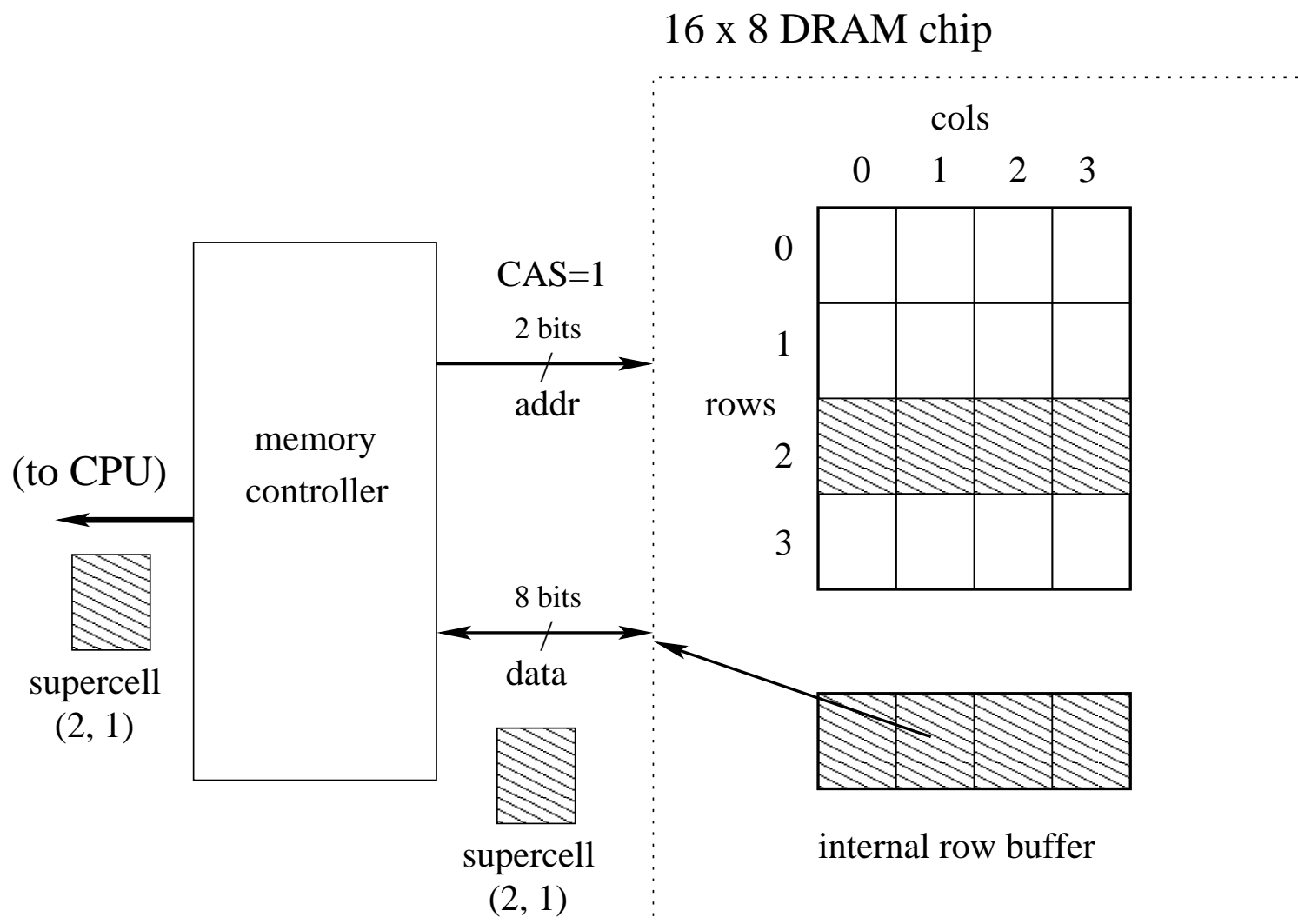DRAM is typically organized as a $d \times w$ array of d supercells of size w bits.

16 x 8 DRAM chip
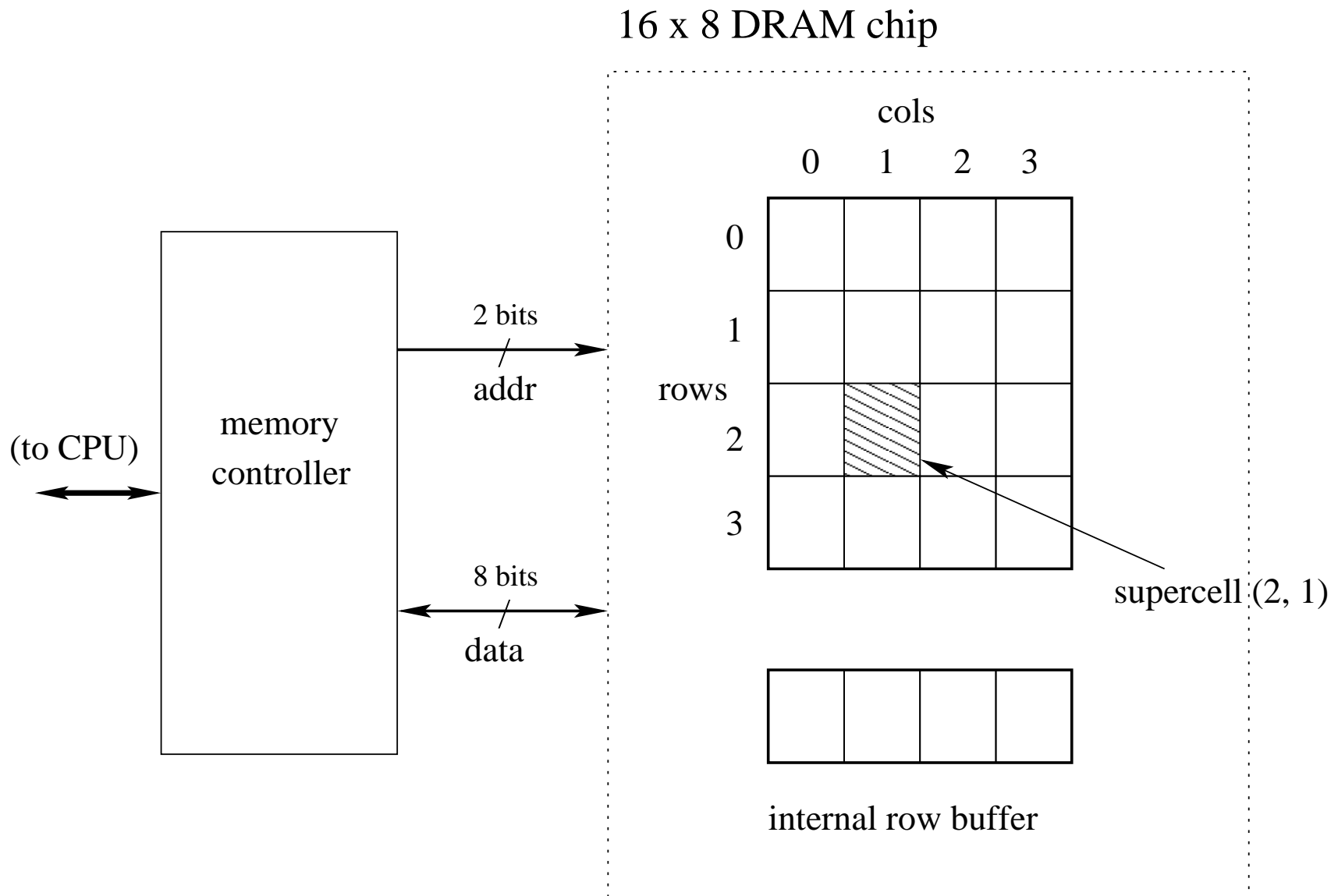
Reading DRAM Supercell (2, 1)

- Step 1(a): Row access strobe (RAS) selects row 2.
- Step 1(b): Row copied from DRAM array to row buffer.

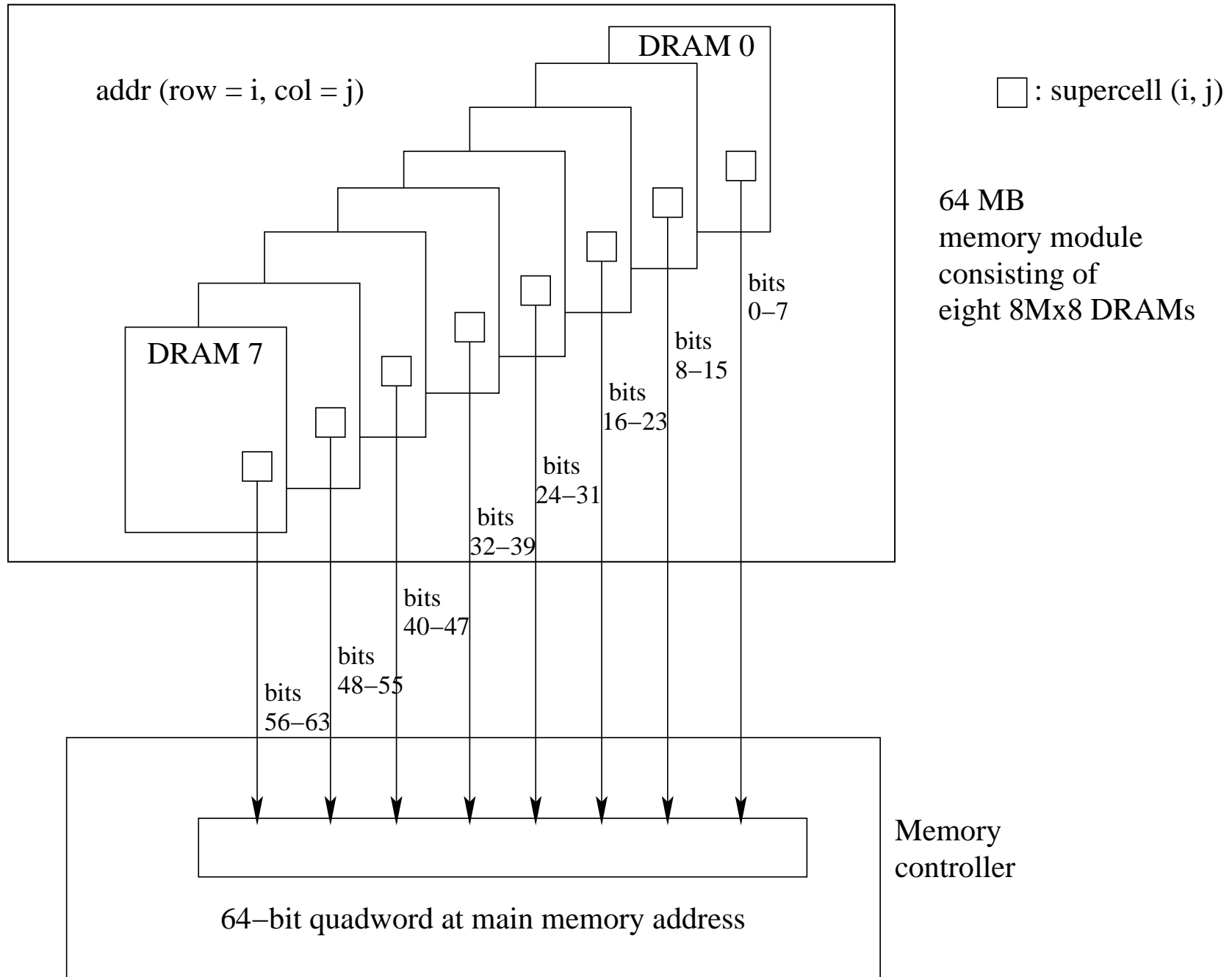16 x 8 DRAM chip

- Step 2(a): Column access strobe (CAS) selects col 1.
- Step 2(b): Supercell (2, 1) copied from buffer to data lines, and eventually back to the CPU.

16 x 8 DRAM chip

cols

0   1   2   3

CAS=1

2 bits

addr

rows

(to CPU)

memory
controller

supercell
(2, 1)

8 bits

data

supercell
(2, 1)

internal row buffer

addr (row = i, col = j)

DRAM 0

DRAM 7

□ : supercell (i, j)

64 MB
memory module
consisting of
eight 8Mx8 DRAMs

bits
0–7

bits
8–15

bits
16–23

bits
24–31

bits
32–39

bits
40–47

bits
48–55

bits
56–63

Memory
controller

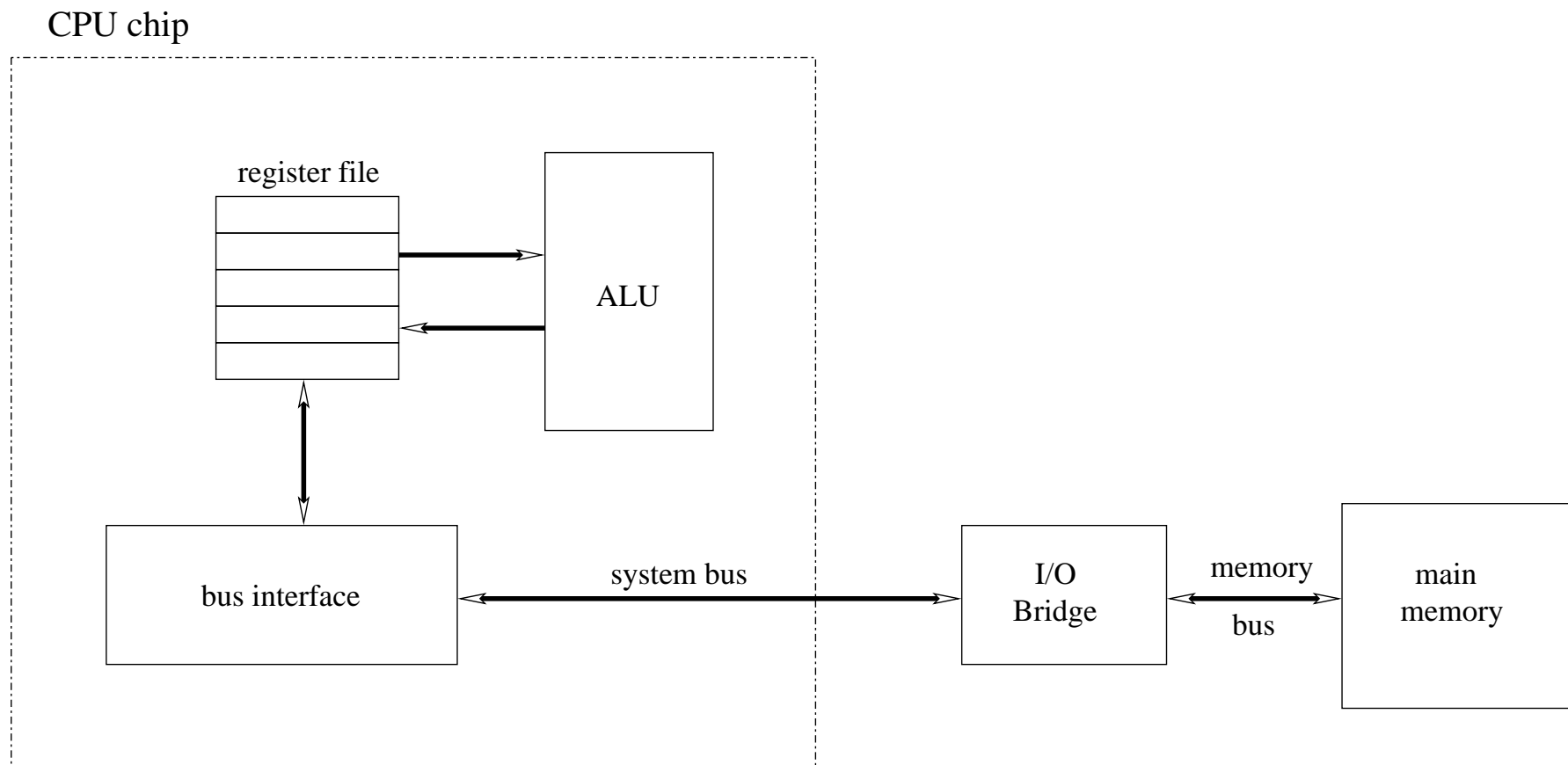64–bit quadword at main memory address

Nonvolatile Memories

- DRAM and SRAM are volatile memories; they lose information if powered off.
- Nonvolatile memories retain their value even if powered off.
  - The generic name is read-only memory (ROM).
  - This is misleading because some ROMs can be read and modified.
- Types of ROMs
  - Programmable ROM (PROM)
  - Eraseable programmable ROM (EPROM)
  - Electrically eraseable PROM (EEPROM)
  - Flash memory
- Firmware: Program stored in a ROM
  - Boot time code, BIOS (basic input/output system)
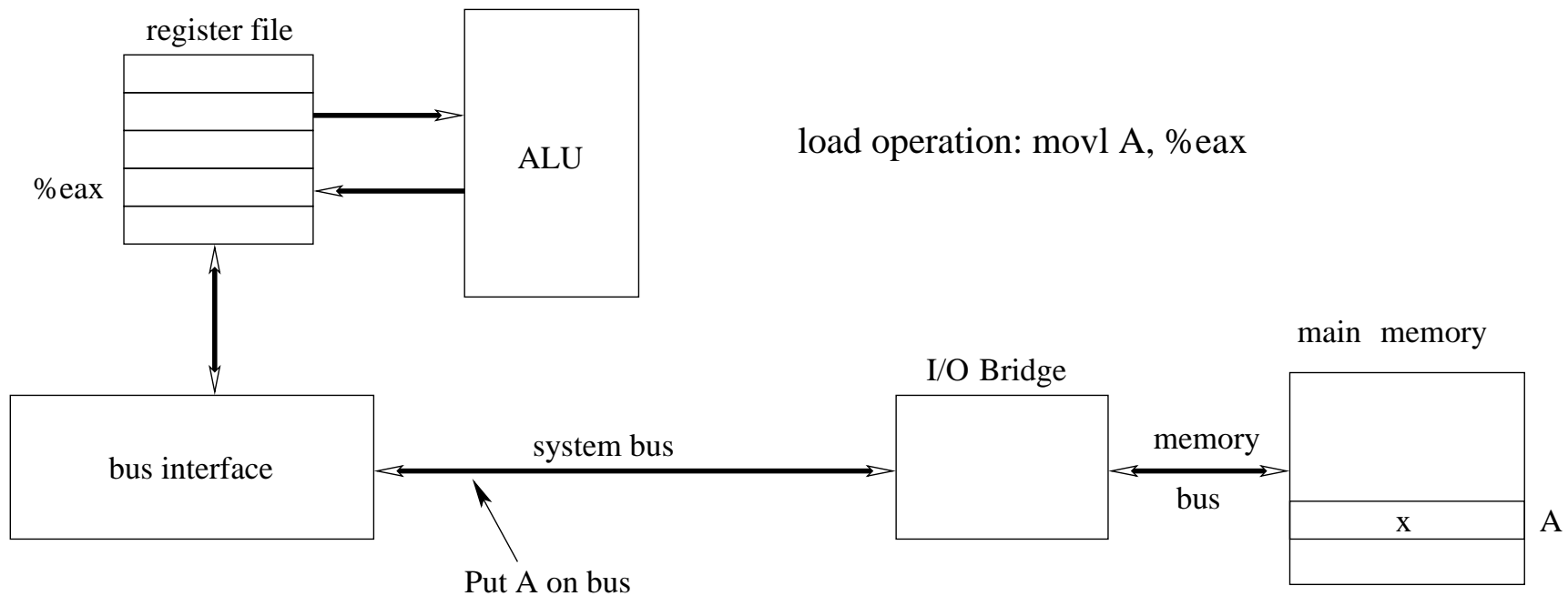 - Graphics cards, disk controllers

Connecting CPU and Memory

- A *bus* is a collection of parallel wires that carry address, data, and control signals.

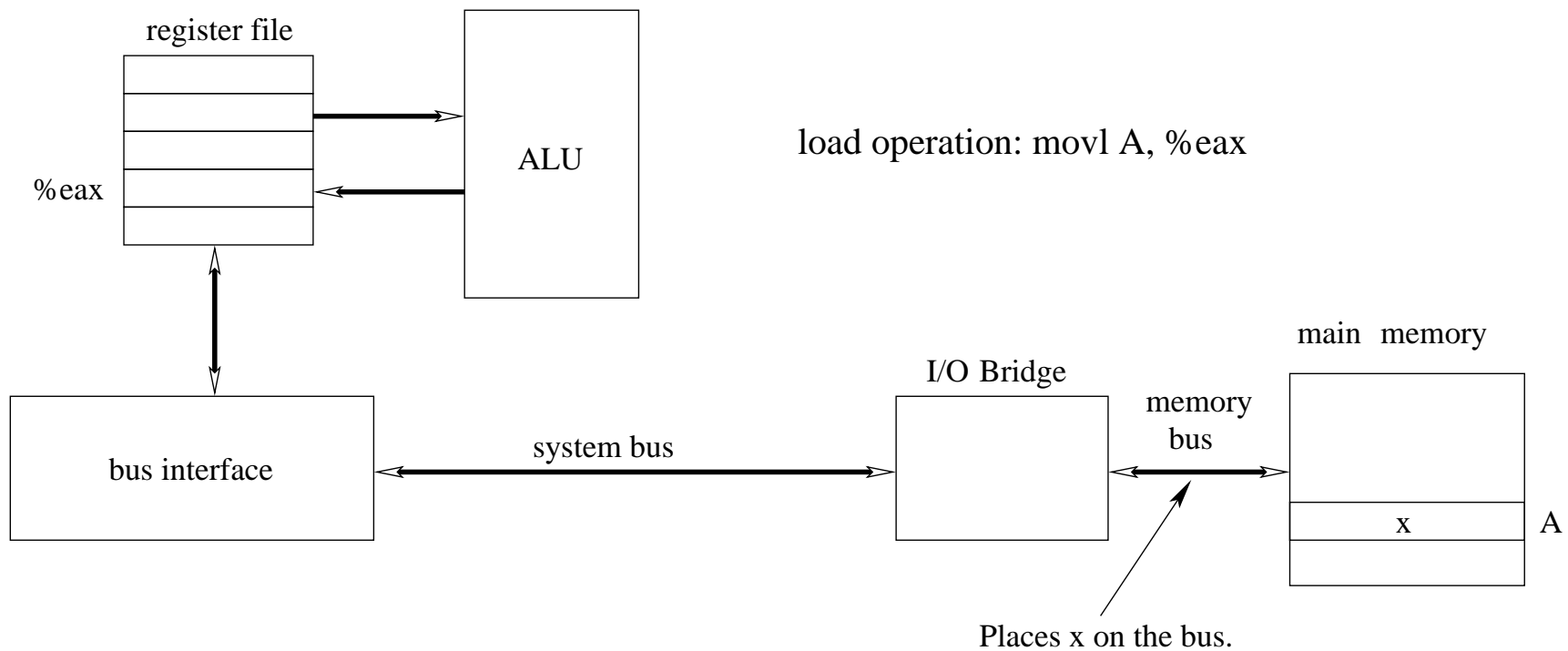- Buses are typically shared by multiple devices.

CPU chip

register file

ALU

bus interface

system bus

I/O Bridge

memory bus

main memory

CPU places address A on the memory bus.

register file

%eax

ALU

load operation: movl A, %eax

bus interface

system bus

Put A on bus

I/O Bridge

main memory

memory

bus

x

A

Main memory reads A from the memory bus, retrieves word x, and places it on the bus.

register file

%eax

ALU

load operation: movl A, %eax

bus interface

system bus

I/O Bridge

memory bus

main memory

x   A

Places x on the bus.

Memory Read Transaction (3)

CPU reads word x from the bus and copies it into register %eax.

register file

%eax | x

ALU

load operation: movl A, %eax

Copy x to register %eax

bus interface
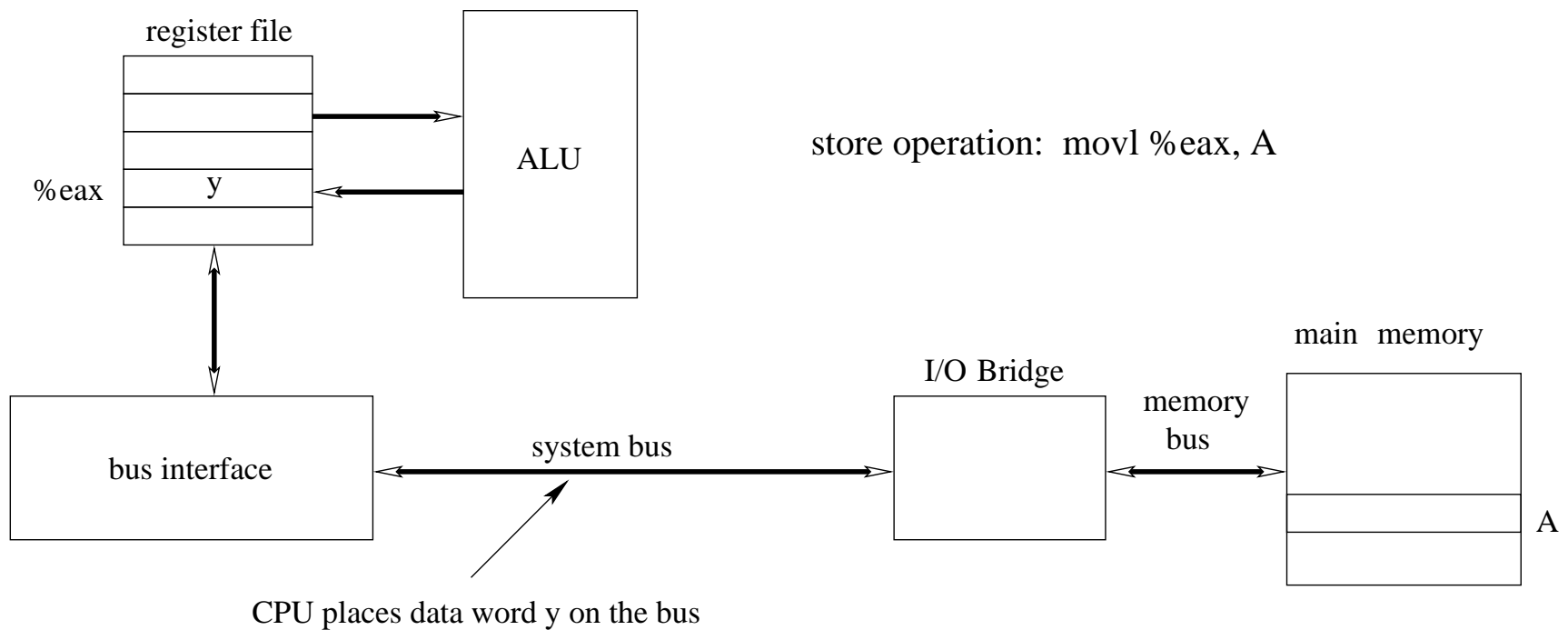
system bus

I/O Bridge

memory bus

main memory

x | A
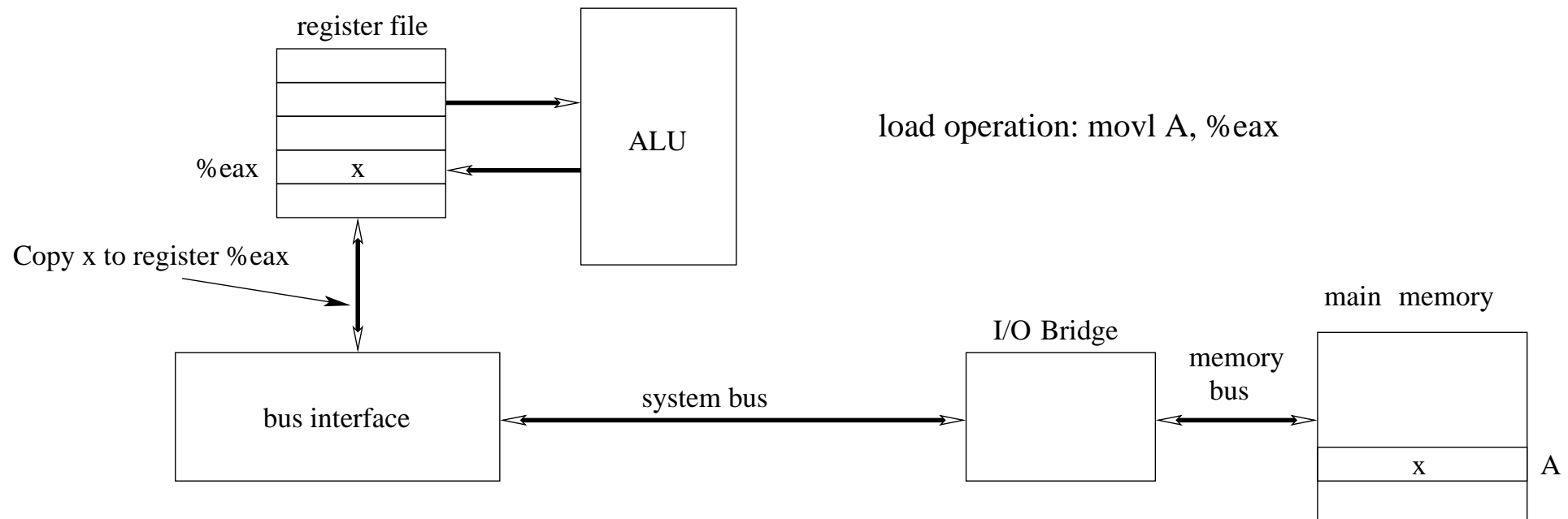
Memory Write Transaction (1)

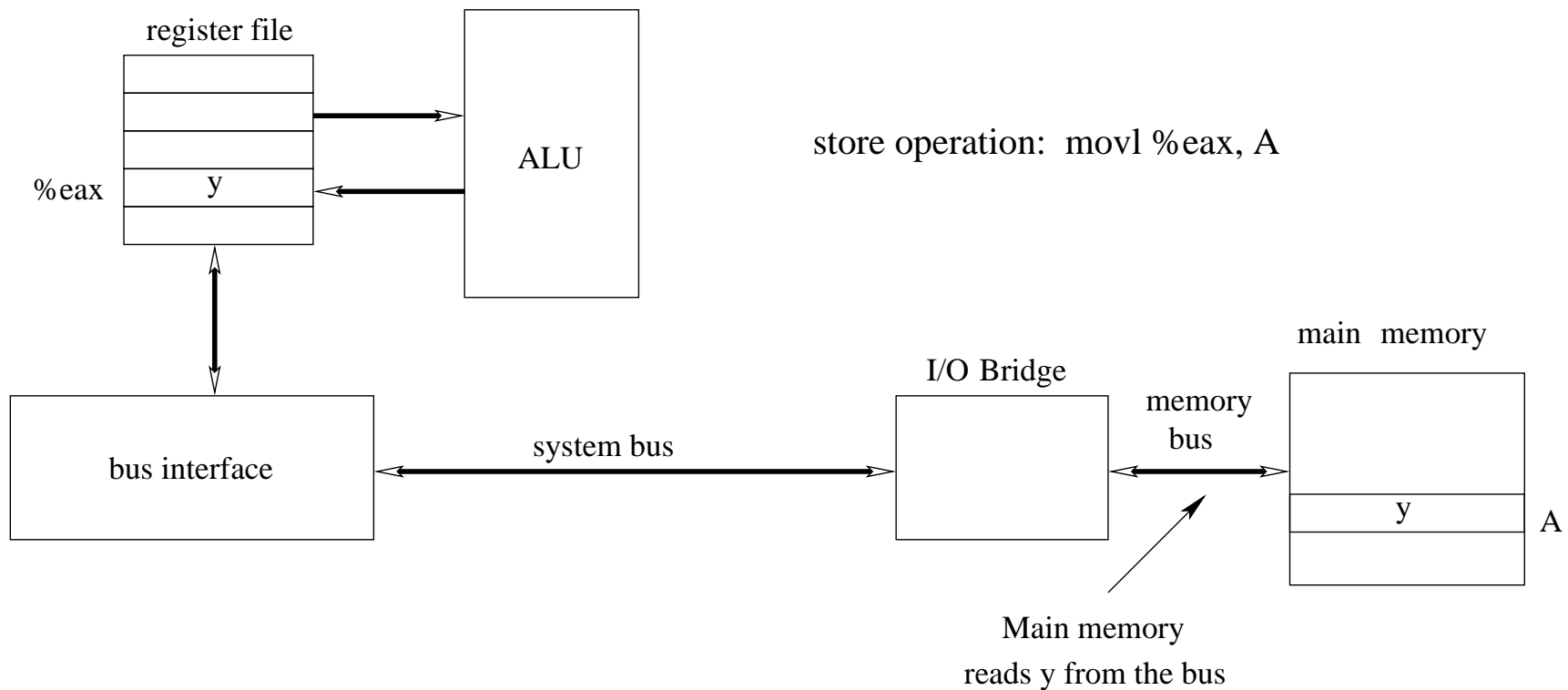CPU places address A on bus. Main memory reads it and waits for the corresponding data word to arrive.

store operation: movl %eax, A
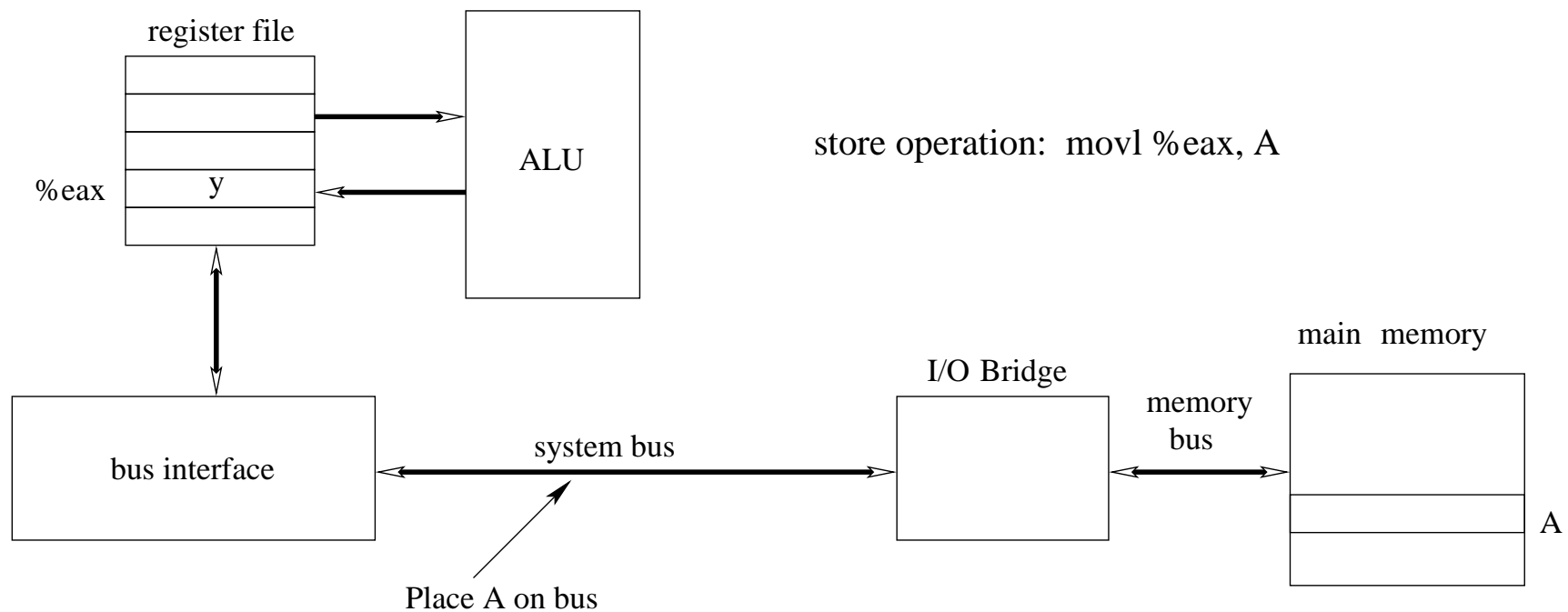
Memory Write Transaction (2)

CPU places data word y on the bus.

register file

%eax   y

ALU

store operation: movl %eax, A

main memory

I/O Bridge

bus interface

system bus

memory bus

A

CPU places data word y on the bus

Main memory reads data word y from the bus and stores it at address A.

register file

ALU

%eax   y

store operation: movl %eax, A

main memory

I/O Bridge

bus interface   system bus

memory bus

y   A

Main memory reads y from the bus

- Disks consist of platters, typically each have two *surfaces* though not always.

- Each surface consists of concentric rings called *tracks*.

- Each track consists of *sectors* separated by gaps.
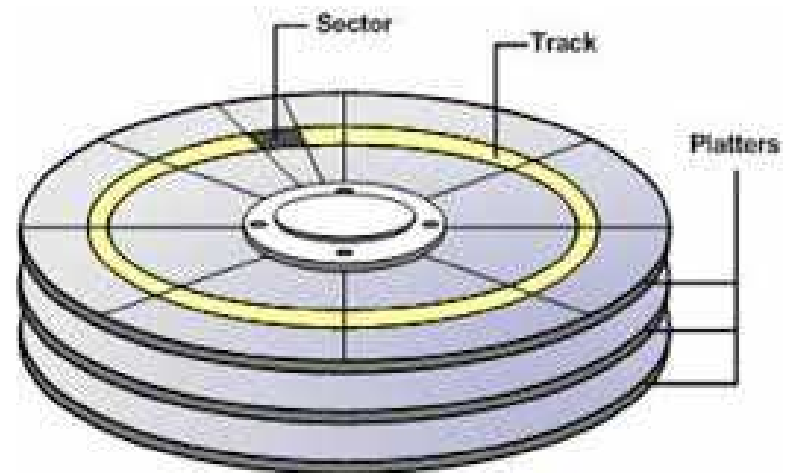
Disk Geometry (Multiple-Platter View)

Aligned tracks form a cylinder. Read/write heads move in unison so are all on the same cylinder at any one time.
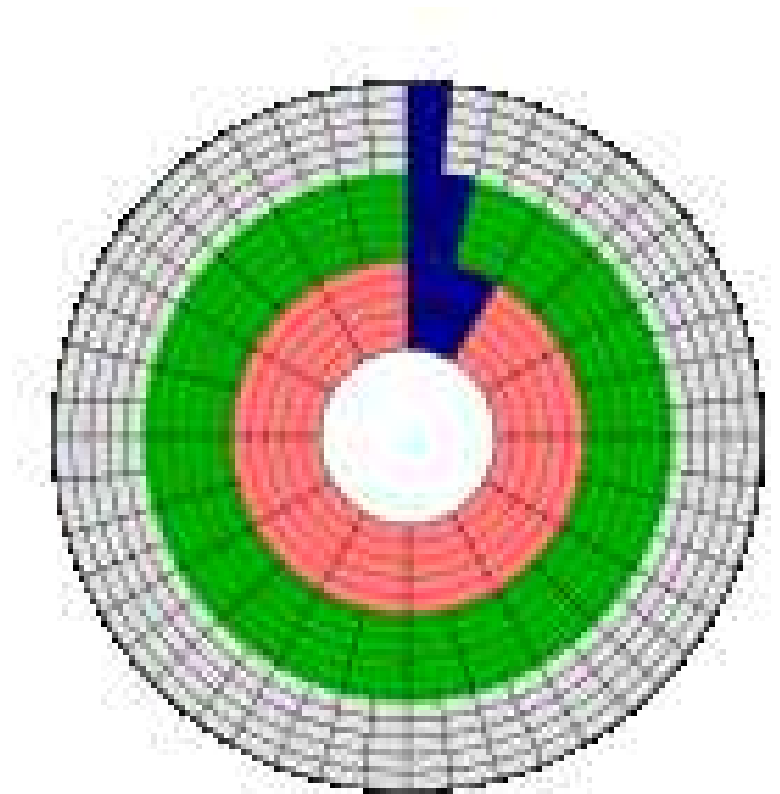
Disk Capacity
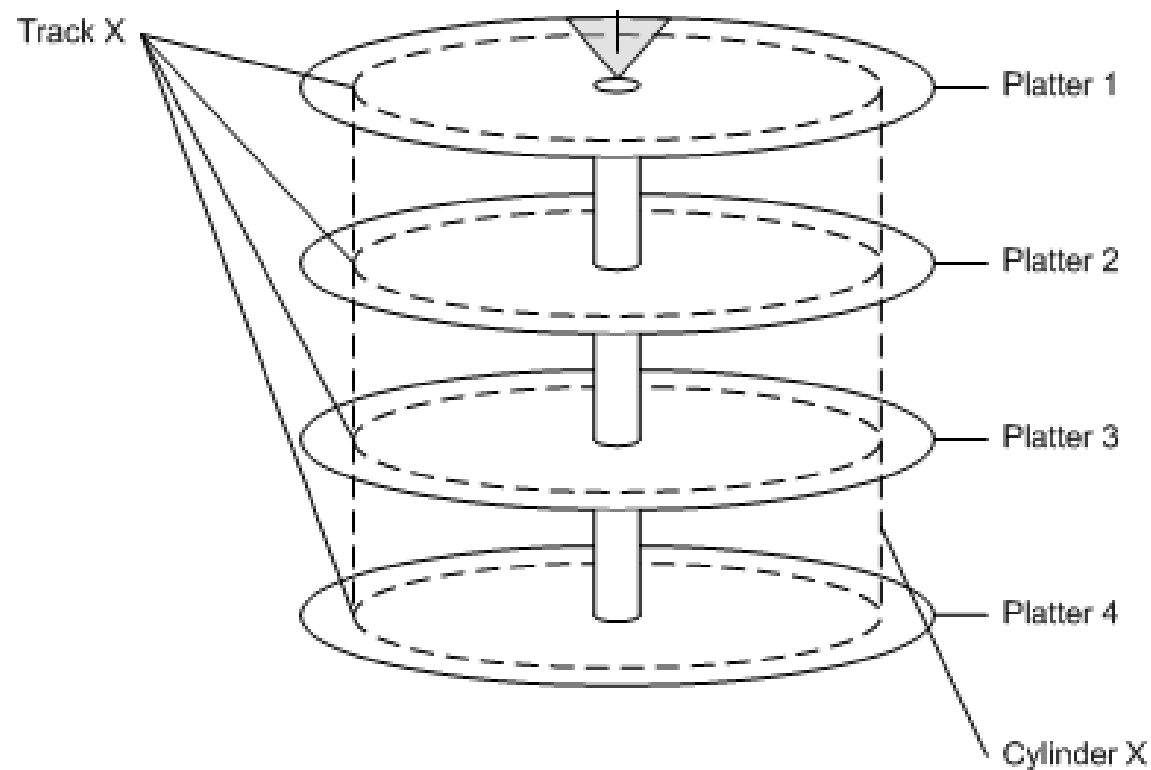
- **Capacity:** maximum number of bits that can be stored. Vendors express this in terms of gigabytes (GB), where $1\text{GB} = 10^9$ bytes.
- Capacity is determined by these technology factors:
  - **Recording density** (bits/in): number of bits that can be squeezed into a 1 inch segment of a track.
  - **Track density** (tracks/in): number of tracks that can be squeezed into a 1 inch radial segment.
  - **Areal density** (bits/in^2): product of recording and track density.

Disk Zones

Modern disks partition tracks into disjoint subsets called **recording zones**.

- Each track in a zone has the same number of sectors, determined by the circumference of the innermost track.

- Each zone has a different number of sectors/track.

- Why does this make sense?

Computing Disk Capacity

Capacity = (bytes/sector) × (avg. sectors/track) × (tracks/surface) × (surfaces/platter) × (platters/disk)

Example:

- 512 bytes/sector
- 300 sectors/track (on average)
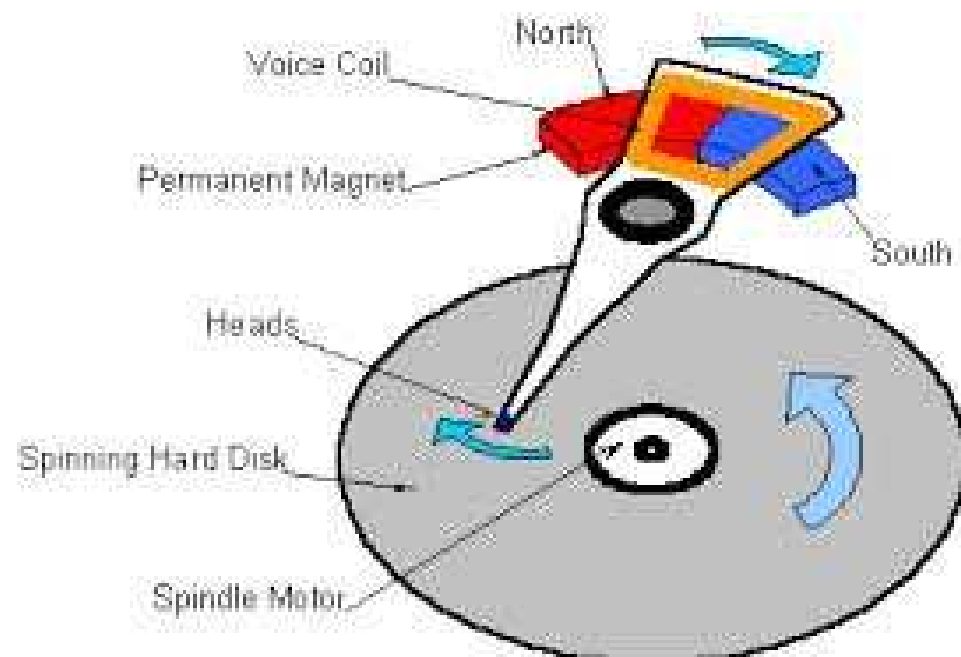- 20,000 tracks/surface
- 2 surfaces/platter
- 5 platters/disk

Capacity = $512 \times 300 \times 20000 \times 2 \times 5 = 30,720,000,000 = 30.72$GB
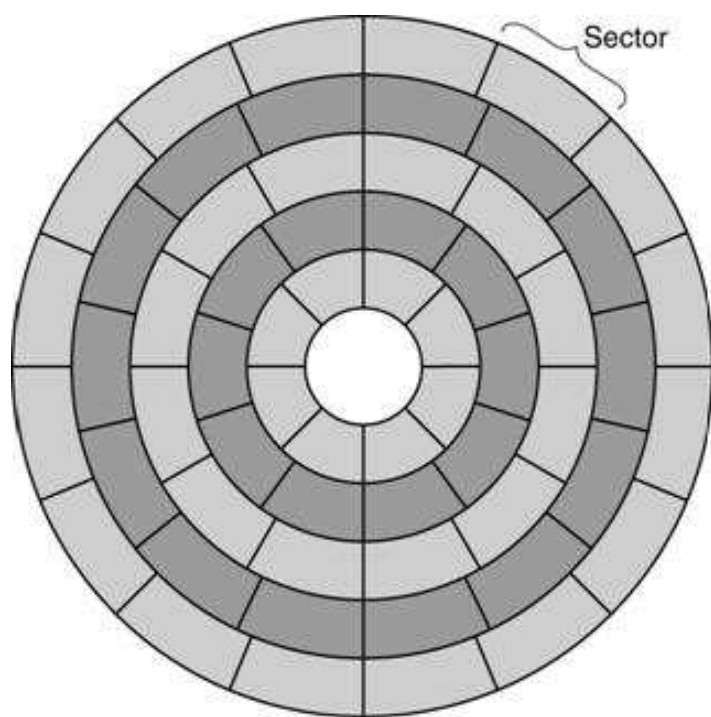
The disk surface spins at a fixed rotational rage.

The read/write head is attached to the end of the arm and flies over the disk surface on a a very thin cushion of air (around 0.1 microns).

By moving radially, the arm can position the read/write head over any track.

Sector

To read a sector on a disk requires:

- **Seek:** the read head is moved to the proper track.

- **Rotational latency:** the desired sector must rotate to the read head.

- **Data transfer:** the sector is read as it rotates under the read head.

Writing is the same.

Which of these do you suppose is longest?

Disk Access Time

The average time to access a target sector is approximately:

$$T_{access} = T_{seek} + T_{rotation} + T_{transfer}$$

- **Seek time** (T_{seek})
  - Time to position heads over cylinder containing the target sector.
  - Average $T_{seek} = 9$ms
- **Rotational latency** ($T_{rotation}$)
  - Time waiting for first bit of target sector to pass under read/write head.
  - Average $T_{rotation} = 1/2 \times 1/\text{RPMs} \times 60\text{sec}/1\text{min}$
- **Transfer time** ($T_{transfer}$)
  - Time to read the bits in the target sector.
  - Average $T_{transfer} = 1/\text{RPM} \times 1/(\text{average sectors/track}) \times 60\text{sec}/1\text{min}$

Disk Access Time Example

Given:

- Rotational rate: 7,200 RPM

- Average seek time: 9 ms

- Average sectors/track: 400

Derived:

- Average $T_{rotation}$:
  $1/2 \times (60\text{sec}/7200\text{RPM}) \times 1000\text{ms/sec} = 4\text{ms}$

- Average $T_{transfer}$:
  $60/7200\text{RPM} \times 1/(400 \text{ sectors/track}) \times 1000\text{ms/sec} = 0.02\text{ms}$

- T_{access}: 9 ms + 4 ms + 0.02 ms

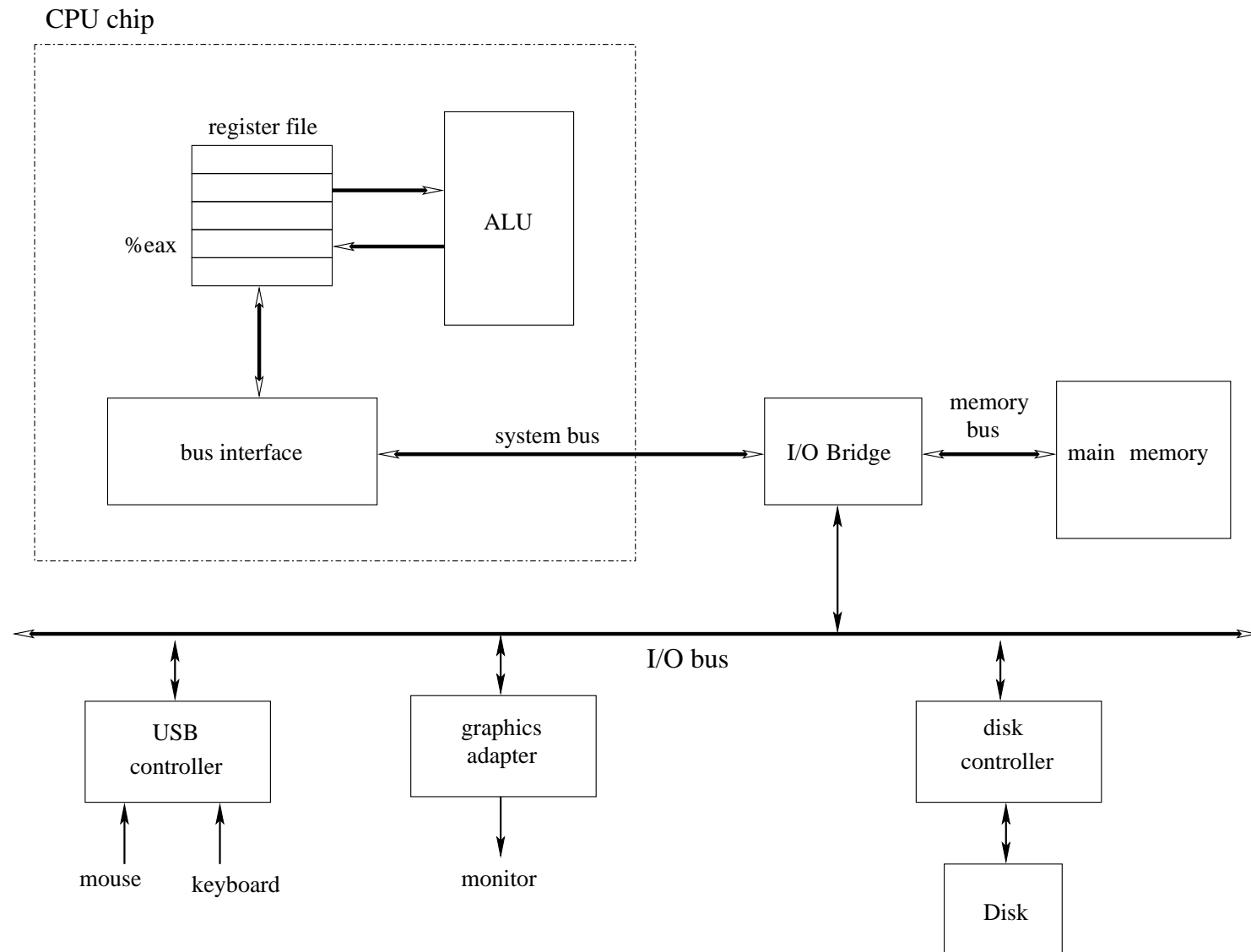# Disk Access Time Key Points

Important points:

- Access time is dominated by seek time and rotational latency.

- The first bit in a sector is the most expensive; the rest are basically free.

- SRAM access time is about 4ns / doubleword; DRAM about 60ns.

- Disk is about 40,000 times slower than SRAM, and 2,500 times slower than DRAM.

Logical Disk Blocks

- Modern disks present a simpler abstract view of the complex sector geometry.
  - The set of available sectors is modeled as a sequence of b-sized **logical blocks** $(0, 1, 2, \ldots)$.
- Mapping between logical blocks and actual (physical) sectors:
  - Is maintained by a hardware/firmware device called a disk controller.
  - Converts requests for logical blocks into (surface, track, sector) triples.
- Allows the controller to set aside spare cylinders for each zone.
  - This accounts for the difference between "formatted capacity" and "maximum capacity."
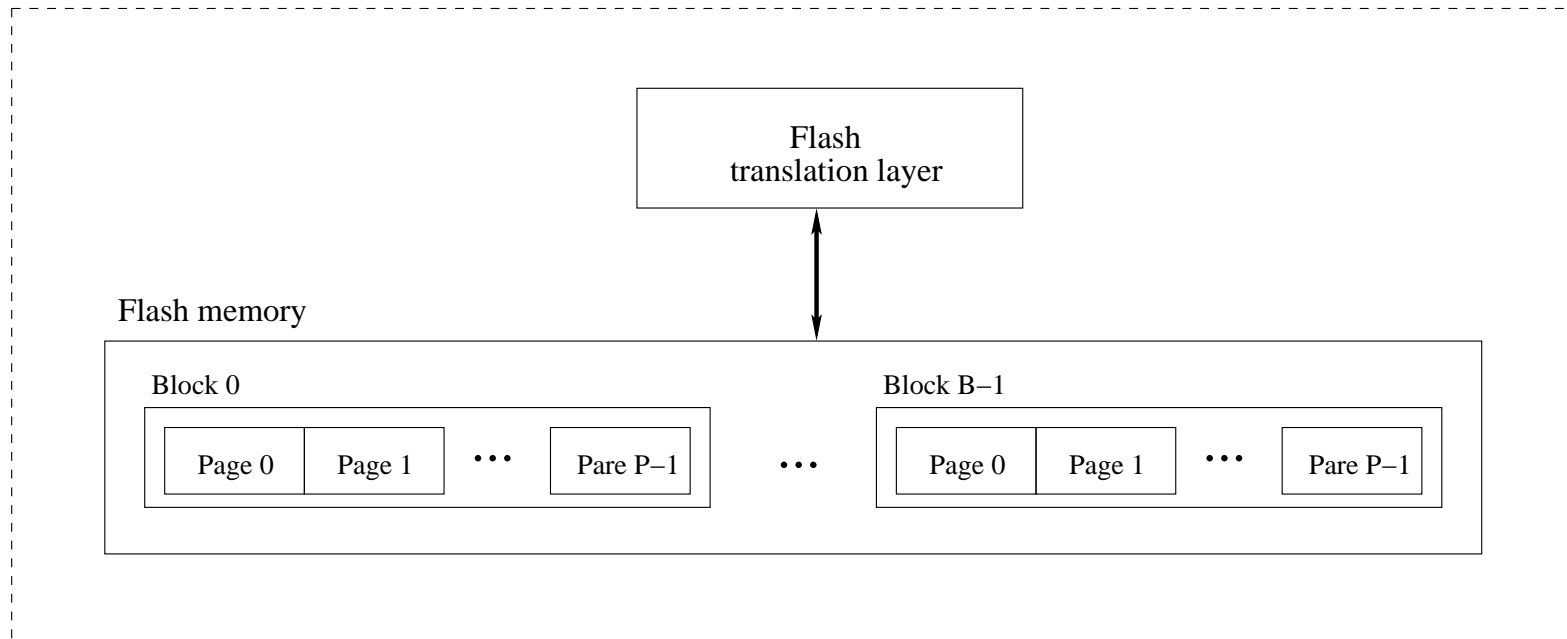
I/O Bus

CPU chip

register file

%eax

ALU

bus interface

system bus

I/O Bridge

memory bus

main memory

I/O bus

USB controller

mouse   keyboard

graphics adapter

monitor

disk controller

Disk

1. The CPU initiates a disk read by writing a command, logical block number, and destination memory address to a *port* (address) associated with the disk controller.

2. The disk controller reads the associated sector and performs a direct memory access (DMA) transfer into main memory.

3. When the DMA transfer completes, the disk controller notifies the CPU with an *interrupt* (i.e., asserts a special "interrupt" pin on the CPU).

Solid State Drives (SSDs)

Solid State Disk (SSD)

Flash
translation layer

Flash memory

Block 0

| Page 0 | Page 1 | ... | Pare P−1 |

...

Block B−1

| Page 0 | Page 1 | ... | Pare P−1 |

- Requests to read and write logical blocks come across the I/O bus to the Flash translation layer.
- Pages are 512KB to 4KB; blocks are 32 to 128 pages.
- Data is read/written in units of pages.
- A page can only be written after its block has been erased.
- A block wears out after around 100,000 repeated writes.

SSDs Performance Characteristics

Sequential read tput	250 MB/s	Sequential write tput	170 MB/s
Random read tput	140 MB/s	Random write tput	14 MB/s
Random read access	30 μs	Random write access	300 μs

Why are random writes so slow?

- Erasing a block is slow (around 1 ms).
- Write to a page triggers a copy of all useful pages in the block.
- Must find a used block (new block) and erase it.
- Write the page into the new block.
- Copy other pages from the old block to the new block.

SSD vs. Rotating Disks

Advantages:

- No moving parts; faster, less power, more rugged.

Disadvantages:

- Have the potential to wear out. This is mitigated by "wear leveling logic" in the flash translation layer.

- E.g., Intel X25 guarantees 1 petabyte (10^{15} bytes) of random writes before they wear out.

- In 2010, they were about 100X more expensive. But by November, 2013 this has fallen to 10X. By February, 2015, this was about 2X.

Applications:

- MP3 players, smart phones, laptops.

- They are beginning to appear in desktops and servers.

Storage Trends

Year:	1980	1985	1990	1995	2000	2005	2010	1980:2010
SRAM								
$/MB	19.2K	2.9K	320	256	100	75	60	320
access (ns)	300	150	35	15	3	2	1.5	200
DRAM								
$/MB	8K	880	100	30	1	0.1	0.06	130K
access (ns)	375	200	100	70	60	50	40	9
typical size	0.064	0.256	4	16	64	2K	8K	125K
Disk								
$/MB	500	100	8	0.30	0.001	0.005	0.0003	1.6M
access (ms)	87	75	28	10	8	4	3	29
typical size	1	10	160	1K	20K	160K	1.5M	1.5M

CPU Clock Rates

Year:	1980	1985	1990	1995	2000	2005	2010	1980:2010
CPU	8080	386	Pentium	P-III	P-4	Core 2	Core i7	
Clock MHz	1	20	150	600	3300	2000	2500	2500
Cycle (ns)	1000	50	6	1.6	0.3	0.5	0.4	2500
Cores	1		1	1	1	1 2	4	4
Effective Cycle time	1000	50	6	1.6	0.3	0.25	0.1	10K

Around 2003, was the inflection point in computer history when designers hit the "Power Wall." Cores increased, but the clock rate actually decreased.

CPU-Memory Gap

CPU speed increases *faster* than memory speed, meaning that:

- memory is more and more a limiting factor on performance;
- increased importance for caching and similar techniques.