

Computing Maximum Unavoidable Subgraphs Using SAT Solvers

Cuong Chau & Marijn Heule

{ckcuong,marijn}@cs.utexas.edu

Department of Computer Science

The University of Texas at Austin

July 7, 2016

Outline

- 1 Introduction and Motivation
- 2 Computing Unavoidable Subgraphs (USGs) Using SAT Solvers
- 3 Multi-Component USG
- 4 Deriving Symmetry-Breaking Predicates (SBPs) from USGs
- 5 Conclusions

- 1 Introduction and Motivation
- 2 Computing Unavoidable Subgraphs (USGs) Using SAT Solvers
- 3 Multi-Component USG
- 4 Deriving Symmetry-Breaking Predicates (SBPs) from USGs
- 5 Conclusions

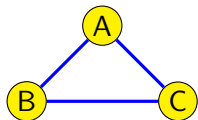
Definition 1 (Graph isomorphism)

Two graphs G and H are isomorphic if there exists an **edge-preserving bijection** from the vertices of G to the vertices of H . Isomorphic graphs occur in the same **isomorphism class**.

Definition 2 (Unavoidable subgraph)

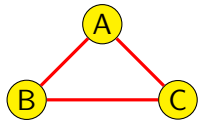
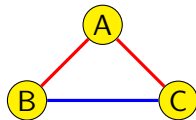
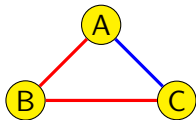
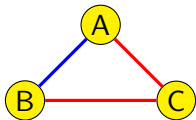
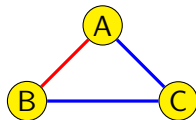
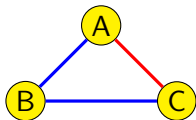
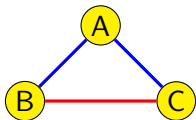
A graph G is called an unavoidable subgraph (USG) of the **fully-connected graph** K_n if **every red/blue edge-coloring** of K_n contains an **isomorphic graph** of G **in only one color**.

Introduction

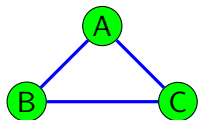


For all red/blue edge-colorings of K_3 ,
exists a monochromatic path of two edges.

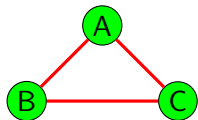
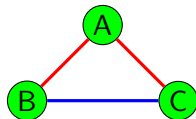
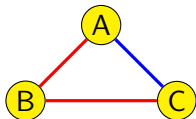
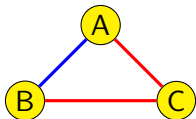
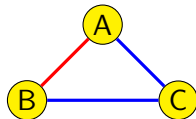
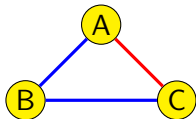
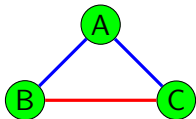
(Unavoidable subgraph)



Introduction



There exists a graph in each isomorphism class of K_3 s.t. the path B-A-C is monochromatic.



Motivation

Our approach tries to compute a **maximum** unavoidable subgraph (measured in the number of edges) for a given complete graph using **SAT solvers**.

Motivation

Our approach tries to compute a **maximum** unavoidable subgraph (measured in the number of edges) for a given complete graph using **SAT solvers**.

Unlike many **nicely structured** unavoidable subgraphs (USGs) (e.g., cliques, cycles, stars) that have been heavily studied, **maximum USGs** may not have a clear structure.

Motivation

Our approach tries to compute a **maximum** unavoidable subgraph (measured in the number of edges) for a given complete graph using **SAT solvers**.

Unlike many **nicely structured** unavoidable subgraphs (USGs) (e.g., cliques, cycles, stars) that have been heavily studied, **maximum USGs** may not have a clear structure.

USGs allow for an alternative **symmetry-breaking** approach for graph problems: given a USG, we can simplify graph problems by enforcing that **all edges** in the USG are **either all present or all absent**.

Motivation

Our approach tries to compute a **maximum** unavoidable subgraph (measured in the number of edges) for a given complete graph using **SAT solvers**.

Unlike many **nicely structured** unavoidable subgraphs (USGs) (e.g., cliques, cycles, stars) that have been heavily studied, **maximum USGs** may not have a clear structure.

USGs allow for an alternative **symmetry-breaking** approach for graph problems: given a USG, we can simplify graph problems by enforcing that **all edges** in the USG are **either all present or all absent**.

The larger the USG (measured in the number of edges), the stronger the **symmetry-breaking predicate** (SBP) can be derived (explained in Section 4).

- 1 Introduction and Motivation
- 2 Computing Unavoidable Subgraphs (USGs) Using SAT Solvers**
- 3 Multi-Component USG
- 4 Deriving Symmetry-Breaking Predicates (SBPs) from USGs
- 5 Conclusions

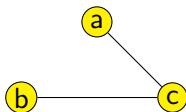
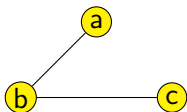
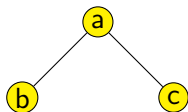
SAT Encoding of USGs

We employ a SAT solver to check whether a given graph G of order k is a USG of K_n ($k \leq n$).

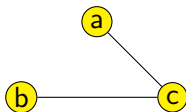
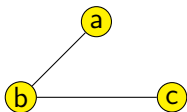
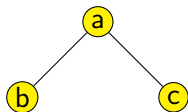
SAT Encoding of USGs

We employ a SAT solver to check whether a given graph G of order k is a USG of K_n ($k \leq n$).

Encoding: Let's see how we encode the USG problem into SAT through the following example: *Check if a path of two edges is a USG of K_3 .*



SAT Encoding of USGs



Let ab , ac , and bc denote the **Boolean variables representing the color of the edge** connecting vertices a and b , a and c , and b and c , respectively. If a Boolean variable has value T , the corresponding edge has color **red**. Otherwise it has color **blue**.

$$\mathcal{F} = (ab \wedge ac) \vee (\overline{ab} \wedge \overline{ac}) \vee (ab \wedge bc) \vee (\overline{ab} \wedge \overline{bc}) \vee (ac \wedge bc) \vee (\overline{ac} \wedge \overline{bc})$$

A path of two edges is a USG of K_3 .

$\Leftrightarrow \mathcal{F}$ is VALID.

$\Leftrightarrow \overline{\mathcal{F}}$ is UNSATISFIABLE.

$$\overline{\mathcal{F}} = (\overline{ab} \vee \overline{ac}) \wedge (ab \vee ac) \wedge (\overline{ab} \vee \overline{bc}) \wedge (ab \vee bc) \wedge (\overline{ac} \vee \overline{bc}) \wedge (ac \vee bc)$$

Since $\overline{\mathcal{F}}$ is in CNF, SAT solvers can solve it directly.

Computing USGs Mechanically

SAT encoding of a USG problem (construct $\overline{\mathcal{F}_{G, K_n}}$ – referred to as $\overline{\mathcal{F}}$ in the previous slide):

Computing USGs Mechanically

SAT encoding of a USG problem (construct $\overline{\mathcal{F}_{G,K_n}}$ – referred to as $\overline{\mathcal{F}}$ in the previous slide):

For each subgraph H of K_n that is **isomorphic** to G , construct the following two clauses:

- **disjunction** of **positive** literals representing **red** color of edges in H ,
- **disjunction** of **negative** literals representing **blue** color of edges in H .

Computing USGs Mechanically

SAT encoding of a USG problem (construct $\overline{\mathcal{F}_{G,K_n}}$ – referred to as $\overline{\mathcal{F}}$ in the previous slide):

For each subgraph H of K_n that is **isomorphic** to G , construct the following two clauses:

- **disjunction** of **positive** literals representing **red** color of edges in H ,
- **disjunction** of **negative** literals representing **blue** color of edges in H .

$\overline{\mathcal{F}_{G,K_n}}$ is the **conjunction** of all of these clauses.

Computing USGs Mechanically

SAT encoding of a USG problem (construct $\overline{\mathcal{F}_{G,K_n}}$ – referred to as $\overline{\mathcal{F}}$ in the previous slide):

For each subgraph H of K_n that is **isomorphic** to G , construct the following two clauses:

- **disjunction** of **positive** literals representing **red** color of edges in H ,
- **disjunction** of **negative** literals representing **blue** color of edges in H .

$\overline{\mathcal{F}_{G,K_n}}$ is the **conjunction** of all of these clauses.

Our method computes USGs mechanically using a **SAT solver** in combination with the tool **nauty** [B. McKay and A. Piperno, 2014] (for automatically generating input graphs) and **symmetry-breaking methods**.

Computing USGs Mechanically

SAT encoding of a USG problem (construct $\overline{\mathcal{F}_{G,K_n}}$ – referred to as $\overline{\mathcal{F}}$ in the previous slide):

For each subgraph H of K_n that is **isomorphic** to G , construct the following two clauses:

- **disjunction** of **positive** literals representing **red** color of edges in H ,
- **disjunction** of **negative** literals representing **blue** color of edges in H .

$\overline{\mathcal{F}_{G,K_n}}$ is the **conjunction** of all of these clauses.

Our method computes USGs mechanically using a **SAT solver** in combination with the tool **nauty** [B. McKay and A. Piperno, 2014] (for automatically generating input graphs) and **symmetry-breaking methods**.

A graph G is unavoidable in $K_n \Leftrightarrow \text{UNSAT}(\overline{\mathcal{F}_{G,K_n}} \wedge \text{SBP}(\overline{\mathcal{F}_{G,K_n}}))$.

Reducing the Maximum USG Search Space

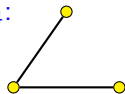
We detect the [lower bound on the size](#) and [upper bound on the maximum degree](#) of maximum USGs.

⇒ Using these bounds to reduce the maximum USG search space.

n	3	4	5	6	7	8	9
# isomorphism classes	4	11	34	156	1,044	12,346	274,668
# checked graphs	2	2	6	35	97	291	904

USG Results

K_3, K_4 :



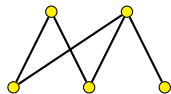
$$|E| = 2$$

K_5 :



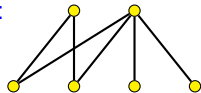
$$|E| = 3$$

K_6 :



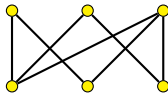
$$|E| = 5$$

K_7 :



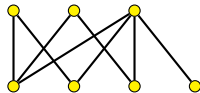
$$|E| = 6$$

K_8 :



$$|E| = 7$$

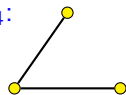
K_9 :



$$|E| = 8$$

USG Results

K_3, K_4 :



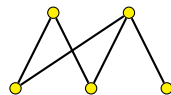
$$|E| = 2$$

K_5 :



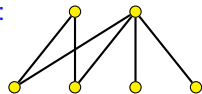
$$|E| = 3$$

K_6 :



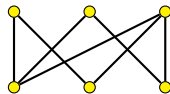
$$|E| = 5$$

K_7 :



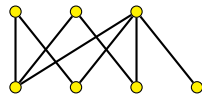
$$|E| = 6$$

K_8 :



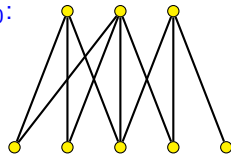
$$|E| = 7$$

K_9 :



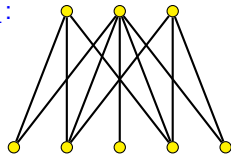
$$|E| = 8$$

K_{10} :



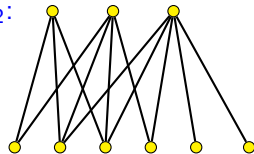
$$|E| = 10$$

K_{11} :



$$|E| = 11$$

K_{12} :



$$|E| = 12$$

- 1 Introduction and Motivation
- 2 Computing Unavoidable Subgraphs (USGs) Using SAT Solvers
- 3 Multi-Component USG**
- 4 Deriving Symmetry-Breaking Predicates (SBPs) from USGs
- 5 Conclusions

Multi-Component USG

The concept USG can be generalized to **multiple components**, such that each component must occur monochromatic in all red/blue edge-colorings of K_n .

Multi-Component USG

The concept USG can be generalized to **multiple components**, such that each component must occur monochromatic in all red/blue edge-colorings of K_n .

We require that each component must have **at least two edges**.

Multi-Component USG

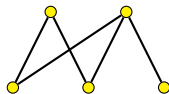
The concept USG can be generalized to **multiple components**, such that each component must occur monochromatic in all red/blue edge-colorings of K_n .

We require that each component must have **at least two edges**.

As heuristic to reduce the vast number of possible multi-component graphs, we restricted the search to graphs that have at most **three** components.

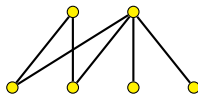
Multi-Component USG Results

K_6 :



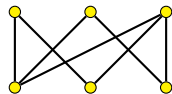
$$|E| = 5$$

K_7 :

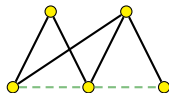


$$|E| = 6$$

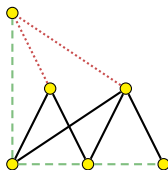
K_8 :



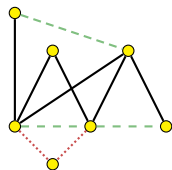
$$|E| = 7$$



$$|E| = 7$$



$$|E| = 10$$



$$|E| = 11$$

Outline

- 1 Introduction and Motivation
- 2 Computing Unavoidable Subgraphs (USGs) Using SAT Solvers
- 3 Multi-Component USG
- 4 Deriving Symmetry-Breaking Predicates (SBPs) from USGs**
- 5 Conclusions

Deriving SBPs from USGs

Converting a USG G of K_n into an SBP by **forcing all edges in each component of G to be either all present or all absent.**

Deriving SBPs from USGs

Converting a USG G of K_n into an SBP by **forcing all edges in each component of G to be either all present or all absent**.

Let e_1, e_2, \dots, e_ℓ denote the Boolean variables representing the edges of one component in G .

$$\begin{aligned} e_1 \leftrightarrow e_2 \leftrightarrow e_3 \leftrightarrow \dots \leftrightarrow e_\ell &\equiv e_1 \rightarrow e_2 \rightarrow e_3 \rightarrow \dots \rightarrow e_\ell \\ &\equiv (\bar{e}_1 \vee e_2) \wedge (\bar{e}_2 \vee e_3) \wedge \dots \wedge (\bar{e}_\ell \vee e_1) \end{aligned}$$

Deriving SBPs from USGs

Converting a USG G of K_n into an SBP by **forcing all edges in each component of G to be either all present or all absent**.

Let e_1, e_2, \dots, e_ℓ denote the Boolean variables representing the edges of one component in G .

$$\begin{aligned} e_1 \leftrightarrow e_2 \leftrightarrow e_3 \leftrightarrow \dots \leftrightarrow e_\ell &\equiv e_1 \rightarrow e_2 \rightarrow e_3 \rightarrow \dots \rightarrow e_\ell \\ &\equiv (\bar{e}_1 \vee e_2) \wedge (\bar{e}_2 \vee e_3) \wedge \dots \wedge (\bar{e}_\ell \vee e_1) \end{aligned}$$

Each monochromatic component of ℓ edges can be encoded as a CNF formula consisting of ℓ binary clauses.

Deriving SBPs from USGs

Converting a USG G of K_n into an SBP by **forcing all edges in each component of G to be either all present or all absent**.

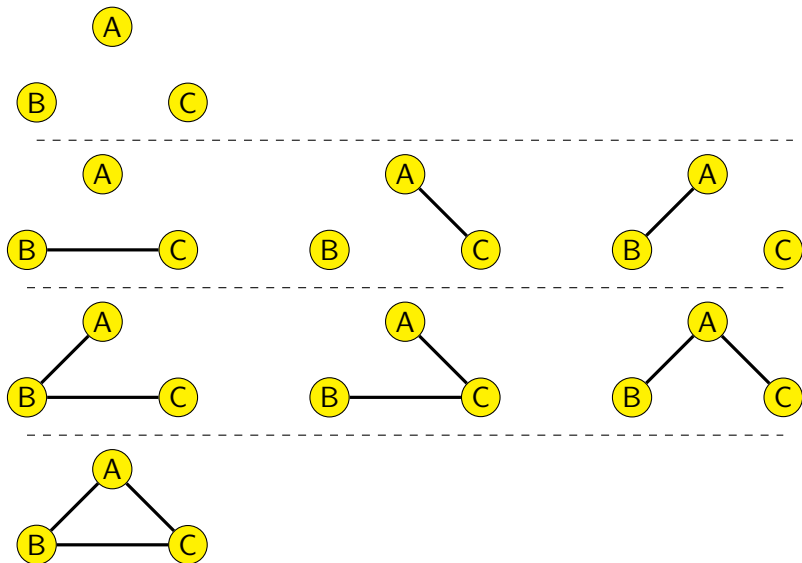
Let e_1, e_2, \dots, e_ℓ denote the Boolean variables representing the edges of one component in G .

$$\begin{aligned} e_1 \leftrightarrow e_2 \leftrightarrow e_3 \leftrightarrow \dots \leftrightarrow e_\ell &\equiv e_1 \rightarrow e_2 \rightarrow e_3 \rightarrow \dots \rightarrow e_\ell \\ &\equiv (\bar{e}_1 \vee e_2) \wedge (\bar{e}_2 \vee e_3) \wedge \dots \wedge (\bar{e}_\ell \vee e_1) \end{aligned}$$

Each monochromatic component of ℓ edges can be encoded as a CNF formula consisting of ℓ binary clauses.

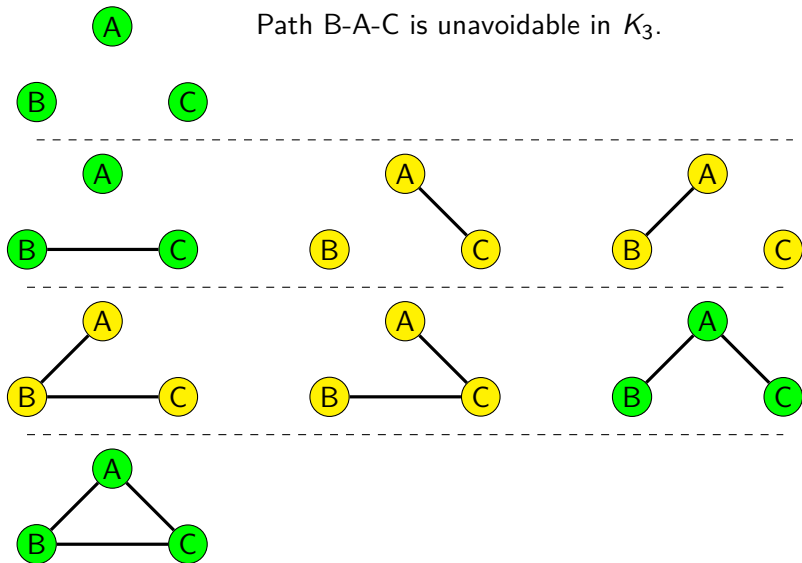
Applying this encoding for all components of G results in an SBP of $|E(G)|$ binary clauses.

Example



Example

Path B-A-C is unavoidable in K_3 .



How Useful Are the USG-Based SBPs?

The number of graphs of order n is $2^{|E_{K_n}|}$, where

$$|E_{K_n}| = \binom{n}{2} = \frac{n(n-1)}{2}$$

How Useful Are the USG-Based SBPs?

The number of graphs of order n is $2^{|E_{K_n}|}$, where

$$|E_{K_n}| = \binom{n}{2} = \frac{n(n-1)}{2}$$

Applying the SBP derived from a USG G of m components, the search space is reduced to $2^{|E_{K_n}| - |E_G| + m}$.

How Useful Are the USG-Based SBPs?

The number of graphs of order n is $2^{|E_{K_n}|}$, where

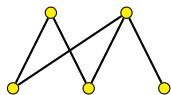
$$|E_{K_n}| = \binom{n}{2} = \frac{n(n-1)}{2}$$

Applying the SBP derived from a USG G of m components, the search space is reduced to $2^{|E_{K_n}| - |E_G| + m}$.

⇒ The larger the USG (measured in the number of edges), the stronger the SBP can be derived.

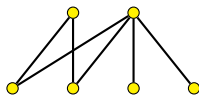
Single vs. Multi-Component USGs

$$K_6: 2^{|E(K_6)|} = 2^{15}$$



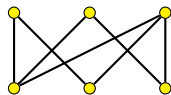
$$2^{|E(K_6)|-5+1} = 2^{11}$$

$$K_7: 2^{|E(K_7)|} = 2^{21}$$

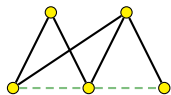


$$2^{|E(K_7)|-6+1} = 2^{16}$$

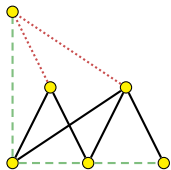
$$K_8: 2^{|E(K_8)|} = 2^{28}$$



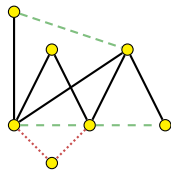
$$2^{|E(K_8)|-7+1} = 2^{22}$$



$$2^{|E(K_6)|-7+2} = 2^{10}$$



$$2^{|E(K_7)|-10+3} = 2^{14}$$



$$2^{|E(K_8)|-11+3} = 2^{20}$$

Runtime Results

Table: Runtime (in seconds) to compute the maximum or largest found single-component USGs of K_6 to K_{12} using the [glucose 3.0 SAT solver](#) [G. Audemard and L. Simon, 2009]. The experiments were run on 3.5GHz Intel Xeon E31280 processors with 8MB L3 cache size. A '-' means a timeout after 24 hours.

n	6	7	8	9	10	11	12
No SBP	0	0.025	0.38	4.85	11,690.70	-	-
USG-SBP	0	0.002	0.01	0.07	26.45	266.94	532.48
L-SBP	0	0	0.01	0.11	4.77	18.73	312.60
Q-SBP	0	0	0.01	0.11	7.98	19.40	303.40

USG-SBP: SBP derived from the largest found single-component USG of K_{n-1} .

L-SBP: Linear SBP [F. Aloul et al., 2003].

Q-SBP: Quadratic SBP [M. Codish et al., 2013].

Outline

- 1 Introduction and Motivation
- 2 Computing Unavoidable Subgraphs (USGs) Using SAT Solvers
- 3 Multi-Component USG
- 4 Deriving Symmetry-Breaking Predicates (SBPs) from USGs
- 5 Conclusions**

Conclusions

We have presented a method for computing maximum USGs mechanically via SAT solving and demonstrated how USGs can be converted into SBPs.

Conclusions

We have presented a method for computing maximum USGs mechanically via SAT solving and demonstrated how USGs can be converted into SBPs.

We observe that all maximum USGs for small graphs (up to K_9) are **bipartite** and conjecture that this holds in general.

Conclusions

We have presented a method for computing maximum USGs mechanically via SAT solving and demonstrated how USGs can be converted into SBPs.

We observe that all maximum USGs for small graphs (up to K_9) are **bipartite** and conjecture that this holds in general.

It appears that the maximum USGs of K_{n+1} are strictly larger than the maximum USGs of K_n for $n > 3$.

Conclusions

We have presented a method for computing maximum USGs mechanically via SAT solving and demonstrated how USGs can be converted into SBPs.

We observe that all maximum USGs for small graphs (up to K_9) are **bipartite** and conjecture that this holds in general.

It appears that the maximum USGs of K_{n+1} are strictly larger than the maximum USGs of K_n for $n > 3$.

Symmetry breaking was crucial to obtain our results. However, current symmetry-breaking techniques are not strong enough to compute some relatively simple USG problems using SAT.

Conclusions

We have presented a method for computing maximum USGs mechanically via SAT solving and demonstrated how USGs can be converted into SBPs.

We observe that all maximum USGs for small graphs (up to K_9) are **bipartite** and conjecture that this holds in general.

It appears that the maximum USGs of K_{n+1} are strictly larger than the maximum USGs of K_n for $n > 3$.

Symmetry breaking was crucial to obtain our results. However, current symmetry-breaking techniques are not strong enough to compute some relatively simple USG problems using SAT.

We envision that knowledge about the maximum USGs, both the single and multi-component variants, could be a basis for novel symmetry-breaking techniques for SAT solvers.

-  Fadi A. Aloul and Karem A. Sakallah and Igor L. Markov (2003)
Efficient Symmetry Breaking for Boolean Satisfiability
The 18th International Joint Conference on Artificial Intelligence, 271–276.
-  Michael Codish and Alice Miller and Patrick Prosser and Peter J. Stuckey (2013)
Breaking Symmetries in Graph Representation
The 23rd International Joint Conference on Artificial Intelligence, 510–516.
-  Brendan D. McKay and Adolfo Piperno (2014)
Practical Graph Isomorphism, II
Journal of Symbolic Computation, 60, 94–112.
-  Gilles Audemard and Laurent Simon (2009)
Predicting Learnt Clauses Quality in Modern SAT Solvers
The 21st International Joint Conference on Artificial Intelligence, 399–404.

Questions?