CS395T: Structured Models for NLP Lecture 13: Neural Networks



Greg Durrett

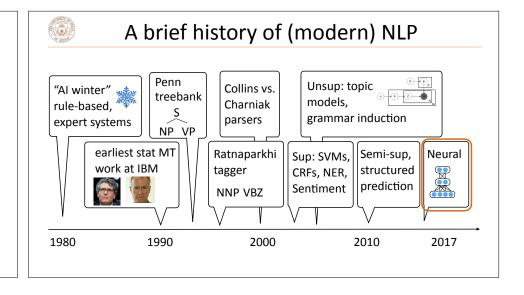


Administrivia

- ▶ Project 2 due on Tuesday
- ▶ Project 1 samples posted on website

This Lecture

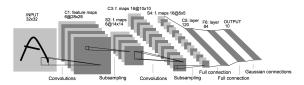
- ▶ Neural network history
- Neural network basics
- ▶ Feedforward neural networks
- ▶ Backpropagation
- ▶ Applications



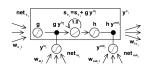


History: NN "dark ages"

▶ Convnets: applied to MNIST by LeCun in 1998



LSTMs: Hochreiter and Schmidhuber (1997)

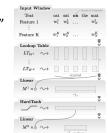


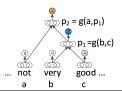
▶ Henderson (2003): neural shift-reduce parser, not SOTA



2008-2013: A glimmer of light...

- ▶ Collobert and Weston 2011: "NLP (almost) from scratch"
 - Feedforward neural nets induce features for sequential CRFs ("neural CRF")
 - ▶ 2008 version was marred by bad experiments, claimed SOTA but wasn't, 2011 version tied SOTA
- ▶ Krizhevskey et al. (2012): AlexNet for vision
- ▶ Socher: tree-structured RNNs
 - Started working well for sentiment in 2013, but only worked for weird tasks before that, some lackluster parsing results







2014: Stuff starts working

- ▶ Kim (2014) + Kalchbrenner et al. (2014): sentence classification / sentiment
 - ▶ Basic convnets work pretty well for NLP
- ▶ Sutskever et al., Bahdanau et al. seq2seq for neural MT
 - ▶ LSTMs actually do well at NLP problems
- ▶ Chen and Manning transition-based dependency parser
 - ▶ Feedforward neural networks for parsing
- ▶ 2015: explosion of neural nets for everything under the sun



Why didn't they work before?

- ▶ Datasets too small: for MT, not really better until you have 1M+ parallel sentences (and really need a lot more)
- ▶ Optimization not well understood: good initialization, per-feature scaling
- + momentum (Adagrad / Adadelta / Adam) work best out-of-the-box
 - ▶ Regularization: dropout was very important
 - ▶ Computers not big enough: can't run for enough iterations
- Inputs: need word representations to have the right continuous semantics
 - Dealing with unknown words: word pieces, use character LSTMs, ... complex stuff!

Neural Net Basics



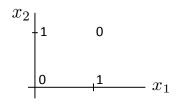
Neural Networks

- Linear classification: $\operatorname{argmax}_{y} w^{\top} f(x, y)$
- ▶ How can we do nonlinear classification?
- ▶ Polynomial, etc. from kernels, but these are slow!
- ▶ Kernels are neither necessary nor sufficient: not every pair of features interacts, might need to go beyonds pairs
- Instead, want to learn intermediate conjunctive features of the input



Neural Networks: XOR

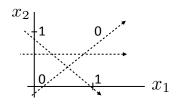
- ▶ Let's see how we can use neural nets to learn a simple nonlinear function
- Inputs x_1, x_2 (generally $\mathbf{x} = (x_1, \dots, x_m)$)
- Output y(generally $\mathbf{y} = (y_1, \dots, y_n)$)



x_1	x_2	$y = x_1 \text{ XOR } x_2$
0	0	0
0	1	1
1	0	1
1	1	0

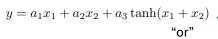


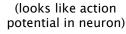
Neural Networks: XOR

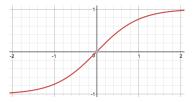


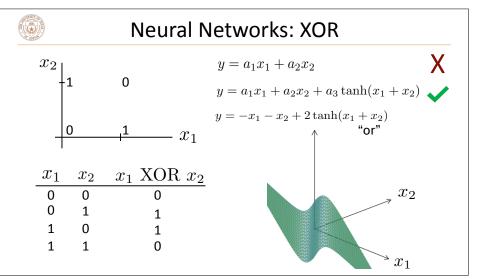
x_1	x_2	$x_1 \text{ XOR } x_2$
0	0	0
0	1	1
1	0	1
1	1	0

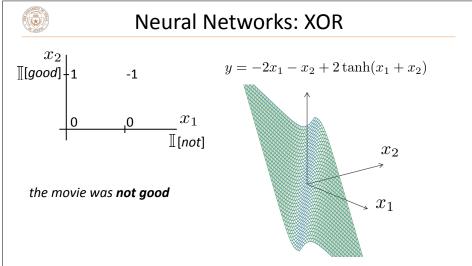
$$y = a_1 x_1 + a_2 x_2$$

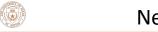










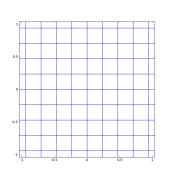


Neural Networks

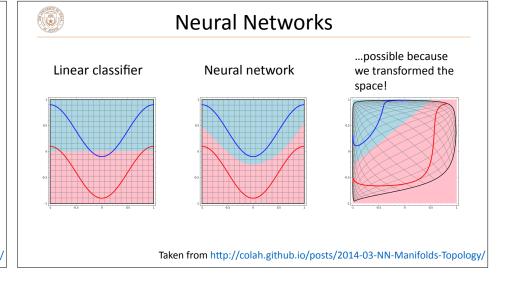
(Linear model: $y = \mathbf{w} \cdot \mathbf{x} + b$)

$$y = g(\mathbf{w} \cdot \mathbf{x} + b)$$
$$\mathbf{y} = g(\mathbf{W}\mathbf{x} + \mathbf{b})$$

Nonlinear Warp Shift transformation space



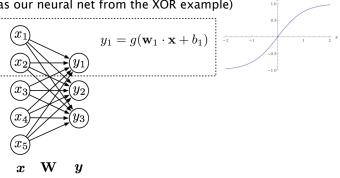
Taken from http://colah.github.io/posts/2014-03-NN-Manifolds-Topology/



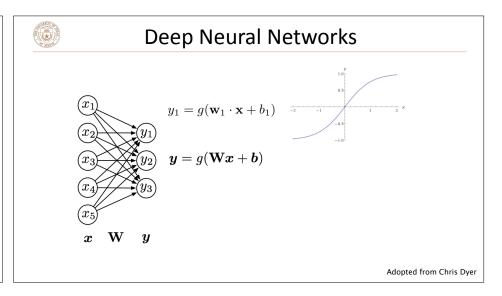


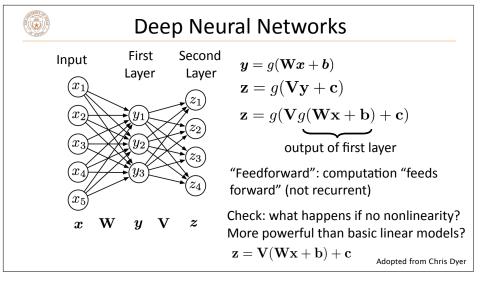
Deep Neural Networks

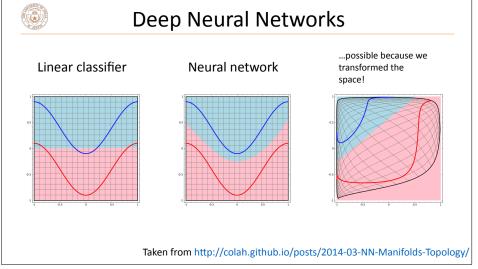
(this was our neural net from the XOR example)

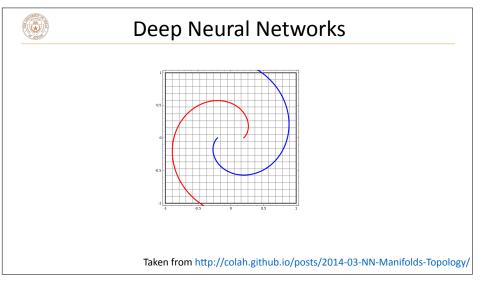


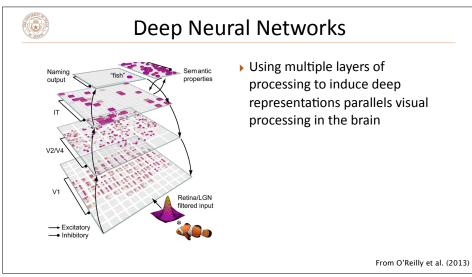












Feedforward Networks, Backpropagation



Logistic Regression with NNs

$$P(y|\mathbf{x}) = \frac{\exp(w^{\top} f(\mathbf{x}, y))}{\sum_{y'} \exp(w^{\top} f(\mathbf{x}, y'))}$$

$$P(y|\mathbf{x}) = \operatorname{softmax}_y(w^{\top} f(\mathbf{x}, y))$$

$$P(y|\mathbf{x}) = \operatorname{softmax}_y(w_y^\top g(Vf(\mathbf{x})))$$

Hidden representation **z**, can see this as "induced features"

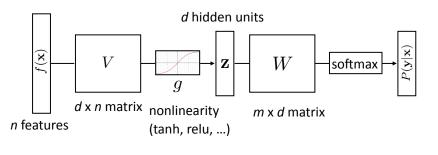
$$P(\mathbf{y}|\mathbf{x}) = \operatorname{softmax}(Wg(Vf(\mathbf{x})))$$

- ▶ Single scalar probability
- ▶ softmax_y: score vector -> prob of y
- Feature function no longer looks at label — same shared processing for each label.
- softmax: score vector -> probability vector
- Assumes that the labels y are indexed and associated with coordinates in a vector space



Neural Networks for Classification

$$P(\mathbf{y}|\mathbf{x}) = \operatorname{softmax}(Wg(Vf(\mathbf{x})))$$





Training Neural Networks

$$P(\mathbf{y}|\mathbf{x}) = \operatorname{softmax}(Wg(Vf(\mathbf{x})))$$

Maximize log likelihood of training data

$$\log P(y = i^* | \mathbf{x}) = \log \left(\operatorname{softmax}(Wg(Vf(\mathbf{x}))) \cdot e_{i^*} \right)$$

- ▶ i*: index of the gold label
- $ightharpoonup e_i$: 1 in the *i*th row, zero elsewhere. Dot by this = select *i*th index

$$\mathcal{L}(\mathbf{x}, i^*) = Wg(Vf(\mathbf{x})) \cdot e_{i^*} - \log \sum_{j=1}^{m} \exp(Wg(Vf(\mathbf{x})) \cdot e_j)$$



Computing Gradients

$$\mathcal{L}(\mathbf{x}, i^*) = Wg(Vf(\mathbf{x})) \cdot e_{i^*} - \log \sum_{j=1}^{m} \exp(Wg(Vf(\mathbf{x})) \cdot e_j)$$

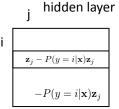
$$\mathcal{L}(\mathbf{x}, i^*) = Wg(Vf(\mathbf{x})) \cdot e_{i^*} - \log \sum_{j=1}^m \exp(Wg(Vf(\mathbf{x})) \cdot e_j)$$

$$\mathcal{L}(\mathbf{x}, i^*) = W\mathbf{z} \cdot e_{i^*} - \log \sum_{j=1}^m \exp(W\mathbf{z} \cdot e_j) \quad \mathbf{z} = g(Vf(\mathbf{x}))$$
Activations at hidden layer

▶ Gradient with respect to W

$$\frac{\partial}{\partial W_{ij}} \mathcal{L}(\mathbf{x}, i^*) = \begin{cases} \mathbf{z}_j - P(y = i | \mathbf{x}) \mathbf{z}_j & \text{if } i = i^* \\ -P(y = i | \mathbf{x}) \mathbf{z}_j & \text{otherwise} \end{cases}$$

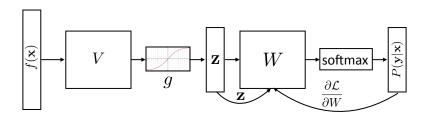
▶ Looks like logistic regression with **z** as the features!





Neural Networks for Classification

$$P(\mathbf{y}|\mathbf{x}) = \text{softmax}(Wg(Vf(\mathbf{x})))$$





Computing Gradients: Backpropagation

$$\mathcal{L}(\mathbf{x}, i^*) = W\mathbf{z} \cdot e_{i^*} - \log \sum_{j=1}^m \exp(W\mathbf{z} \cdot e_j) \qquad \mathbf{z} = g(Vf(\mathbf{x}))$$
Activations at hidden layer

▶ Gradient with respect to *V*: apply the chain rule

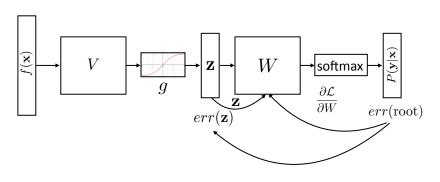
$$\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{Q\mathbf{z}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} = \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{ij}} \underbrace{\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}}}_{V_{i$$

- weights(gold) E[weights(guess)], like LR with weights and features flipped!
- $\text{Or:} \begin{array}{l} err(\text{root}) = e_{i^*} P(\mathbf{y}|\mathbf{x}) & \frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}} = err(\mathbf{z}) = W^\top err(\text{root}) \\ \dim = \mathbf{d} & \text{dim} = \mathbf{d} \end{array}$



Backpropagation: Picture

$$P(\mathbf{y}|\mathbf{x}) = \operatorname{softmax}(Wg(Vf(\mathbf{x})))$$





Computing Gradients: Backpropagation

$$\mathcal{L}(\mathbf{x}, i^*) = W\mathbf{z} \cdot e_{i^*} - \log \sum_{j=1}^m \exp(W\mathbf{z} \cdot e_j) \qquad \mathbf{z} = g(Vf(\mathbf{x}))$$
Activations at hidden layer

▶ Gradient with respect to *V*: apply the chain rule

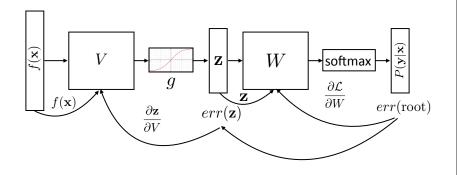
$$\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial V_{ij}} = \frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{V_{ij}} \qquad \frac{\partial \mathbf{z}}{V_{ij}} = \frac{\partial g(\mathbf{a})}{\partial \mathbf{a}} \frac{\partial \mathbf{a}}{\partial V_{ij}} \qquad \mathbf{a} = V f(\mathbf{x})$$

- ▶ First term: gradient of nonlinear activation function at *a* (depends on current value)
- ▶ Second term: gradient of linear function
- ▶ Straightforward computation once we have *err*(**z**)



Backpropagation: Picture

$$P(\mathbf{y}|\mathbf{x}) = \operatorname{softmax}(Wg(Vf(\mathbf{x})))$$





Backpropagation

$$P(\mathbf{y}|\mathbf{x}) = \operatorname{softmax}(Wg(Vf(\mathbf{x})))$$

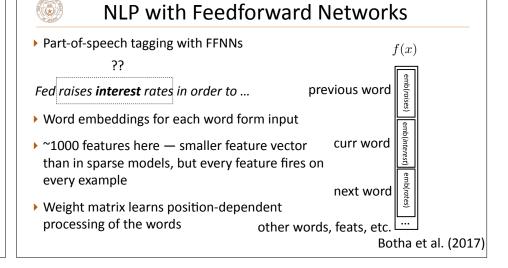
- Step 1: compute $err(root) = e_{i^*} P(\mathbf{y}|\mathbf{x})$ (vector)
- ▶ Step 2: compute derivatives of W using err(root) (matrix)
- ▶ Step 3: compute $\frac{\partial \mathcal{L}(\mathbf{x}, i^*)}{\partial \mathbf{z}} = err(\mathbf{z}) = W^{\top}err(\text{root})$ (vector)
- ▶ Step 4: compute derivatives of V using err(z) (matrix)
- ▶ Step 5+: continue backpropagation (compute $err(f(\mathbf{x}))$) if necessary...)

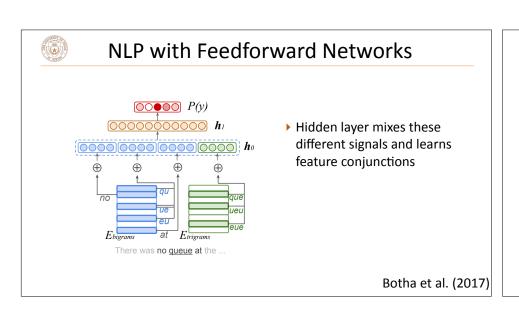


Backpropagation: Takeaways

- ▶ Gradients of output weights W are easy to compute looks like logistic regression with hidden layer z as feature vector
- ► Can compute derivative of loss with respect to **z** to form an "error signal" for backpropagation
- ▶ Easy to update parameters based on "error signal" from next layer, keep pushing error signal back as backpropagation
- Need to remember the values from the forward computation

Applications







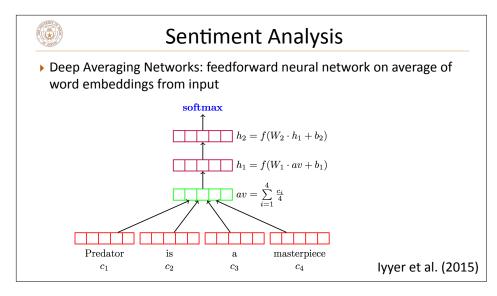
NLP with Feedforward Networks

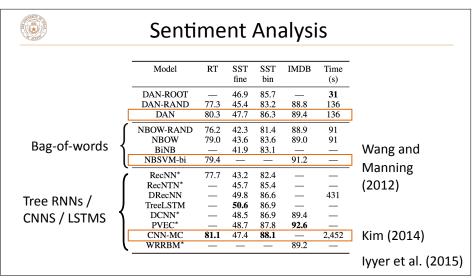
Multilingual tagging results:

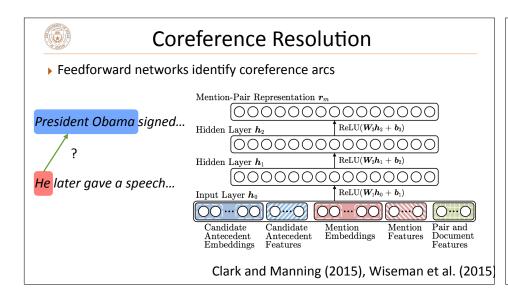
Model	Acc.	Wts.	MB	Ops.
Gillick et al. (2016)	95.06	900k	-	6.63m
Small FF	94.76	241k	0.6	0.27m 0.31m 0.18m
+Clusters	95.56	261k	1.0	0.31m
$rac{1}{2}$ Dim.	95.39	143k	0.7	0.18m

▶ Gillick used LSTMs; this is smaller, faster, and better

Botha et al. (2017)









Next Time

- ▶ How to implement neural networks for NLP
 - ▶ Tensorflow
 - ▶ Practical training techniques
- Word representations / word vectors
- word2vec, GloVe