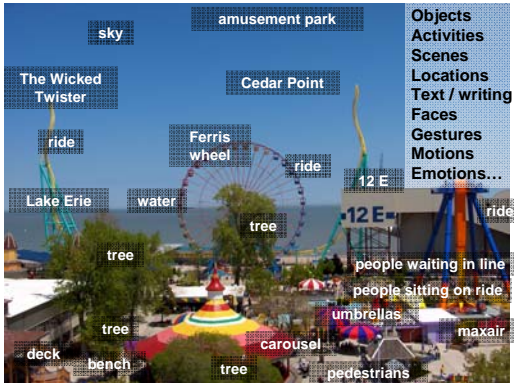
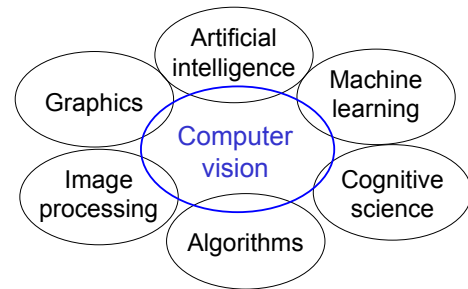


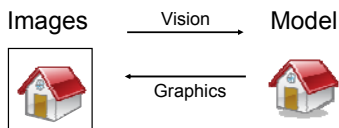
Vision for perception, interpretation



Related disciplines



Vision and graphics



Inverse problems: analysis and synthesis.

Why vision?

- As image sources multiply, so do applications
 - Relieve humans of boring, easy tasks
 - Enhance human abilities: human-computer interaction, visualization
 - Perception for robotics / autonomous agents
 - Organize and give access to visual content

Why vision?

- Images and video are everywhere!



Faces and digital cameras



Camera waits for everyone to smile to take a photo [Canon]



Setting camera focus via face detection

Linking to info with a mobile device



Situated search
Yeh et al., MIT



MSR Lincoln



kooaba

Video-based interfaces



Human joystick
NewsBreaker Live

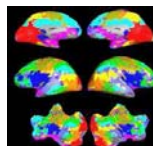


Assistive technology systems
Camera Mouse
Boston College

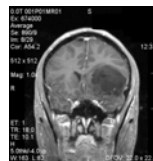
Vision for medical & neuroimages



Image guided surgery
MIT AI Vision Group



fMRI data
Golland et al.



Special visual effects



The Matrix



What Dreams May Come

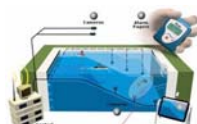


Mocap for *Pirates of the Caribbean*, Industrial Light and Magic
Source: S. Seitz

Safety & security



Navigation,
driver safety



Monitoring pool
(Poseidon)

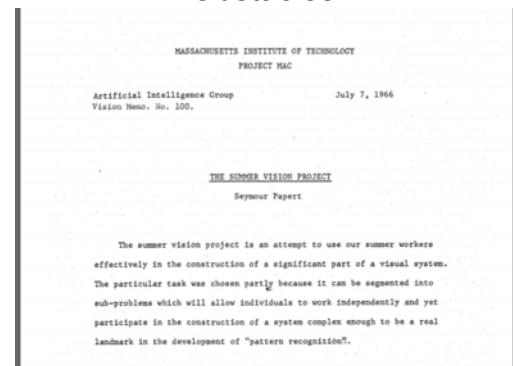


Pedestrian detection
MERL, Viola et al.

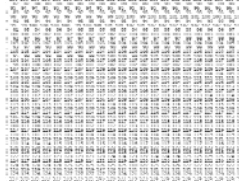


Surveillance

Obstacles?



What the computer gets



Why is vision difficult?

- Ill-posed problem: real world much more complex than what we can measure in images
 - 3D \rightarrow 2D
- Impossible to literally “invert” image formation process

Challenges: many nuisance parameters



Illumination



Object pose



Clutter



Occlusions



Intra-class appearance



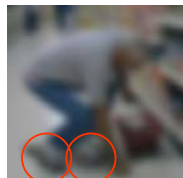
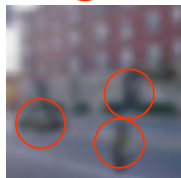
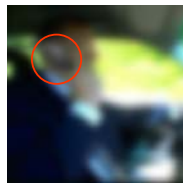
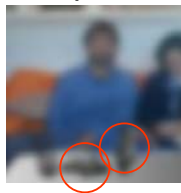
Viewpoint

Challenges: intra-class variation



slide credit: Fei-Fei, Fergus & Torralba

Challenges: importance of context



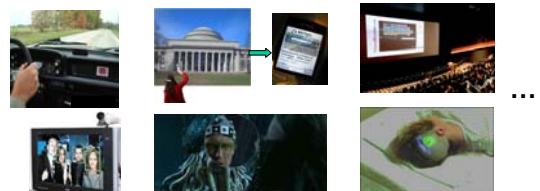
slide credit: Fei-Fei, Fergus & Torralba

Challenges: complexity

- Thousands to millions of pixels in an image
- 3,000-30,000 human recognizable object categories
- 30+ degrees of freedom in the pose of articulated objects (humans)
- Billions of images indexed by Google Image Search
- 18 billion+ prints produced from digital camera images in 2004
- 295.5 million camera phones sold in 2005
- About half of the cerebral cortex in primates is devoted to processing visual information [Felleman and van Essen 1991]

-

1. What functionality should the system have?
2. Intuitively, what are the technical components or sub-problems that must be solved?

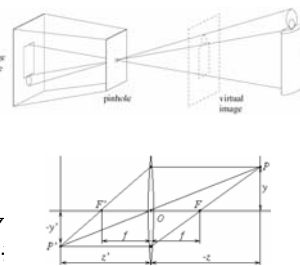
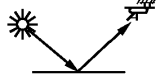
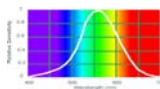


- Upper division undergrad course
- Introduction to primary topics
- Hands-on experience with algorithms
- Views of vision as a research area

- Image formation
- Features
- Grouping & fitting
- Multi-view geometry
- Recognition & learning
- Motion & tracking

Focus is on algorithms, rather than specific systems.

- How does light in 3d world project to form 2d images?



Transforming and describing images; textures, colors, edges

Grouping & fitting

Parallelism

Symmetry

Continuity

Closure

Clustering, segmentation, fitting; what parts belong together?

[fig from Shi et al]

Multiple views

Multi-view geometry,
 matching, invariant
 features, stereo vision

Hartley and Zisserman

Lowe

Fei-Fei Li

Recognition and learning

Recognizing objects and categories, learning techniques

Motion and tracking

Tracking objects, video analysis, low level motion, optical flow

Tomas Szo



Course web page

<http://www.cs.utexas.edu/~grauman/courses/fall2008/main.htm>

Computer Vision
 Fall 2008
 Tues/Thurs 12:30 – 2:00 pm
 Parlin Hall 1 ([PAR.1](#))
 CS 378, Unique # 55770

Instructor: [Prof. Kristen Grauman](#)
 Email: last name @ cs.utexas.edu
 Office hours: Tues/Thurs 2:00-3:00 pm in [CSA.114](#)

TA: Harshdeep Singh
 Email: first name @ gmail.com
 Office hours: TBD

The TA station is in the basement of ENS inside room 31NR.
 Directions to the TA stations are posted right outside the basement elevator, and also outside room 31NR.

[Schedule](#) [Blackboard](#) [Overview](#) [Requirements](#) [Links](#) [Syllabus outline](#)

Announcements

Pset 0 is due Thurs Sept 4: getting to know Matlab.

Schedule

Computer Vision Fall 2008					
Please note - specifics of this schedule are subject to change.					
F&P = Forsyth & Ponce S&S = Shapiro & Stockman T&V = Trucco & Verri					
Dates	Topic	Reading and references	Of related interest	Lectures	Assignments
8/28	Image formation	F&P Chapter 1	Who Invented Ray Tracing? By G. Hoffmann		Pset 0 Pset 0 images
9/2	Matlab tutorial	Matlab intro	Building a camera with a Ching's can		
9/4	Color	F&P Chapter 6 The foundations of color measurement and color perception by Brian A. Wandell (optional)			Pset 0 due 9/4
9/9 9/11 9/16	Features and texture	F&P Chapters 7, 9 T&V Chapter 4 S&S Chapter 3 S&S Chapter 5			
9/18 9/23 9/25	Grouping and fitting				Pset 1 due 9/18

Textbooks

- Forsyth & Ponce is recommended book
- This and others are on reserve at PCL
- For some topics, we'll post small sections from external sources on Blackboard.

Requirements / Grading

- Problem sets (55%)
- Midterm exam (15%)
- Final exam (20%)
- Class participation, including attendance (10%)

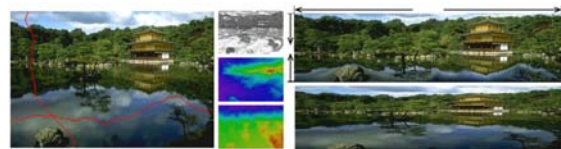
Problem sets

- Some short answer concept questions
- Programming problem
 - Implementation
 - Explanation, results
- Code in Matlab – available on CS Unix machines

Preview of problem sets

- Pset 0: Matlab warmup

Preview of problem sets



Pset 1: Content-aware image resizing

Shai Avidan, Ariel Shamir
[Seam Carving for Content-Aware Image Resizing](#)
 ACM Transactions on Graphics, Volume 26, Number 3,
 SIGGRAPH 2007

Preview of problem sets



Pset 2: Image mosaics

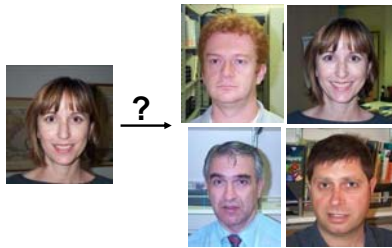
Image from Fei-Fei Li

Preview of problem sets



Pset 3: Video search

Preview of problem sets



Pset 4: Face recognition

Preview of problem sets



Pset 5: Tracking

Collaboration policy

All responses and code must be written individually.

Students submitting problem sets / code found to be identical or substantially similar (due to inappropriate collaboration) risk failing the course.

CSA

Computer Science Annex - CSA



My office : CSA 114

Engineering Area



TAY

T. U. Taylor Hall - TAY



Harshdeep's office
hours in TAY CS Lab,
basement

East Mall Area



Note: each building is a hot link to its page
Also see:

[Area Overview](#)
[Area Accessibility](#)

Due dates

- Assignments in by 11:59 PM on due date
 - Follow submission instructions given in assignment regarding hardcopy/electronic
- Lose half of possible remaining credit each day late
- Three free late days, total
 - Notify TA **by due date** if using

Sharing results (optional)

- We'll review results for some problems afterwards
- Share your results in class for extra credit
 - Email beforehand
 - Brief description (≈2 minutes), visual
 - Up to 6 points extra credit on midterm

Current events (optional)

- Any vision-related piece of news; may revolve around policy, editorial, technology, new product, ...
- Brief overview to the class (≈5 minutes)
- Must be current
- Email the relevant links or information beforehand
- Extra credit: up to 6 points on midterm score

Miscellaneous

- Check class website regularly
- Make sure you are on class mailing list
- No laptops in class please
- Feedback welcome and useful

Next

Problem set 0 due Sept 4 (next Thursday)

- Matlab warmup: download from class page

Tuesday: in-class tutorial on Matlab

Thursday: Image formation

- Read F&P Chapter 1,6