

### **Motivations**

- Object classification methods generally require large number of training examples.
- Constructing training set is very time-consuming task, and it costs a lot. (time == money)
- Do we need many training examples for ALL classes? There exist a lot of classes in real world, and it is not possible to collect training images for all of them.
- Humans can distinguish >>10k classes

### **Overview**

- Develop a feature-based object classification model that can learn a novel class from a single training example.
- Experience from already learned classes facilitate the learning and constrain overfitting.
- Features for a novel class are obtained by adapting the features from similar familiar (already learned) classes.
- Cross-generalized model outperforms the stand-alone algorithm on a large dataset with 107 classes of objects.

# Introduction

- Hypothesis : A feature is likely to be useful for a novel class (e.g. dogs) if a similar feature proved effective for a similar class (e.g. cows).
- Assume a sufficient number of training examples are available for a set of object classes (say, cows, horses, and flowers) to extract suitable discriminating features.
- These classes are referred to as "known" or "familiar" classes.
- The objective is to learn a new class, say dog, from a single example. Challenge :
   Proposed solution : Obtain suitable features (restrict overfitting). Adapt the features from similar familiar class



# Related Works

- Data Manufacturing

   Pros: Can significantly improve classification when generative model is available.

  Cons : Constructing generative models which reflect natural variations of visual objects is very difficult.
- Perona et al. proposed a parametric class model and obtains a prior for parameters for a novel class based on the examples of familiar class. Pros: Avoid inaccurate parameter estimate and increases performance compared to no prior.
  - Cons : A single prior is used for all novel classes, hence biases novel class parameters towards frequently appearing familiar class.
- Freeman *et al.* proposed feature sharing between classes.
  Pros Reduces the total number of representative features.
  Cons Produces generic features (like edges) and requires simultaneous training of all classes.

Proposed algorithm obtains class-specific features and novel class features are adapted only from similar familiar class features.

## Using Image Fragments as Features

#### Feature Extraction

- Extract sub-images of multiple sizes from multiple locations
- With each fragment, its location in the original image is stored and used to determine relative locations of different fragments
- Features are selected in a greedy manner that maximize the mutual information between the feature and the class it represents.

### For Classification

- Set of fragments is searched for in the image, using the absolute value of normalized cross-correlation.
- For each fragment F, the relevant locations in the image are determined by the location of F relative to the common reference frame.
- Image patches at the relevant locations are compared with F, and the location with the highest correlation is selected. If this highest correlation exceeds a pre-determined threshold  $\theta_r$ , the fragment is considered present, or active in the image

[2] E.Bart, E.Byvatov, and S. Ullman. "View-invariant recognition using corresponding object fragments." In ECCV, pages 113-127, 2002. [17] S.Ullman, M. Vidal-Naquet, and E.Sali. "Visual features of intermediate complexity and their use in classification." Nature Neuroscience 10. [20] S.Ullman, M. Vidal-Naquet, and E.Sali. "Visual features of intermediate complexity and their use in classification." Nature Neuroscience [20] S.Ullman, M. Vidal-Naquet, and E.Sali. "Visual features of intermediate complexity and their use in classification." Nature Neuroscience



- Let  $f_i = 1$  or 0 indicate whether  $F_i$  exist or not in the test image.
- $\hfill \hfill \hfill$

$$\sum_{i} w_i(f_i) > T \quad \text{where} \quad w_i(d) = \log \frac{P(f_i = d \mid C)}{P(f_i = d \mid \overline{C})}, \quad d \in \{0, 1\}$$

- $P(f_i = d \,|\, C)$  represents the probability that fragment  $F_i$  is present in images belonging to class k.
- It is needed to invoke a new class if an image under testing does not get classified into one of the familiar classes.
- Should be able to estimate reliable features from only one example of the new class.

### **Cross-generalization**

A feature F is likely to be useful for class C if a similar feature F' proved field to a similar class C'.

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- For an example image  $E_i$  each familiar fragment  $F_i^k\,$  is searched within E using Normalized cross-correlation.
- The location is selected with maximum cross-correlation S<sup>k</sup><sub>i</sub> and a fragment F<sup>new</sup> is extracted from the same location of image E.
- The process continues to choose J new fragments from E that corresponds to J highest cross-correlation among all familiar fragments  $F_i^k$  (J = 25)
- The original fragments  $F_j^{\rm new}$  extracted from E and their relative locations are used for the design of the new classifier.
- Note that features are chosen independently without incorporating any spatial correlation between them, although familiar classes offer this information.

# Classification of Novel Class

- Each novel fragment  $F_j^{\rm new}$  was nominated by some fragment  $F_i^k$  to which it was similar.
- Since F<sub>j</sub><sup>new</sup> and F<sub>i</sub><sup>k</sup> belong to different classes one needs to prevent F<sub>j</sub><sup>new</sup> being detected in images that contain F<sub>i</sub><sup>k</sup> so a threshold higher that S<sub>i</sub><sup>k</sup> is required.
  The authors set the threshold to 1.1S<sub>i</sub><sup>k</sup>.
- A new classifier that uses the fragments F<sub>i</sub><sup>new</sup> has the form

#### $\sum_{i} w_{i}^{new}(f_{i}^{new}) > T^{new} \quad f_{i}^{new} \in \{0,1\}$

$$\sum_{i} w_{i}^{k}(f_{i}^{k}) > T^{k} \quad \text{where} \quad w_{i}^{k}(d) = \log \frac{p(f_{i}^{k} = d \mid c = k)}{p(f_{i}^{k} = d \mid c = \overline{k})}, \quad d \in \{0, 1\}$$

The weights cannot be empirically estimates as shown before (one data point to court). The authors suggest

 $w_j^{new}(0) = w_i^k(0) \text{ and } w_j^{new}(1) = w_i^k(1)$ 

• Alternative :  $w_j^{new}(0) = 0 \text{ and } w_j^{new}(1) = 1$  offers poor performance!

# Results (1)

- Classification results are compared against a stand-alone algorithm (SA). SA uses two examples for each class and two examples from a non-class for training.
- The tests are performed on a set of 107 object classes, with each class having 40 to 100 examples, along with a set of 400 non-class images.
- Leave-one-out scheme was used, where performance on each class as a novel class was tested with training done on the rest 106 classes. Test images consist of the novel class and a set of non-class images.





- A classification algorithm is proposed that is able to learn a novel class from a single example.
- New features are adapted from the similar features of familiar classes.
- The algorithm tries to mimic human cognition system. Will not work for a completely new class (having nothing common with familiar classes).
- No negative example is required to learn the new classifier (although negative examples are used to learn the familiar class discrimination).
- No spatial correlation is used to obtain features for the novel class. Scope for future research.



