#### Multiscale Conditional Random Fields for Image Labeling

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#### Contributions

- 1) Generalization of conditional random fields (CRF) to multiscale conditional random fields (mCRF)
- Learning features of the random field at multiple scales

#### Motivation

- 1) Segment and recognize each part by class Useful for database queries
- 2) Retain contextual information
  - a) Local regions have ambiguity; using neighboring regions can aid in accurate labeling
  - b) Limited geometric relationships
     Fish in water; airplanes in sky
     Sky at top of image; water at bottom

#### Differences from Earlier Methods

- 1) Discriminative, not generative
- 2) Uses multiple scales
  - a) Locality is a major problem for Markov random fields
  - b) Limitedly solved by Hierarchical Markov random fields
- 3) Does not require joint probabilities

Conditional Random Fields and Restricted Boltzmann Machines

#### Conditional Random Field

- 1) Probabilistic framework for labeling, parsing, or segmenting structured data
- Uses a conditional distribution over label sequences given an observation sequence, not the joint distribution over label and observation sequences.



#### **Restricted Boltzmann Machine**

- Type of simulated annealing stochastic recurrent neural network
   Invented by G. Hinton and T. Sejnowski
- 2) Does not allow connections between hidden nodes
- 3) Can be organized into multiple layers Example: Handwritten digit recognition





#### Local Features

- 1) Classify site using a statistical classifier
- 2) Limited performance due to noise, class overlap, etc.
- 3) This looks much like the standard conditional random field diagram

#### **Regional Features**

- 1) Represent geometric relationships between objects
  - Corners
  - Edges
  - T-Junctions
- Separate hidden variables; shared conditional probability table with other regions



#### **Global Features**

- 1) Either whole image or large local patches
- 2) Like region, specifies a joint distribution over the labels given the hidden variables
- 3) Specifies a multinomial distribution over each label node by their parameters







#### **Combining Components**

- 1) Probability distributions are combined multiplicatively
- Many unconfident, but similar predictions, can yield a confident prediction
- Should behave like a cascade; components should focus on aspects where previous components fail



#### Image Labeling

- 1) Given a new image, what is the optimal label configuration?
- 2) Paper uses maximal posterior marginals Minimizes the expected number of mislabeled sites
- 3) Alternative: maximum a posteriori Difficult to compute for high dimensional and discrete domains



#### Data Sets

- 1) Corel images of African and Arctic Wildlife 100 images (60 training / 40 test) Image size: 180 x 120 pixels
- 2) Sowerby Image of British Aerospace
  Color scenes of rural & suburban roads
  104 images (60 training / 44 test)
  Image size: 96 x 64 pixels

#### Image Statistics (X<sub>i</sub>)

30 image statistics per pixel

1) Color: CIE colorspace

#### 2) Edge & Texture

- a) Difference-of-Gaussian (3 scales)
- b) Quadrature pairs of even-symmetric and odd-symmetric filters (3 scales; 4 orientations)

Orientations: 0,  $\pi/4$ ,  $\pi/2$ ,  $3\pi/4$ 

#### Performance Evaluation

 Compare against generative method (Markov random field)





Classification Rates							
Best Published						90.7	
mCRF					8	89.5 0.0	
MRF				66	2	81.8	
MLP				60	<mark>.9</mark>	82.4	
(	0 10	20 30	40 Corel	50 60	70 99	80 90	100

Corel Confusion Matrix								
	Rhino/ Hippo	Polar Bear	Water	Snow	Vegetation	Ground	Sky	
Rhino/ Hippo	9.27	0.14	0.53	0.01	1.01	1.00	0.00	
Polar Bear	0.08	8.06	0.01	0.52	0.12	0.63	0.00	
Water	0.33	0.00	12.87	0.00	0.42	0.76	0.05	
Snow	0.00	0.82	0.00	12.83	0.23	0.09	0.04	
Vegetation	0.95	0.55	0.09	3.18	15.06	2.99	0.06	
Ground	1.13	1.18	1.11	0.26	1.56	21.19	0.00	
Sky	0.00	0.00	0.00	0.00	0.19	0.01	0.66	

Sowerby Confusion Matrix							
	Sky	Vegetation	Road Markings	Road Surface	Building	Street Objects	Cars
Sky	12.01	0.53	0.00	0.01	0.03	0.00	0.01
Vegetation	0.83	33.39	0.01	1.41	2.71	0.03	0.09
Road Markings	0.00	0.00	0.08	0.10	0.00	0.00	0.00
Road Surface	0.01	0.94	0.02	40.33	0.10	0.01	0.05
Building	0.06	2.60	0.02	0.30	3.05	0.01	0.05
Street Objects	0.02	0.25	0.00	0.03	0.12	0.02	0.01
Cars	0.02	0.27	0.00	0.09	0.24	0.00	0.14



#### Select Rhino



#### Select Rhino











# Select Street Scene

#### Select Street Scene





#### Select Street Scene



#### Select Street Scene Multiscale Conditional Original Random Field

Hand Labeled

### Confidence

Multiscale Conditional Random Field

## Select Street Scene

