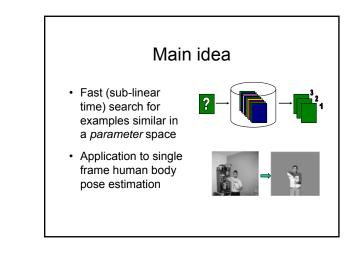
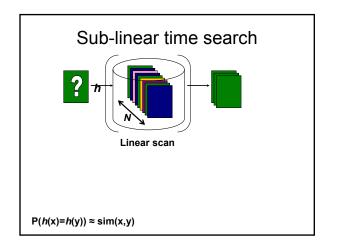
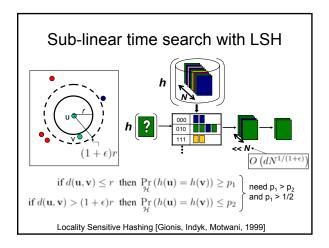
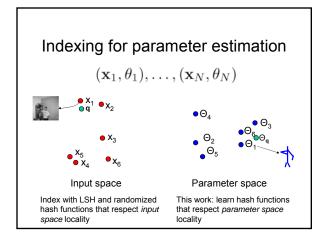


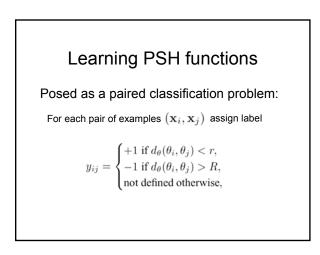
G. Shakhnarovich, P. Viola, T. Darrell

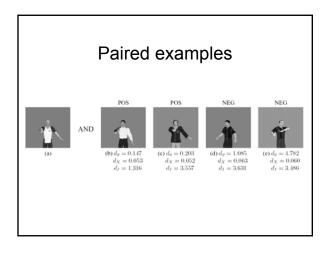


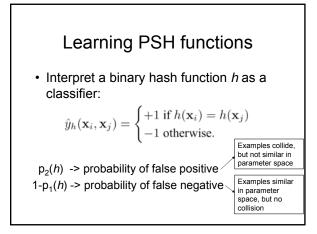


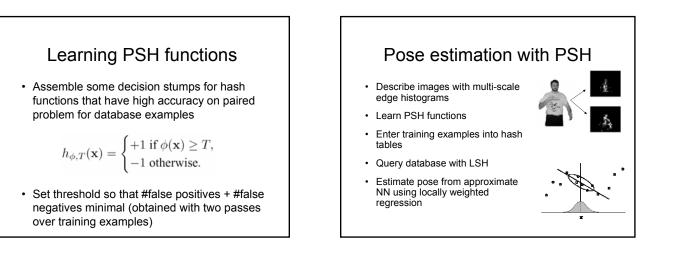


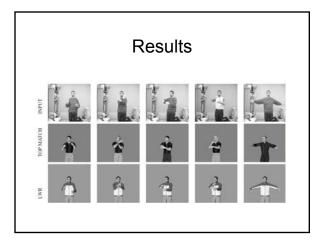


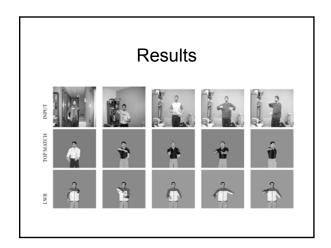


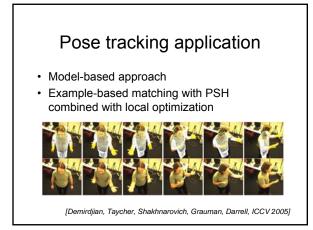


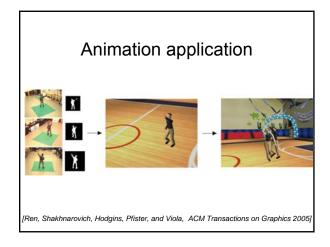












Strengths and contributions

- General method that allows fast indexing more attuned to parameter space
- Practical, scalable system for examplebased learning
- Single-frame 3D pose estimation
- · Interesting use of realistic synthetic data

Assumptions / Limitations

- System requires good body detection and localization
- Training examples must be representative of problem space
- Need good guess for radius parameter

