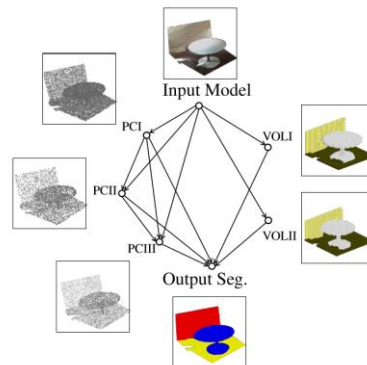
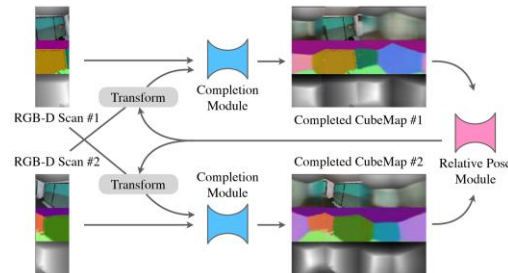
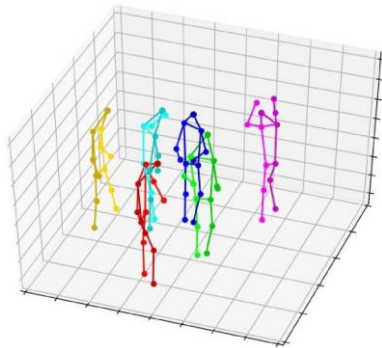
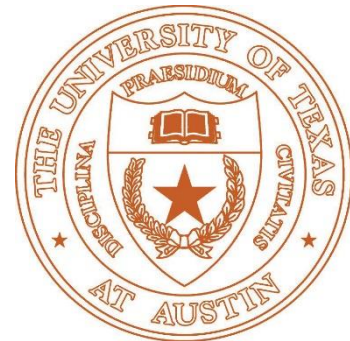


# CS376 Computer Vision

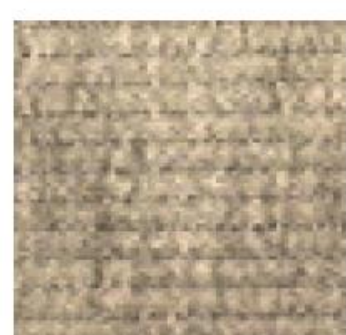
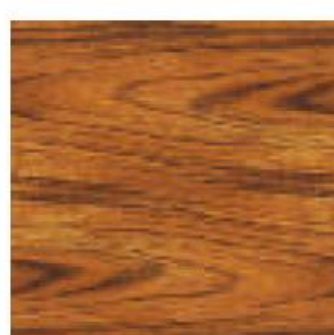
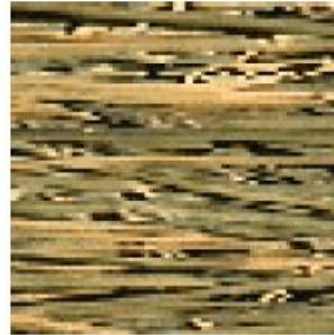
## Lecture 5: Texture



Qixing Huang  
Feb. 6<sup>th</sup> 2019

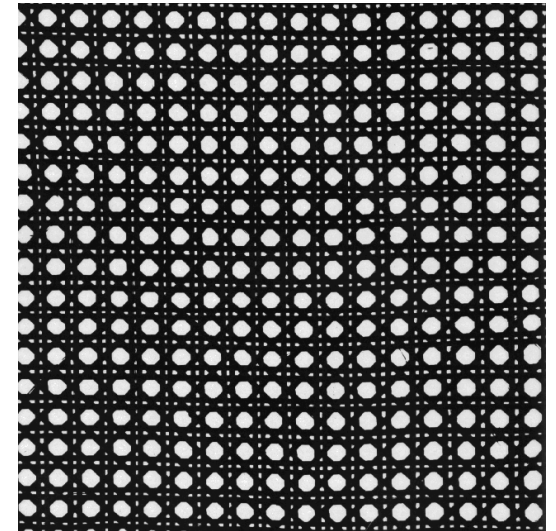
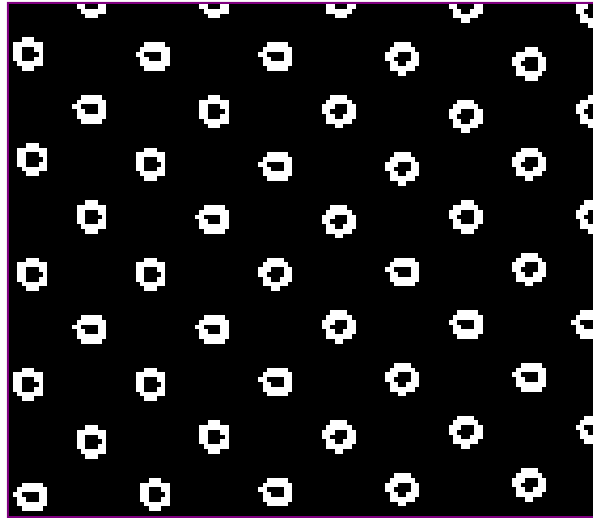
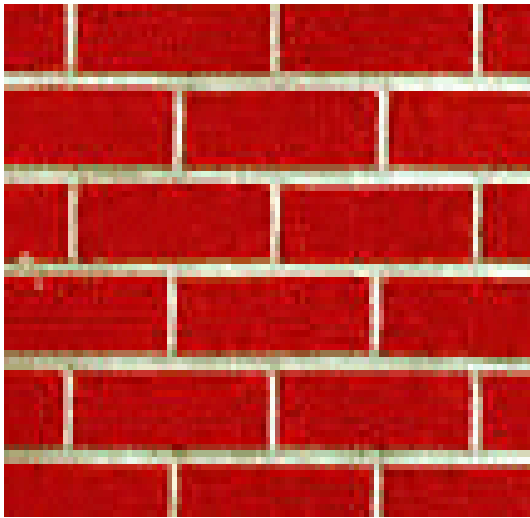


# Today: Texture

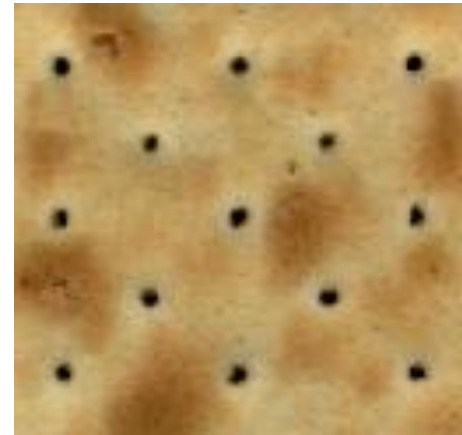
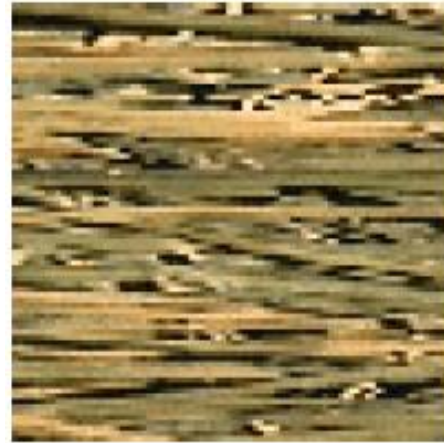


What defines a texture?

# Includes: more regular patterns



# Includes: more random patterns





# Scale and texture

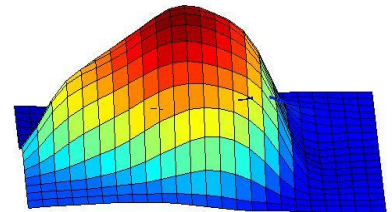
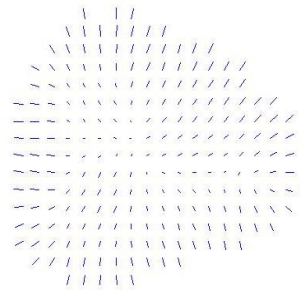
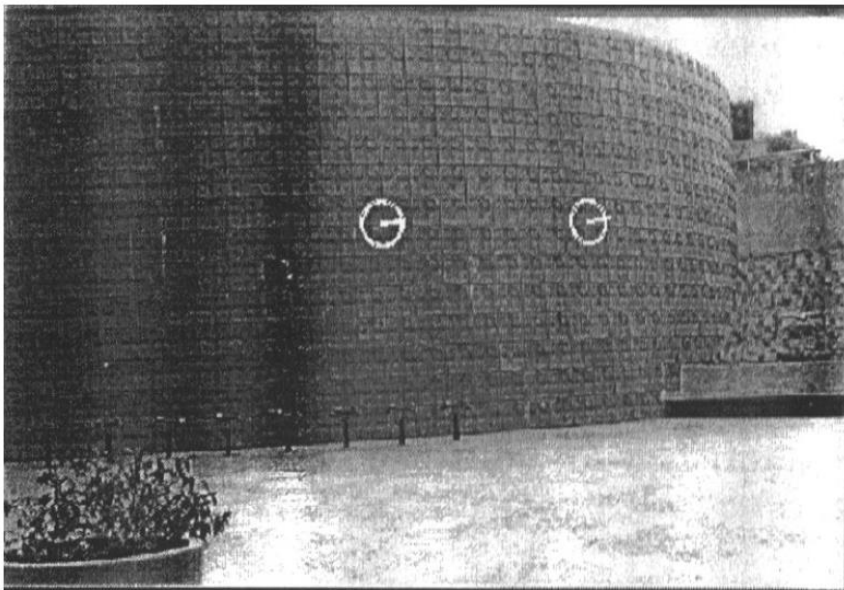


# Texture-related tasks

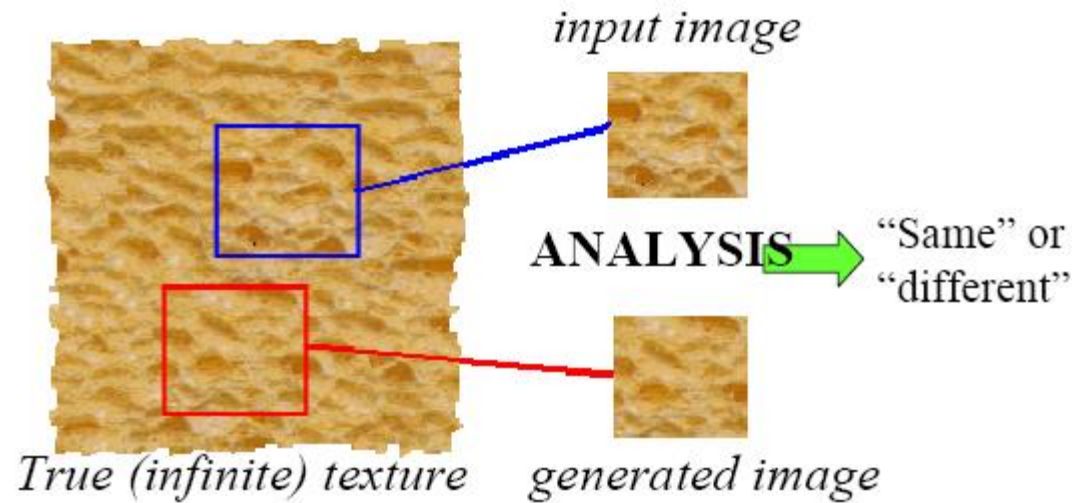
- **Shape from texture**
  - Estimate surface orientation or shape from image texture

# Shape from texture

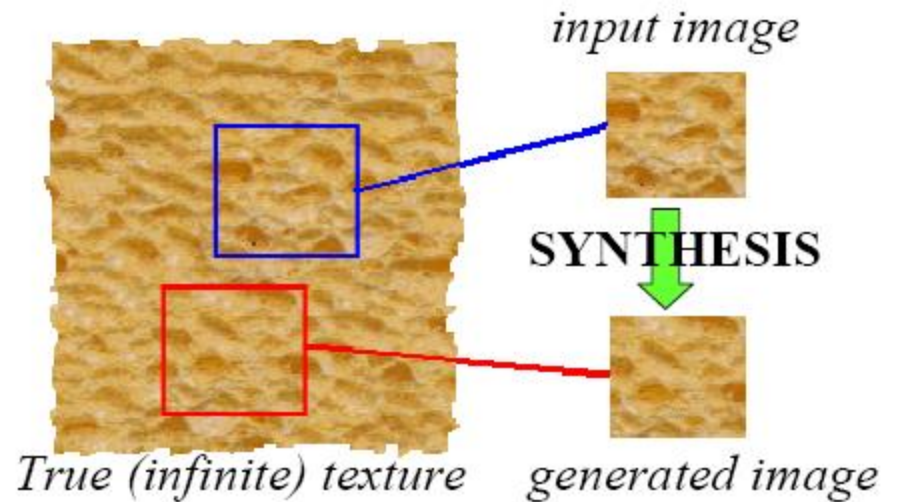
- Use deformation of texture from point to point to estimate surface shape



# Analysis vs. Synthesis



Why analyze texture?





# Texture-related tasks

- **Shape from texture**
  - Estimate surface orientation or shape from image texture
- **Segmentation/classification** from texture cues
  - Analyze, represent texture
  - Group image regions with consistent texture
- **Synthesis**
  - Generate new texture patches/images given some examples



Slide credit: Kristen Grauman



What kind of response will we get with an edge detector for these images?





...and for this image?

# Why analyze texture?

Importance to perception:

- Often indicative of a material's properties
- Can be important appearance cue, especially if shape is similar across objects
- Aim to distinguish between shape, boundaries, and texture

Technically:

- Representation-wise, we want a feature one step above “building blocks” of filters, edges.

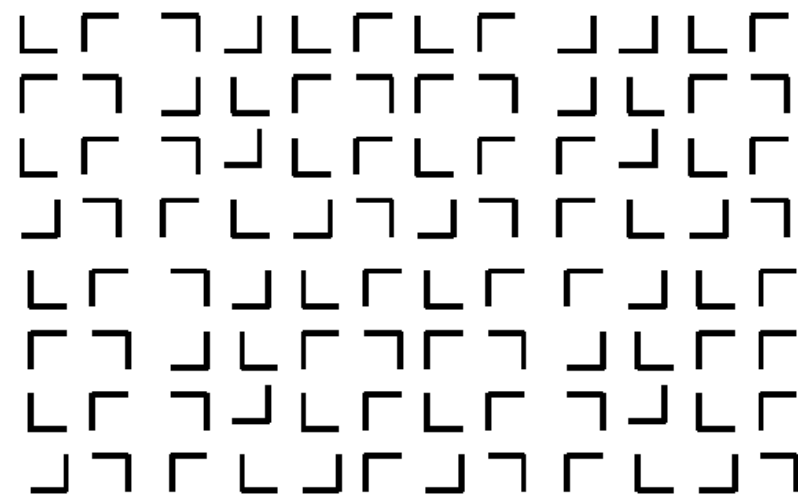


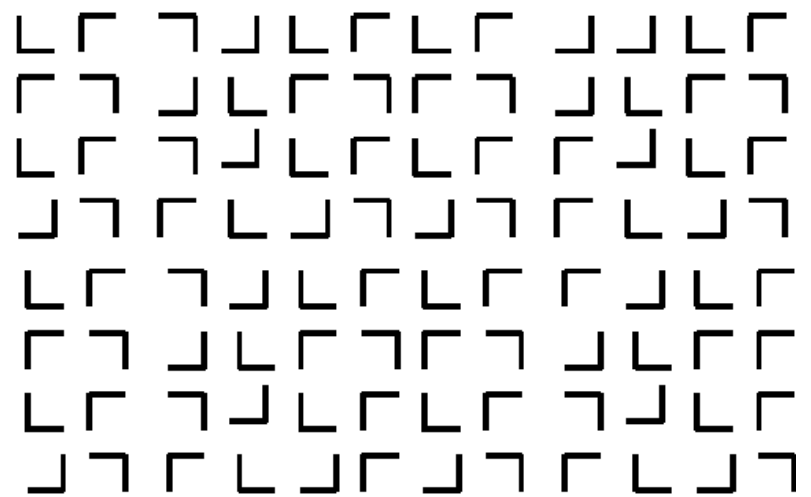
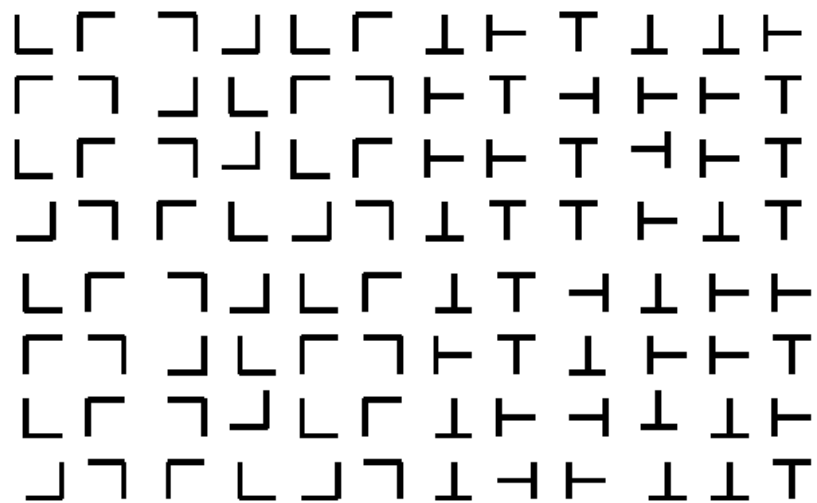
# Psychophysics of texture

- Some textures distinguishable with *preattentive* perception—without scrutiny, eye movements [Julesz 1975]

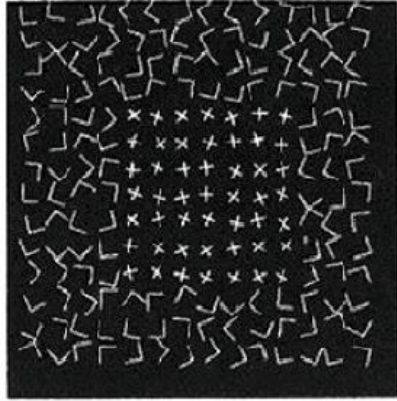
Same or different?

L	┐	┌	└	L	┐	└	┌	T	└	└	┌
┐	┌	└	└	┐	┌	┌	T	└	┌	┌	T
L	┐	┌	└	L	┐	┌	T	T	└	┌	T
└	┌	┐	└	└	┌	└	T	T	┌	└	T
L	┐	┌	└	L	┐	└	T	└	└	┌	┌
┐	┌	└	└	┐	┌	┌	T	└	┌	┌	T
L	┐	┌	└	L	┐	└	┌	└	└	└	┌
└	┌	┐	└	└	┌	└	└	┌	└	└	T





# Capturing the local patterns with image measurements



[Bergen &  
Adelson,  
*Nature* 1988]

Scale of  
patterns  
influences  
discriminability

Size-tuned  
linear filters



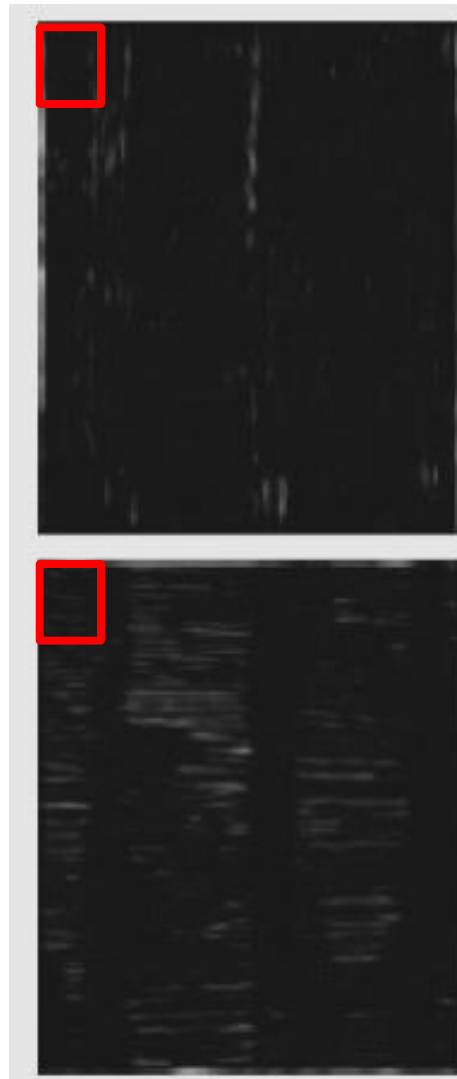
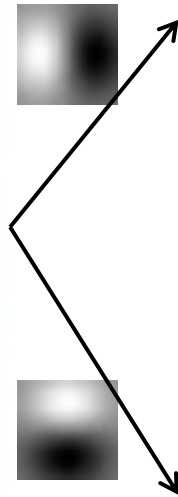
# Texture representation

- Textures are made up of repeated local patterns, so:
  - Find the patterns
    - Use filters that look like patterns (spots, bars, raw patches...)
    - Consider magnitude of response
  - Describe their statistics within each local window, e.g.,
    - Mean, standard deviation
    - Histogram
    - Histogram of “prototypical” feature occurrences

# Texture representation: example



**original image**



**derivative filter**  
**responses, squared**

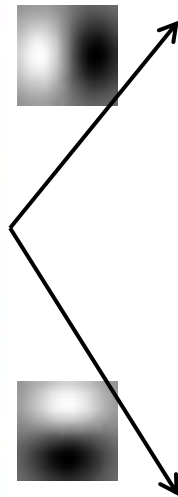
	<u>mean</u> <u>d/dx</u> <u>value</u>	<u>mean</u> <u>d/dy</u> <u>value</u>
Win. #1	4	10

## statistics to summarize patterns in small windows

# Texture representation: example



**original image**



**derivative filter**  
**responses, squared**

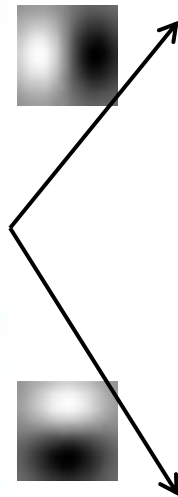
	<u>mean</u> <u>d/dx</u> <u>value</u>	<u>mean</u> <u>d/dy</u> <u>value</u>
Win. #1	4	10
Win.#2	18	7
	⋮	

## statistics to summarize patterns in small windows

# Texture representation: example



**original image**

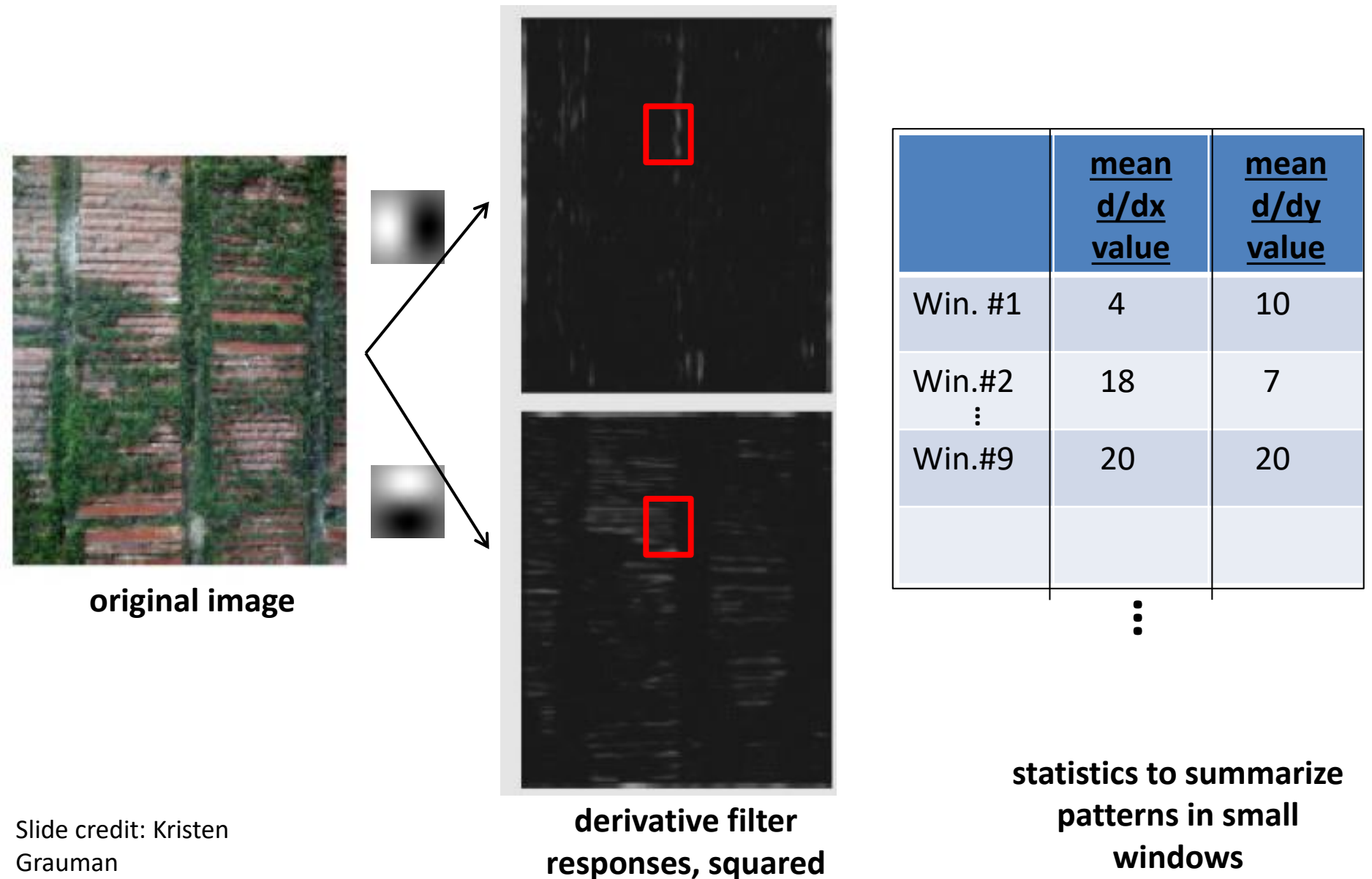


**derivative filter**  
**responses, squared**

	<u>mean</u> <u>d/dx</u> <u>value</u>	<u>mean</u> <u>d/dy</u> <u>value</u>
Win. #1	4	10
Win.#2	18	7
	⋮	

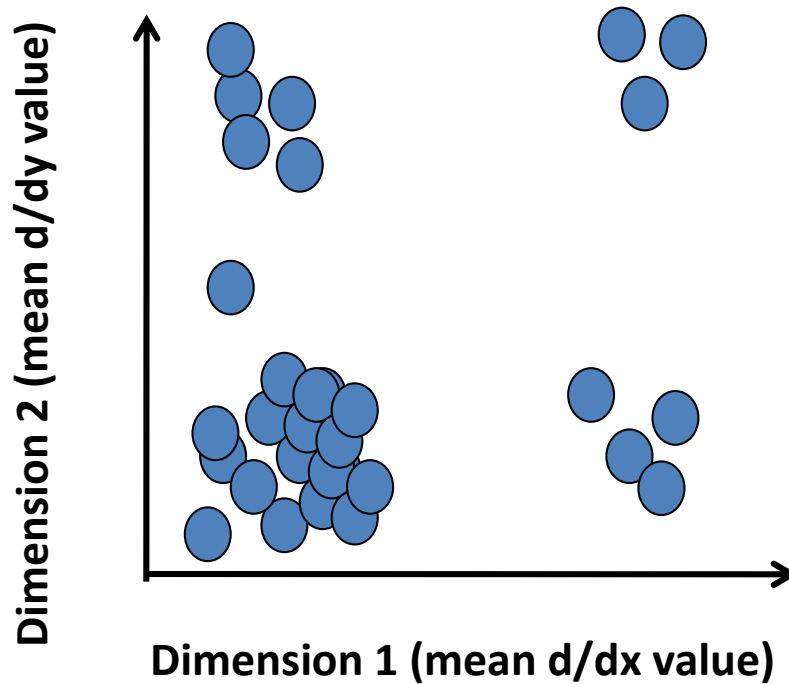
## statistics to summarize patterns in small windows

# Texture representation: example





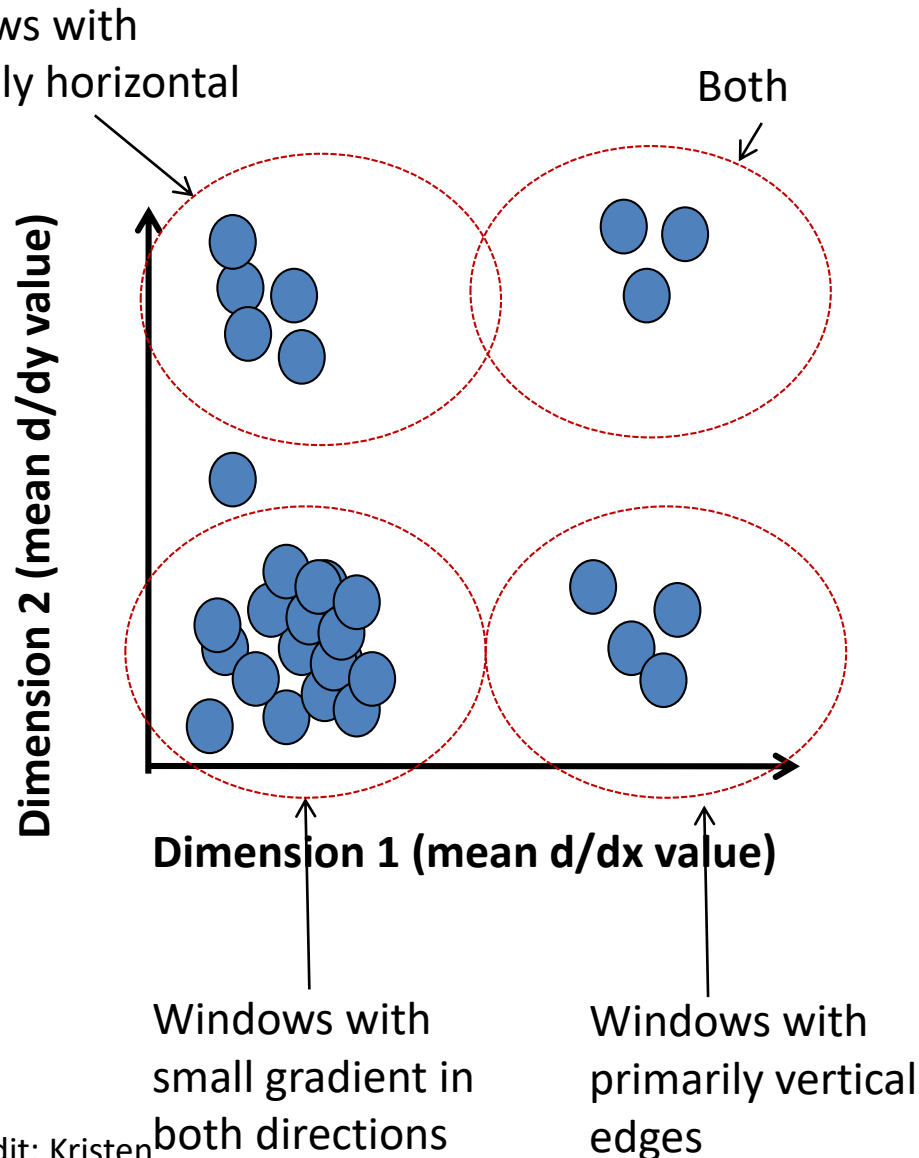
# Texture representation: example



	<u>mean d/dx value</u>	<u>mean d/dy value</u>
Win. #1	4	10
Win.#2	18	7
⋮		
Win.#9	20	20
	⋮	

statistics to summarize  
patterns in small  
windows

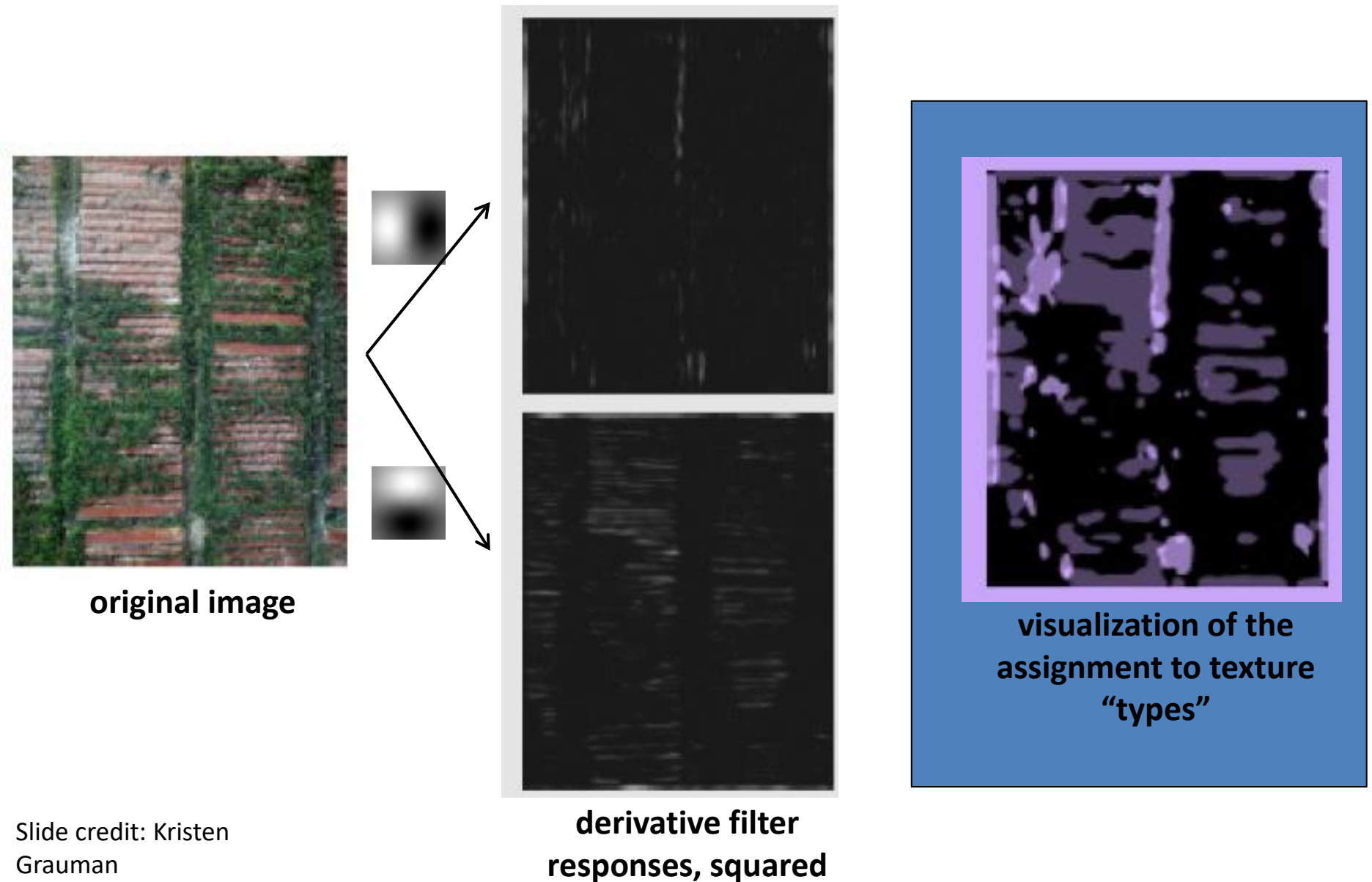
# Texture representation: example



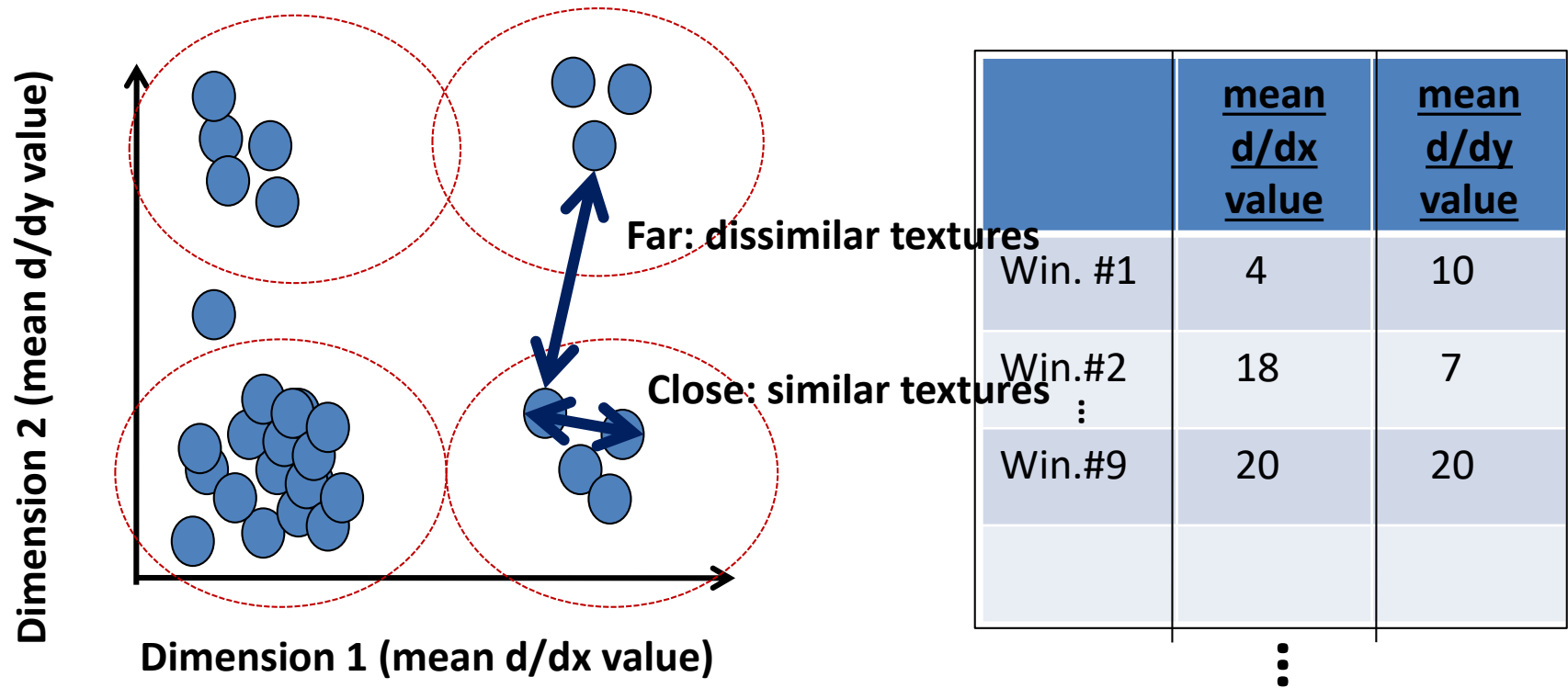
	<u>mean</u> <u><math>d/dx</math></u> <u>value</u>	<u>mean</u> <u><math>d/dy</math></u> <u>value</u>
Win. #1	4	10
Win.#2	18	7
⋮		
Win.#9	20	20
	⋮	

statistics to summarize  
patterns in small  
windows

# Texture representation: example

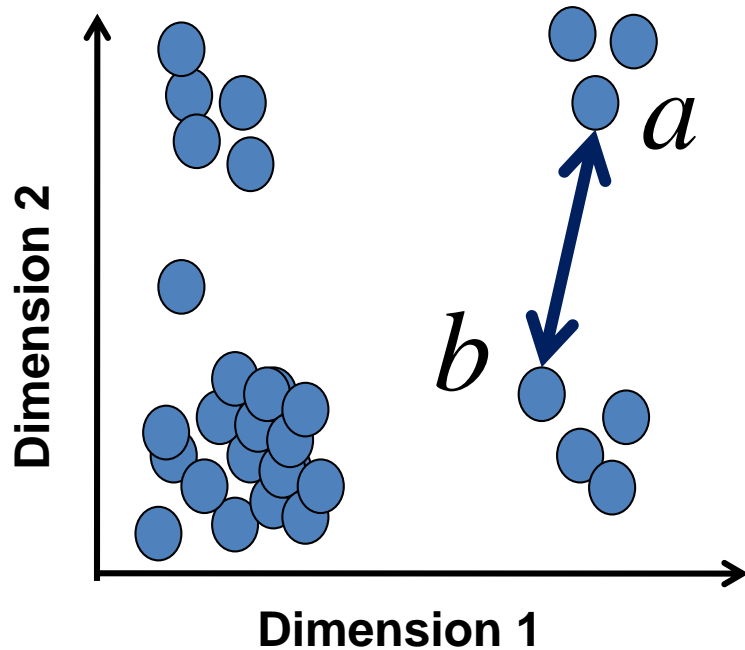


# Texture representation: example



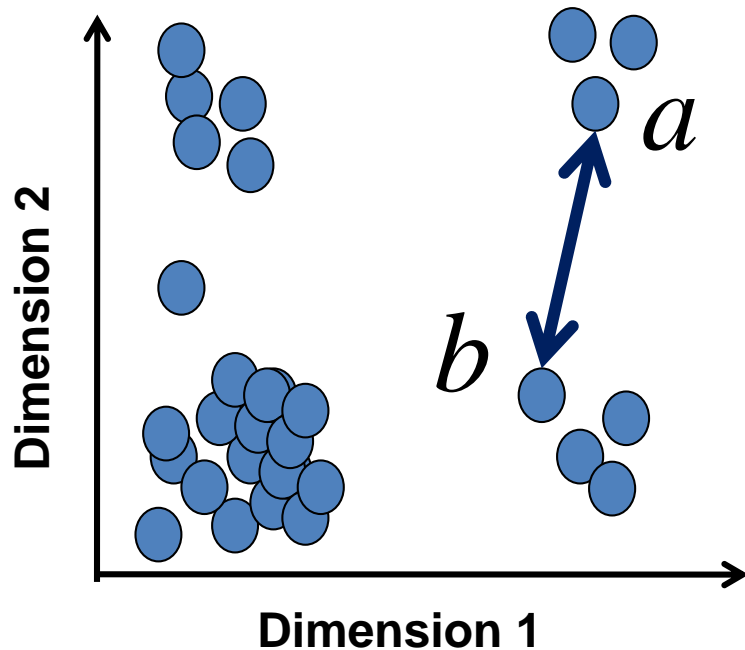
statistics to summarize  
patterns in small  
windows

# Texture representation: example

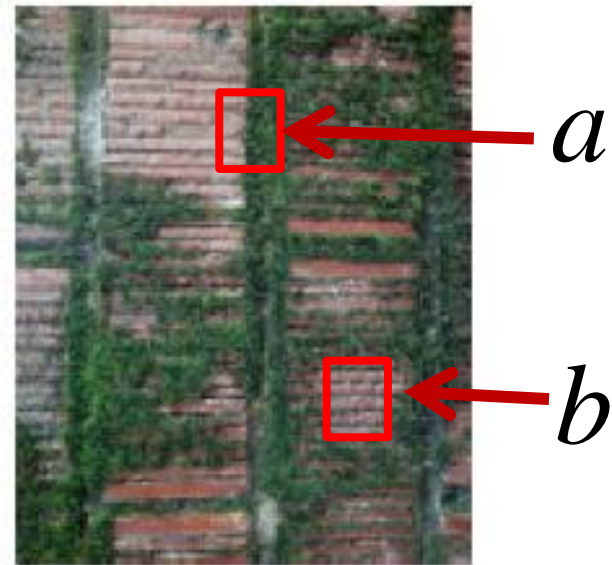


$$D(a,b) = \sqrt{(a_1 - b_1)^2 + (a_2 - b_2)^2}$$

# Texture representation: example

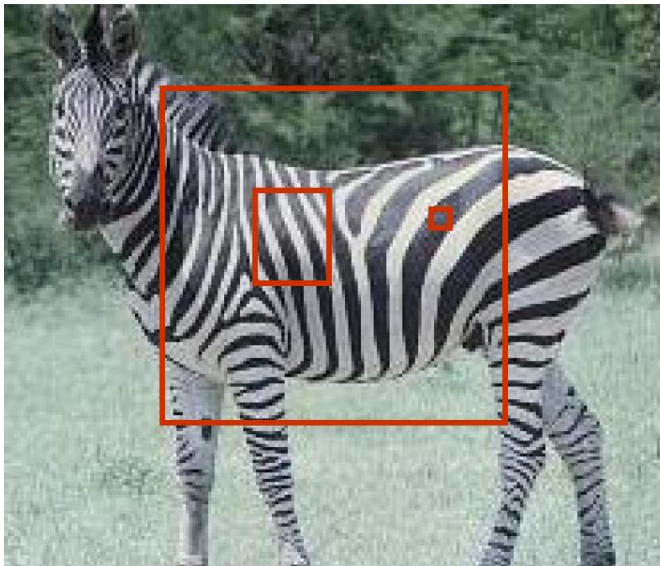


Distance reveals how dissimilar texture from window  $a$  is from texture in window  $b$ .



# Texture representation: window scale

- We're assuming we know the relevant window size for which we collect these statistics.



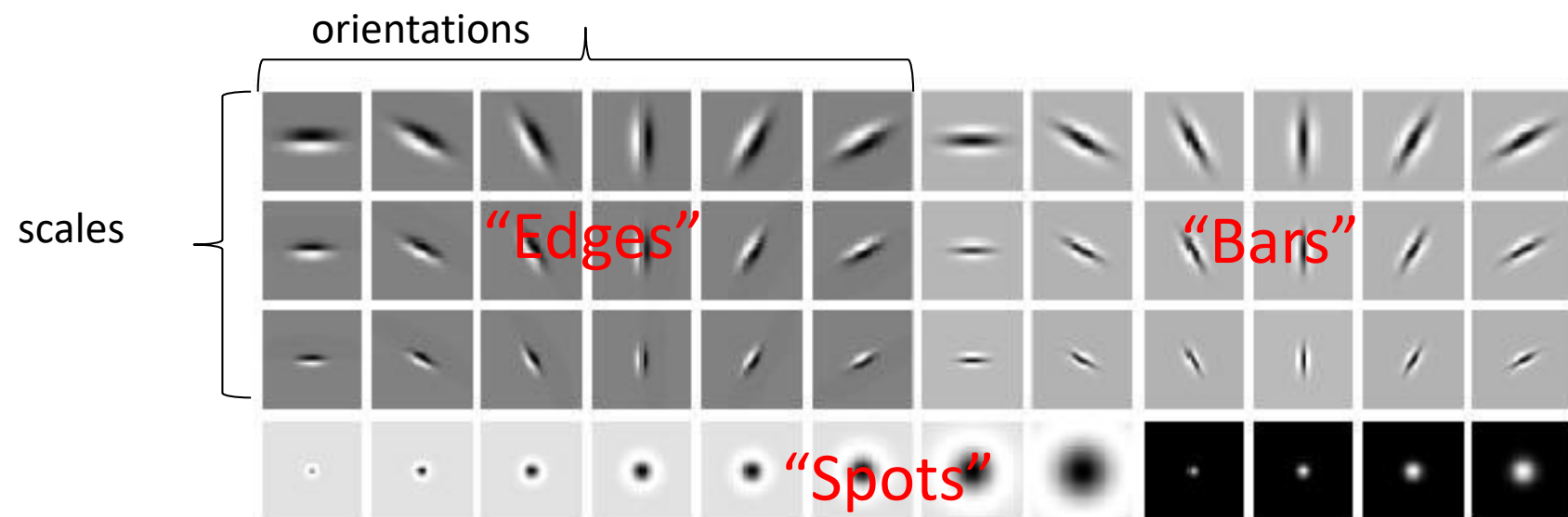
Possible to perform **scale selection** by looking for window scale where texture description not changing.



# Filter banks

- Our previous example used two filters, and resulted in a 2-dimensional feature vector to describe texture in a window.
  - $x$  and  $y$  derivatives revealed something about local structure.
- We can generalize to apply a collection of multiple ( $d$ ) filters: a “filter bank”
- Then our feature vectors will be  $d$ -dimensional.
  - still can think of nearness, farness in feature space

# Filter banks



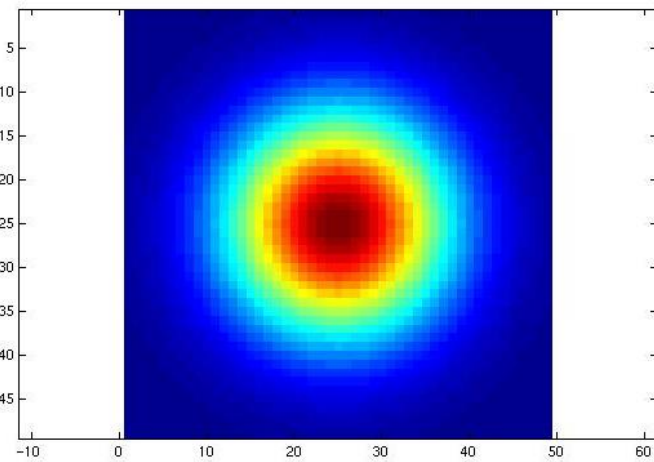
- What filters to put in the bank?
  - Typically we want a combination of scales and orientations, different types of patterns.

Matlab code available for these examples:

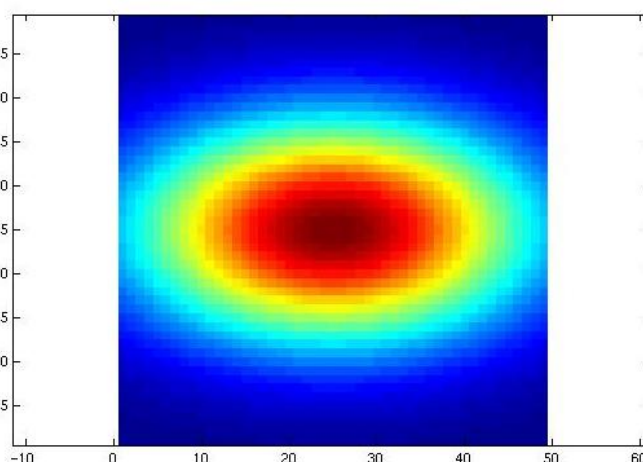
<http://www.robots.ox.ac.uk/~vgg/research/texclass/filters.html>

# Multivariate Gaussian

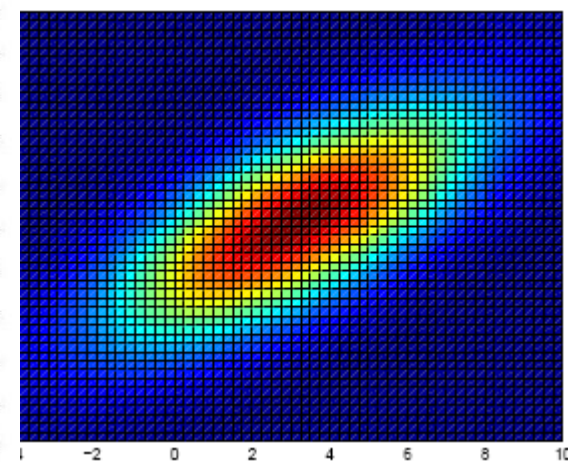
$$p(x; \mu, \Sigma) = \frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \exp \left( -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right).$$



$$\Sigma = \begin{bmatrix} 9 & 0 \\ 0 & 9 \end{bmatrix}$$

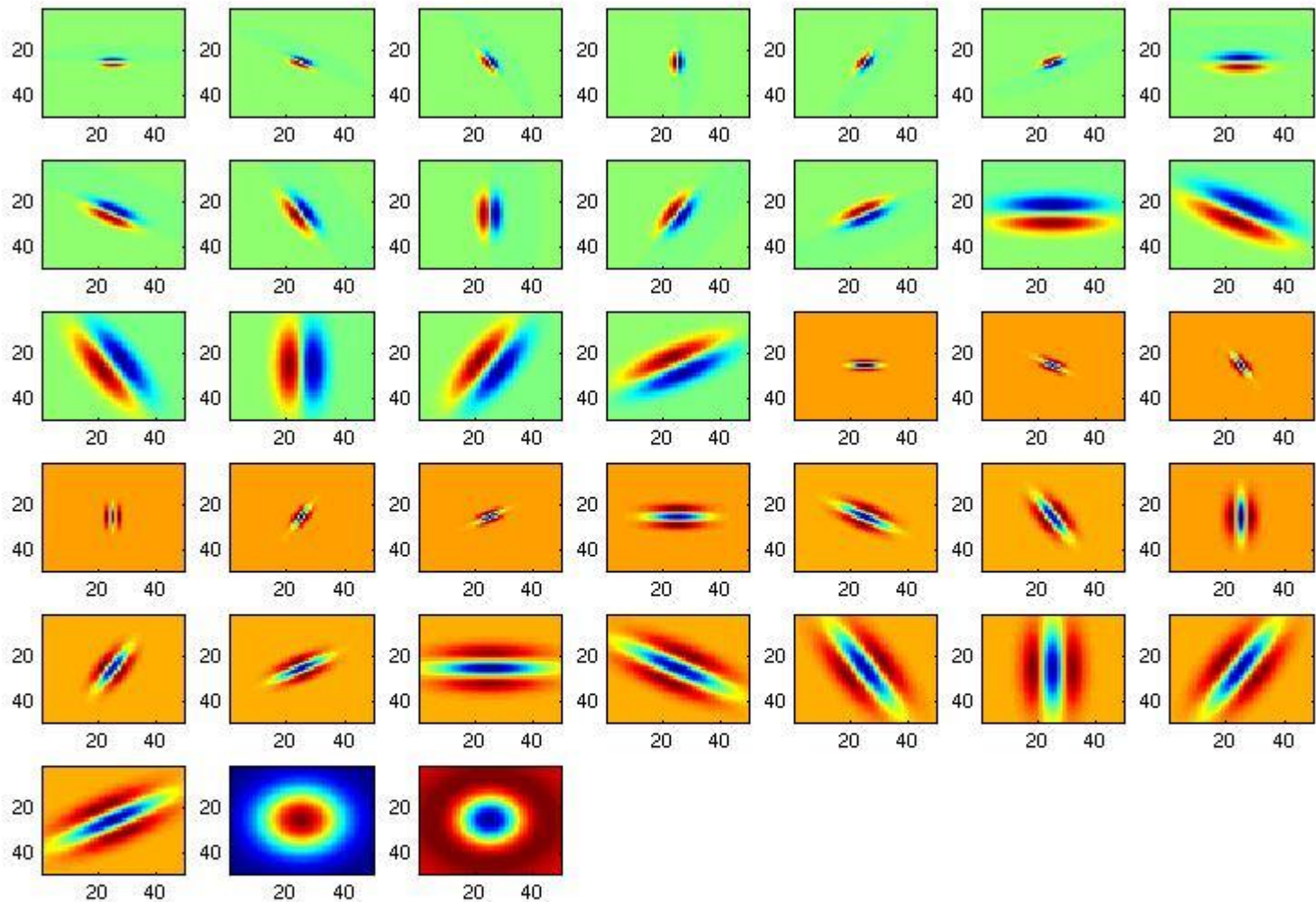


$$\Sigma = \begin{bmatrix} 16 & 0 \\ 0 & 9 \end{bmatrix}$$



$$\Sigma = \begin{bmatrix} 10 & 5 \\ 5 & 5 \end{bmatrix}$$

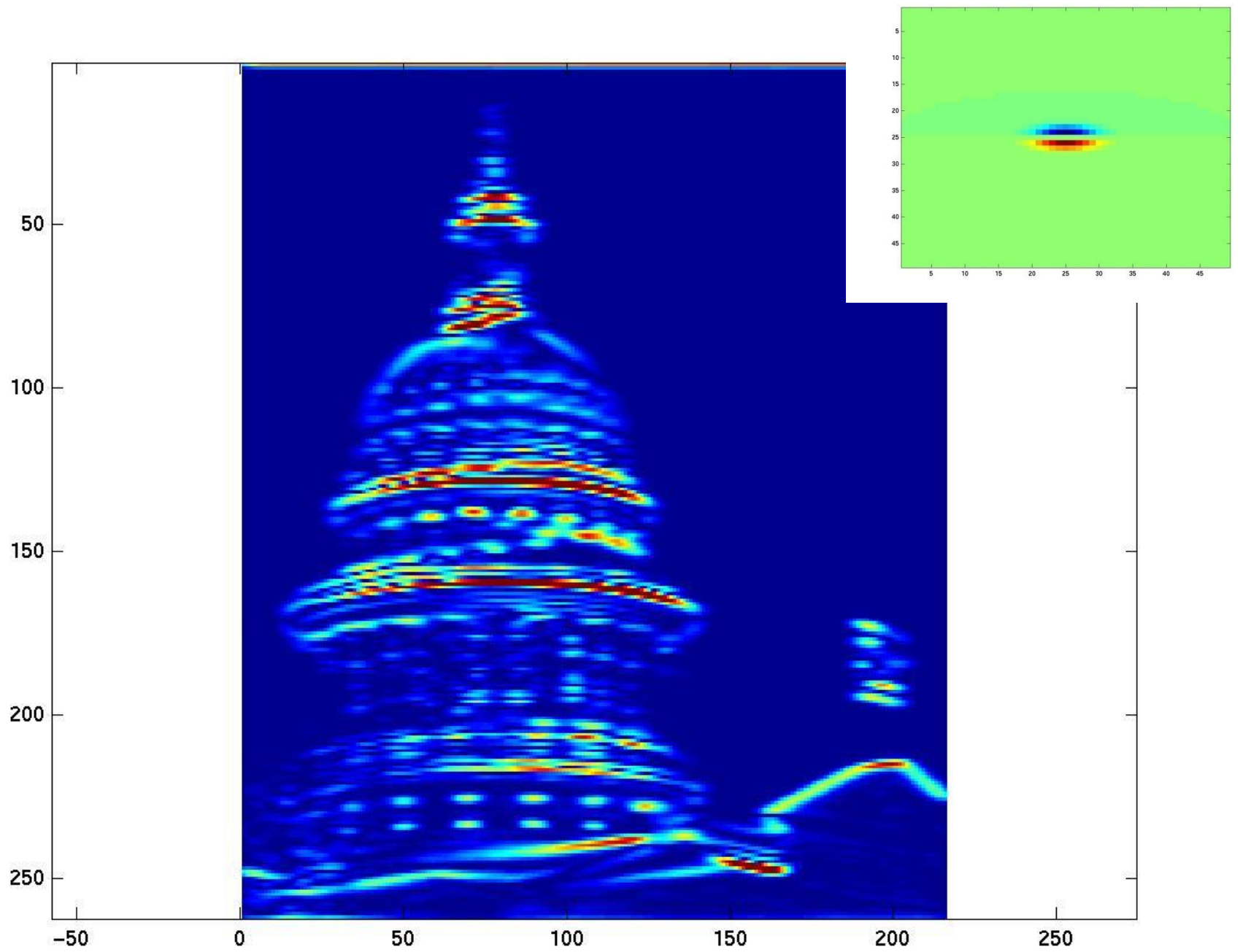
# Filter bank



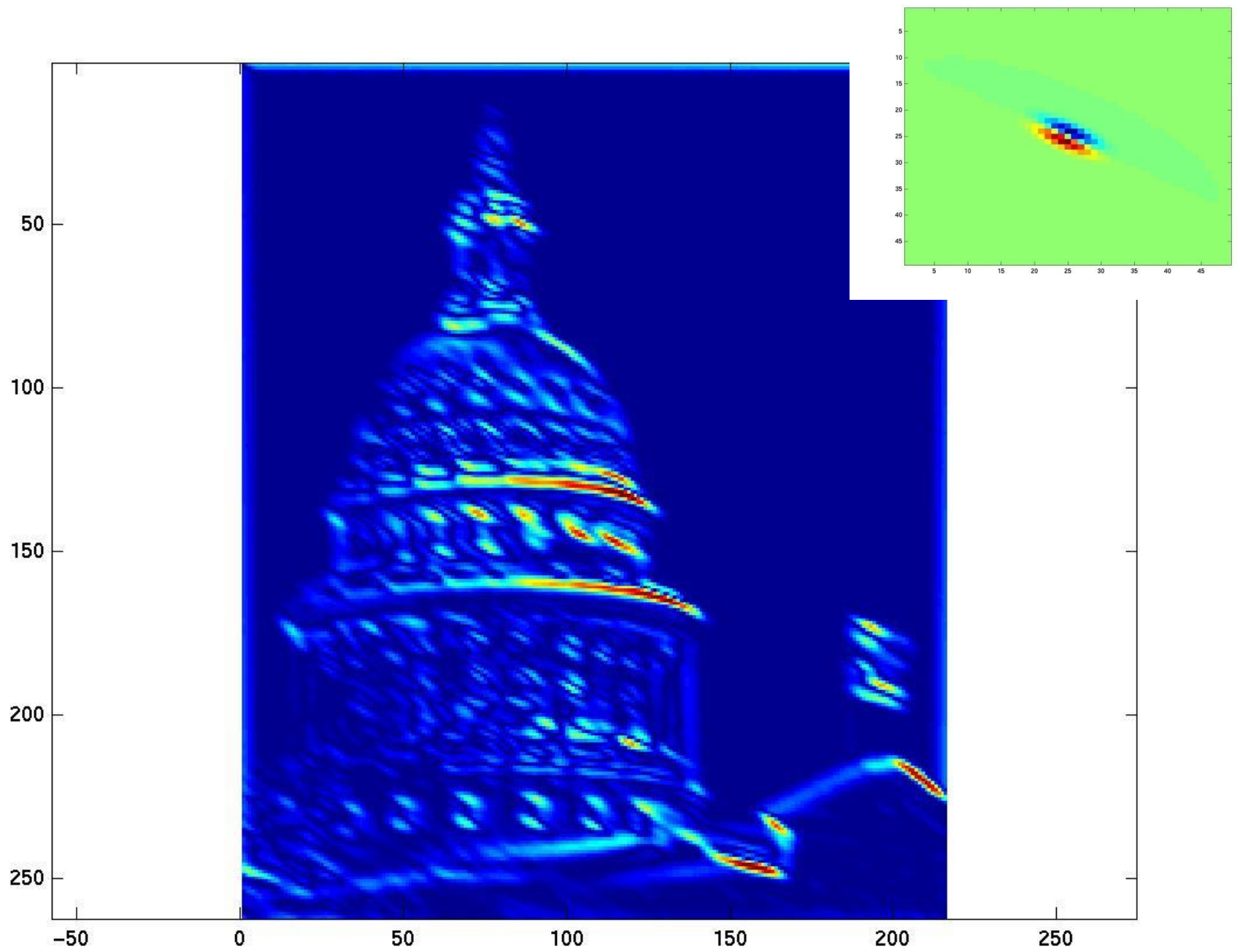


Slide credit: Kristen  
Grauman



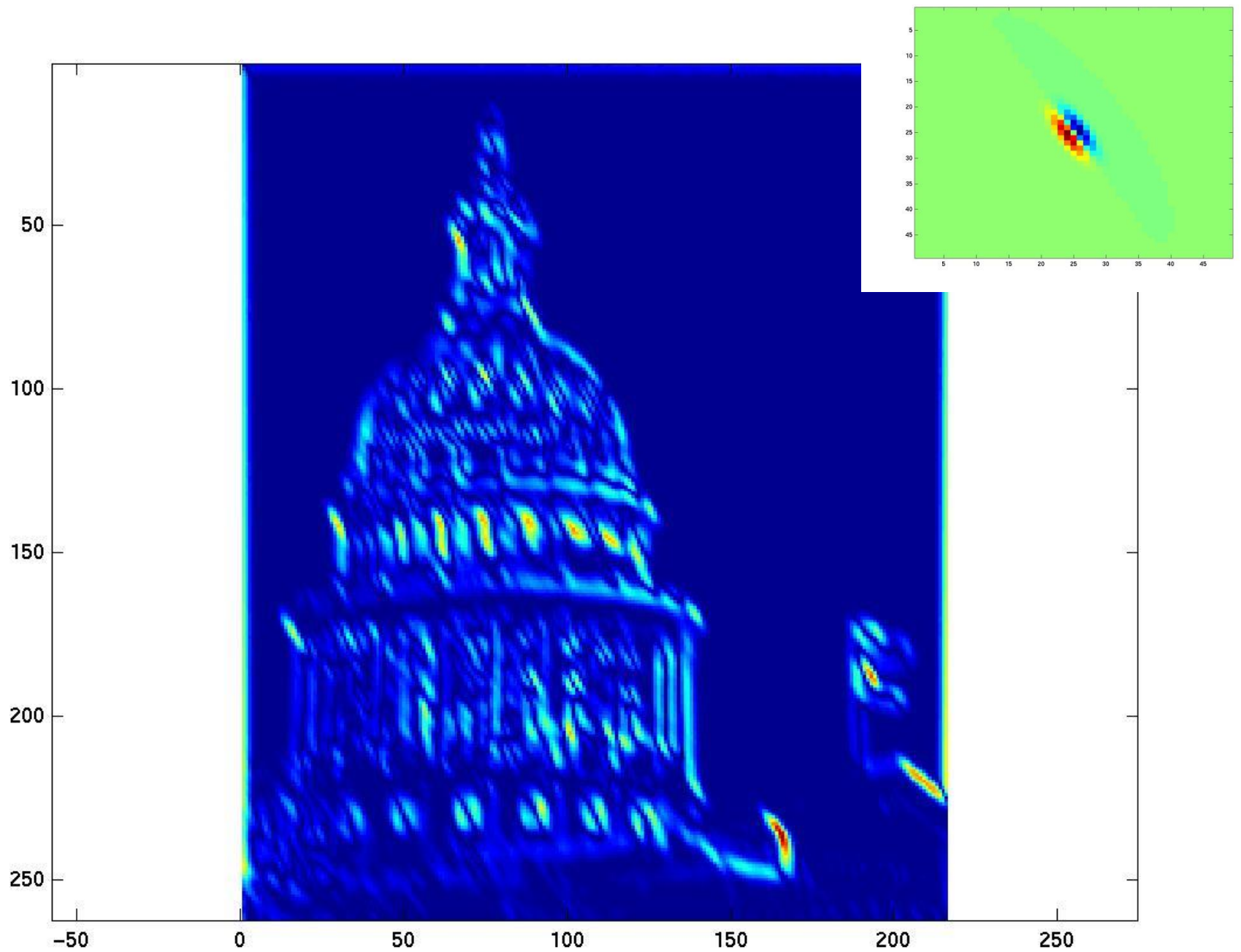


Slide credit: Kristen  
Grauman

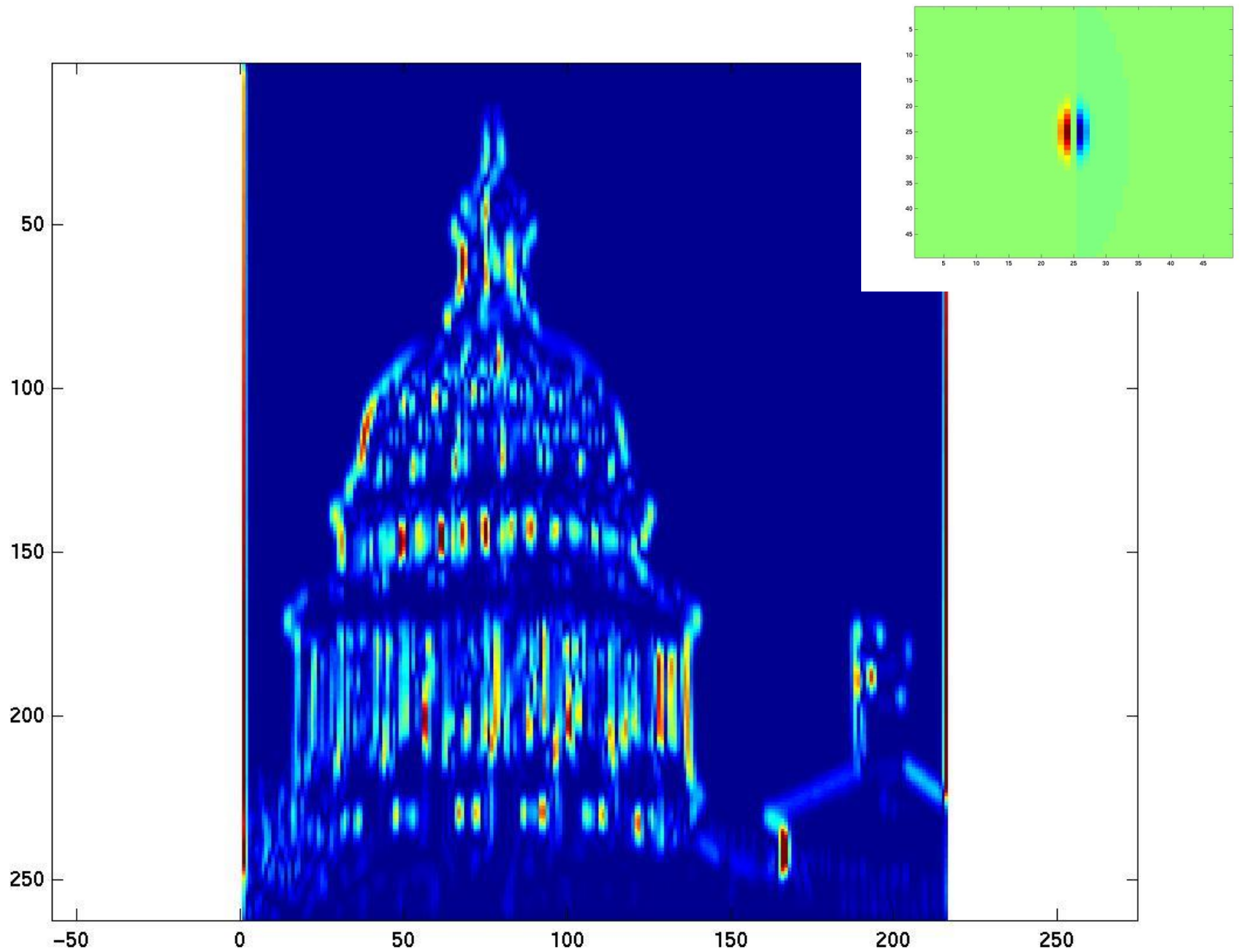


Slide credit: Kristen  
Grauman

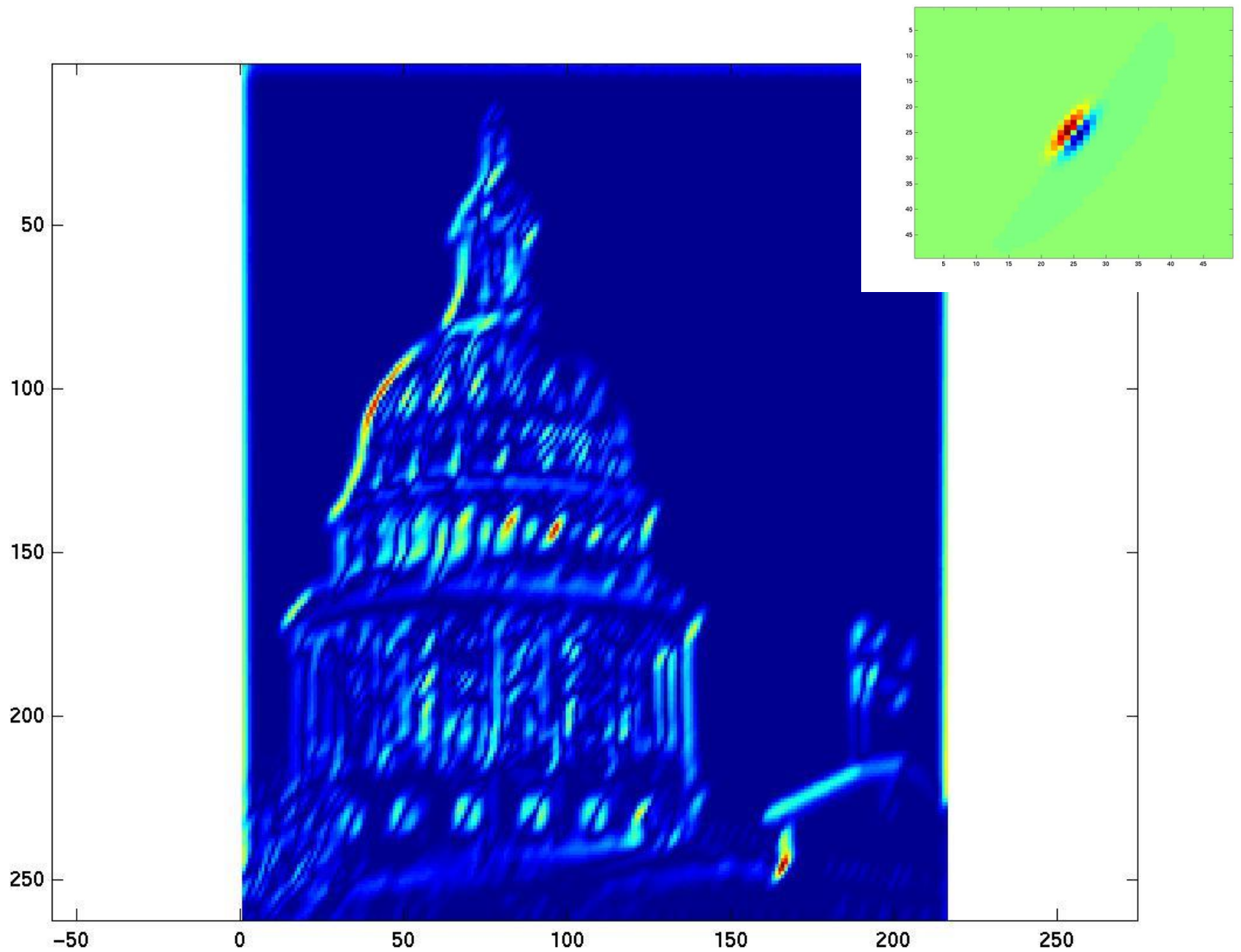




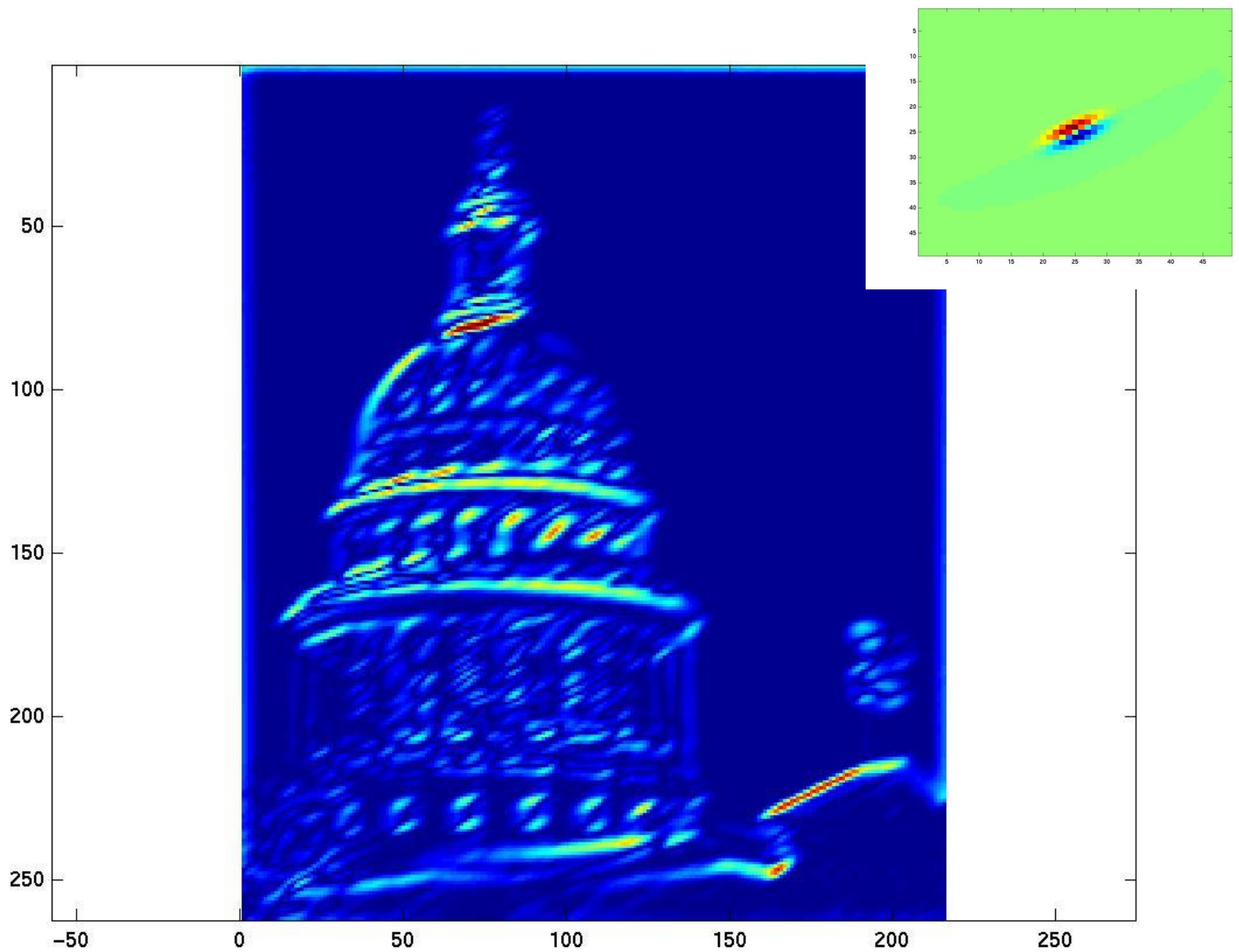
Slide credit: Kristen  
Grauman



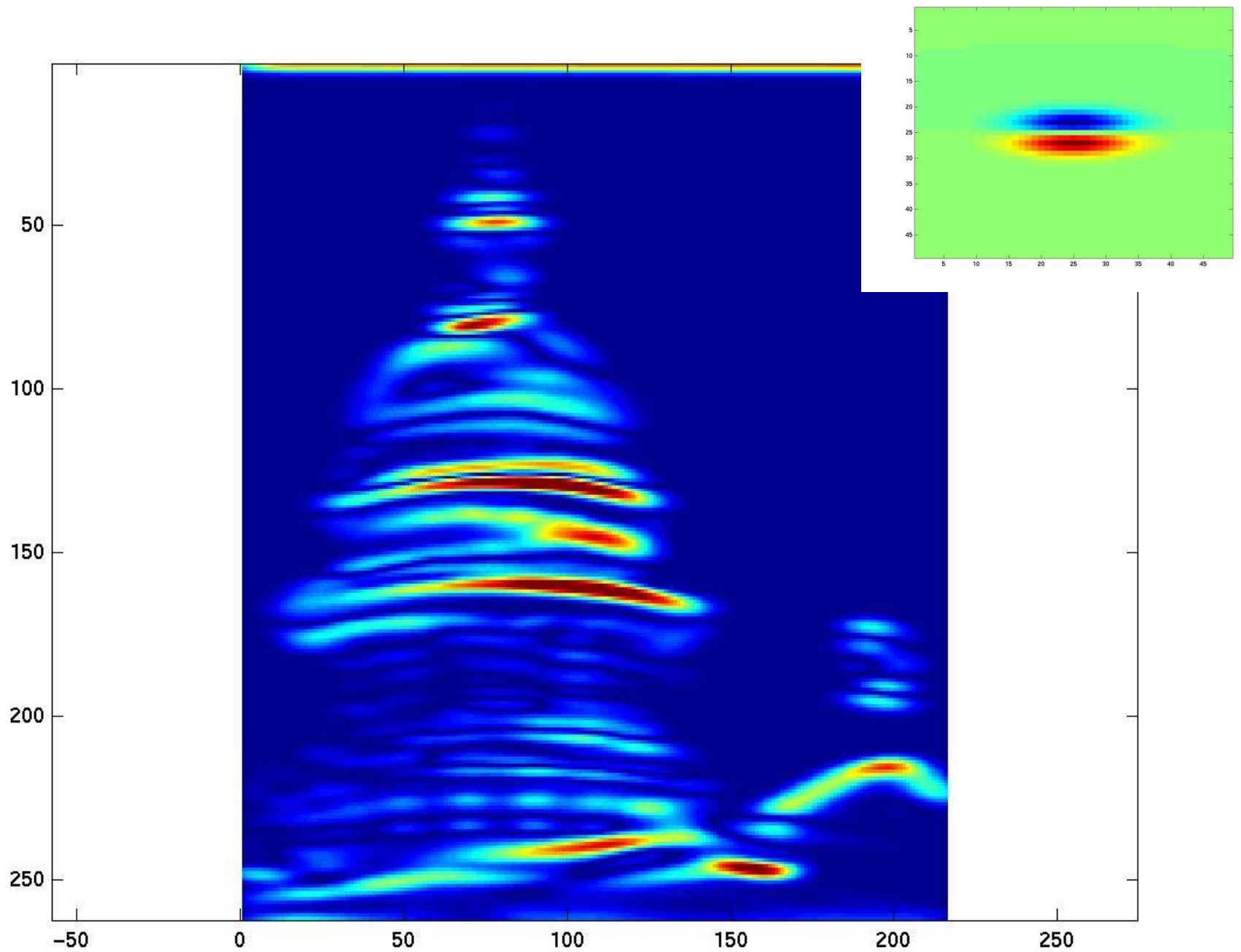
Slide credit: Kristen  
Grauman



Slide credit: Kristen  
Grauman

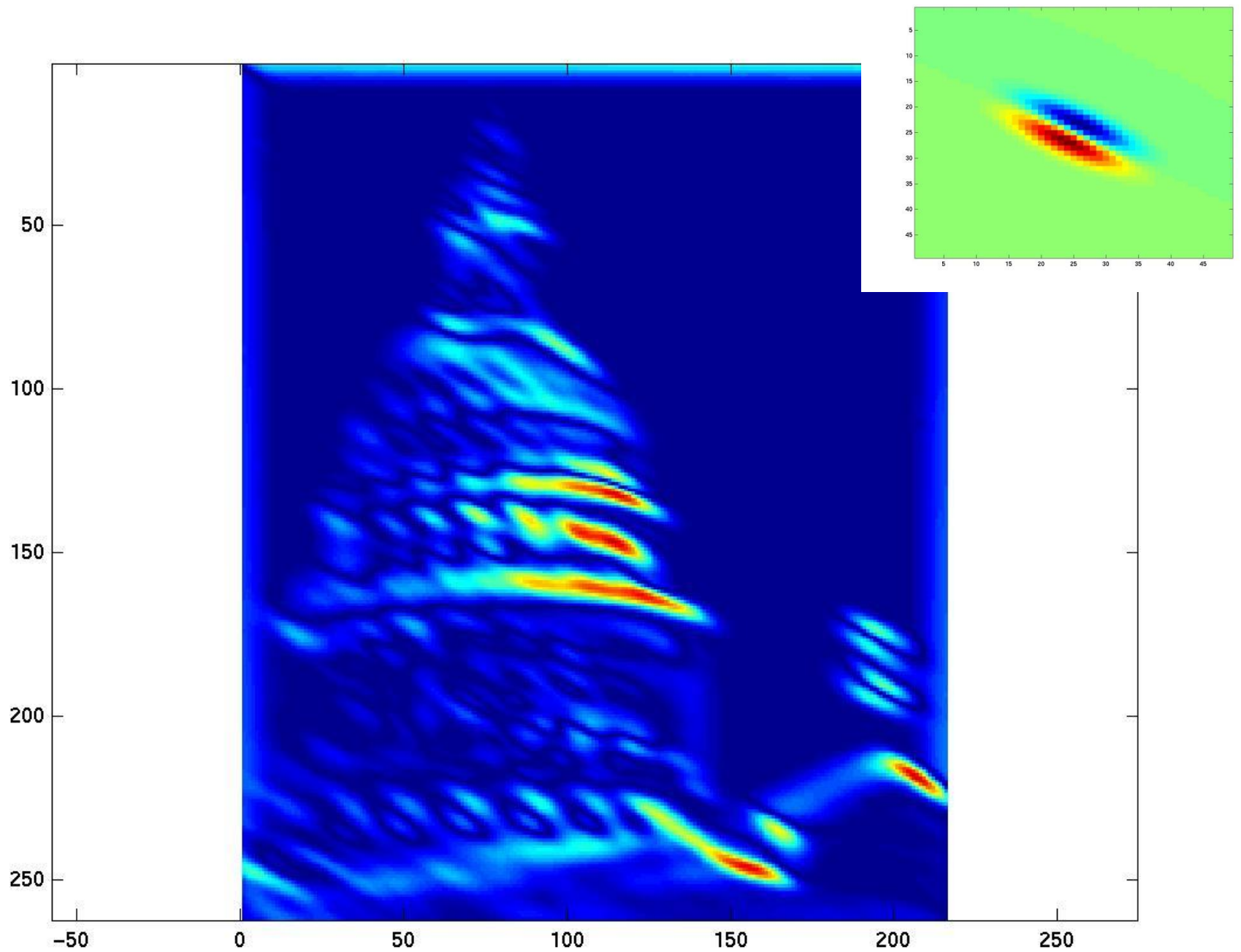


Slide credit: Kristen  
Grauman



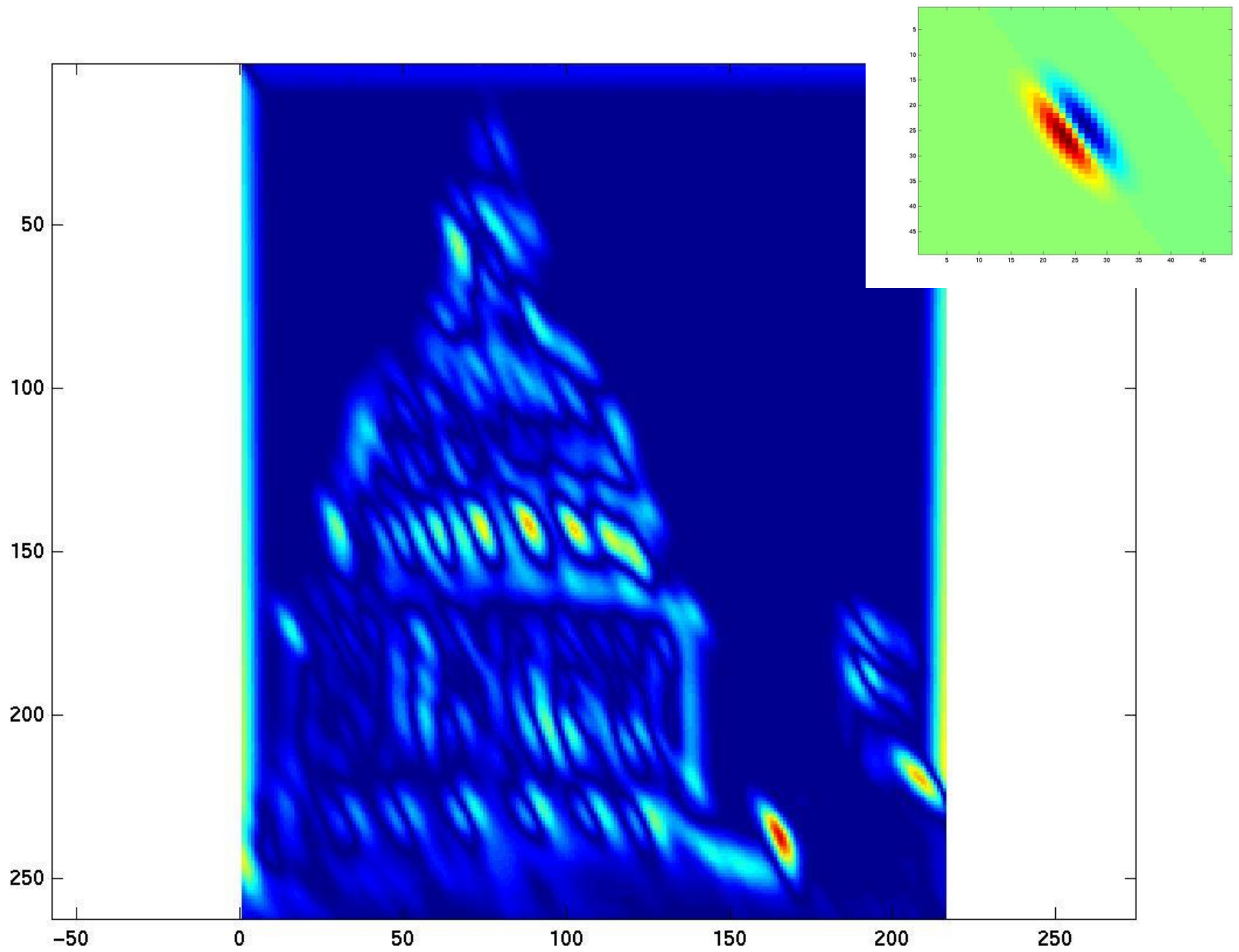
Slide credit: Kristen  
Grauman



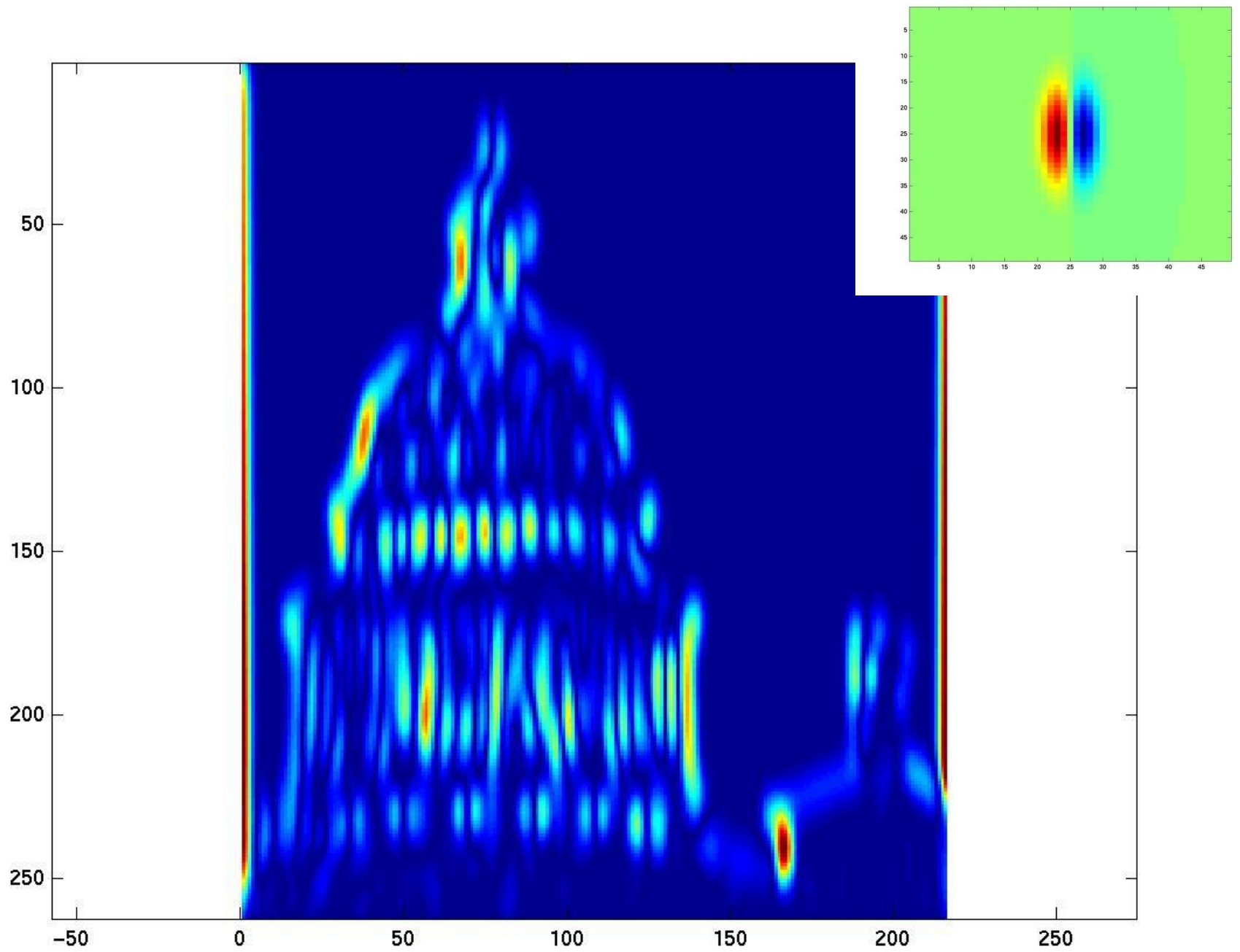


Slide credit: Kristen  
Grauman

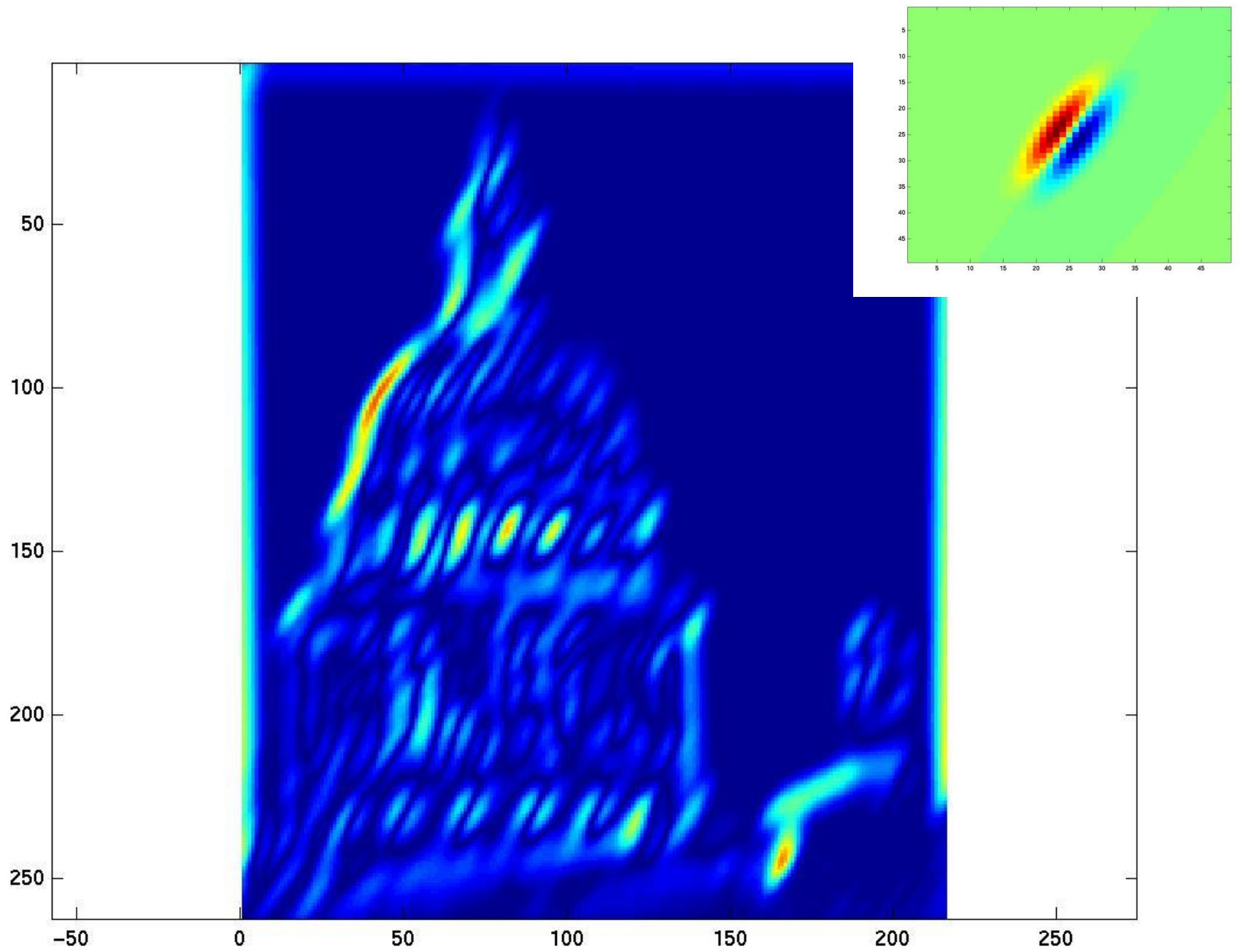




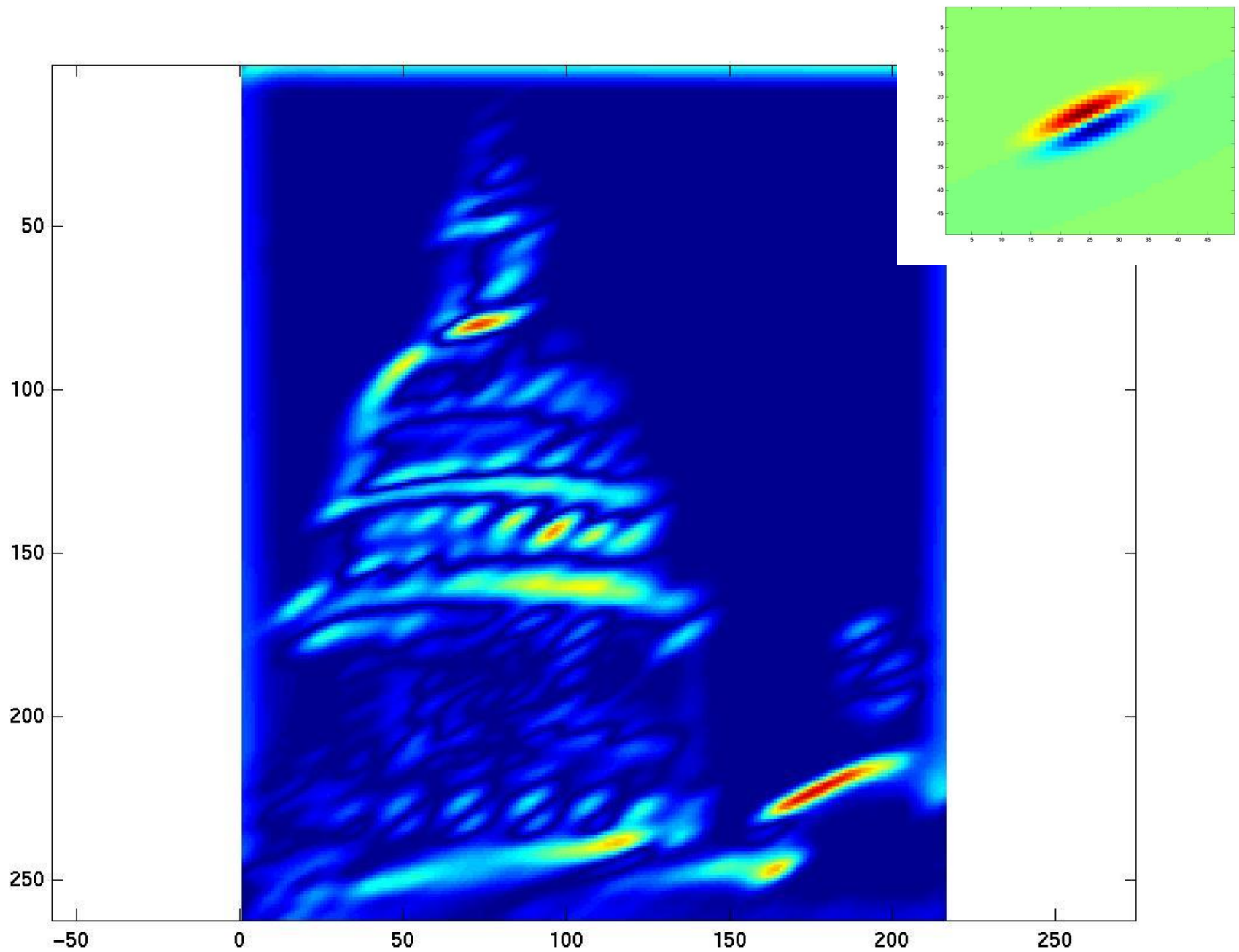
Slide credit: Kristen  
Grauman



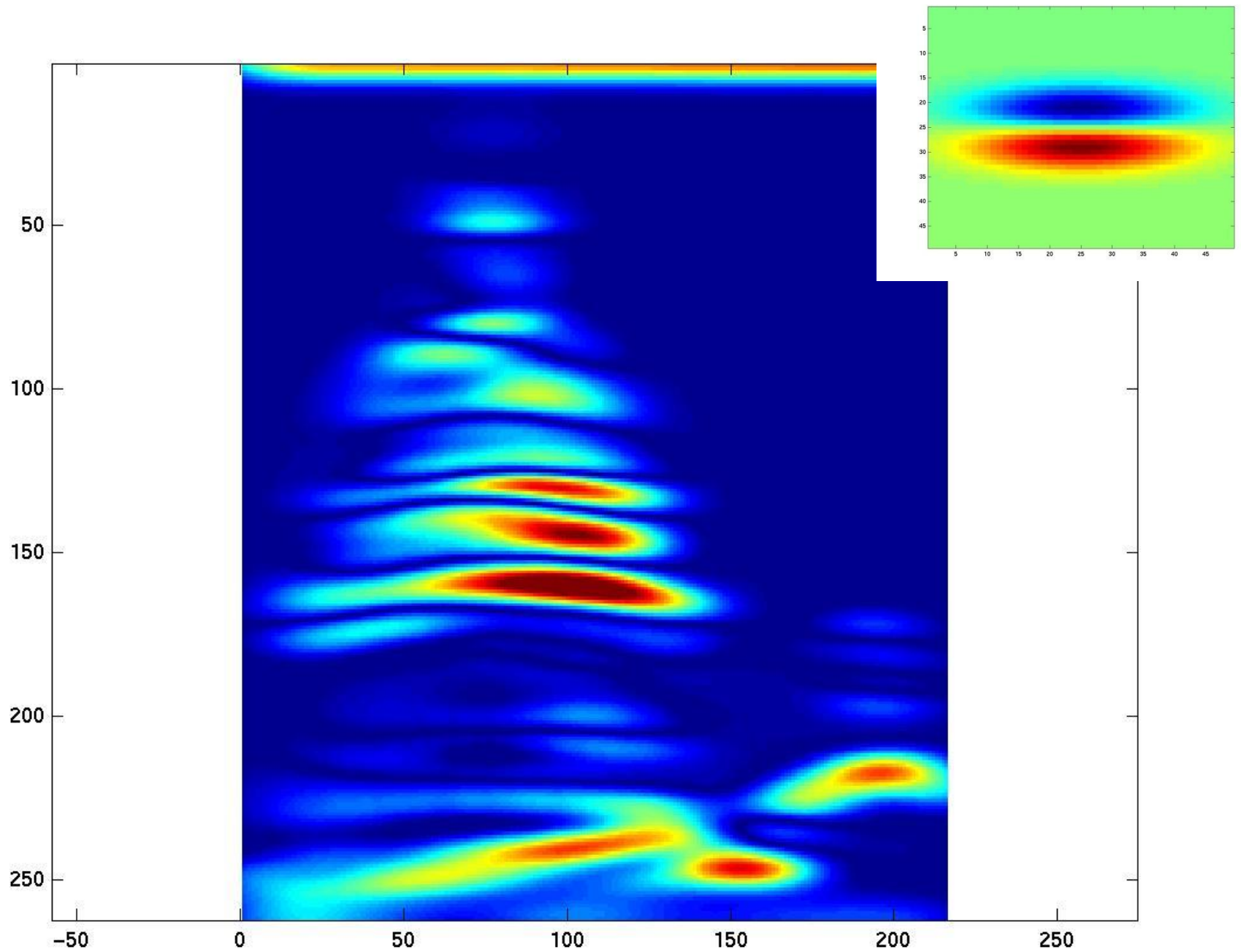
Slide credit: Kristen  
Grauman



Slide credit: Kristen  
Grauman

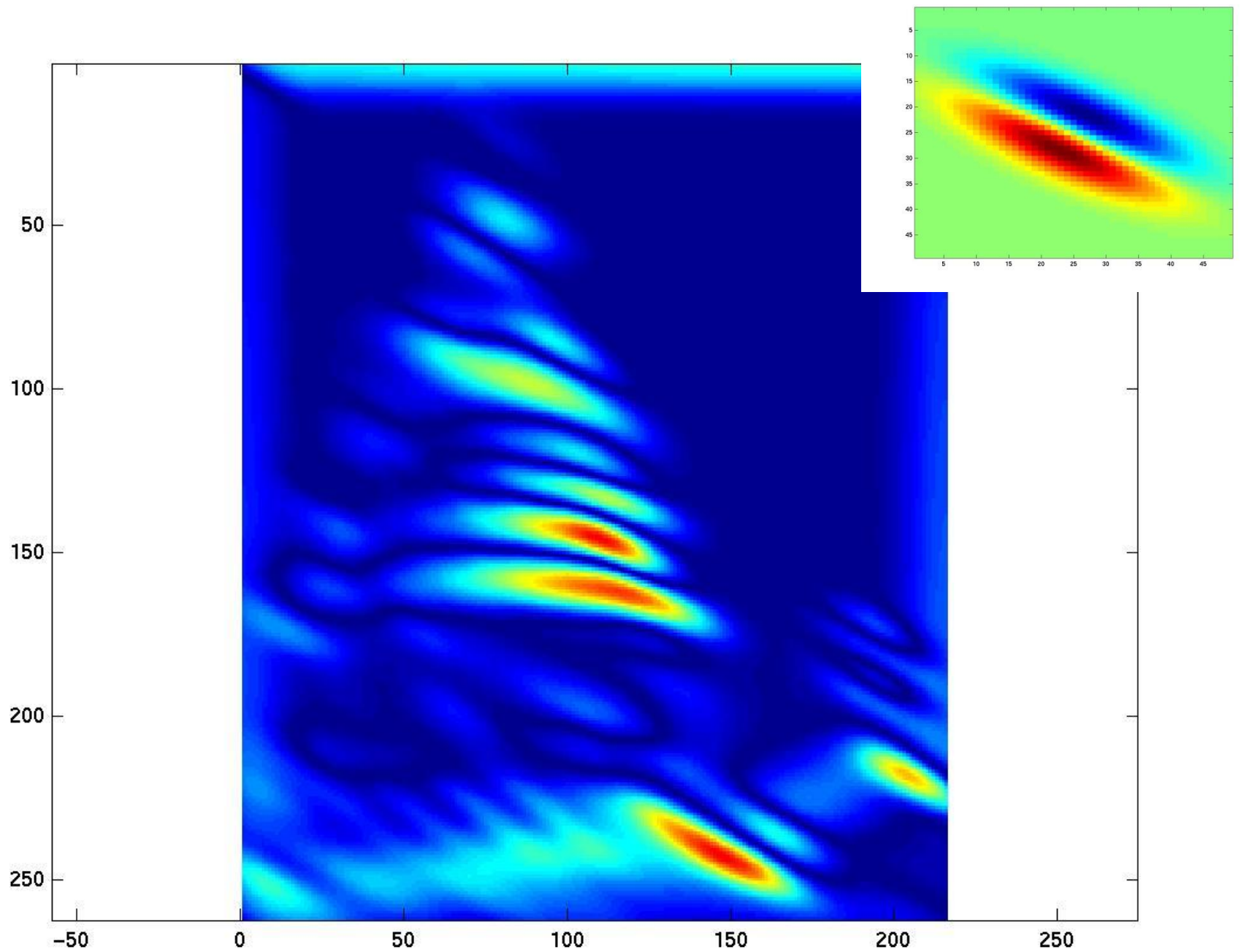


Slide credit: Kristen  
Grauman



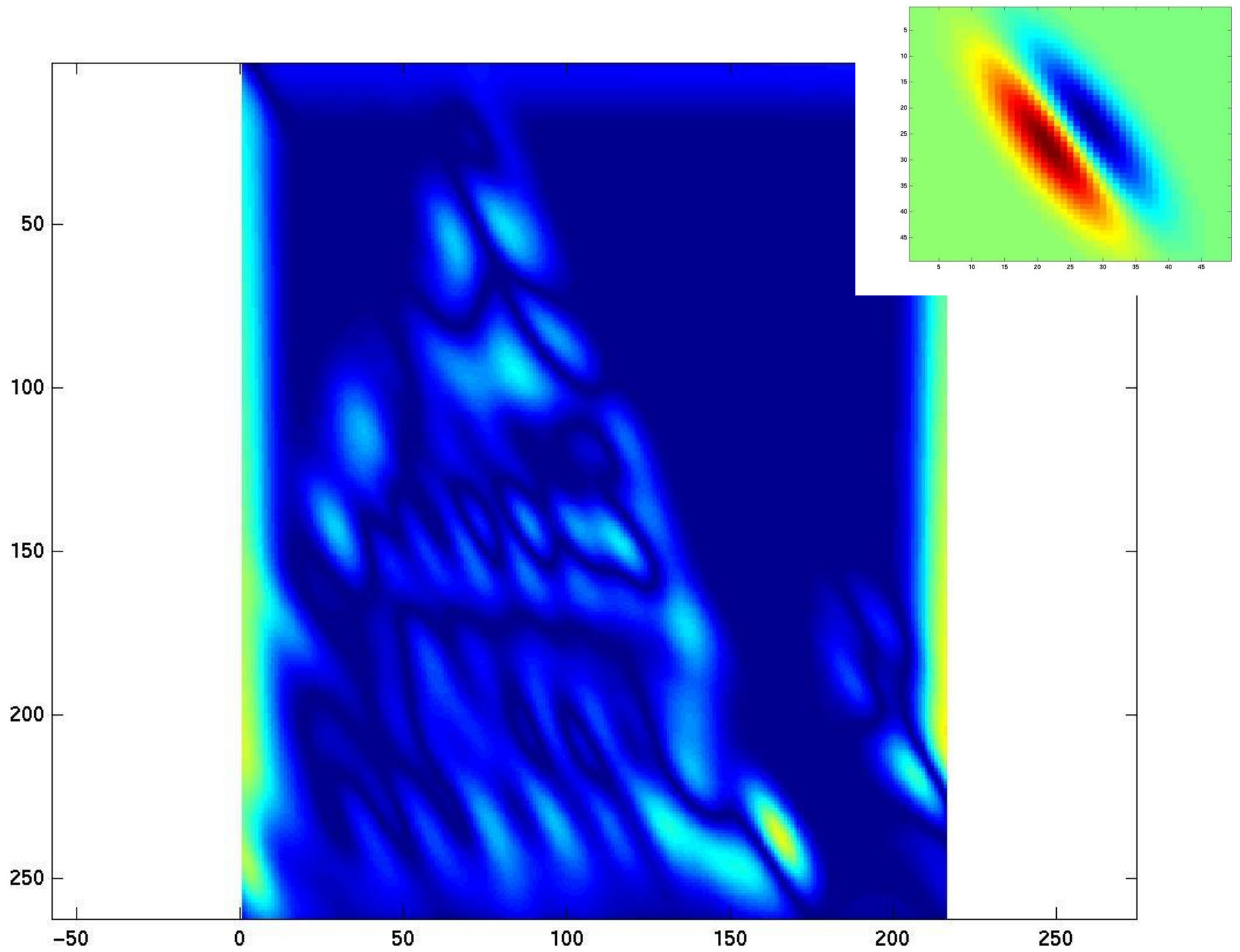
Slide credit: Kristen  
Grauman



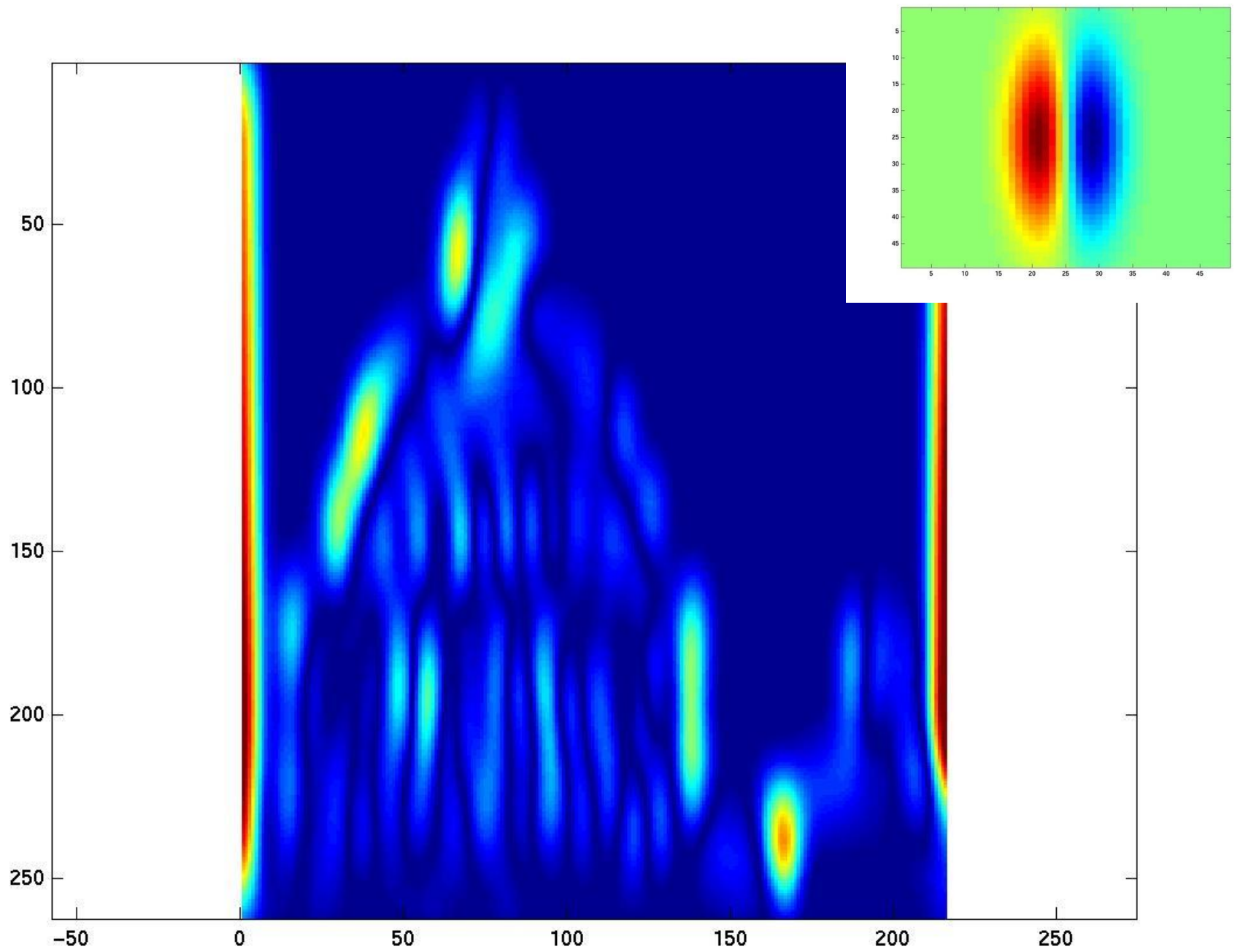


Slide credit: Kristen  
Grauman

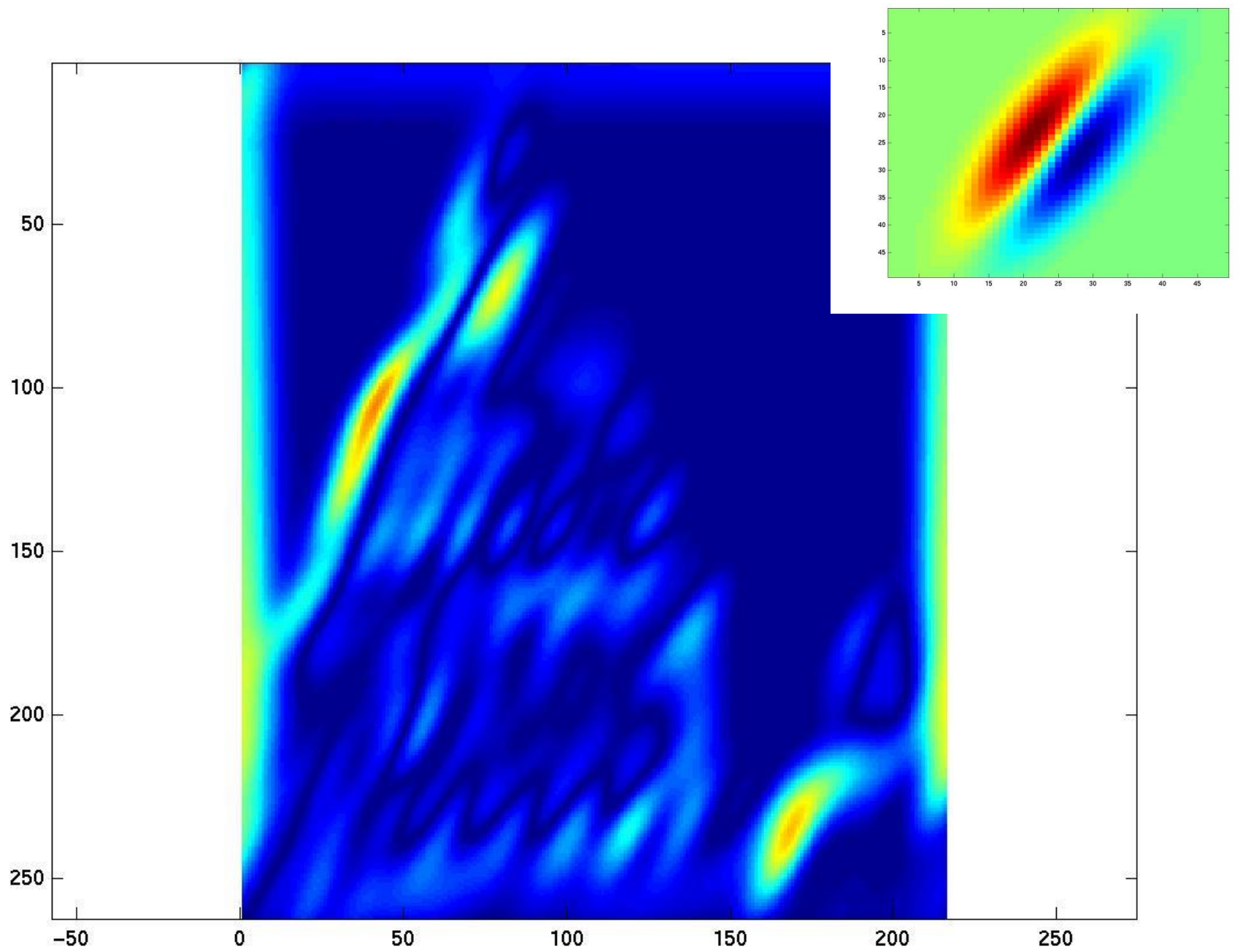




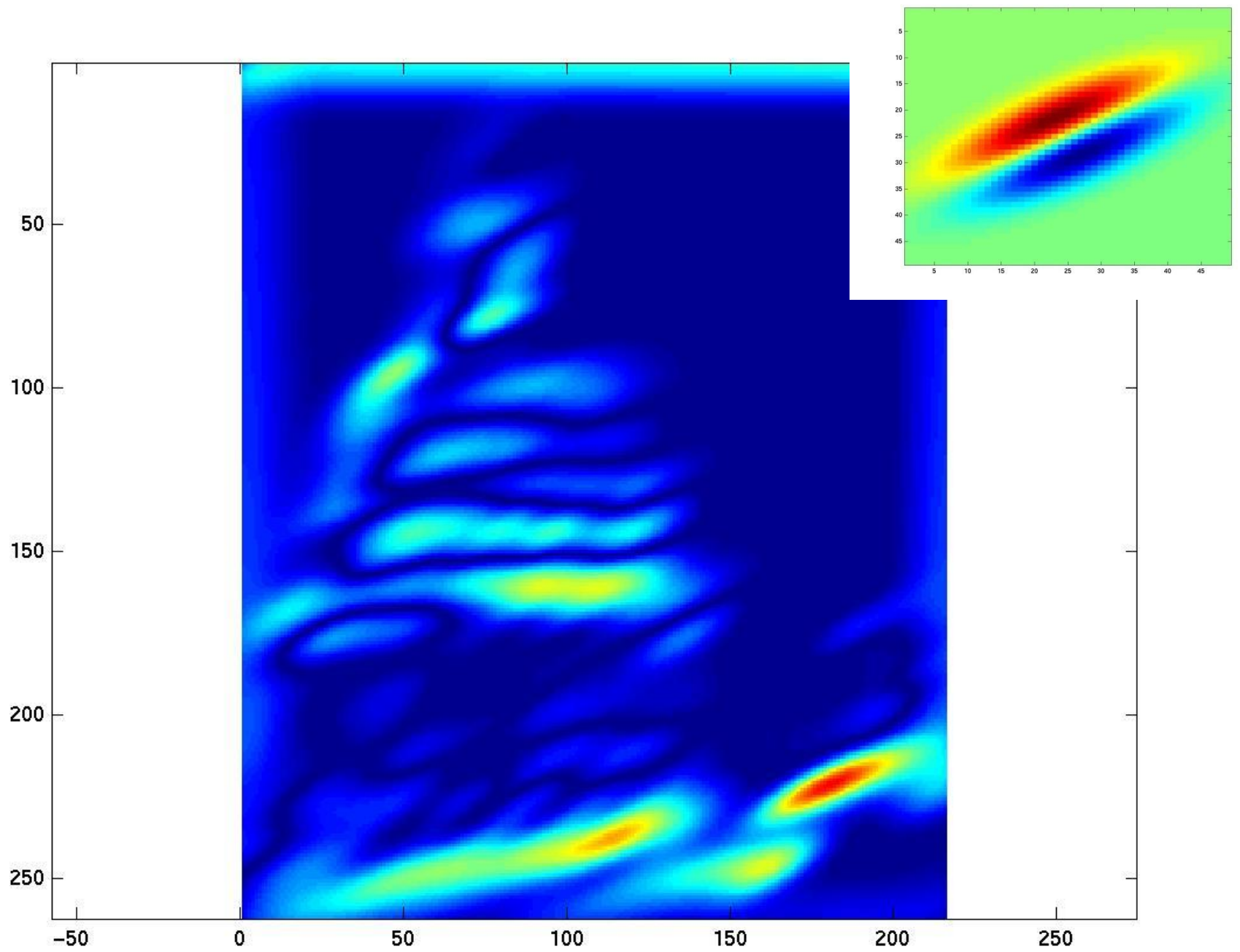
Slide credit: Kristen  
Grauman



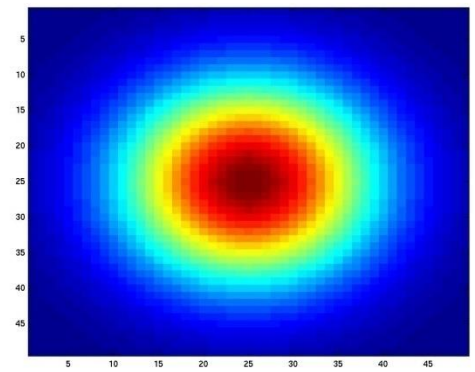
Slide credit: Kristen  
Grauman



Slide credit: Kristen  
Grauman



Slide credit: Kristen  
Grauman

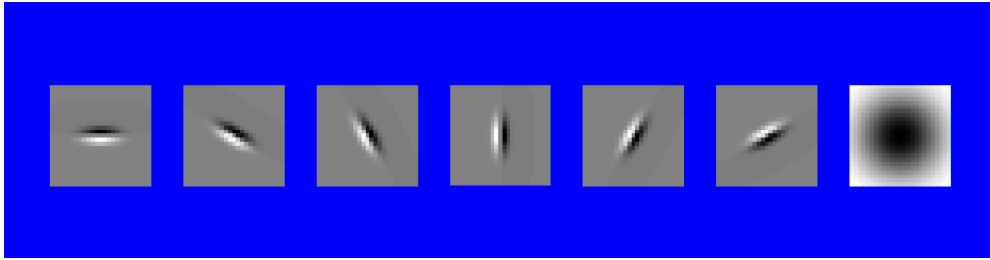


Slide credit: Kristen  
Grauman

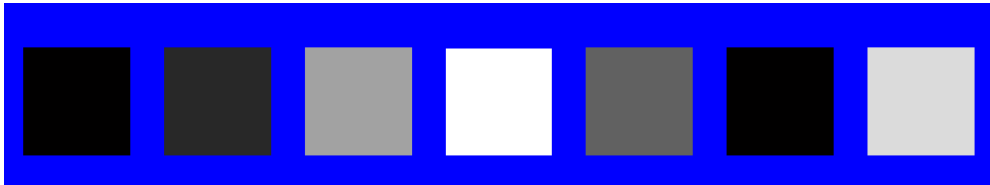


# You try: Can you match the texture to the response?

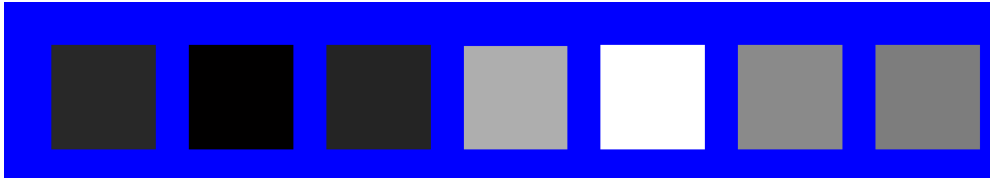
Filters



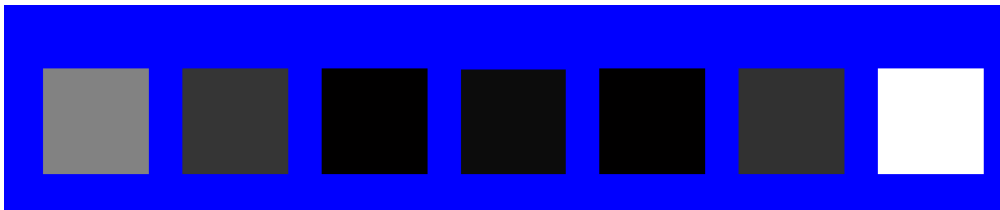
1



2

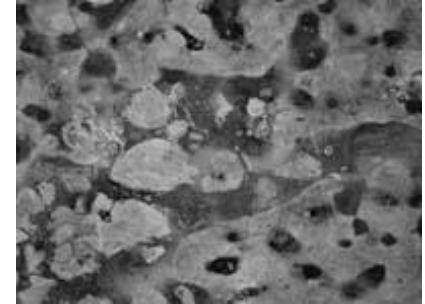


3



Mean abs responses

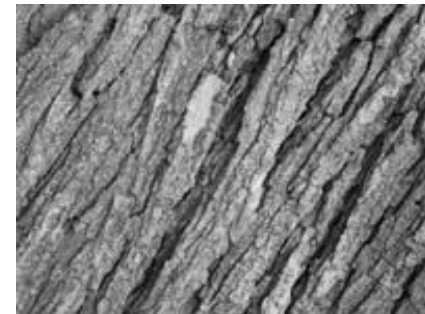
A



B

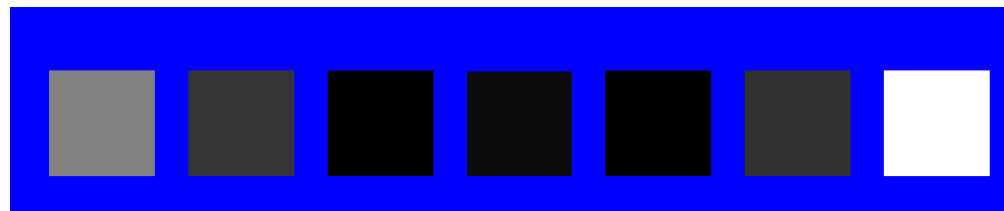
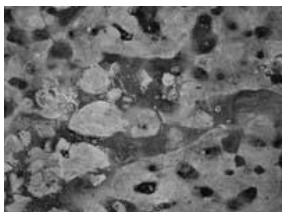
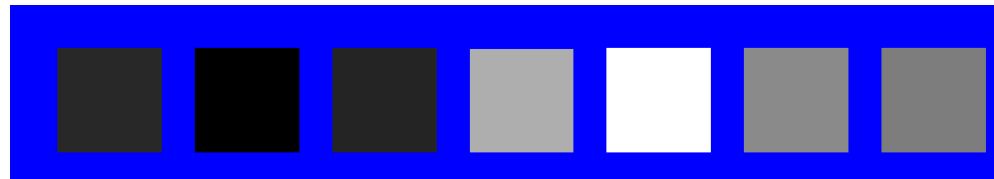
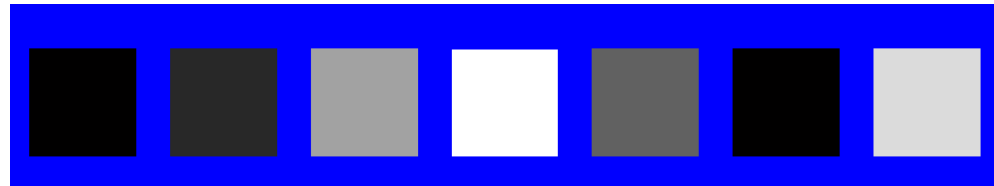
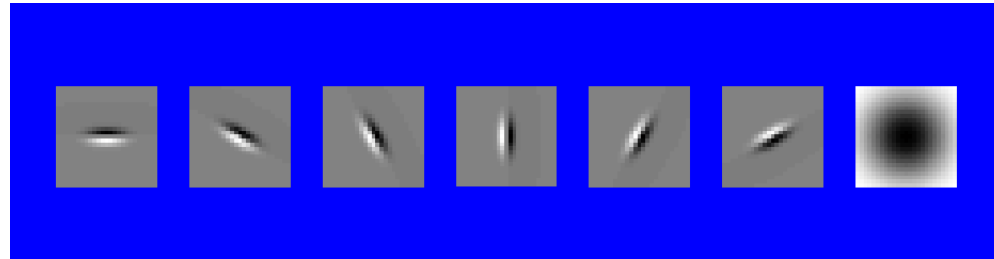


C



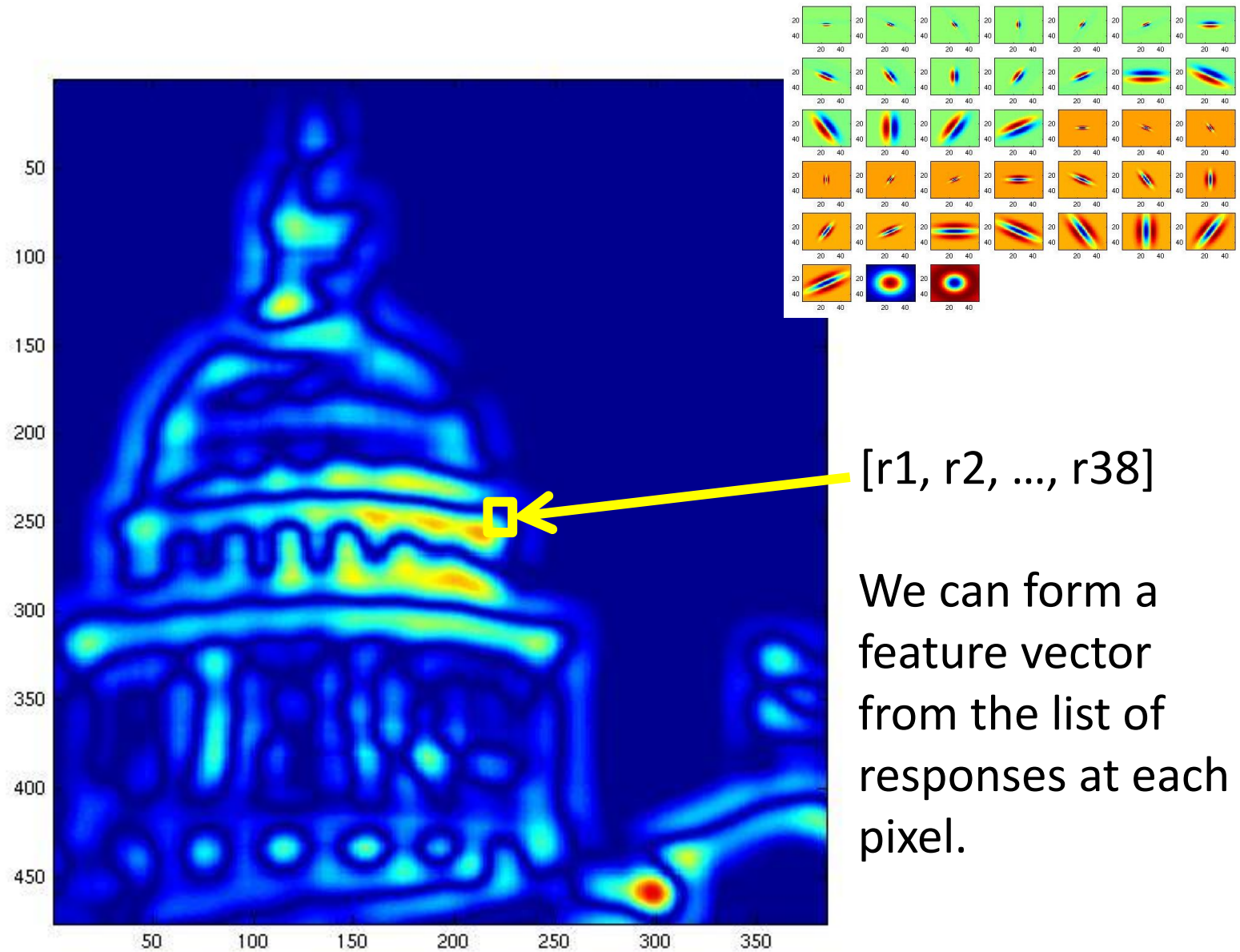
# Representing texture by mean abs response

Filters



Mean abs responses

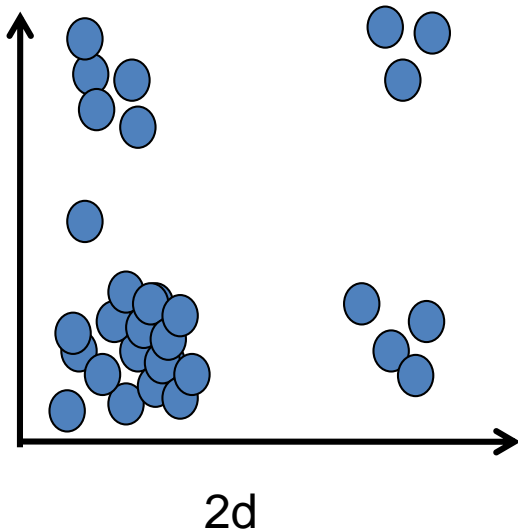




# $d$ -dimensional features

$$D(a, b) = \sqrt{\sum_{i=1}^d (a_i - b_i)^2}$$

Euclidean distance ( $L_2$ )



Example uses of  
texture in vision:  
analysis

# Classifying materials, “stuff”



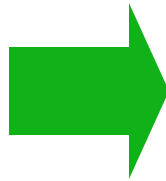
Figure by Varma & Zisserman

# Texture-related tasks

- **Shape from texture**
  - Estimate surface orientation or shape from image texture
- **Segmentation/classification** from texture cues
  - Analyze, represent texture
  - Group image regions with consistent texture
- **Synthesis**
  - Generate new texture patches/images given some examples

# Texture synthesis

- Goal: create new samples of a given texture
- Many applications: virtual environments, hole-filling, texturing surfaces

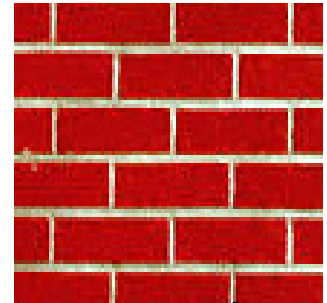




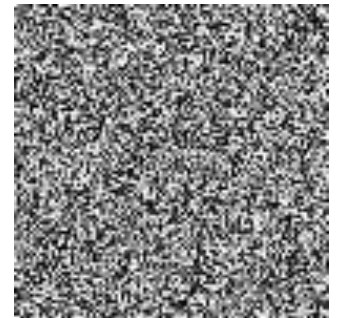
# The Challenge

- Need to model the whole spectrum: from repeated to stochastic texture

Alexei A. Efros and Thomas K. Leung, “Texture Synthesis by Non-parametric Sampling,” Proc. International Conference on Computer Vision (ICCV), 1999.



**repeated**



**stochastic**



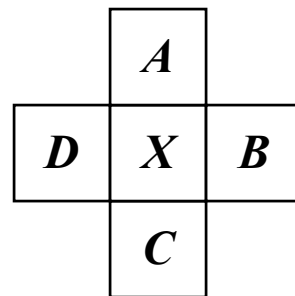
**Both?**

# Markov Random Field

## First-order MRF:

- probability that pixel  $X$  takes a certain value given the values of neighbors  $A$ ,  $B$ ,  $C$ , and  $D$ :

$$P(X|A, B, C, D)$$



# Texture Synthesis [\[Efros & Leung, ICCV 99\]](#)

- Can apply 2D version of text synthesis

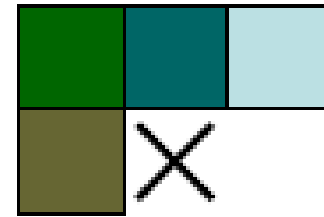
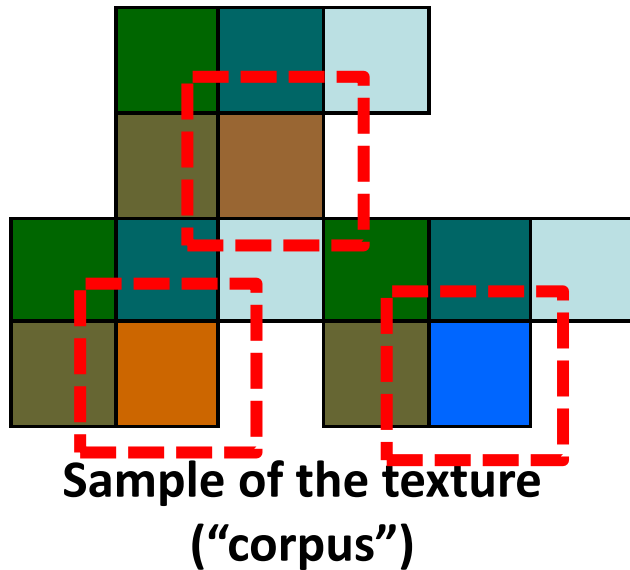
Texture corpus  
(sample)



Output

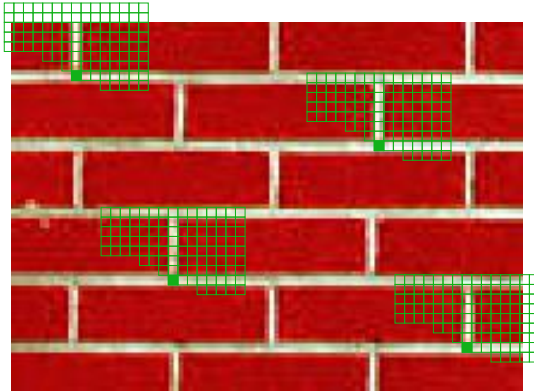
# Texture synthesis: intuition

We want to insert **pixel intensities** based on existing nearby pixel values.

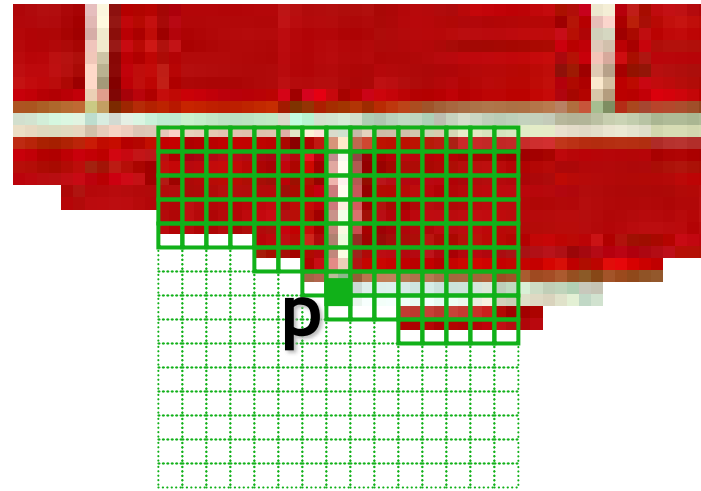


Distribution of a value of a pixel is conditioned on its neighbors alone.

# Synthesizing One Pixel



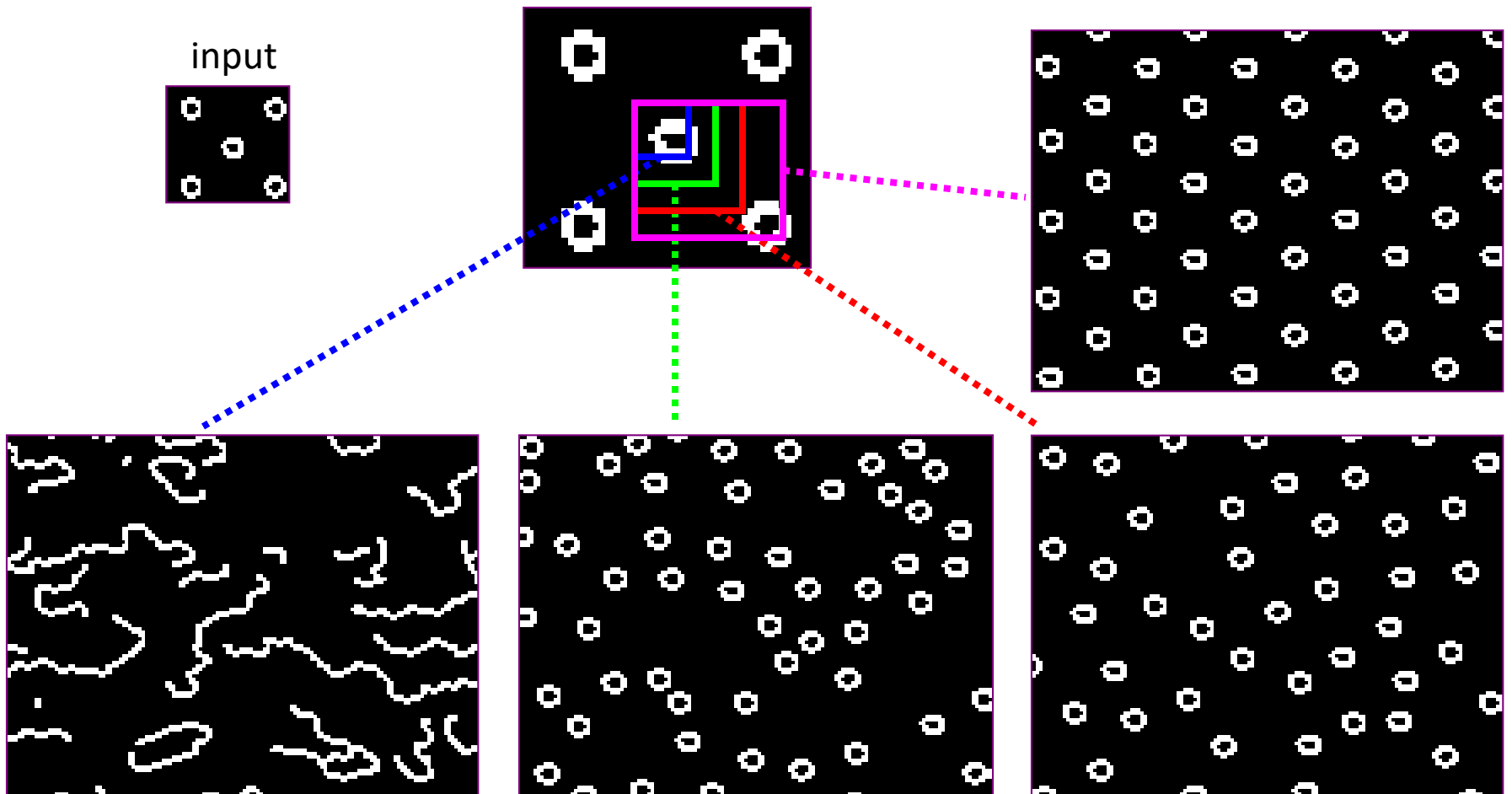
input image



synthesized image

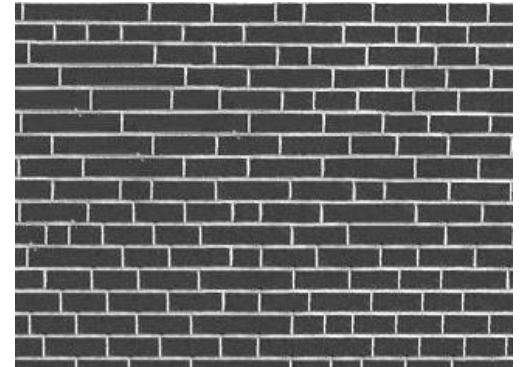
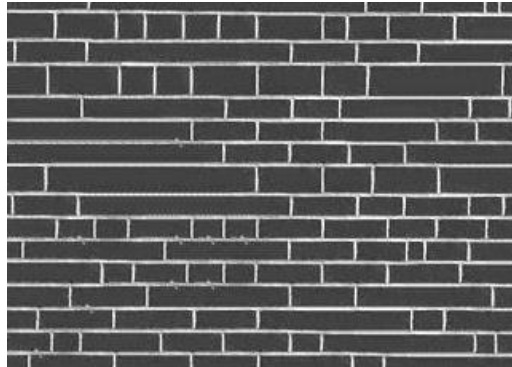
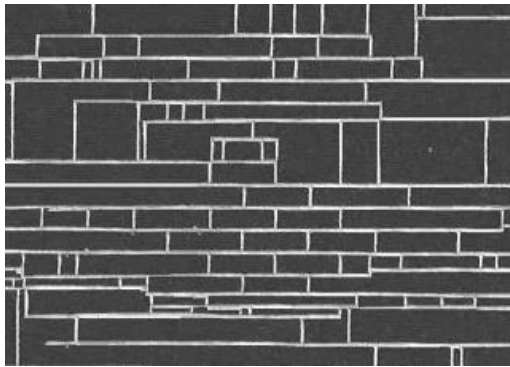
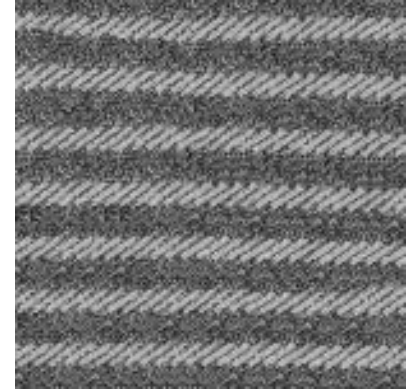
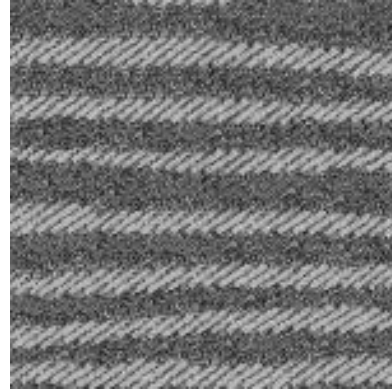
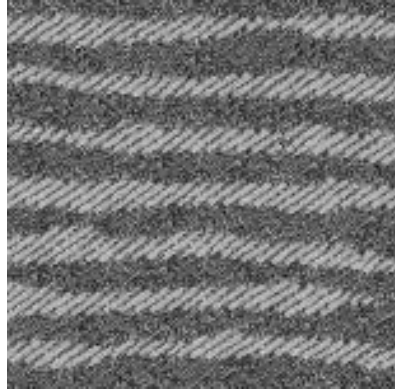
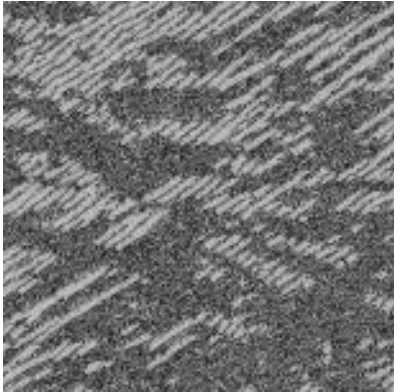
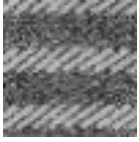
- What is  $P(\mathbf{x} | \text{neighborhood of pixels } \hat{\mathbf{x}} \text{ around } \mathbf{x})$
- Find all the windows in the image that match the neighborhood
- To synthesize  $\mathbf{x}$ 
  - pick one matching window at random
  - assign  $\mathbf{x}$  to be the center pixel of that window
- An **exact** neighbourhood match might not be present, so find the **best** matches using **SSD error** and randomly choose between them, preferring better matches with higher probability

# Neighborhood Window





# Varying Window Size

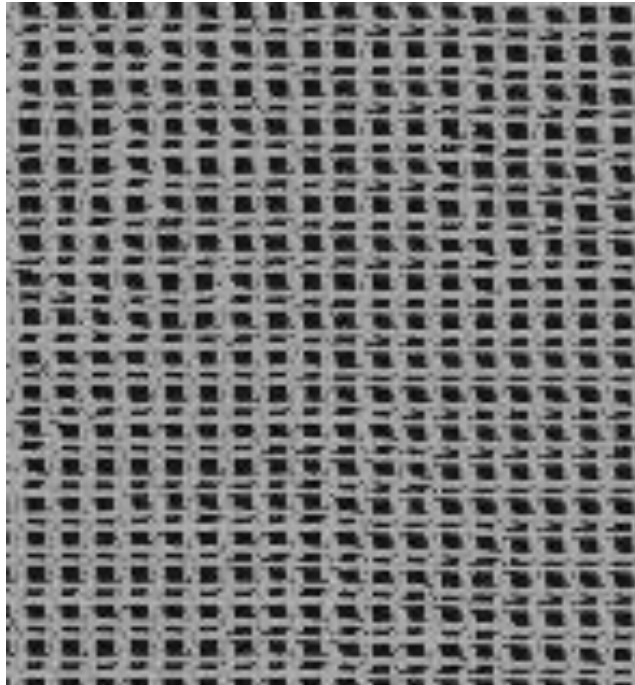
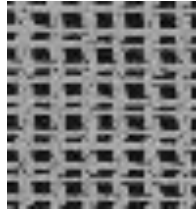


Increasing window size

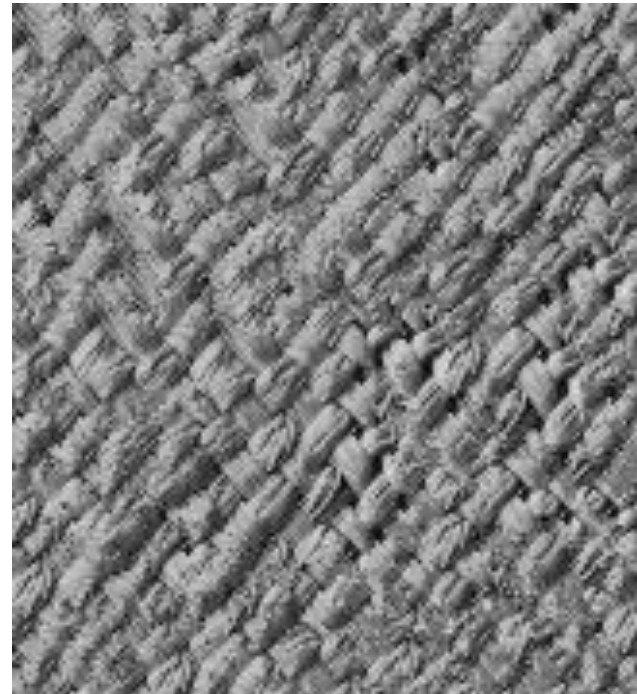


# Synthesis results

french canvas



rafia weave

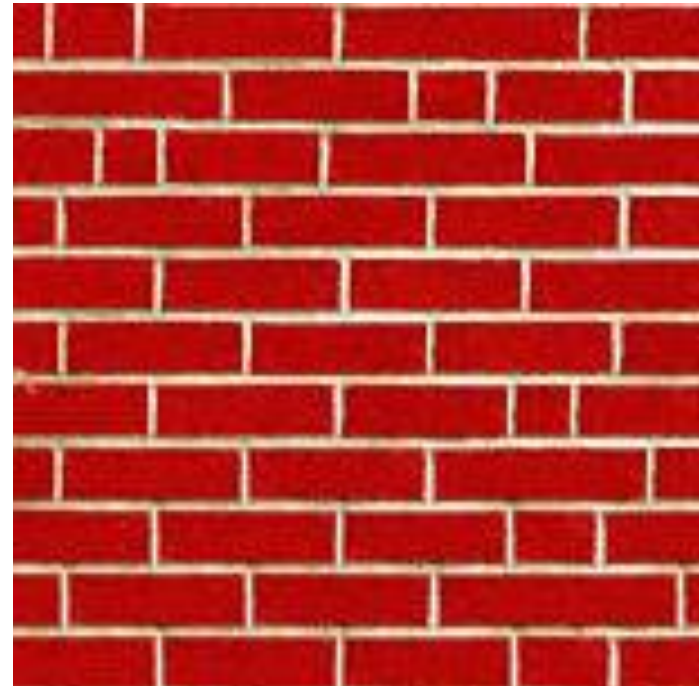
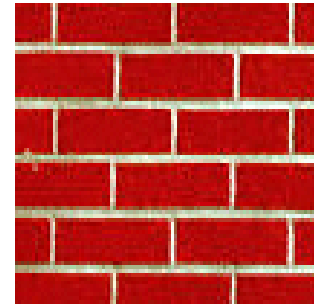


# Synthesis results

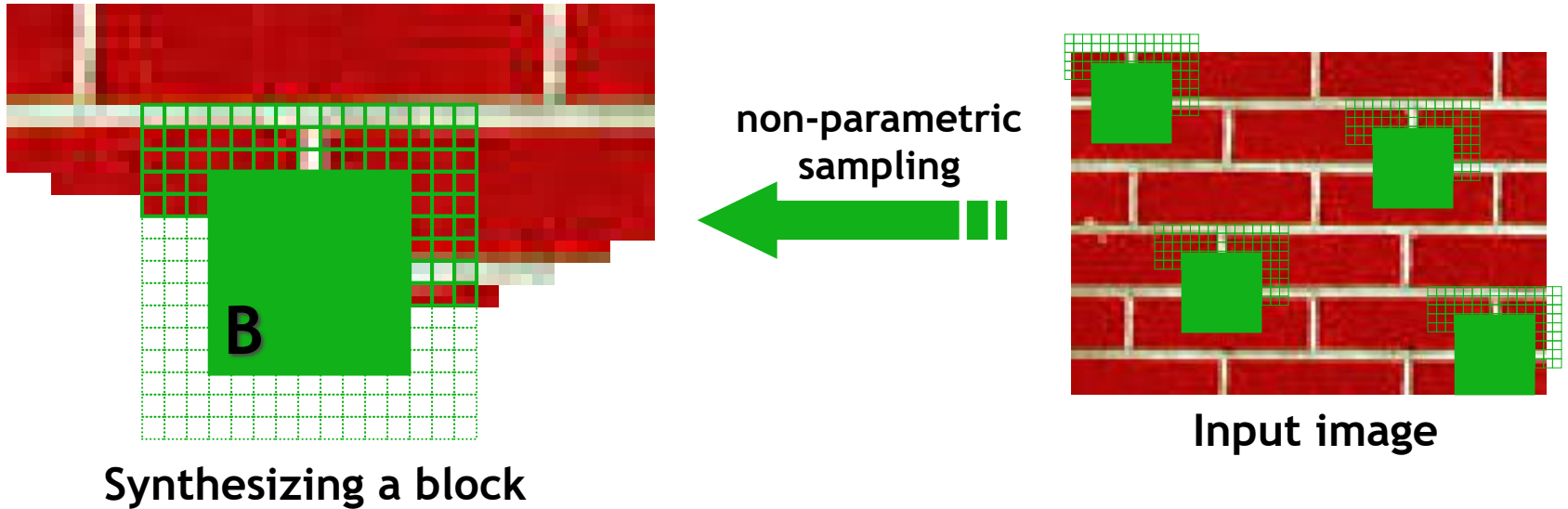
white bread



brick wall



# Image Quilting [Efros & Freeman 2001]

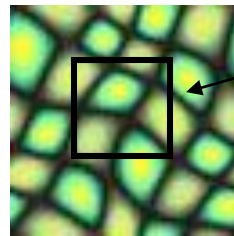


- Observation: neighbor pixels are highly correlated

**Idea: unit of synthesis = block**

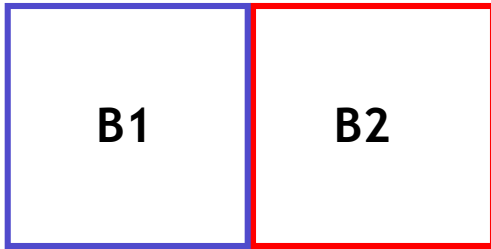
- Exactly the same but now we want  $P(B|N(B))$
- Much faster: synthesize all pixels in a block at once



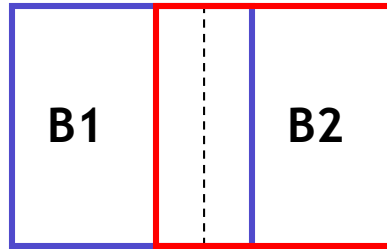


block

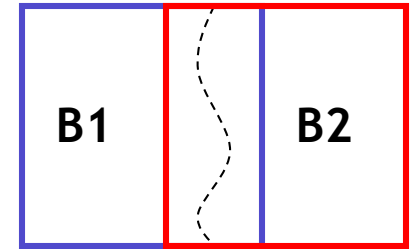
Input texture



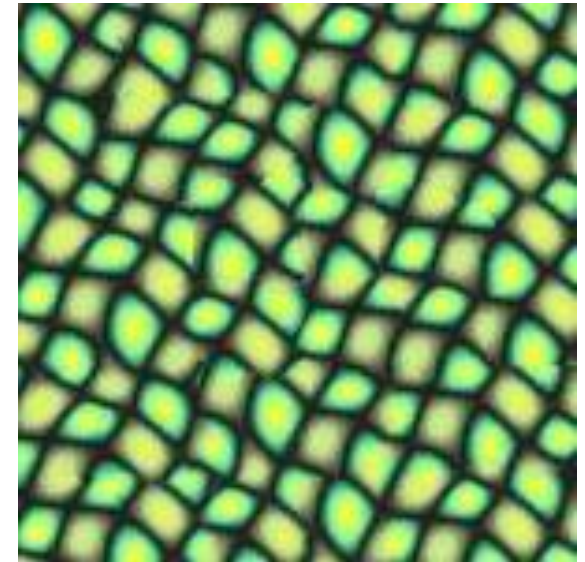
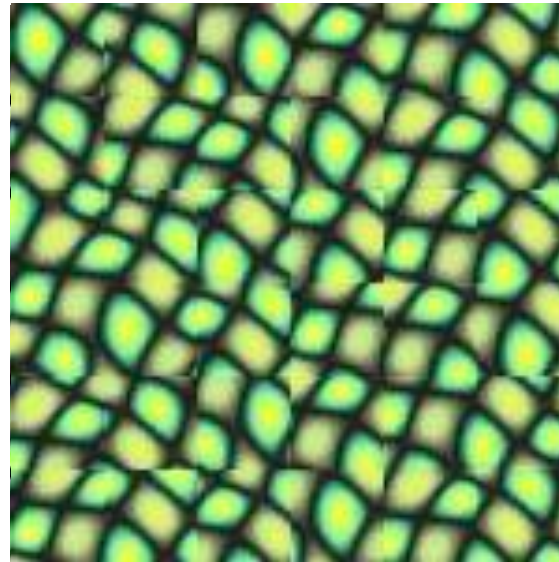
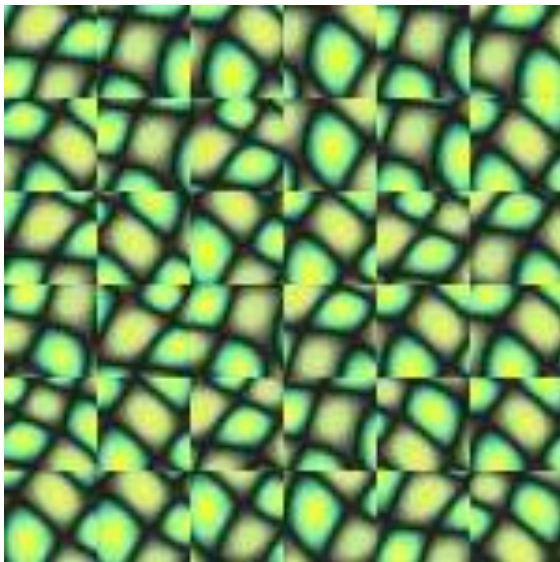
Random placement  
of blocks



Neighboring blocks  
constrained by overlap

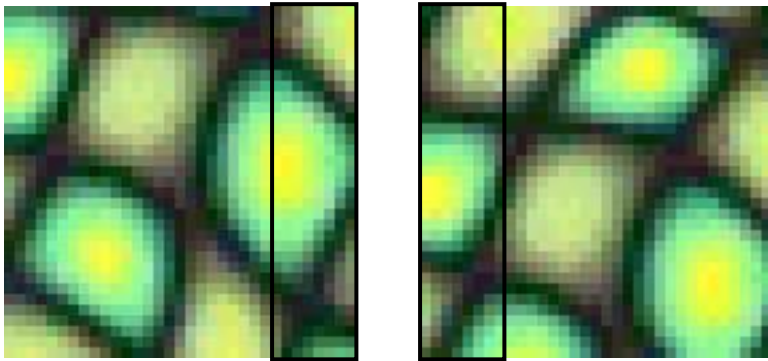


Minimal error  
boundary cut

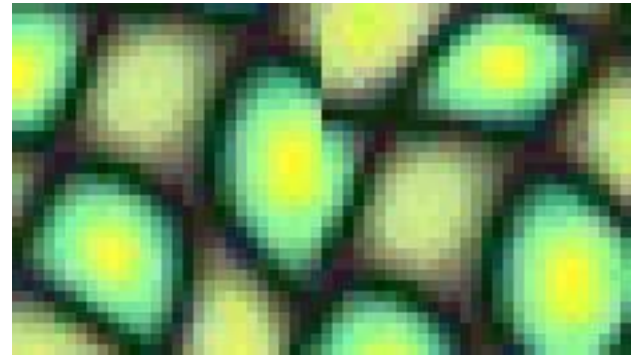


# Minimal error boundary

overlapping blocks

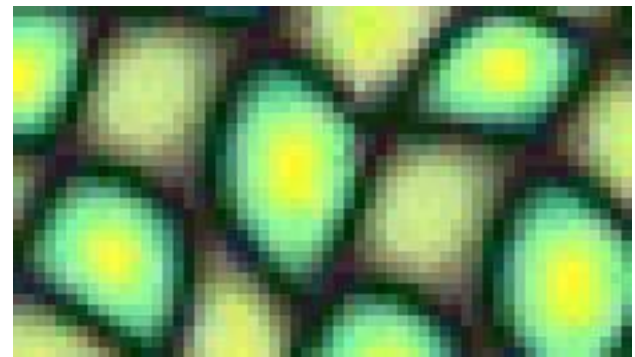


vertical boundary



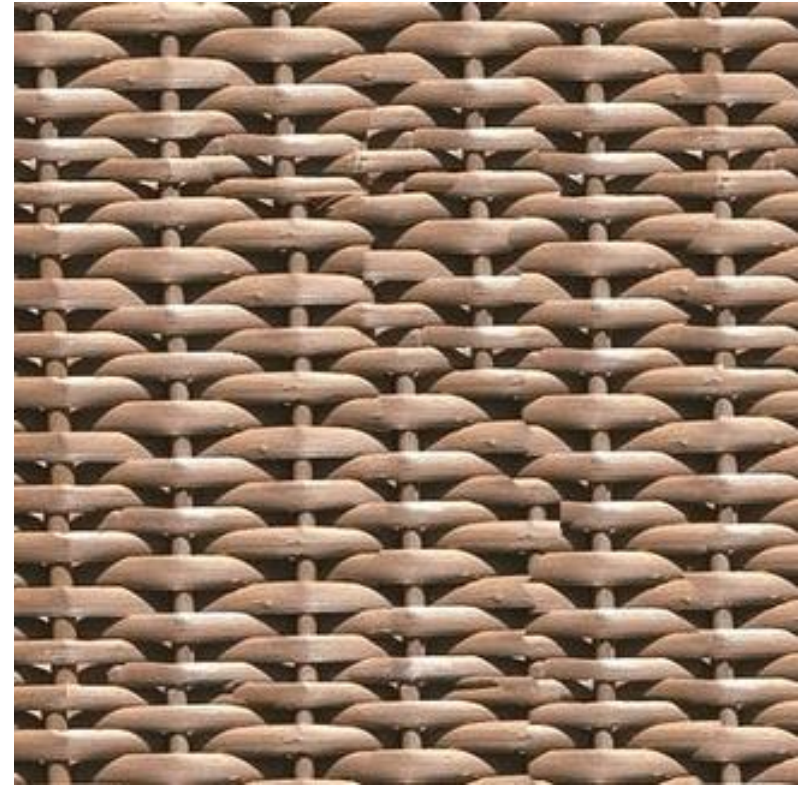
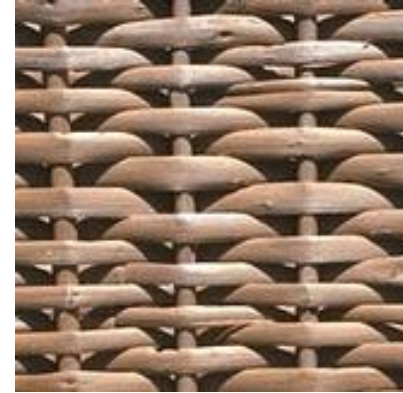
A diagram showing the calculation of overlap error. Two vertical blocks are shown side-by-side, with a minus sign between them, all enclosed in large square brackets. To the right of the brackets is a superscript '2'. This is followed by an equals sign and a vertical strip of the image showing the overlapping region, with a red jagged line indicating the boundary that minimizes the error.

overlap error

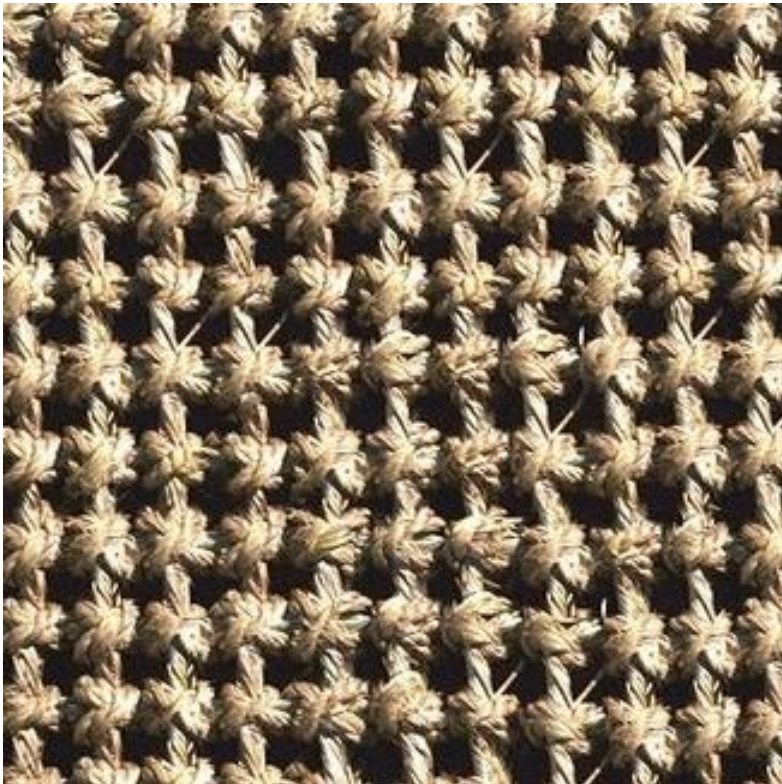


min. error boundary









# (Manual) texture synthesis in the media





# (Manual) texture synthesis in the media

