Automatic Generation of Local Repairs for Boolean Programs

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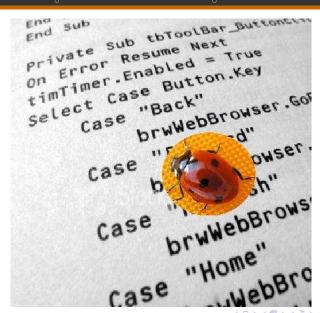
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- Motivation
- Solution Framework
- The Algorithm
- Conclusions





- Program synthesis
 - Correct by construction
 - Detailed specification
 - Hard
 - Also, legacy code?
- Program verification
- Program design + verification + fault localization + repair

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 - Long, unreadable error traces
 - Essentially manual debugging



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The repair problem

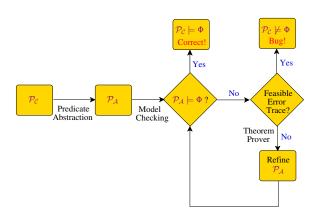
Given a program \mathcal{P} and a specification Φ such that $\mathcal{P} \nvDash \Phi$, transform \mathcal{P} to \mathcal{P}' such that $\mathcal{P}' \models \Phi$



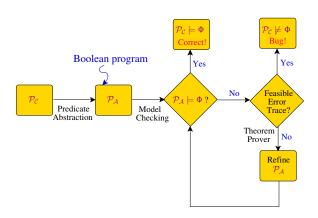
A specialization ...

- Program model: sequential Boolean programs [BallRaja00]
- Specifications: Hoare-style pre-conditions, post-conditions
- Permissible faults/repairs: incorrect Boolean expressions

Iterative (predicate) abstraction-refinement



Iterative (predicate) abstraction-refinement



What are Boolean programs?

- Abstractions of concrete programs
- Boolean variables
- Similar control flow
 - Conditionals, loops, procedures
- Nondeterminism
 - Some expressions may evaluate to either true or false



Example C program and Boolean program

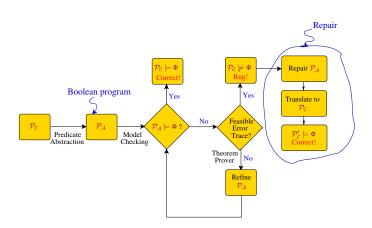
```
while (x>0) {
  x := x-1;
```

```
p: x > 0
while (p) {
  p := nd(0,1);
```

Why Boolean programs?

- Used as program abstractions for software verification
 - e.g., SLAM, BLAST, etc.

Repair of software programs



Why Boolean programs?

- Used as program abstractions for software verification
 - e.g., SLAM, BLAST, etc.
- Could be used to model some Boolean circuits

Program Syntax

- Prog $\mathcal{P} = (\mathcal{V}, \text{main}, \mathcal{F})$
 - $\mathcal{V} = \{v_1, v_2, \dots, v_t\}$: Boolean vars
 - main = (S, \mathcal{V}) , $S: s_1; s_2; \dots; s_n$: stmts
 - \mathcal{F} : functions, $f = (S_f, \mathcal{V}_{f,l})$
- Expr E: Boolean expr + nd(0,1)
 - e.g., $v_2 \wedge nd(0,1)$
- Prog stmt s_i: function call or return or.
 - assignment: v_i := E;
 - conditional: if (G) S_{if} else S_{else} ;
 - loop: while (G) S_{body} ;



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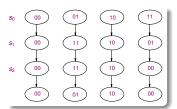
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Example Boolean program and its state diagram

```
swap(x, y) {
   x := x \oplus y;
      := x \wedge y;
   x := x \oplus y;
```



Specification

Total correctness: $\langle \varphi \rangle \mathcal{P} \langle \psi \rangle$

ullet Pre-condition φ : init states of ${\mathcal P}$

• Post-condition ψ : desired final states

 ${\mathcal P}$ is correct *iff* execution of ${\mathcal P}$, begun in any state in φ , terminates in a state in ψ , for *all* choices that ${\mathcal P}$ might make.



Specification

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Example Boolean program with its specification

φ : true

$$x := x \oplus y;$$

 $y := x \wedge y;$

$$x := x \oplus y;$$

$$\psi: y(f) \equiv x(0) \wedge x(f) \equiv y(0)$$

Fault/repair model

- Extra statement (needs deletion)
- Assignment: faulty LHS or RHS
- Conditional: faulty G or faulty statement in S_{if} or S_{else}
- Loop: faulty G or faulty statement in S_{body}



Fault/repair model

Motivation

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Our algorithm seeks to repair only the above kinds of faults.



The Algorithm

Algorithm sketch

- Annotation:
 - Propagate φ and ψ through statements
- Repair:
 - Use annotations to inspect statements for repairability
 - Generate repair if possible

 φ_0 : true

Incorrect Program

$$s_0: x' := x(0) \oplus y(0);$$

$$s_1: y' := x \wedge y;$$

$$s_2$$
: x(f) := x \oplus y;

$$\psi_3: x(f) \equiv y(0) \land y(f) \equiv x(0)$$

φ_0 : true

Incorrect Program

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Post-condition

propagation

φ_0 : true

Incorrect Program

$$S_0: x' := x(0) \oplus y(0);$$

$$S_1: y' := x \wedge y;$$

$$S_2: x(f) := x \oplus y;$$

 ψ_2 $\psi_3: x(f) \equiv y(0) \land y(f) \equiv x(0)$

propagation

Program annotation

φ_0 : true

Incorrect Program

$$s_0: x' := x(0) \oplus y(0);$$
 $s_1: y' := x \wedge y;$
 $s_2: x(f) := x \oplus y;$
 ψ_1
 ψ_2
 $\psi_3: x(f) \equiv y(0) \wedge y(f) \equiv x(0)$

Post-condition

4 m b 4 m b 4 m b 4 m b 4 m b 4 m b 4 m b 4 m b 4 m b 4 m b 4 m b 6 m b

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$$S_0: x' := x(0) \oplus y(0);$$

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Pre-condition propagation

 φ_0 : true

Incorrect Program

$$S_0: x' := x(0) \oplus y(0);$$

 $S_1: y' := x \wedge y;$
 $S_2: x(f) := x \oplus y;$

$$\psi_1$$

7 1

$$\psi_2$$

$$\psi_3: x(f) \equiv y(0) \wedge y(f) \equiv x(0)$$



Pre-condition propagation

 φ_3

Incorrect Program

 $\varphi_0: true$ $\left| \begin{array}{c} s_0: x' := x(0) \oplus y(0); \\ s_1: y' := x \wedge y; \end{array} \right|$

 s_2 : x(f) := x \oplus y;

 ψ_{1}

 ψ_2

 ψ_2

 $\psi_3: x(f) \equiv y(0) \wedge y(f) \equiv x(0)$

Motivation

Backward propagation of ψ_i through s_i

Weakest pre-condition $wp(s_i, \psi_i)$:

Set of all *input* states from which s_i is guaranteed to terminate in ψ_i for all choices made by s_i .

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To propagate ψ_i back through s_i , compute $wp(s_i, \psi_i)$.

Details ...

Assignments:
$$v_j := E$$
; $\psi_{i-1} = \psi_i [v_i' \to E$, for each $m \neq j, v_m' \to v_m]$

Rule for sequential composition:

$$wp((s_{i-1};s_i),\psi_i) = wp(s_{i-1},wp(s_i,\psi_i))$$

Conditionals: if (G)
$$S_{if}$$
 else S_{else} ; $\psi_{i-1} = (G \Rightarrow wp(S_{if}, \psi_i)) \land (\neg G \Rightarrow wp(S_{else}, \psi_i))$

Loops: while (G)
$$S_{body}$$
; $\psi_{i-1} = (\psi_i \wedge \neg G) \vee \bigvee_{l=1}^{L} wp(S_{body}, Y_{l-1} \wedge \neg G)$ where, $Y_0 = \psi_i$, $Y_k = wp(S_{body}, Y_{k-1} \wedge \neg G)$

Forward propagation of φ_{i-1} through s_i

Strongest post-condition $sp(s_i, \varphi_{i-1})$:

Smallest set of *output* states in which s_i is guaranteed to terminate, starting in φ_{i-1} , for all choices that s_i might make.

To propagate φ_{i-1} forward through s_i , compute $sp(s_i, \varphi_{i-1})$.



Example program annotation

Pre-condition propagation

φ₀: true

$$\varphi_1: x' \equiv (x(0) \oplus y(0)) \land y' \equiv y(0)$$

$$\varphi_2$$
: $x' \equiv (x(0) \oplus y(0)) \land y' \equiv (\neg x(0) \land y(0))$

$$\varphi_3: x' \equiv (x(0) \land \neg y(0)) \land y' \equiv (\neg x(0) \land y(0))$$

Incorrect Program

$$x' := x(0) \oplus y(0);$$

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Post-condition propagation

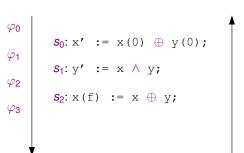
 ψ_0

 ψ_2

 ψ_3

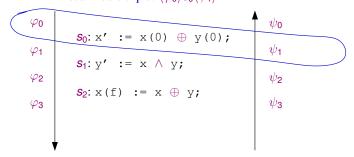
The Algorithm 00000

Local Hoare triples



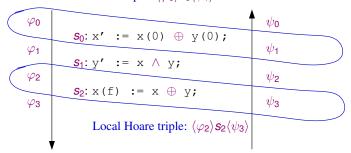
Local Hoare triples

Local Hoare triple: $\langle \varphi_0 \rangle s_0 \langle \psi_1 \rangle$



The Algorithm 00000

Local Hoare triple: $\langle \varphi_0 \rangle s_0 \langle \psi_1 \rangle$



A key lemma

 $\langle \varphi \rangle \mathcal{P} \langle \psi \rangle$ false \Leftrightarrow all local Hoare triples false. All local Hoare triples *false* ⇔ some local Hoare triple *false*.

The Algorithm 000000

What does this lemma mean for us?

If for some *i*, s_i can be fixed to make $\langle \varphi_{i-1} \rangle s_i \langle \psi_i \rangle$ *true*, then we have found \mathcal{P}' such that $\langle \varphi \rangle \mathcal{P}' \langle \psi \rangle$!

The Algorithm 0000000



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This is the basis for our repair algorithm.



- Choose promising order



- Choose promising order
- Query stmts in turn for repairability
 - If yes, Repair stmt, return modified program
 - If not, move to next stmt
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Query for assignment statement

- Let $\hat{s_i}$: $v_i := \exp r$ be potential repair for s_i

The Algorithm 0000000



Query for assignment statement

- Let $\hat{s_i}$: $v_i := \exp r$ be potential repair for s_i
- Use variable z to denote expr to enable formulation of Quantified Boolean Formula (QBF)

Query returns yes iff following QBF is true for some j: $\forall v_1(0) \forall v_2(0) \dots \forall v_t(0) \exists z \ \varphi_{i-1} \Rightarrow \psi_{i-1,i}$



Repair for assignment statement

- Let mth QBF be true
- Thus, $\hat{s_i}$: $\forall_m := z_i$

$$\forall v_1(0) \forall v_2(0) \dots \forall v_l(0) \exists z \ \underbrace{\varphi_{i-1} \Rightarrow \widehat{\psi}_{i-1,m}}_{\tau}$$

Motivation

The Algorithm 0000000

Repair for assignment statement

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The Algorithm 0000000

Motivation

Repair for assignment statement

- Let mth QBF be true
- Thus, $\widehat{s_i}$: $v_m := z_i$
- How do we obtain z in terms of variables in \mathcal{V} ?

$$\forall v_1(0) \forall v_2(0) \dots \forall v_t(0) \exists z \quad \underbrace{\varphi_{i-1} \Rightarrow \widehat{\psi}_{i-1,m}}_{T}$$

$$z = T|_{z=1} \text{ is a witness to QBF validity}$$



Example

Pre-condition propagation

 φ_0 : true

Motivation

$$\varphi_1: x' \equiv (x(0) \oplus y(0)) \land y' \equiv y(0)$$

$$\varphi_2$$
: $x' \equiv (x(0) \oplus y(0)) \land y' \equiv (\neg x(0) \land y(0))$

$$\varphi_3: x' \equiv (x(0) \land \neg y(0)) \land y' \equiv (\neg x(0) \land y(0))$$

Incorrect Program

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$$\psi_0: y(0) \equiv (x(0) \land \neg y(0)) \land x(0) \equiv (\neg x(0) \land y(0))$$

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: $y(0) \equiv x \oplus y \land x(0) \equiv y$

$$\psi_3$$
: $x(f) \equiv y(0) \land v(f) \equiv x(0)$

Post-condition propagation

QBF for
$$\widehat{s_2}$$
: $\forall x(0) \forall y(0) \exists z \ \varphi_1 \Rightarrow \widehat{\psi}_{1,y} = true$
Synthesized repair: $y' := x \oplus y$;

Motivation

Worst-case complexity is exponential in # Boolean predicates

In practice, most computations are efficient using BDDs

- Symbolic storage
- Efficient manipulation of pre-/post-conditions
- Efficient computation of fix-points
- Easy QBF validity checking
- Easy cofactor computation



Complexity

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Extant work

- Error localization based on analyzing error traces: [Zeller02], [Ball+03], [Shen+04], [Groce05]
- Repair of Boolean programs: [Griesmayer+06]
- Sketching: [Solar-Lezama⁺06]
- Repair of circuits using QBFs: [StaberBloem07]
- Dynamic repair of data structures: [DemskyRinard03]



- Novel application of Hoare logic
- Identification of program model, fault model and specification logic for tractable repair algorithm
- Framework for repair without prior fault localization
- Exponentially lower complexity than existing algorithm ([Griesmayer+06]) for our fragment

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The road ahead

- More general fault models
 - e.g., swapped statements, multiple incorrect expressions
- Boolean programs with arbitrary recursion
- Bit-vector programs
 - VHDL or Verilog programs
 - Software programs with small integer domains



Post-condition propagation

Assignments:

E contains nd(0,1):

Compute *conjunction* of wps over $v'_i := E|_0$ and $v'_i := E|_1$

```
Conditionals: G = nd(0, 1):
Compute wp(S_{if}, \psi_i) \wedge wp(S_{else}, \psi_i)
```

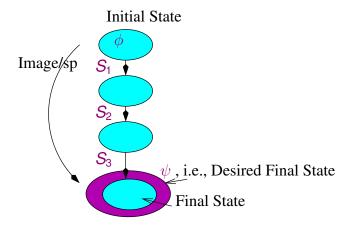
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Loops: G = nd(0,1):

\psi_{i-1} = false, or,

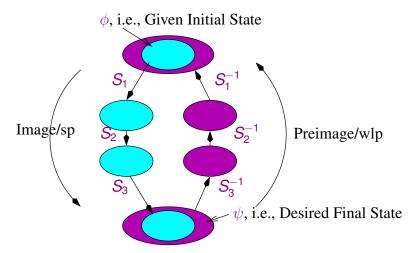
\psi_{i-1} = \bigwedge_{l=0}^{L'} Z_l

Z_0 = \psi_i, Z_k = wp(S_{body}, Z_{k-1})
```

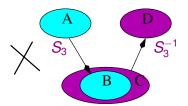
Proof of lemma

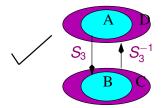


Proof



Proof





Functions

Non-recursive and tail-recursive functions

- Compute functions summaries
- Compute forward summary by sp propagation thru f
- Assume inital pre-condition is $\bigwedge_y (arg_y \equiv x_y)$
- Compute backward summary by wp propagation thru f
- Assume final post-condition is the return value
- Use summaries for propagation thru the call-site of f
- To repair, replace suspect expression by z
- Reannotate program before solving for z