

A Primal-Dual Resource Augmentation Analysis of a Constant Approximate Algorithm for Stable Coalitions in a Cluster

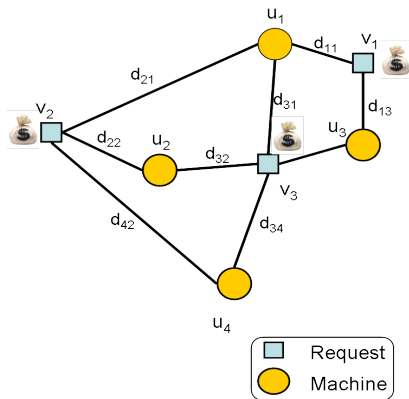
Nedialko B. Dimitrov and Indrajit Roy

Department of Computer Science
University of Texas at Austin

- Cluster Profit Problem
- Contributions
- Algorithm
- Clarifying Examples
- Analysis
- Conclusion

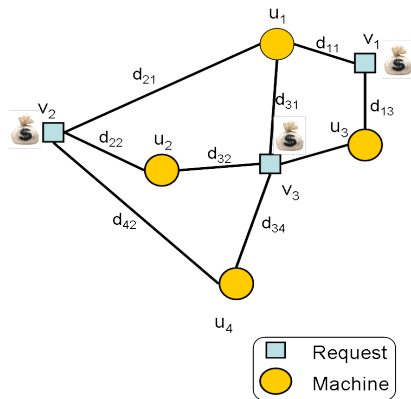
Cluster Profit Problem

- Highly parallelizable requests are present on some network nodes
- Each request is associated with a tuple (g, r) .
- The requester is willing to pay g to each machine that executes the request.



Cluster Profit Problem

- Machines must pay the request processing cost, r .
- Machines also pay the connection cost d_v to serve a request v .



Cluster Profit Problem

Objective

Find a profit maximizing assignment of machines to requests, such that each machine works on at most one request.

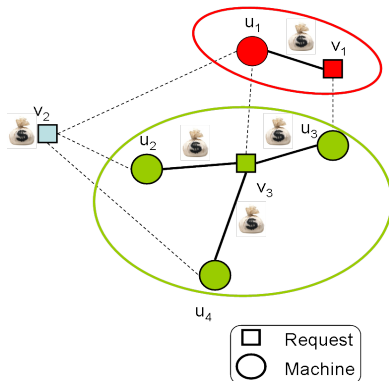


Figure: A possible assignment of machines to requests.

Application: Facility Location Variant

- Cluster Profit Problem (CPP) has more general interpretations
- The problem can be viewed as a variant of the Facility Location Problem
- Each facility is associated with a tuple (g, r)
- The number g signifies the quality of the facility
- Each customer is willing to pay g for being connected to a facility.
- Note that the standard Facility Location Problem has no quality values

Application: Coalition Formation

- CPP can also be viewed as an instance of a coalition formation problem.
- We would like to partition a set of agents and assign each resulting subset to some task
- Ensure that the assignment maximizes some utility function
- Consider tasks as the requests, the agents as the machines, and the utility function as the profit
- We would like the coalition to be resilient to selfish behavior of the system's participants !

- Cluster Profit Problem is NP-hard
- CPP can be viewed as a profit maximizing variant of facility location problem
- However facility location algorithms provide no guarantees on the profit
 - There could be assignments with high costs that yield high profits
 - So a facility location algorithm that finds lowest cost assignment provides no guarantees on the maximum profit earned

- We analyze this problem under **Resource Augmentation (RA)** [3]
- In resource augmentation a given algorithm competes with constant factor resource advantage over optimal algorithm
 - LRU caching analysis gives constant factor larger cache size [4]
- Our algorithm (ALG) operates on an instance where distances are shorter by a constant factor

- Consider a large company with millions of machines which the company does not own.
- The company suggests coalitions to the participating machines.
- If the machines follow the company's suggestion, they use the company's proprietary bandwidth to communicate.
- If they deviate, the machines must use some other method of communication and incur slightly larger communication costs.
- Resource augmentation captures this increase in communication costs

Result

We show ALG gives a constant RA approximation.

- ALG gains at least a constant fraction of the profit of an optimal algorithm
- ALG is given the resource advantage to operate on the same graph instance with edge lengths decreased by a constant factor

Result

We show ALG gives a constant RA approximation.

- ALG gains at least a constant fraction of the profit of an optimal algorithm
- ALG is given the resource advantage to operate on the same graph instance with edge lengths decreased by a constant factor

Result

We show ALG is constant RA stable to group deviations.

- Every subset of the machines gains at least a constant fraction of the profit they would gain under an optimal deviation
- Assume deviating increases communication costs by a constant factor

- Cluster Profit Problem
- Contributions
- **Algorithm**
- Clarifying Examples
- Analysis
- Conclusion

- Greedily find a subset of machines and a request such that the corresponding assignment gives the maximum profit density.

- Greedily find a subset of machines and a request such that the corresponding assignment gives the maximum profit density.

Definition

- Let $S = (v_S, \mathcal{A}_S)$, denote a tuple of a request, v_S , and a set of machines, \mathcal{A}_S
- The profit of S is $p_S = (|S| \cdot g_{v_S} - \sum_{u \in S} d_{u, v_S} - r_{v_S})$.
- The profit density of S is $p_S / |S|$.

- Greedily find a subset of machines and a request such that the corresponding assignment gives the maximum profit density.

Definition

- Let $S = (v_S, \mathcal{A}_S)$, denote a tuple of a request, v_S , and a set of machines, \mathcal{A}_S
- The profit of S is $p_S = (|S| \cdot g_{v_S} - \sum_{u \in S} d_{u, v_S} - r_{v_S})$.
- The profit density of S is $p_S / |S|$.
- Find $S^* = (v_{S^*}, \mathcal{A}_{S^*})$ with the highest profit density and assigns the machines in \mathcal{A}_{S^*} to work on the request v_{S^*} .

Primal

$$\max \quad \sum_{S \in \mathcal{T}} p_S \cdot x_S \quad (\text{P})$$

s. t.

$$\sum_{S \in \mathcal{T}: u \in S} x_S \leq 1 \quad \forall u \in \mathcal{U} \quad (1)$$

$$x_S \in \{0, 1\} \quad \forall S \in \mathcal{T} \quad (2)$$

- Let x_S be a binary variable denoting whether S has been picked

Dual

$$\min \quad \sum_{u \in \mathcal{U}} \alpha_u \quad (\text{D})$$

s.t.

$$\sum_{u \in \mathcal{U}} \max(0, g_v - \alpha_u - d_{u,v}) \leq r_v \quad \forall v \in \mathcal{V}. \quad (3)$$

$$\alpha_u \geq 0 \quad \forall u \in \mathcal{U}$$

- Interpret α_u as the profit made by the machine u after paying its distance costs and its share of the resource cost

Initialization Set each α_u to g_{\max} .

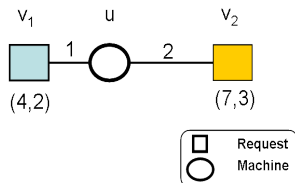
Loop Decrease α_u for each machine in $u \in \mathcal{U}$ at a uniform rate until one of the following happens:

- If α_u becomes zero or \mathcal{U} is empty, then we stop the algorithm.
- If some inequalities of type become tight, pick one arbitrarily. Say we picked the inequality corresponding to v . Assign all machines in $\mathcal{A} = \{u \mid g_v - \alpha_u - d_{u,v} \geq 0, u \in \mathcal{U}\}$ to request v . Set $r_v = 0$ and $\mathcal{U} = \mathcal{U} - \mathcal{A}$ and proceed with the uniform decrease once again.

Example

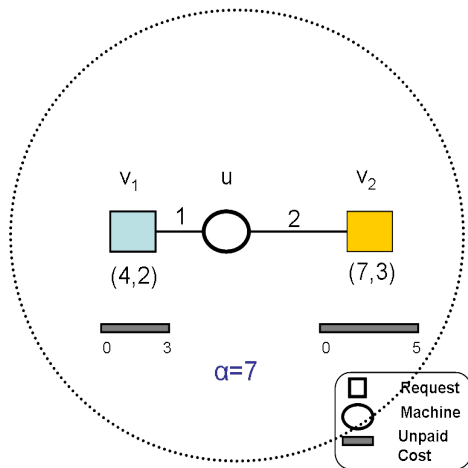
- A single machine u and two requests v_1, v_2

Request	Payment	Cost	Distance from u
v_1	4	2	1
v_2	7	3	2



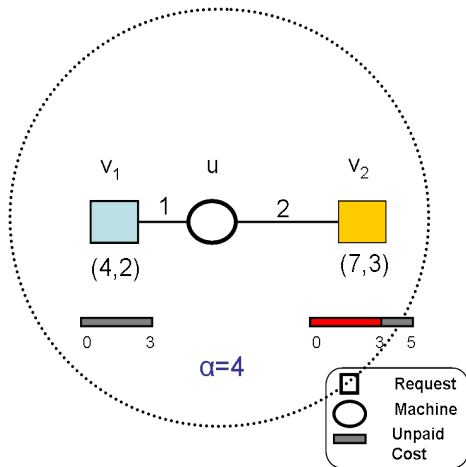
Algorithm: Example

- Initialize a ball of radius 7 around u (i.e. $\alpha = g_{\max} = 7$)



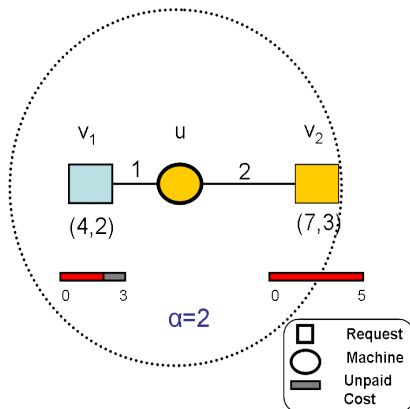
Algorithm: Example

- At $\alpha = 4$, 60% of the costs involved with servicing v_2 has been paid



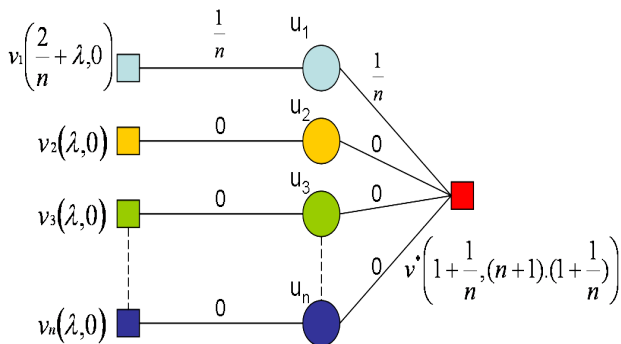
Algorithm: Example

- At $\alpha = 2$ the u has paid all the costs of v_2 and hence gets assigned.
- Total profit is 2
- Assigning u to v_1 would give a profit of 1.



- Cluster Profit Problem
- Contributions
- Algorithm
- **Clarifying Examples**
- Analysis
- Conclusion

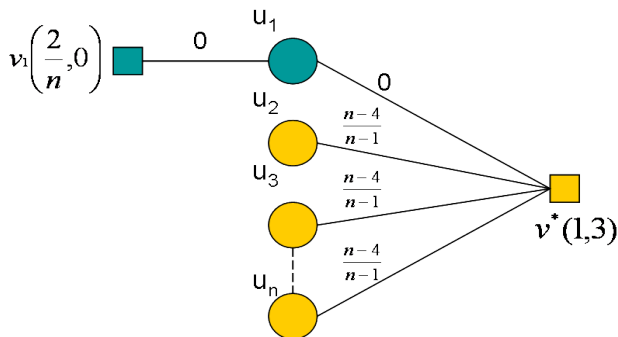
Clarifying Example 1



- ALG assigns machine u_i to request v_i . Total profit is $\frac{1}{n} + n \cdot \lambda$ ($\lambda \rightarrow 0$).
- If all machines are assigned to request v^* , then the total profit is 1
- In this case ALG has an approximation ratio of $\Theta(n)$

- Observation: v^* has high resource cost and would require almost all machines to work on it
- Need to constrain the values of resource cost
- Assume requester pays at least the resource cost if ω machines work on the request ($r_v \leq \omega g_v$)

Clarifying Example II



- ALG assigns u_1 to request v_1 and remaining machines to v^* . Total profit is $\frac{2}{n}$.
- If all machines are assigned to v^* then total profit is 1
- Again ALG has an approximation ratio of $\Theta(n)$

- Observation: If distances are θ -factor shorter then ALG can recover $\frac{(\theta-1)(n-4)}{\theta} + \frac{2}{n}$ profit in this instance
- Previous examples motivate the need for another constraint
- If ALG operates on a graph G with distance metric d , we compare with OPT operating on a graph G' with distance metric $\theta \cdot d$
- These constraints help us prove meaningful bounds

- Cluster Profit Problem
- Contributions
- Algorithm
- Clarifying Examples
- **Analysis**
- Conclusion

- Our analysis is based on the technique of *factor revealing* LP as used by Jain et. al. [1]

Definition

- Let P be the problem, π the corresponding variables and OPTVAL_P its optimal values
- Let D be the dual problem, and α the variables
- Let P^L and D^L denote the primal and relaxed dual pair for the resource hampered instance

General approach of primal-dual algorithms:

- Find real-valued dual variables α' feasible in D
- Find corresponding integer-valued primal variables π' feasible in P s.t.
 $D(\alpha') \leq \gamma \cdot P(\pi')$
- This gives γ -approximate algorithm since
 $P(\pi') \leq \text{OPTVAL}_P \leq D(\alpha') \leq \gamma \cdot P(\pi')$

Using factor-revealing LP technique:

- We find an π' feasible in P and α' which is infeasible in D s.t.
 $D(\alpha') = P(\pi')$.
- We attempt to find a γ , such that $\gamma\alpha'$ is feasible in D .
- We then have $D(\gamma\alpha') = \gamma D(\alpha') = \gamma P(\pi')$,

Steps for the resource augmented version:





- Find γ such that $\gamma\alpha'$ is feasible in the optimal algorithm's D^L .
- We can then show
$$\text{OPTVAL}_{\text{PL}} \leq D^L(\gamma\alpha') = \gamma D^L(\alpha') = \gamma D(\alpha') = \gamma P(\pi')$$

Theorem

Let ALG finish with variables α . Then, there exists a constant γ , only dependent on the constants ω and θ , such that $\gamma\alpha$ is feasible in D^L .

- We formalize the Cluster Profit Problem that has applications as profit maximizing facility location and coalition formation problem.
- We give an algorithm that gives a constant RA approximation.
- We show our algorithm is constant RA stable to group deviations.

References

-  K. Jain, M. Mahdian, E. Markakis, A. Saberi, and V. V. Vazirani.
Greedy facility location algorithms analyzed using dual fitting with factor-revealing lp.
J. ACM, 50(6):795–824, 2003.
-  M. Pál and E. Tardos.
Group strategy proof mechanisms via primal-dual algorithms.
In *Proceedings of the 44th annual IEEE Symposium on Foundations of Computer Science*, pages 584–593, October 2003.
-  Cynthia A. Phillips, Cliff Stein, Eric Torng, and Joel Wein.
Optimal time-critical scheduling via resource augmentation (extended abstract).
In *STOC '97: Proceedings of the twenty-ninth annual ACM symposium on Theory of computing*, pages 140–149, 1997.
-  Daniel D. Sleator and Robert E. Tarjan.
Amortized efficiency of list update and paging rules.

Thank You !

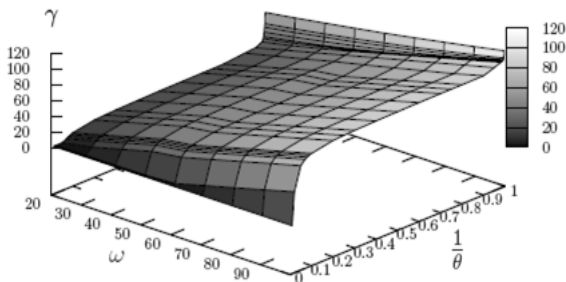


Figure: The exact competitiveness factor, γ , as a function of the parameters ω and θ . In the experiments, ω was varied between 20 and 100, while θ was varied between 0 and 1.

- As θ goes to zero, γ approaches one.
- As θ goes to one, γ approaches infinity.
- For the mid-ranges of θ , γ varies almost linearly with ω .

Extra Slides: Analysis

$$z_k = \min_{\mu} \max_{g,r,\alpha,d} \mu$$

s.t.

$$kg - r - \theta \sum_{i=1}^k d_i \leq \mu \sum_{i=1}^k \alpha_i$$

$$\alpha_i \leq \alpha_{i-1} \quad \forall i \in \{2, \dots, k\}$$

$$\alpha_i \leq \alpha_j + d_i + d_j \quad \forall i, j \in \{1, \dots, k\}$$

$$\theta \mathbf{d} \leq \mathbf{g} \quad \forall i \in \{1, \dots, k\}$$

$$\mathbf{r} \leq \omega \cdot \mathbf{g}$$

$$\sum_{j=i}^k \max(0, g - \alpha_j - d_j) \leq r \quad \forall i \in \{1, \dots, k\}$$

$$\alpha_i, d_i, r, g \geq 0 \quad \forall i \in \{1, \dots, k\}$$

- z_k represents the worst approximation factor given that at most k machines contribute to the resource cost of any request

Definition

A payoff vector π is γ -RA stable under a transformation L if it satisfies the following inequalities:

Stability inequalities: $\sum_{a \in \mathcal{A}} \pi_a \geq \frac{1}{\gamma} V^{L(x)}(\mathcal{A})$ for all $\mathcal{A} \subseteq \mathcal{P}$

Conservation inequality: $\sum_{a \in \mathcal{P}} \pi_a \leq V^x(\mathcal{P})$.

- $V(\mathcal{A})$ is the maximum amount of profit the machines in \mathcal{A} can achieve working alone.

Lemma (Main Lemma)

If a vector α is feasible in the non-integer-constrained relaxed dual for $V^L(\mathcal{P})$, it is also feasible in the non-integer-constrained relaxed dual for $V^L(\mathcal{A})$ for any $\mathcal{A} \subseteq \mathcal{P}$.