CS395T: Automated Logical Reasoning

Simplification of SMT Formulas

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Overview

- ightharpoonup Last lecture: Learned about DPLL($\mathcal T$) framework to solve SMT formulas
- However, in some applications, solving formula is not enough; also need to find compact representation
- Already saw one example of this idea in propositional logic: binary decision diagrams (BDDs)
- ► This lecture: How to simplify SMT formulas

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Static Program Analysis and SMT

- Heavy user of SMT formulas: static analysis and verification systems
- Static analysis proves properties about programs by analyzing source code (i.e., does not execute program)
- Many static analysis techniques use SMT formulas to symbolically represent program states
- Deciding whether a program procerty holds is achieved by checking satisfiability/validity of SMT formulas
- ► SMT formulas generated by static analysis are very large but typically extremely redundant ⇒ scalability problems

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Motivating Example

 $op = 0 \lor (op \neq 0 \land op = 1) \lor (op \neq 0 \land op \neq 1 \land op \neq 2) \lor (op \neq 0 \land op \neq 1 \land op \neq 2) \lor (op \neq 0 \land op \neq 1 \land op \neq 2 \land op = 3 \land y \neq 0) \lor (op \neq 0 \land op \neq 1 \land op \neq 2 \land op \neq 3)$

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Take-Away Message

- ▶ If we automatically generate constraints from source code, resulting formulas are huge, but very redundant
- To allow analyses to run on large software, necessary to keep size of formulas under control
- Thus, want to find compact representation of SMT formulas called simplified form
- lack Simplified form of formula F should be equivalent to F and should not contain redundancies
- Furthermore, unlike BDDs, simplified form should not cause blow-up in formula size (in fact, should never be larger!)

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Simplified Form

- ▶ Goal: To give algorithm to convert each SMT formula F to a simplified form F' with following guarantees:
 - 1. F' logically equivalent to F (i.e., $F' \Leftrightarrow F$)
 - 2. F' not redundant
 - 3. size of $F' \leq \text{size of } F$
- Our algorithm will deal with qff formulas over any decidable first-order theory and that are in NNF
- ► First, need to be precise about what we mean by redundancy and size of formula

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Atomic Formula vs. Leaf

- ► An atomic formula is a formula without ∧, ∨
- ► Each syntactic occurence of an atomic formula is called leaf
- ► How many leaves does this formula have? 3

$$\neg f(x) = 1 \lor (\neg f(x) = 1 \land x + y \le 1)$$

Leaves:

$$\underbrace{\neg f(x) = 1}_{L_1} \lor \underbrace{(\neg f(x) = 1}_{L_2} \land \underbrace{x + y \le 1}_{L_3}))$$

▶ Size of formula ϕ is number of leaves ϕ contains

 $\phi^+(L)$ and $\phi^-(L)$

- lacktriangle Define over and underapproximations of formula ϕ w.r.t leaf L
- $ightharpoonup \phi^+(L)$ obtained by replacing L with \top in ϕ and constant folding resulting formula (i.e., removing \top, \bot)
- ▶ Consider again formula ϕ :

$$\phi: \underbrace{\neg f(x) = 1}_{L_1} \lor \underbrace{(\neg f(x) = 1}_{L_2} \land \underbrace{x + y \leq 1}_{L_3})$$

- ▶ What is $\phi^+(L_1)$? \top
- $\phi^-(L)$ obtained by replacing L with \perp in ϕ and constant folding resulting formula (i.e., removing \top, \bot)
- ▶ What is $\phi^-(L_2)$? $\neg f(x) = 1$

Properties of ϕ^+ and ϕ^-

- ▶ What is the relationsip between the size of $\phi^+(L)$ and ϕ ? $size(\phi^+(L)) < size(\phi)$
- ▶ Similarly, $size(\phi^-(L)) < size(\phi)$
- $\phi^+(L)$ overapproximates ϕ because $\phi \Rightarrow \phi^+(L)$
- ▶ Similarly, $\phi^-(L)$ underapproximates ϕ because $\phi^-(L) \Rightarrow \phi$

Redundancy of Leaves

- ▶ If $\phi^+(L) \Rightarrow \phi$, then leaf L is called non-constraining
- ▶ Thus, if L is non-constraining, we have $\phi^+(L) \Leftrightarrow \phi$
- ightharpoonup In this case, L does not "constrain" the formula can replace it with \top to get equivalent formula
- ▶ If $\phi \Rightarrow \phi^-(L)$, then leaf L is called non-relaxing
- ▶ Hence, if L is non-relaxing, we have $\phi^-(L) \Leftrightarrow \phi$
- ▶ A leaf *L* is redundant if it is either non-constraining or non-relaxing
- lacktriangle Such a leaf is redundant because can be replaced with \top or \bot to obtain smaller, but equivalent formula

Example

▶ Consider again formula ϕ :

$$\phi: \ \underbrace{\neg f(x) = 1}_{L_1} \lor (\underbrace{\neg f(x) = 1}_{L_2} \land \underbrace{x + y \leq 1}_{L_3})$$

- ▶ Is L_1 redundant? no
- ▶ Is L_2 redundant? yes because non-relaxing
- ▶ Is L_3 redundant? yes, both non-constraining and non-relaxing

Simplified Form

- ▶ Fact: If no leaf in ϕ is redundant, can't obtain smaller equivalent formula by replacing any subset of leaves by \top, \bot
- Thus, a formula with no redundant leaves is said to be in simplified form
- ▶ Goal: Given formula ϕ , we want to compute simplified form of ϕ by removing all redundant leaves in $\boldsymbol{\phi}$
- ▶ Resulting simplified form equivalent to original formula but smaller and has no redundancy

Properties of Simplified Form

- A formula in simplified form is satisfiable iff it is not syntactically false.
- Proof: Suppose this is not true (i.e., formula unsat, but simplified form not false).
- ▶ Now consider replacing every leaf by ⊥. Resulting formula: ⊥
- $\,\blacktriangleright\,$ Since formula is unsat, resulting formula \bot equivalent to original formula
- ▶ Thus, formula could not have been in simplied form.

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Properties of Simplified Form, cont

- ▶ A formula in simplified form is valid iff it is syntactically true.
- Thus, if formulas are kept in simplified form, deciding satisfiability and validity just a syntactic check
- Recall: A representation is called canonical if two equivalent formulas have same representation
- ▶ Is simplified form a canonical representation? No
- ▶ Formulas $a \land (b \lor c)$ and $(a \land b) \lor (a \land c)$ are equivalent and both in simplified form, but not syntactically identical
- ► Thus, if we keep formulas in simplified form, checking equivalence is not a syntactic test

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Simple Algorithm to Compute Simplified Forms

- ▶ Definition of simplified form suggests very simple algorithm:
 - 1. Pick any leaf L in formula ϕ
 - 2. Compute $\phi^+(L)$ by replacing L with \top
 - 3. Test if $\phi^+(L) \Rightarrow \phi$ If so, $\phi := \phi[\top/L]$
 - 4. Otherwise, compute $\phi^-(L)$
 - 5. Test if $\phi \Rightarrow \phi^-(L)$ If so, $\phi := \phi[\perp/L]$
 - 6. Repeat until no leaf can be replaced

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Discussion of Simple Algorithm

- ▶ Algorithm requires checking $\phi^+(L) \Rightarrow \phi$ and $\phi^-(L) \Rightarrow \phi$
- ▶ What is the size of formula $\phi^+(L) \Rightarrow \phi$? twice as large as ϕ
- Thus, algorithm requires repeatedly checking validity of formulas twice as large as original formula
- ▶ But actually we can do much better!
- ▶ Idea: Can determine if leaf is redundant by querying validity of formula no larger than ϕ
- ► Key concept: critical constraint

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Critical Constraint

- lacktriangle For each leaf L, compute critical constraint C(L)
- Critical constraint has following properties:
 - 1. C(L) is never larger than original formula
 - 2. L is non-constraining iff $C(L) \Rightarrow L$
 - 3. L is non-relaxing iff $C(L) \Rightarrow \neg L$

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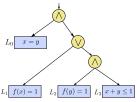
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Computing Critical Constraint

- To compute critical constraint for each leaf, (conceptually) represent formula as tree
- ► For instance, consider formula:

$$x = y \land (f(x) = 1 \lor (f(y) = 1 \land x + y \le 1))$$

▶ Represent formula as tree:



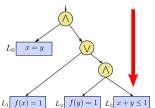
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Computing Critical Constraint, cont

- ▶ Compute critical constraint for each tree node
- ▶ Do this top-down
- ► Start with root node
- Recursively compute critical constraint for each node using critical constraint for parent
- ► Base case: Initialize critical



constraint of root to true

Computing Critical Constraint, cont

- ▶ Inductive case: Let *N* be any non-root node.
- ▶ N has parent P with critical constraint C(P)
- ▶ N has sibling S with formula rooted at S being F_S
- ► There are two cases to consider:
 - 1. If P is an \wedge node, then:

$$C(N) = C(P) \wedge F_S$$

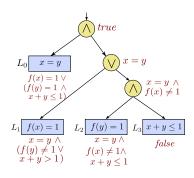
2. If P is an \vee node, then:

$$C(N) = C(P) \land \neg F_S$$

Critical Constraint Example

► Consider again the formula

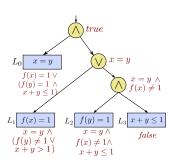
$$x = y \land (f(x) = 1 \lor (f(y) = 1 \land x + y \le 1))$$



Using Critical Constraint to Check Redundancy

- ▶ Recall: Can use critical constraint to check redundancy of leaf
- ▶ Leaf L is non-constraining iff $C(L) \Rightarrow L$
- ▶ Leaf L is non-relaxing iff $C(L) \Rightarrow \neg L$
- ▶ Thus, if $C(L) \Rightarrow L$, we get smaller, equivalent formula when we replace L with boolean constant \top
- ▶ If $C(L) \Rightarrow \neg L$, we get smaller, equivalent formula when we replace L with boolean constant \bot

Example



- ▶ Does $C(L_0)$ imply L_0 or $\neg L_0$? no, so L_0 not redundant
- ▶ Does $C(L_1)$ imply L_1 or $\neg L_1$? no, so L_1 not redundant
- ▶ Does $C(L_2)$ imply L_2 or $\neg L_2$? implies $\neg L_2$, so L_2 non-relaxing
- ▶ Does $C(L_3)$ imply L_3 or $\neg L_3$? implies both, so L_3 non-constraining and non-relaxing

Putting it All Together

- \blacktriangleright We want an algorithm to convert any formula ϕ in NNF to simplified form
- lacktriangle To do this, represent ϕ as tree and formulate auxiliary algorithm simplify(N, C)
- ightharpoonup First arg. of simplify is subformula represented by tree node N
- lacktriangle Second argument C is critical constraint of N
- ▶ The output of simplify(N, C) is a new tree representing simplified form of subformula rooted at N

Putting It All Together, cont.

- ▶ If we have such an auxiliary algorithm simplify(N, C), how do we compute simplified form of ϕ ?
- \blacktriangleright Represent ϕ as tree with root R and call simplify(R, true)
- ▶ Suppose this yields new tree rooted at R'.
- ightharpoonup Simplified form of ϕ is simply R' represented as formula
- ► Thus, if we have auxiliary algorithm simplify(N,C), this immediately gives way to simplify any formula ϕ in NNF

Full Algorithm

- * Recursive algorithm to compute simplified form.
- * N: current subformula, C: critical constraint of N

simplify(N, C)

- ▶ Base case: If N is a leaf:
 - ▶ If $C \Rightarrow N$ return true /* Non-constraining */
 - ▶ If $C \Rightarrow \neg N$ return false /* Non-relaxing */
 - Otherwise, return N

Full Algorithm, cont

simplify(N, C)

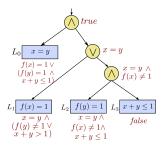
- ▶ Inductive case 1: If N is an \land node with children N_1, N_2 :
 - $N_1' = \text{simplify}(N_1, C \wedge N_2)$
 - $N_2' = \text{simplify}(N_2, C \wedge N_1')$
 - $N_1 := N_1', N_2 := N_2'$; repeat until $N_1' = N_1$ and $N_2' = N_2$
 - ▶ If N'_1 or N'_2 is false, return false
 - ▶ If N_1' and N_2' is true, return true
 - ▶ Else if N'_1 (resp. N'_2) is true, return N'_2 (resp. N'_1)
 - lacktriangle Else return new subtree with root \wedge and children N_1' and N_2'

Full Algorithm, cont

simplify(N, C)

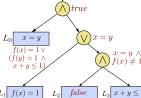
- ▶ Inductive case 2: If N is an \vee node with children N_1, N_2 :
 - $N_1' = \text{simplify}(N_1, C \land \neg N_2)$
 - $N_2' = \text{simplify}(N_2, C \land \neg N_1')$
 - $N_1 := N_1', N_2 := N_2'$; repeat until $N_1' = N_1$ and $N_2' = N_2$
 - ▶ If N_1' or N_2' is true, return true
 - ▶ If N'_1 and N'_2 is false, return false
 - ▶ Else if N'_1 (resp. N'_2) is false, return N'_2 (resp. N'_1)
 - ▶ Else return new subtree with root \lor and children N_1' and N_2'

Example



- ► Simplify children of topmost ∧
- $ightharpoonup L_0$ leaf, but stays the same
- ► To simplify ∨ node, need to simplify children
- ullet L_1 leaf, but stays unchanged
- To simplify bottom \land node, need to simplify L_2, L_3
- lacktriangle For L_2 , $C(L_2) \Rightarrow \neg L_2$, thus replace with: false

Example, cont



- ▶ Now, since child of ∨ node changed, re-simplify \mathcal{L}_1
- New critical constraint: x = y
- ▶ Does L_1 change? no
- $\bigcap_{f(x) \neq 1}^{x-y}$ Result of simplify \lor node: f(x) = 1
- Now simplify L_0 again, new critical constraint: f(x) = 1 $x = y \land$ $(f(y) \neq 1 \lor$
 - ▶ Does L_0 change? no
 - ▶ Simplified form: $x = y \land f(x) = 1$

Discussion of Algorithm

- ► In simplify algorithm, we resimplify children of connectives if any of the siblings change. Why is this necessary?
- Because critical constraint changes, so it might expose new simplification opportunities
- $\qquad \qquad \textbf{Example:} \ \underbrace{x \neq 1}_{L_1} \land \underbrace{\underbrace{(x \leq 0}_{L_2} \lor \underbrace{x > 2}_{L_3} \lor \underbrace{x = 1}_{L_4})}_{N}$
- ▶ Critical constraint for L_1 : $x \le 0 \lor x > 2 \lor x = 1$
- ▶ Does it imply L_1 or $\neg L_1$? no
- \triangleright So, initially can't eliminate L_1

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Discussion of Algorithm, cont.

$$\underbrace{x \neq 1}_{L_1} \land \underbrace{\left(x \leq 0 \lor x > 2 \lor x = 1\right)}_{N}$$

- ► Critical constraint for N: $x \neq 1$
- ▶ Result of simplifying N is $x \le 0 \lor x > 2$
- \blacktriangleright So, if we wouldn't resimplify L_1 , result would be

$$x \neq 1 \land (x \leq 0 \lor x > 2)$$

- ▶ Is this in simplified form? no
- ▶ If we resimplify L_1 , $C(L_1) \Rightarrow L_1$, thus replace with true
- ▶ Actual simplified form: $x \le 0 \lor x > 2$

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Discussion of Algorithm, cont.

- As example illustrates, need to resimplify subformulas as long as siblings change
- ▶ Otherwise, resulting formula might not be in simplified form
- To compute simplified form, algorithm makes at most 2n² validity queries
- However, these validity queries are not independent of each other, so we can optimize

Optimization

- Specifically, all formulas whose validity are queried have same set of leaves
- ▶ How can we use this to our advantage?
- Recall: When solving SMT formulas in DPLL(T) framework, we learn theory conflict clauses
- \blacktriangleright Theory conflict clauses are valid modulo ${\mathcal T}$ and prevent wrong assignments to boolean structure
- Since our formulas have same set of leaves, a theory conflict clause we learned during previous validity query will be useful for next query!

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Optimization, cont

- Thus, if we reuse theory conflict clauses, solving SMT formula should become as fast as solving SAT formula
- ▶ In practice, this optimization makes a huge difference!
- Using this optimization, overhead of simplification over solving observed to be sub-linear (logarithmic)
- Simplifying is more expensive than just solving, but in practice, not quadratically worse

Benefit of Simplification

- If simplifying formula more expensive than solving, why bother simplifying?
- Recall: Motivation for simplification is applications that incrementally build formulas from existing formulas, such as program analysis
- ► In these kinds of applications, redundancies accumulate as formula is built from existing formulas
- ► Goal of simplification: Prevent accumulation of redundancies so that formulas at every step are managable in size
- ► Thus, to evaluate benefit of simplification, need to compare running times of applications that only solve vs. simplify

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Benefit of Simplification in Static Analysis

- We evaluated benefit of simplification in the context of static analysis
- Used a static analysis tool, Compass, that incrementally builds formulas from existing formulas
- Ran Compass on 811 benchmarks, totaling 173,000 LOC to verify memory safety
- ► Compared running time of analysis runs that use simplification with runs that do not
- ► In former case, every time analysis queries satisfiability of formula, we simplify formula and give back this simplified form
- ▶ In latter case, just give yes/no answer

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- ► In applications that incrementally build formulas, simplification might be very beneficial
- ► Looked at one application of simplified forms: static analysis
- Haven't applied this idea to other domains, but could have other interesting applications
- ▶ How does simplified form compare with BDDs?
- Guaranteed not to cause increase in formula size (often desirable)
- ► But it's not a canonical representation, so equivalence checking is not syntactic

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