CS389L: Automated Logical Reasoning

Lecture 8: Introduction to Theorem Proving

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Review

- ▶ What are some decidable fragments of FOL?
- ► What is compactness?
- ▶ What is a property that cannot be expressed in FOL?

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First-Order Theorem Provers

- ▶ A first-order theorem prover is a computer program that proves the validity of formulas in first-order logic.
- ► Since validity in FOL is only semi-decidable, first-order theorem provers are not guaranteed to terminate
- ▶ Despite this limitation, many automated theorem provers exist and are useful: Vampire, SPASS, Otter, . . .
- ► There are even annual competitions between these theorem provers! (just Google "CADE ATP competition")

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Theorem Provers and Mathematical Theorems



- ► First-order theorem provers have been used to prove some mathematical theorems not previously proven by humans.
- ▶ Robbins conjecture (1933): Mathematician Herbert Robbins conjectured that a group of axioms he came up with are equivalent to boolean algebra.
- Neither he nor anyone else could prove this for decades.

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Robbins Conjecture and Automated Theorem Proving

- ▶ 1996: Conjecture eventually proven by first-order theorem prover EQP after 8 days of search!
- ► That a computer can prove theorems that humans could not was shocking
- ► The automated proof of Robbins conjecture even appeared as New York Times article!
- ► Not the only success story: Otter used by mathematician Ken Kunnen to prove results in quasi-group theory



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Overview

- ► Today's lecture and next lecture: Discuss basic principles underlying first-order theorem provers
- ► The basis underlying all theorem provers today is the principle of first-order resolution
- ► First-order theorem provers prove formulas unsatisfiable by showing there is a resolution refutation for that formula

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Recall: Propositional Resolution

► Recall: Resolution in propositional logic:

$$C_1: (l_1 \vee \ldots p \ldots \vee l_k) \qquad C_2: (l'_1 \vee \ldots \neg p \ldots \vee l'_n)$$

Propositional resolution: Deduction of a new clause C_3 , called resolvent:

$$C_3: (l_1 \vee \ldots \vee l_k \vee l'_1 \vee \ldots \vee l'_n)$$

- ► First-order resolution is the same basic principle, but a little bit more involved
 - ► How to obtain clauses given FOL formula?
 - How do we deal with predicates containing syntactically different terms?

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First-Order Resolution Prerequisites

- ➤ To perform resolution in first-order logic, we need two new ingredients:
 - 1. Unification: Which expressions can be made identical?
 - 2. Clausal form: A new normal form for FOL
- ▶ Start with unification; then talk about clausal form

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Unification

- ▶ Unification: problem of determining if two expressions can be made identical by appropriate substitutions for their variables
- ► Substitution: finite mapping from variables to terms
- **Example:** Can expressions p(x) and p(a) be unified?
- ightharpoonup Can p(a) and p(b) be unified?
- We'll write $e\sigma$ to denote the application of substitution σ to expression e
- ▶ What is $p(x)[x \mapsto a]$?

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Unification

- A substitution is a unifier for two expressions e and e' if $e\sigma$ is syntactically identical to $e'\sigma$
- ▶ Two expressions e and e' are unifiable iff they have a unifier; otherwise non-unifiable.
- **Example:** Are p(x, y) and p(a, v) unifiable?
- ► A unifier:
- **Example 2:** Are p(x, x) and p(a, b) unifiable?
- **Example 3:** Are p(x) and p(f(x)) unifiable?

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Non-Uniqueness of Unifiers

- ► If two expressions are unifiable, they don't necessarily have a unique unifier.
- ightharpoonup Example: p(x,y) and p(a,v)
- ▶ Unifier 1: $[x \mapsto a, y \mapsto b, v \mapsto b]$
- ▶ Unifier 2: $[x \mapsto a, y \mapsto v]$
- ▶ Unifier 3: $[x \mapsto a, y \mapsto f(b), v \mapsto f(b)]$
- ▶ But some unifiers are more desirable than others . . .

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Composing Substitutions

- ► To explain what it means for one unifier to be better than another, we define the composition of substitutions.
- lacktriangle Composition of two substitutions σ and δ is written $\sigma\delta=\sigma'$
- ▶ The composition $\sigma\delta$ of substitutions σ and δ is obtained by:
 - 1. applying δ to the range of σ
 - 2. add to σ all mappings $x \mapsto t$ from δ where $x \notin dom(\sigma)$.

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Composing Substitutions Examples

- ▶ What is $[x \mapsto a, y \mapsto z][z \mapsto b]$?
- ▶ What is $[x \mapsto a, y \mapsto f(z, g(w))][z \mapsto 1, w \mapsto 2]$?
- ► Let

$$\sigma = [x \mapsto a, y \mapsto f(u), z \mapsto v]$$
$$\delta = [u \mapsto d, v \mapsto e, z \mapsto g]$$

What is $\sigma \delta$?

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Generality of Unifiers

- ▶ We prefer unifiers that are as general as possible.
- A unifier σ is at least as general as unifier σ' if there exists another substitution δ such that $\sigma\delta = \sigma'$
- ▶ Intuition: σ more general than σ' if σ' can be obtained from σ through another substitution
- We say σ more general than σ' if σ is at least as general as σ' but not the other way around
- $\begin{tabular}{ll} \hline & \begin{tabular}{ll} Which unifier is more general? $\sigma = [x \mapsto a, y \mapsto v]$ or \\ & \begin{tabular}{ll} \sigma' = [x \mapsto a, y \mapsto f(c), v \mapsto f(c)]? \\ \hline \end{tabular}$
- ▶ Which unifier is more general? $\sigma = [x \mapsto a, y \mapsto z]$ or $\sigma' = [x \mapsto a, y \mapsto w]$?

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Most General Unifiers

- $ightharpoonup \sigma$ is a most general unifier (mgu) of expressions e, e' iff σ is at least as general as any other unifier of e and e'.
- ► Intuition: A unifer is most general if it only contains mappings necessary to unify, but nothing extra!
- ightharpoonup Consider again p(x,y) and p(a,v).
- ▶ Is $[x \mapsto a, y \mapsto b, v \mapsto b]$ an mgu?
- ▶ Is $[x \mapsto a, y \mapsto v]$ an mgu?
- ▶ Is $[x \mapsto a, y \mapsto v, v \mapsto y]$ an mgu?
- ▶ If two expressions e and e' are unifiable, then their mgu is unique modulo variable renaming

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Algorithm to Compute MGU

- ► We'll now give an algorithm to find most general unifiers (Robinson's algorithm, 1965)
- ► Function find mgu(e, e') takes expressions e, e' and returns substitution σ that is mgu of e, e' or \bot
- ► Case 1: e = e'. Then $\sigma = [$
- ► Case 2: e is variable x. If e' does not contain x then $[x \mapsto e']$, otherwise \bot
 - Containment check referred to as occurs check; disallows infinite terms as a solution
- ▶ Case 3: e' is variable $y \Rightarrow$ symmetric to case 2
- ightharpoonup Case 4: e or e' is a constant. Return \bot

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Algorithm to Compute MGU, continued

- Case 5: $e = \tau(e_1, \dots, e_k)$.
 - 1. If $e' \neq \tau(e'_1, \ldots, e'_k)$, then \bot
 - 2. Otherwise result of unifying $[e_1 \dots e_k]$ and $[e'_1 \dots e'_k]$
- ightharpoonup Case 6: e is expression list $[h \ T]$.
 - 1. If e' is not expression list of the form $[h' \ T']$, return \bot .
 - 2. Let $\sigma = \text{find}_{mgu}(h, h')$.
 - 3. Apply σ to T, T'
 - 4. Recursively compute MGU σ' for σT and $\sigma T'$
 - 5. Return composition of σ and σ'

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Example of Computing MGUs

- ▶ Apply algorithm to find mgu for p(f(x), f(x)) and p(y, f(a))
- ▶ Predicates match; unify the arguments.
- ▶ Unify first arguments f(x) and y
- ► Result:
- ightharpoonup Apply unifier to second arguments f(x) and f(a) (unchanged)
- ▶ Then, unify f(x) and f(a):
- ▶ Compose $[y \mapsto f(x)]$ and $[x \mapsto a]$
- ► Final result:

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Another Example

- ▶ Apply algorithm to find mgu for p(x,x) and p(y,f(y))
- ▶ Predicates match; unify the arguments.
- ▶ Unify first arguments x and y; result:
- ▶ Apply unifier to second arguments x and f(y):
- Now unify y and f(y):
- ▶ Thus p(x,x) and p(y,f(y)) not unifiable

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Complexity of unification

- Robinson's algorithm has worst-case complexity, but only triggered in "pathological" cases
- ► There are almost-linear time unification algorithms, but Robinson's algorithm still widely used

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First-Order Resolution Ingredients

- ► Recall: Resolution in FOL requires two new ingredients: unification and clausal form
- Next. we'll define clausal form
- ► A formula in FOL in said to be in clausal form it obeys following syntactic restrictions:
 - 1. Formula should be of the form $\forall x_1, \dots, x_k$. $F(x_1, \dots x_k)$ (i.e., only universally quantified variables)
 - 2. The inner formula $F(x_1, \ldots, x_k)$ should be in CNF

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The Bad and The Good News

► Bad News:

In general, if ϕ is the original formula, there may not be an equivalent formula ϕ' that is of this form

► Good News:

But we can always find an equi-satisfiable formula $\phi^{\prime\prime}$ that is of this form

Since we are trying to determine satisfiability of ϕ , this is good enough . . .

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Converting Formulas to Equisatisfiable Clausal Form

Given formula ϕ , there are five steps to convert it to equisatisfiable clausal form:

- 1. Make sure there are no free variables in ϕ
- 2. Convert resulting formula to Prenex normal form
- 3. Apply skolemization to remove existentially quantified variables (resulting formula called Skolem Normal Form)
- 4. Since formula obtained after step 3 is of the form $\forall x_1,\ldots,x_k.\ F(x_1,\ldots x_k)$, convert inner formula F to CNF
- 5. Since all variables are universally quantified, drop explicit quantifiers and write formula as set of clauses

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Step 1: Removing Free Variables

- ightharpoonup Suppose a formula ϕ contains free variable x
- ▶ How can we construct a formula ϕ' such that x is no longer free and ϕ' is equisatisfiable to ϕ ?
- ϕ is satisfiable iff there exists some $o \in U$ under which $U, I, \{x \mapsto o\} \models \phi$
- ▶ But this is the same as saying ϕ is satisfiable iff $U, I \models \exists x. \phi$ for some U, I
- ▶ Thus, to perform step 1 of transformation, existentially quantify all free variables of ϕ

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Prenex Normal Form

► A formula is in prenex normal form (PNF) if all of its quantifiers appear at the beginning of formula:

$$Qx_1, \ldots Qx_n. F(x_1, \ldots, x_n)$$

where F is quantifier-free and $Q \in \{ \forall, \exists \}$

- ▶ Is $\forall x.\exists y.(p(x,y) \rightarrow q(x))$ in PNF?
- ▶ What about $\forall x.((\exists y.p(x,y)) \rightarrow q(x))$ in PNF?

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Step 2: Conversion to Prenex Normal Form

- Step2a: Convert to NNF.
- ► Conversion to NNF is just like in propositional logic, but need new equivalences for distributing negation over quantifiers:

$$\neg \forall x. \phi \iff \exists x. \neg \phi$$
$$\neg \exists x. \phi \iff \forall x. \neg \phi$$

- ► Step 2b: Rename quantified variables as necessary so no two quantified variables have the same name.
- ▶ Step 2c: Move quantifiers to front of formula $Q_1x_1, \ldots, Q_nx_n.F'$ such that if Q_j is in the scope of quantifier Q_i , then i < j.
- ▶ Claim: Formula in PNF is equivalent to original formula.

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Conversion to PNF Example

► Convert formula to PNF:

$$\forall x. \neg (\exists y. p(x, y) \land p(x, z)) \lor \exists y. p(x, y)$$

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Step 3: Skolemization

- After converting formula to PNF, we want to remove all existential quantifiers
- Skolemization produces equisatisfiable formula without existential quantifiers
- ▶ Suppose an existentially quantified variable y appears in the scope of quantifiers x_1, \ldots, x_k
- Skolemization: replaces y with function term: $f(x_1, \ldots, x_n)$ where f is a fresh function symbol
- ightharpoonup This new function f called Skolem function
- ▶ What happens if y is not in scope of any quantifiers?

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Skolemization: Intuition I

- ▶ Consider formula $\exists x.F$
- ▶ We know there is some object for which *F* holds, but we don't want to make any assumptions about this object
- ightharpoonup Thus, we replace x with a fresh object constant c in F
- ▶ The formula F[c/x] is equisatisfiable to $\exists x.F$, but not equivalent

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Skolemization: Intuition II

- ► However, if existential variable *x* is in scope of universally quantified variables, we can't replace it with object constant
- ► Consider formula: $\forall x. \exists y. hates(x, y)$
- ▶ What does this formula say?
- Now, let's replace y with object constant c: $\forall x.hates(x, c)$
- ▶ What does this formula say?
- ► Clearly, very different meaning!
- ▶ Want to capture that two people can hate different people ⇒ introduce function constant

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Skolem Normal Form

▶ The formula after performing skolemization looks like this:

$$\forall x_1, \ldots, \forall x_n. \ F(x_1, \ldots, x_n)$$

- ► This form is called Skolem Normal Form
- Resulting formula not equivalent to original formula, but equisatisfiable

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Conversion to Clausal Form Example

► Convert formula to clausal form:

$$\forall y.(p(y) \land \neg(\forall z.(r(z) \to q(y,z,w))))$$

► Step 1: Remove free variables:

$$\exists w. \forall y. (p(y) \land \neg (\forall z. (r(z) \rightarrow q(y,z,w))))$$

► Step 2a: Convert to NNF (necessary for PNF):

$$\exists w. \forall y. (p(y) \land \neg(\forall z. (\neg r(z) \lor q(y,z,w)))) \text{ remove} \rightarrow \\ \exists w. \forall y. (p(y) \land (\exists z. (r(z) \land \neg q(y,z,w)))) \text{ push negations}$$

► Step 2b: Move quantifiers out (necessary for PNF):

$$\exists w. \forall y. \exists z. (p(y) \land ((r(z) \land \neg q(y, z, w))))$$

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Conversion to Clausal Form Example, continued

► In Prenex Normal Form:

$$\exists w. \forall y. \exists z. (p(y) \land ((r(z) \land \neg q(y, z, w))))$$

ightharpoonup Step 3a: Now, skolemize w (easiest to start outside):

$$\forall y. \exists z. (p(y) \land ((r(z) \land \neg q(y, z, c))))$$

► Step 3b: Skolemize *z*:

$$\forall y.(p(y) \land ((r(f(y)) \land \neg q(y,f(y),c))))$$

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Conversion to Clausal Form Example, continued

► In Skolem Normal Form:

$$\forall y. (p(y) \land ((r(f(y)) \land \neg q(y, f(y), c))))$$

- ► Step 4: Convert inner formula to CNF (already in CNF)
- ► Step 5: Drop universal quantifiers:

$$(p(y) \land ((r(f(y)) \land \neg q(y, f(y), c))))$$

▶ Step 6: Finally, write formula as a set of clauses

$$\{p(y)\}, \{(r(f(y))\}, \{q(y, f(y), c)\}$$

► This formula is now in clausal form

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Summary

- ► Today: Talked about two necessary ingredients for first-order resolution:
 - 1. Unification
 - 2. Clausal form
- ▶ Next lecture: First-order resolution and theorem provers

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