

Today's Plan

Higher level languages

- Using ZPL
- Performance portability

CS380P Lecture 16

Using ZPL

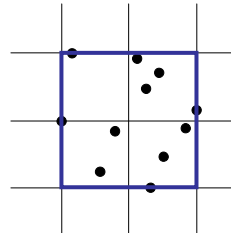
1

Finding the Bounding Box

Given

- X and Y are 1D arrays of coordinates such that (X_i, Y_i) is a position in the 2D plane
- How do you compute the bounding box in ZPL?

```
[R] begin
    rightedge := max<< X;
    topedge   := max<< Y;
    leftedge  := min<< X;
    bottomedge := min<< Y;
end;
```



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Bounding Box Using Records

Using a Point Type

```

type point = record
    x : integer;      -- x coordinate
    y : integer;      -- y coordinate
end;
var Points : [1..n] point; -- points in a plane
. . .
[R] begin
    rightedge := max<< Points.x;
    topedge   := max<< Points.y;
    leftedge  := min<< Points.x;
    bottomedge := min<< Points.y;
end;

```

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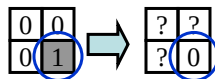
Recall the Connected Components Algorithm



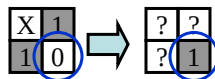
The Amazing Levialdi Shrinking Operator (1972)

- Each pixel simultaneously changes state according to the following rules

- (1) A 1 bit becomes a 0 if there are 0's to its West, NW, and North



- (2) A 0 bit becomes a 1 if there are 1's to its West and North



- (3) All other bits remain unchanged

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8-way Connected Components

ZPL Solution

```

. . .
Count := 0;
repeat
    Next := Image & (Image@north | Image@nw | Image@west);
    Next := Next | (Image@west & Image@north & !Image);
    Conn := Next@east | Next@se | Next@south;
    Conn := Image & !Next & !Conn;
    Count += Conn;
    Image := Next;
    smore := |<< Next;
until !smore;
. . .

```

Rule 1

Rule 2

Test for Poof



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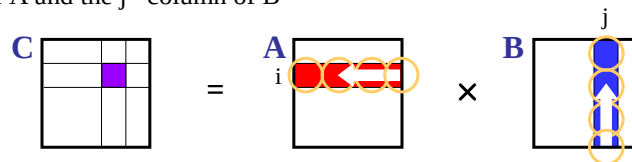
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Matrix Multiplication

Observation

- To compute the (i,j) element of C , we compute the dot product of the i^{th} row of A and the j^{th} column of B



Cannon's algorithm [Cannon '69]

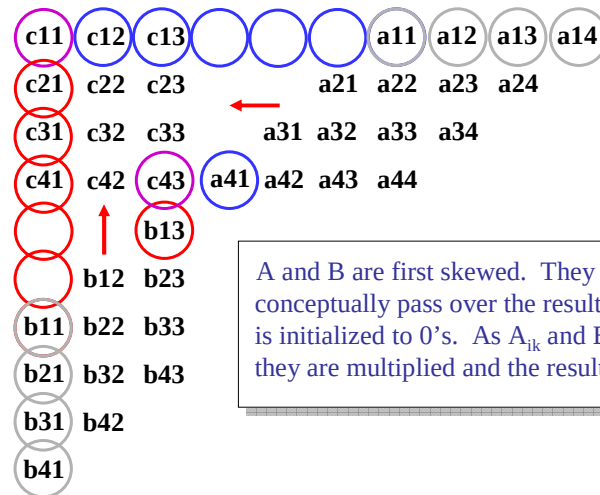
- For $n \times n$ matrices, each dot product consists of n multiplications
- If we **skew** the rows of A and the columns of B appropriately, we can align these n multiplications by shifting the A matrix to the left and the B matrix to the top

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Cannon's Algorithm [1969]



A and B are first skewed. They then conceptually pass over the result array C, which is initialized to 0's. As A_{ik} and B_{kj} pass over C_{ij} , they are multiplied and the result is added to C_{ij} .

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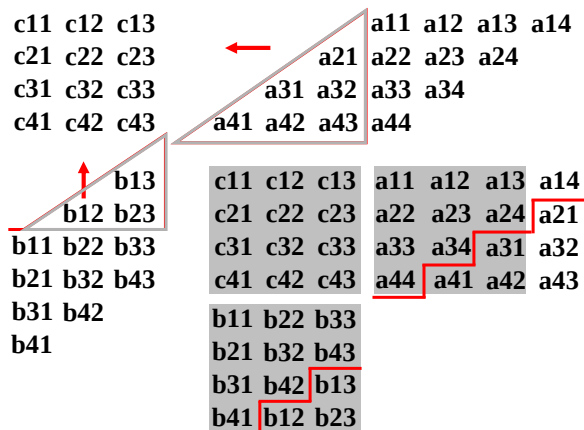
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Skewed Arrays

ZPL supports only dense arrays

– How do we represent skewed arrays?



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Skewing the Arrays

Use the wrap operator

- Wrap the first column to the right border, then shift left

```
region Lop = [1..m, 1..n];
direction right = [0,1];
```

a11	a12	a13	a14		a11	a12	a13	a14
a21	a22	a23	a24		a22	a23	a24	a21
a31	a32	a33	a34		a33	a34	a31	a32
a41	a42	a43	a44		a44	a41	a42	a43

```
for i := 2 to m do
[right of Lop] wrap A;      -- Move col 1 to right border
[i..m, 1..n] A := A@right; -- Shift last i rows left
end;
```

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The Four Steps of Skewing A

```
for i := 2 to m do
[right of Lop] wrap A;      -- Move col 1 to right border
[i..m, 1..n] A := A@right; -- Shift last i rows left
end;
```

a11	a12	a13	a14	-
a21	a22	a23	a24	-
a31	a32	a33	a34	-
a41	a42	a43	a44	-

initially

a11	a12	a13	a14	a11
a21	a22	a23	a24	a21
a31	a32	a33	a34	a31
a41	a42	a43	a44	a41

i=2 wrap A

a11	a12	a13	a14	a11
a22	a23	a24	a21	a21
a32	a33	a34	a31	a31
a42	a43	a44	a41	a41

i=2 A:=A@right

a11	a12	a13	a14	a11
a22	a23	a24	a21	a22
a32	a33	a34	a31	a32
a42	a43	a44	a41	a42

i=3 wrap A

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The Four Steps of Skewing A

```
for i := 2 to m do
  [right of Lop] wrap A;      -- Move col 1 to right border
  [i..m, 1..n] A := A@right; -- Shift last i rows left
end;
```

a11 a12 a13 a14 | a11
 a22 a23 a24 a21 | a22
 a33 a34 a31 a32 | a32
 a43 a44 a41 a42 | a42
 i=3 A:=A@right

a11 a12 a13 a14 | a11
 a22 a23 a24 a21 | a22
 a33 a34 a31 a32 | a33
 a43 a44 a41 a42 | a43
 i=4 wrap A

a11 a12 a13 a14 | a11
 a22 a23 a24 | a21 a22
 a33 a34 a31 a32 | a33
 a44 a41 a42 a43 | a43
 i=4 A:=A@right

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Cannon's Algorithm

Skew A, Skew B, Multiply, Accumulate, Rotate

```

    for i := 2 to m do -- Skew A
  [right of Lop] wrap A;      -- Move col 1 to right
  [i..m, 1..n] A := A@right; -- Shift last i rows left
    end;
    for i := 2 to p do -- Skew B
  [right of Rop] wrap B;      -- Move row 1 to below last
  [1..n, i..p] B := B@below; -- Shift last i columns up
    end;
  [Res] C := 0.0 -- Initialize C
    for i := 1 to n do -- For A & B's common dim
  [Res] C := C + A * B; -- Accumulate product
  [right of Lop] wrap A;      -- Send first col right
  [Lop] A := A@right;         -- Shift array left
  [below of Rop] wrap B;      -- Send top row down
  [Rop] B := B@below;         -- Shift array up
    end;
```

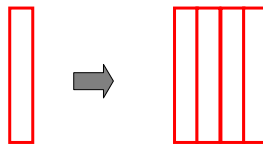
Flood

Flooding

- The Flood operation is the inverse of a reduce operation
- It replicates data from lower dimensions to higher dimensions

Example

- Can use flood to perform matrix-vector operations
 - Flood the vector to be conformal with the array



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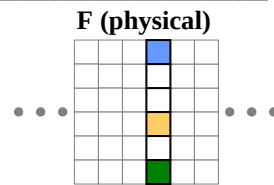
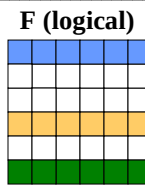
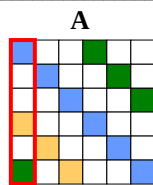
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The Flood Operator

Flooding

- In ZPL, the flood operator ($\gg$) looks like the inverse of a reduction
- It takes two regions, one applied to the statement, and the other applied to the operator

Replicate A's 1st column
`[1..n, 1..m] F :=  $\gg$ [1..n, 1] A;`



Collapsed regions

- One or more of the operator's region must be collapsed to a singleton
- Replication occurs across collapsed regions

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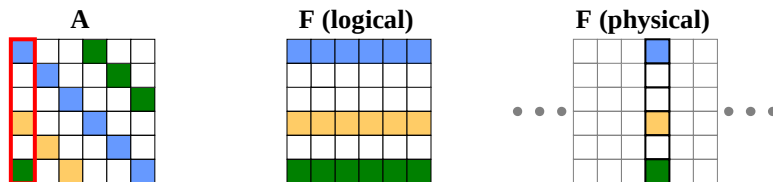
Language Support for Flooding

Flooding

- ZPL has the flood operator ($\gg$)
- Fortran 90 has **spread**
- MATLAB has “Tony’s Trick”

```

ZPL:      [1..n,1..m] F := >>[1..n, 1] A;
Fortran90: F = SPREAD (A[:,1], DIM=2,N)
MATLAB:   F = A(:,ones(1,size(A,2)))
  
```



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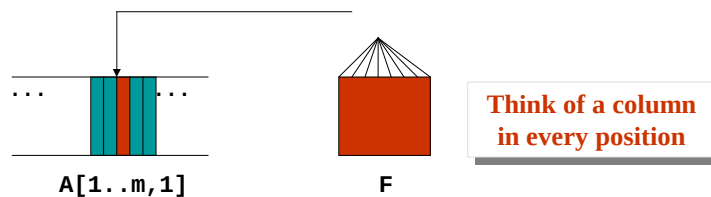
Flood Regions and Flood Arrays

Over-specification

- The collapsed singleton dimension over-specifies the situation
- To specify **any** column, use *****

```

region   FloodCol = [1..m, *];      -- Flood region
[FloodCol] F := >> [1..m, 1] A;
  
```



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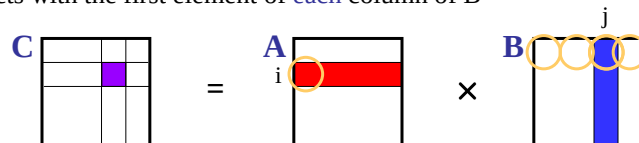
Using ZPL

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Matrix Multiplication Revisited

Observation

- The first element of the i^{th} row of A will be used to compute partial dot products with the first element of **each** column of B



SUMMA algorithm [Watts and van de Geijn 95]

- Each element in each **column** of A contributes to n dot products
- Each element in each **row** of B contributes to n dot products
- Iteratively
 - Broadcast columns of A to all processors
 - Broadcast rows of B to all processors
 - Compute $1/n^{\text{th}}$ of the dot product for each element of C

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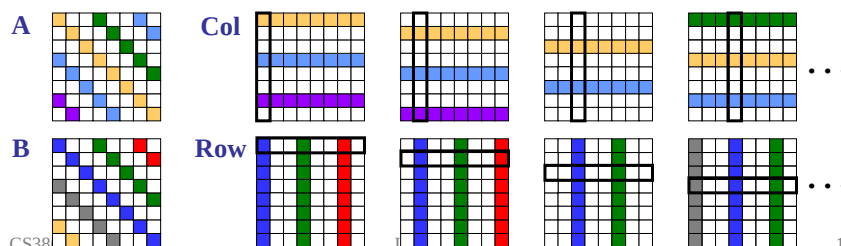
Matrix Multiplication Revisited

SUMMA algorithm

- Iteratively flood a column of A and a row of B into temporary matrices
- Multiply and accumulate these results into C

```

[1..n,1..n] C := 0.0;           -- Initialize C
[1..n,1..n] for k := 1 to n do
    [, *]   Col := >>[,k] A;    -- Flood kth col of A
    [* ,]   Row := >>[k,] B;    -- Flood kth row of B
    C := C+Col*Row;             -- Accumulate product
end;
```



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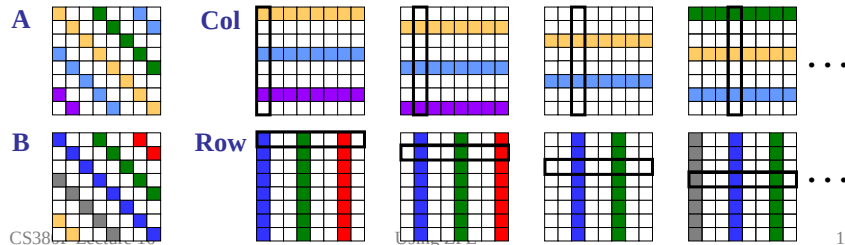
SUMMA Algorithm

Invariant

- On the k^{th} iteration, the k^{th} term in the dot-product of row i and column j is accumulated into position i,j

```

[1..n,1..n] C := 0.0;           -- Initialize C
[1..n,1..n] for k := 1 to n do
    [,*] Col := >>[,k] A;      -- Flood kth col of A
    [*,:] Row := >>[k,] B;     -- Flood kth row of B
    C := C+Col*Row;            -- Accumulate product
end;
```



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Comparing the Algorithms

Which matrix multiplication algorithm is better?

Cannon
 Skew A
 Skew B
 loop through n
 C += A*B
 rotate A, B

SUMMA
 loop through n
 flood A[,k]
 flood B[k,]
 C += A*B

Other ZPL Constructs

Permutation

- ZPL supports non-local data movement with the permutation operators
 - Gather: **# on rhs**
 - Scatter: **# on lhs**

Hierarchical arrays

Sparse arrays

Distribution change