
Deep Variational Inference

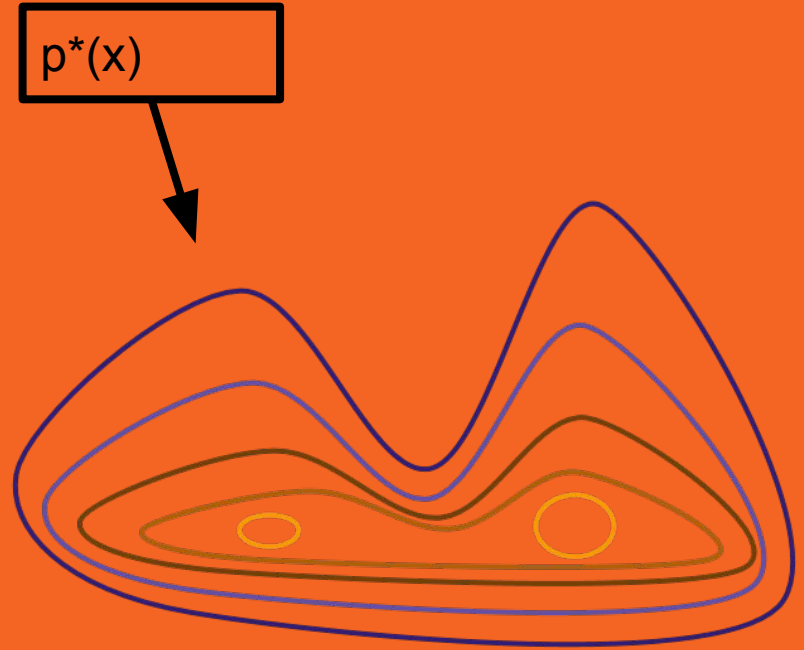
FLARE Reading Group Presentation
Wesley Tansey
9/28/2016

What is Variational Inference?



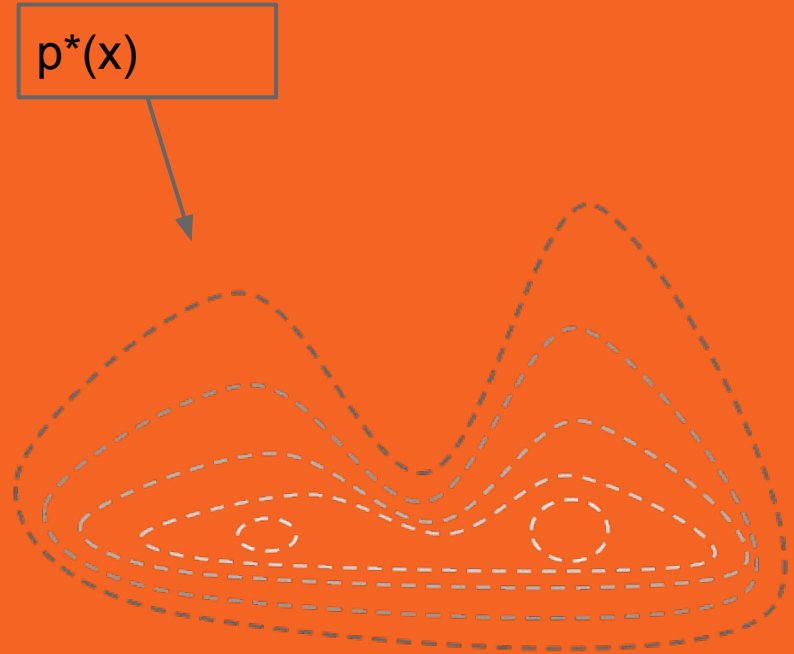
What is Variational Inference?

- Want to estimate some distribution, $p^*(x)$



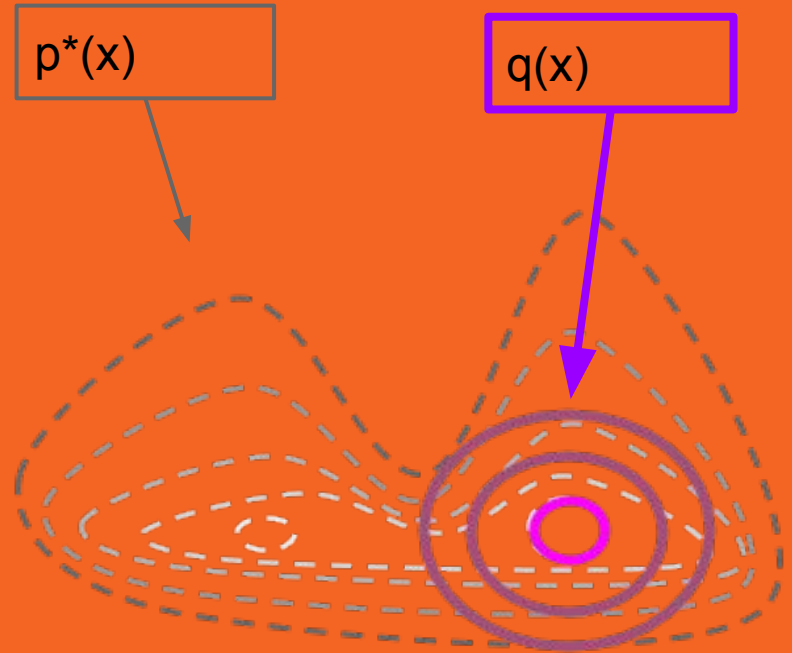
What is Variational Inference?

- Want to estimate some distribution, $p^*(x)$
- Too expensive to estimate



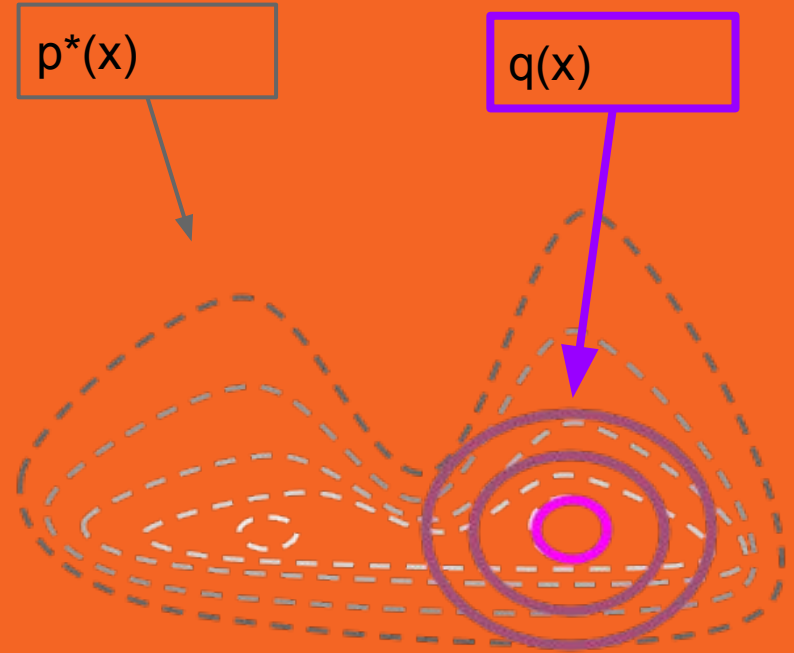
What is Variational Inference?

- Want to estimate some distribution, $p^*(x)$
- Too expensive to estimate
- Approximate it with a tractable distribution, $q(x)$



What is Variational Inference?

- Fit $q(x)$ inside of $p^*(x)$
- Centered at a single mode
 - $q(x)$ is unimodal here
 - VI is a MAP estimate



What is Variational Inference?

- Mathematically:

$$\text{KL}(q \parallel p^*)$$

$$= \sum_x q(x) \log(q(x) / p^*(x))$$

Still hard!

$p^*(x)$ usually has a
tricky normalizing
constant



What is Variational Inference?

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- Use unnormalized p^\sim instead

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$$\log(q(x) / p^*(x))$$

$$= \log(q(x)) - \log(p^*(x))$$

$$= \log(q(x)) - \log(p^\sim(x) / Z)$$

$$= \log(q(x)) - \log(p^\sim(x)) - \log(Z)$$

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Constant

⇒ Can ignore in our optimization problem

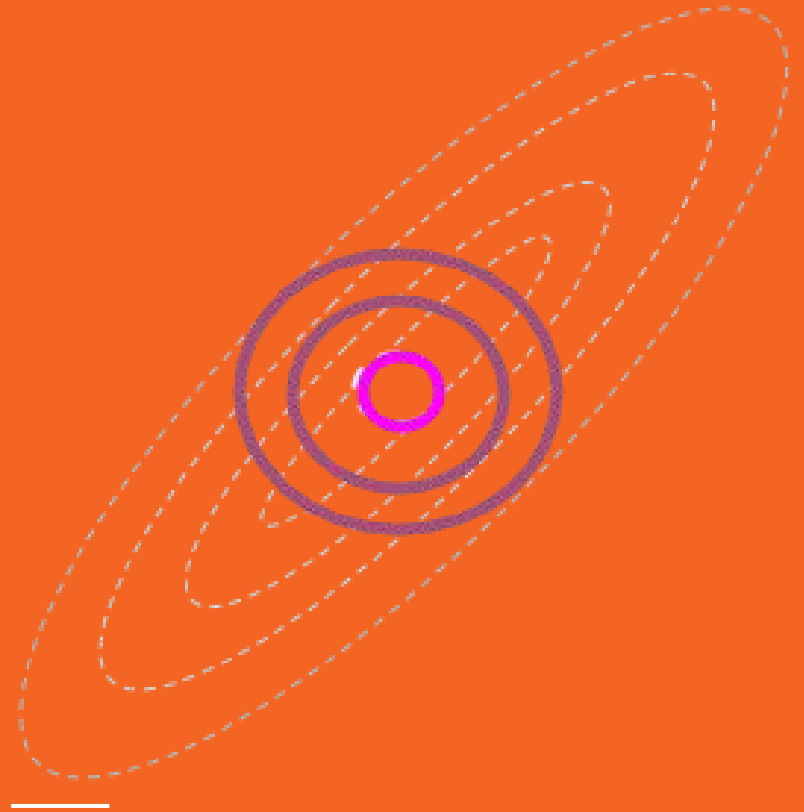
Mean Field VI

- Classical method
- Uses a factorized q :

$$q(x) = \prod_i q_i(x_i)$$

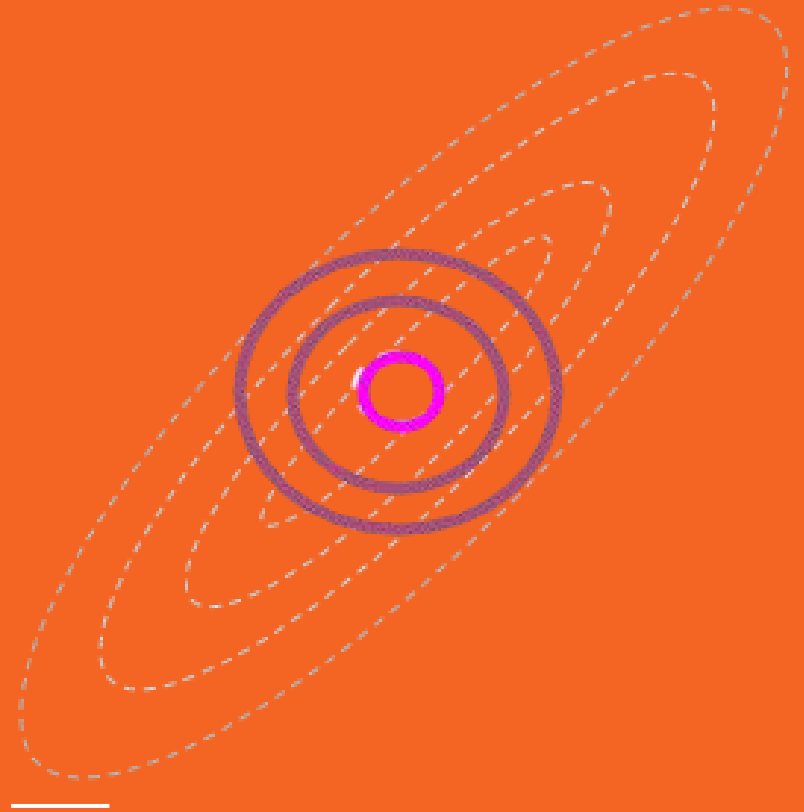
Mean Field VI

- Example: Multivariate Gaussian
- Product of independent Gaussians for q
- Spherical covariance underestimates true covariance



Variational Bayes

- Vanilla mean field VI assumes you know all the parameters, θ , of the true distribution, $p^*(x)$



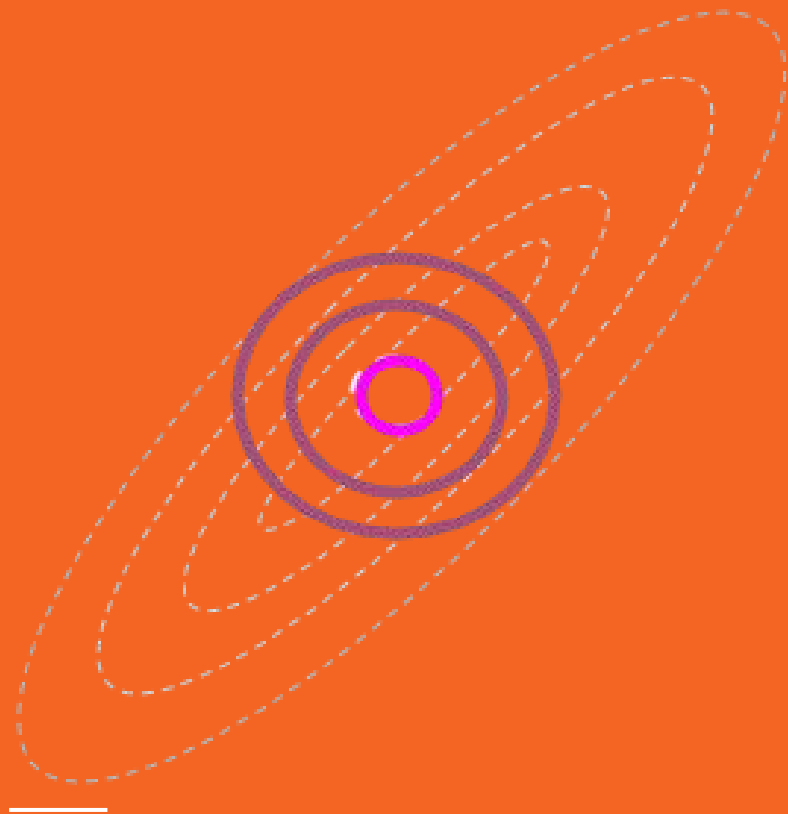
Variational Bayes

- Vanilla mean field VI assumes you know all the parameters, θ , of the true distribution, $p^*(x)$
- Enter: Variational Bayes (VB)



Variational Bayes

- VB infers both the latent $q(x)$ variables, z , *and* the $p^*(x)$ parameters, θ
- VB-EM was popularized for LDA¹
 - E for z , M for θ

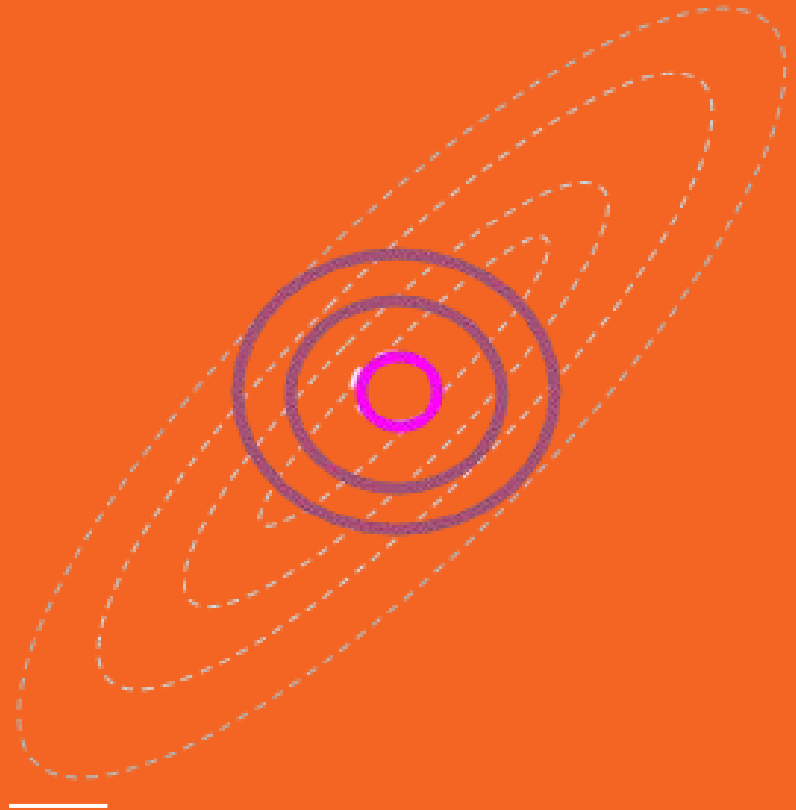


[1] Blei, Ng, Jordan, "Latent Dirichlet Allocation", JMLR, 2003.

Variational Bayes

- VB usually uses a mean field approximation of the form:

$$q(\mathbf{x}) = q(z_i | \theta) \prod_i q_i(x_i | z_i)$$




Issues with Mean Field VB

- Requires analytical solutions of expectations w.r.t. q_i
 - Intractable in general
- Factored form limits the power of the approximation

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Solution:
Auto-Encoding
Variational Bayes
(Kingma and Welling, 2013)



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- Requires analytical solutions of expectations w.r.t. q_i
 - Intractable in general

- Factored form limits the power of the approximation

Solution:
Auto-Encoding
Variational Bayes
(Kingma and Welling, 2014)

Solution:
Variational Inference
with Normalizing Flows
(Rezende and Mohamed, 2015)

Auto-Encoding Variational Bayes¹

High-level idea:

- 1) Optimizing the same lower bound that we get in VB
- 2) Data augmentation trick leads to lower-variance estimator
- 3) Lots of choices of $q(z|x)$ and $p(z)$ lead to partial closed-form
- 4) Use a neural network to parameterize $q_\phi(z | x)$ and $p_\theta(x | z)$
- 5) SGD to fit everything

[1] Kingma and Welling, “Auto-Encoding Variational Bayes”, ICLR, 2014.

1) VB Lower Bound

- Given N iid data points, (x^1, \dots, x^n)
- Maximize the marginal likelihood:

$$\log p_{\theta}(x^1, \dots, x^n) = \sum_i \log p_{\theta}(x^{(i)})$$

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$$\begin{aligned} & \log p_{\theta}(\mathbf{x}^{(i)}) \\ &= D_{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}^{(i)}) || p_{\theta}(\mathbf{x}^{(i)}|\mathbf{z})) \\ & \quad + \mathcal{L}(\theta, \phi; \mathbf{x}^{(i)}) \end{aligned}$$

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Always
positive



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$$+ \mathcal{L}(\theta, \phi; \mathbf{x}^{(i)})$$

Lower bound

Always positive

1) VB Lower Bound

- Write lower bound

$$\mathcal{L}(\boldsymbol{\theta}, \phi; \mathbf{x}^{(i)}) = \mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x})} [-\log q_{\phi}(\mathbf{z}|\mathbf{x}) + \log p_{\theta}(\mathbf{x}, \mathbf{z})]$$

1) VB Lower Bound

- Write lower bound

$$\mathcal{L}(\boldsymbol{\theta}, \phi; \mathbf{x}^{(i)}) =$$

$$\mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x})} [-\log q_{\phi}(\mathbf{z}|\mathbf{x}) + \log p_{\theta}(\mathbf{x}, \mathbf{z})]$$

Anyone want the derivation?

1) VB Lower Bound

- Write lower bound
- Rewrite lower bound

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Derivation?

1) VB Lower Bound

- Write lower bound
- Rewrite lower bound
- Monte Carlo gradient estimator of expectation part

$$\begin{aligned}\mathcal{L}(\boldsymbol{\theta}, \phi; \mathbf{x}^{(i)}) &= \\ &\mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{x})} [-\log q_\phi(\mathbf{z}|\mathbf{x}) + \log p_\theta(\mathbf{x}, \mathbf{z})] \\ &= -D_{KL}(q_\phi(\mathbf{z}|\mathbf{x})||p_\theta(\mathbf{z})) + \mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{x})} [\log p_\theta(\mathbf{x}|\mathbf{z})] \\ \nabla_\phi \mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{x})} [f(\mathbf{z})] &= \mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{x})} [f(\mathbf{z}) \nabla_\phi \log q_\phi(\mathbf{z}|\mathbf{x})] \\ &\quad \text{---} \approx \frac{1}{L} \sum_{l=1}^L f(\mathbf{z}^{(l)}) \nabla_\phi \log q_\phi(\mathbf{z}^{(l)}|\mathbf{x})\end{aligned}$$

1) VB Lower Bound

- Write lower bound
- Rewrite lower bound
- Monte Carlo gradient estimator of expectation part
 - Too high variance

$$\mathcal{L}(\boldsymbol{\theta}, \phi; \mathbf{x}^{(i)}) =$$

$$\mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{x})} [-\log q_\phi(\mathbf{z}|\mathbf{x}) + \log p_\theta(\mathbf{x}, \mathbf{z})]$$

$$= -D_{KL}(q_\phi(\mathbf{z}|\mathbf{x})||p_\theta(\mathbf{z})) + \mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{x})} [\log p_\theta(\mathbf{x}|\mathbf{z})]$$

$$\nabla_\phi \mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{x})} [f(\mathbf{z})] = \mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{x})} [f(\mathbf{z}) \nabla_\phi \log q_\phi(\mathbf{z}|\mathbf{x})]$$

$$\approx \frac{1}{L} \sum_{l=1}^L f(\mathbf{z}^{(l)}) \nabla_\phi \log q_\phi(\mathbf{z}^{(l)}|\mathbf{x})$$

2) Reparameterization trick

- Rewrite $q_{\phi}(z^{(l)} | \mathbf{x})$
- Separate q into a deterministic function of \mathbf{x} and an auxiliary noise variable $\boldsymbol{\epsilon}$
- Leads to lower variance estimator

$$\mathbf{z} \sim q_{\phi}(\mathbf{z} | \mathbf{x})$$

$$\mathbf{z} = g_{\phi}(\boldsymbol{\epsilon}, \mathbf{x})$$

$$\boldsymbol{\epsilon} \sim p(\boldsymbol{\epsilon})$$

2) Reparameterization trick

- Example: univariate Gaussian
- Can rewrite as sum of mean and a scaled noise variable

$$z \sim q_{\phi}(z|x) = \mathcal{N}(\mu, \sigma^2)$$

$$z = \mu + \sigma \epsilon$$

$$\epsilon \sim \mathcal{N}(0, 1)$$

2) Reparameterization trick

- Lots of distributions like this. Three classes given:

- Tractable inverse CDF
- Location-scale
- Composition

Exponential, Cauchy, Logistic, Rayleigh, Pareto, Weibull, Reciprocal, Gompertz, Gumbel, Erlang

Laplace, Elliptical, Student's t, Logistic, Uniform, Triangular, Gaussian

Log-Normal (exponentiated normal)
Gamma (sum of exponentials)
Dirichlet (sum of Gammas)
Beta, Chi-Squared, F

2) Reparameterization trick

- Yields a new MC estimator

$$\begin{aligned} & \mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x})} [f(\mathbf{z})] \\ &= \mathbb{E}_{p(\boldsymbol{\epsilon})} [f(g_{\phi}(\boldsymbol{\epsilon}, \mathbf{x}))] \\ &\approx \frac{1}{L} \sum_{l=1}^L f(g_{\phi}(\boldsymbol{\epsilon}^{(l)}, \mathbf{x})) \end{aligned}$$

2) Reparameterization trick

- Plug estimator into the lower bound eq.
- KL term often can be integrated analytically
 - Careful choice of priors

$$\tilde{\mathcal{L}} = -D_{KL}(q_{\phi}(\mathbf{z}|\mathbf{X})||p_{\theta}(\mathbf{z})) + \frac{1}{L} \sum_{l=1}^L \log p_{\theta}(\mathbf{x}|\mathbf{z}^{(l)})$$

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3) Partial closed form

- KL term often can be integrated analytically
 - Careful choice of priors
 - E.g. both Gaussian

$$\tilde{\mathcal{L}} = -D_{KL}(q_{\phi}(\mathbf{z}|\mathbf{X})||p_{\theta}(\mathbf{z})) + \frac{1}{L} \sum_{l=1}^L \log p_{\theta}(\mathbf{x}|\mathbf{z}^{(l)})$$

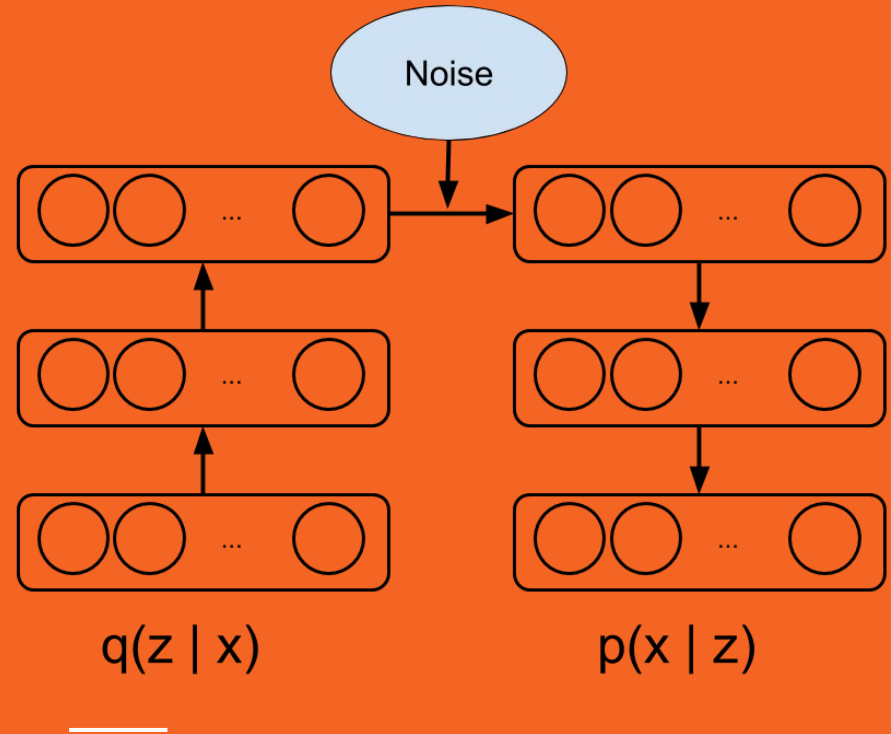
4) Auto-encoder connection

- Regularizer
- Reconstruction error
- Neural nets
 - Encode: $q(\mathbf{z} | \mathbf{x})$
 - Decode: $p(\mathbf{x} | \mathbf{z})$

$$\tilde{\mathcal{L}} = -D_{KL}(q_{\phi}(\mathbf{z} | \mathbf{X}) || p_{\theta}(\mathbf{z})) + \frac{1}{L} \sum_{l=1}^L \log p_{\theta}(\mathbf{x} | \mathbf{z}^{(l)})$$

4) Auto-encoder connection (alt.)

- $q(z | x)$ encodes
- $p(x | z)$ decodes
- “Information layer(s)” need to compress
 - Reals = infinite info
 - Reals + random noise = finite info



Where are we with VI now? (2013'ish)

- Deep networks parameterize both $q(z | x)$ and $p(x | z)$
 - Lower-variance estimator of expected log-likelihood
 - Can choose from lots of families of $q(z | x)$ and $p(z)$
-

Where are we with VI now? (2013'ish)

- Problem:
 - Most parametric families available are simple
 - E.g. product of independent univariate Gaussians
 - Most posteriors are complex
-

Variational Inference with Normalizing Flows¹

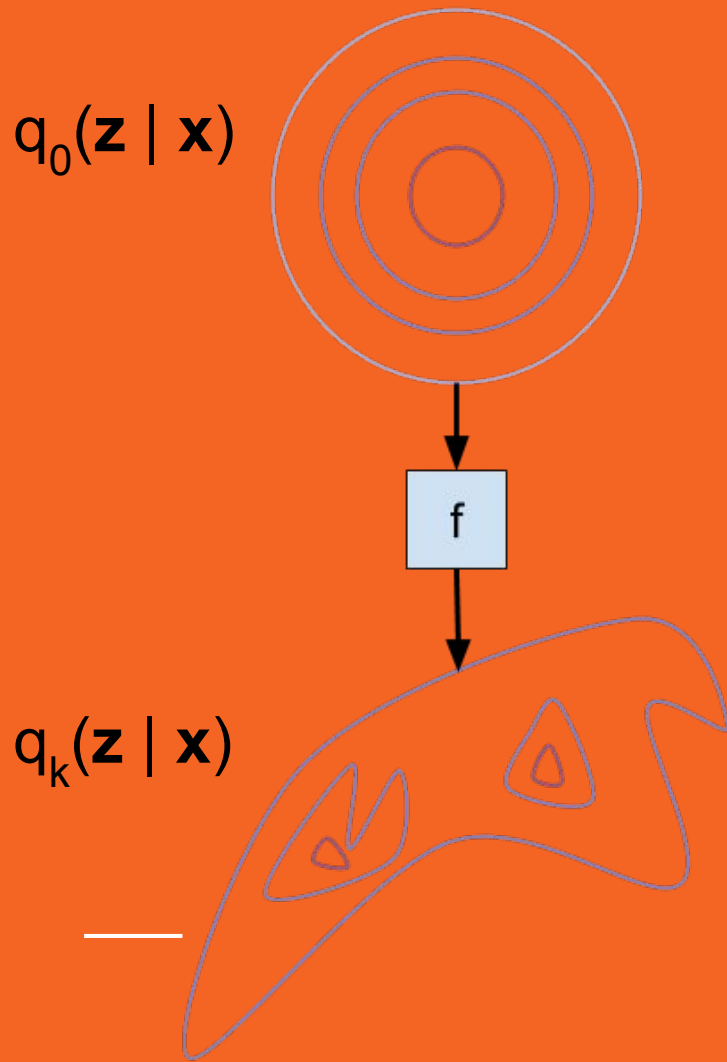
High-level idea:

- 1) VAEs are great, but our posterior $q(z|x)$ needs to be simple
- 2) Take simple $q(z | x)$ and apply series of k transformations to z to get $q_k(z | x)$. Metaphor: z “flows” through each transform.
- 3) Be clever in choice of transforms (computational issue)
- 4) Variational posterior q now converges to true posterior p
- 5) Deep NN now parameterizes q and flow parameters

[1] Rezende, Danilo Jimenez, and Shakir Mohamed. "Variational inference with normalizing flows." *arXiv preprint arXiv:1505.05770* (2015)..

What is a normalizing flow?

- Function that transforms a probability density through a sequence of invertible mappings



Key equations (1)

- Chain rule lets us write q_k as product of q_0 and inverted determinants

$$\begin{aligned} q(\mathbf{z}') &= q(\mathbf{z}) \left| \det \frac{\partial f^{-1}}{\partial \mathbf{z}'} \right| \\ &= q(\mathbf{z}) \left| \det \frac{\partial f}{\partial \mathbf{z}} \right|^{-1} \end{aligned}$$

Key equations (2)

- Density $q_k(\mathbf{z}')$ obtained by successively composing k transforms

$$\mathbf{z}_K = f_K \circ \cdots \circ f_2 \circ f_1(\mathbf{z}_0)$$

Key equations (3)

- Log likelihood of $q_k(\mathbf{z}')$ has a nice additive form

$$\log q_K(\mathbf{z}_K) = \log q_0(\mathbf{z}_0) - \sum_{k=1}^K \log \left| \det \frac{\partial f_k}{\partial \mathbf{z}_{k-1}} \right|$$

Key equations (4)

- Expectation over q_k can be written as an expectation under q_0
- Cute name: law of the unconscious statistician (LOTUS)

$$\mathbb{E}_{q_K} [h(\mathbf{z})] = \mathbb{E}_{q_0} [h(f_K \circ f_{K-1} \circ \cdots \circ f_1(\mathbf{z}_0))]$$

Types of flows

1) Infinitesimal Flows:

- Can show convergence in the limit
- Skipping (theoretical; computationally expensive)

2) Invertible Linear-Time Flows:

- log-det can be calculated efficiently
-

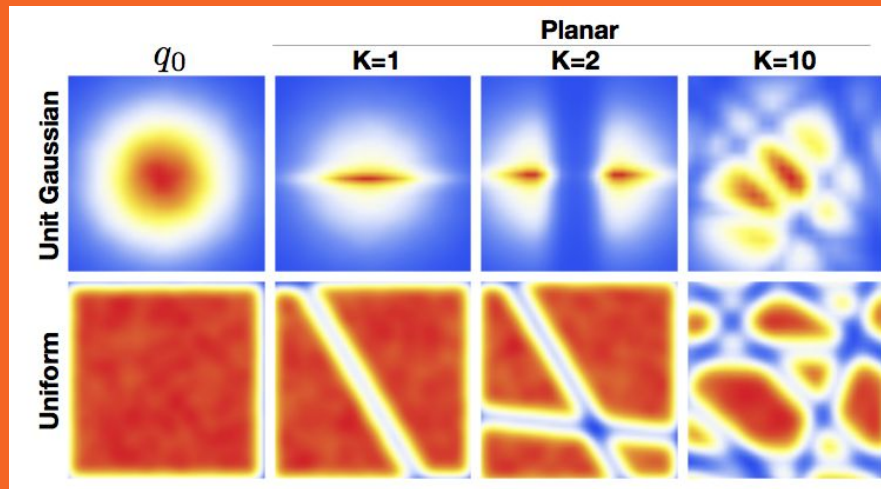
Planar Flows

- Applies the transform:

$$f(\mathbf{z}) = \mathbf{z} + \mathbf{u}h(\mathbf{w}^T \mathbf{z} + b)$$

where:

$$\mathbf{w} \in \mathbb{R}^D, \mathbf{u} \in \mathbb{R}^D, b \in \mathbb{R}$$



Radial Flows

- Applies the transform:

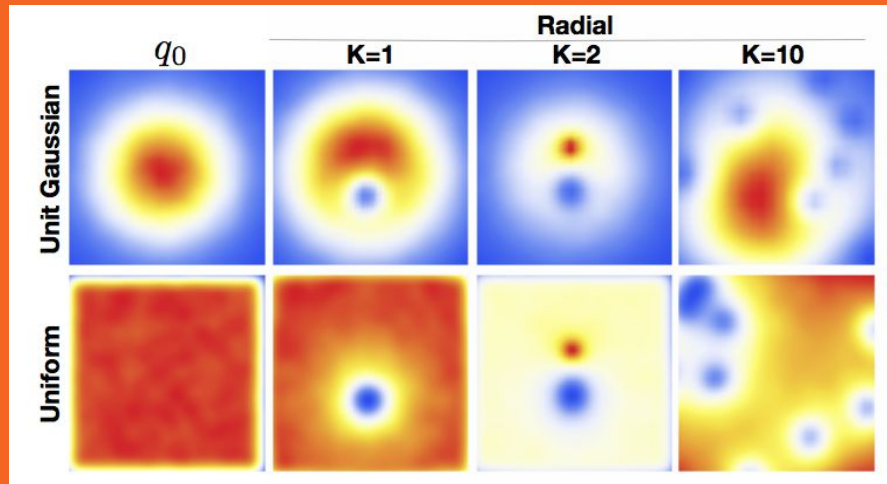
$$f(\mathbf{z}) = \mathbf{z} + \beta h(\alpha, r)(\mathbf{z} - \mathbf{z}_0)$$

where:

$$r = |\mathbf{z} - \mathbf{z}_0|$$

$$h(\alpha, r) = 1/(\alpha + r)$$

$$\mathbf{z}_0 \in \mathbb{R}^D, \alpha \in \mathbb{R}^+, \beta \in \mathbb{R}$$



– Summary

- VI approx. $p(x)$ via latent variable model
 - $p(x) = \sum_z p(z)p(x | z)$
 - VAE introduces an auto-encoder approach
 - Reparameterization trick makes it feasible
 - Deep NNs parameterize $q(z | x)$ and $p(x | z)$
 - NF takes $q(z|x)$ from simple to complex
 - Series of linear-time transforms
 - Convergence in the limit
-