

# Inference

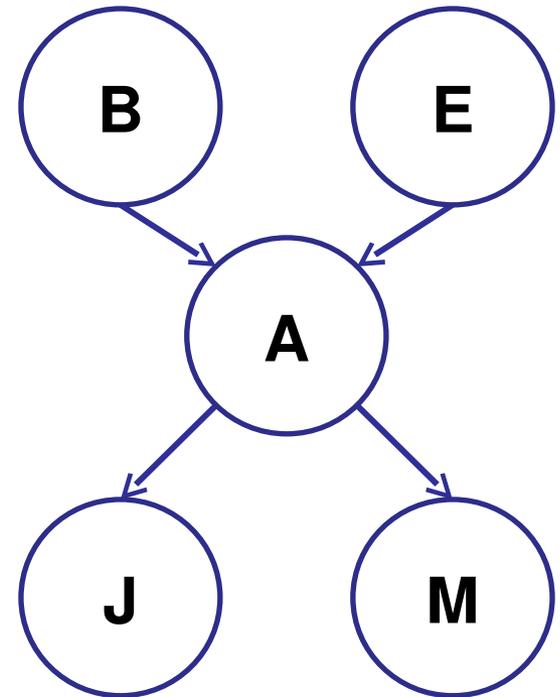
---

- Inference: calculating some useful quantity from a joint probability distribution
- Examples:
  - Posterior probability:

$$P(Q|E_1 = e_1, \dots, E_k = e_k)$$

- Most likely explanation:

$$\operatorname{argmax}_q P(Q = q|E_1 = e_1 \dots)$$

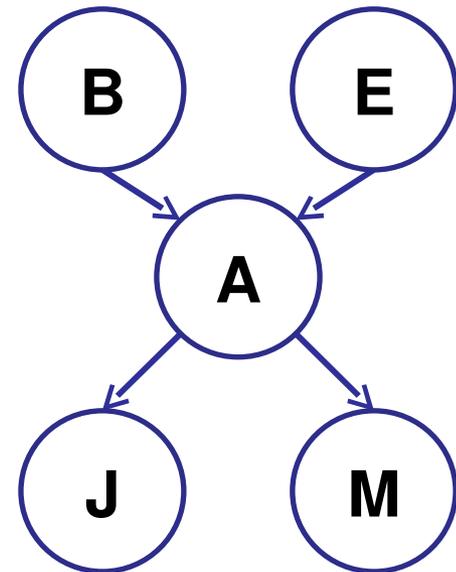


# Inference by Enumeration

---

- Given unlimited time, inference in BNs is easy
- Recipe:
  - State the marginal probabilities you need
  - Figure out ALL the atomic probabilities you need
  - Calculate and combine them
- Example:

$$P(+b | +j, +m) = \frac{P(+b, +j, +m)}{P(+j, +m)}$$



# Example: Enumeration

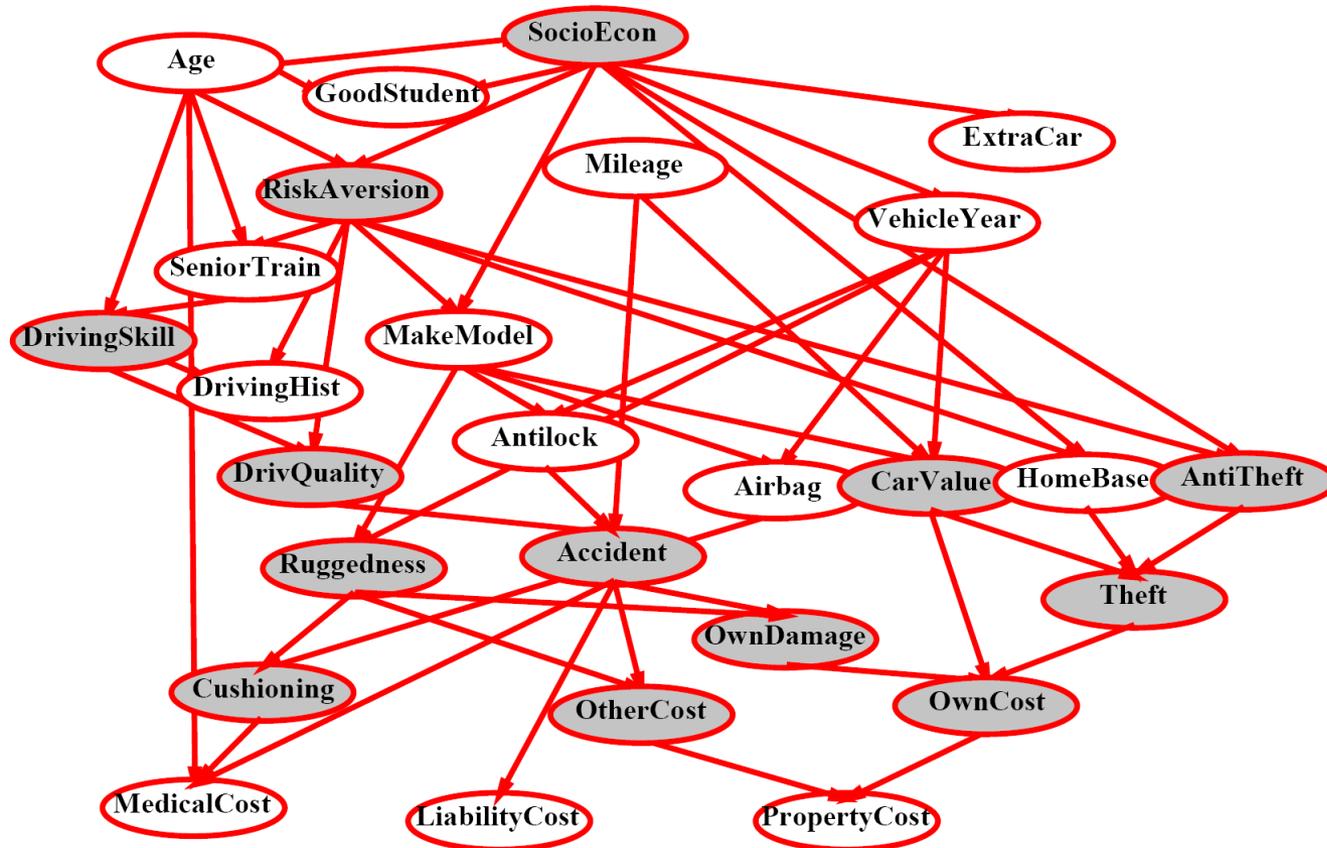
---

- In this simple method, we only need the BN to synthesize the joint entries

$$P(+b, +j, +m) =$$

$$\begin{aligned} & P(+b)P(+e)P(+a|+b, +e)P(+j|+a)P(+m|+a) + \\ & P(+b)P(+e)P(-a|+b, +e)P(+j|-a)P(+m|-a) + \\ & P(+b)P(-e)P(+a|+b, -e)P(+j|+a)P(+m|+a) + \\ & P(+b)P(-e)P(-a|+b, -e)P(+j|-a)P(+m|-a) \end{aligned}$$

# Inference by Enumeration?



# Variable Elimination

---

- Why is inference by enumeration so slow?
  - You join up the whole joint distribution before you sum out the hidden variables
  - You end up repeating a lot of work!
- Idea: interleave joining and marginalizing!
  - Called “Variable Elimination”
  - Still NP-hard, but usually much faster than inference by enumeration
- We’ll need some new notation to define VE

# Factor Zoo I

- Joint distribution:  $P(X, Y)$

- Entries  $P(x, y)$  for all  $x, y$
- Sums to 1

$P(T, W)$

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

- Selected joint:  $P(x, Y)$

- A slice of the joint distribution
- Entries  $P(x, y)$  for fixed  $x$ , all  $y$
- Sums to  $P(x)$

$P(\text{cold}, W)$

T	W	P
cold	sun	0.2
cold	rain	0.3

# Factor Zoo II

- Family of conditionals:

$P(X | Y)$

- Multiple conditionals
- Entries  $P(x | y)$  for all  $x, y$
- Sums to  $|Y|$

$P(W|T)$

T	W	P
hot	sun	0.8
hot	rain	0.2
cold	sun	0.4
cold	rain	0.6

$P(W|hot)$

$P(W|cold)$

- Single conditional:  $P(Y | x)$

- Entries  $P(y | x)$  for fixed  $x$ , all  $y$
- Sums to 1

$P(W|cold)$

T	W	P
cold	sun	0.4
cold	rain	0.6

# Factor Zoo III

$$P(\text{rain}|T)$$

- Specified family:  $P(y | X)$ 
  - Entries  $P(y | x)$  for fixed  $y$ , but for all  $x$
  - Sums to ... who knows!

T	W	P
hot	rain	0.2
cold	rain	0.6

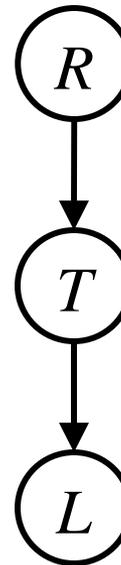
}  $P(\text{rain}|\text{hot})$   
}  $P(\text{rain}|\text{cold})$

- In general, when we write  $P(Y_1 \dots Y_N | X_1 \dots X_M)$ 
  - It is a “factor,” a multi-dimensional array
  - Its values are all  $P(y_1 \dots y_N | x_1 \dots x_M)$
  - Any assigned  $X$  or  $Y$  is a dimension missing (selected) from the array

# Example: Traffic Domain

- Random Variables

- R: Raining
- T: Traffic
- L: Late for class!



$$P(R)$$

+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(L|R)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

- First query:  $P(L)$

# Variable Elimination Outline

- Track objects called **factors**
- Initial factors are local CPTs (one per node)

+r	0.1
-r	0.9

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

- Any known values are selected
  - E.g. if we know  $L = +\ell$ , the initial factors are

+r	0.1
-r	0.9

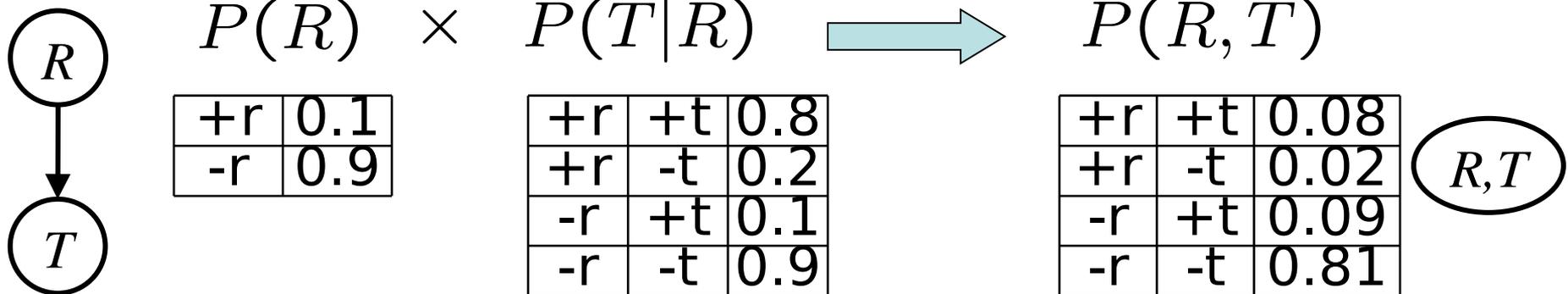
+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

+t	+l	0.3
-t	+l	0.1

- VE: Alternately join factors and eliminate variables

# Operation 1: Join Factors

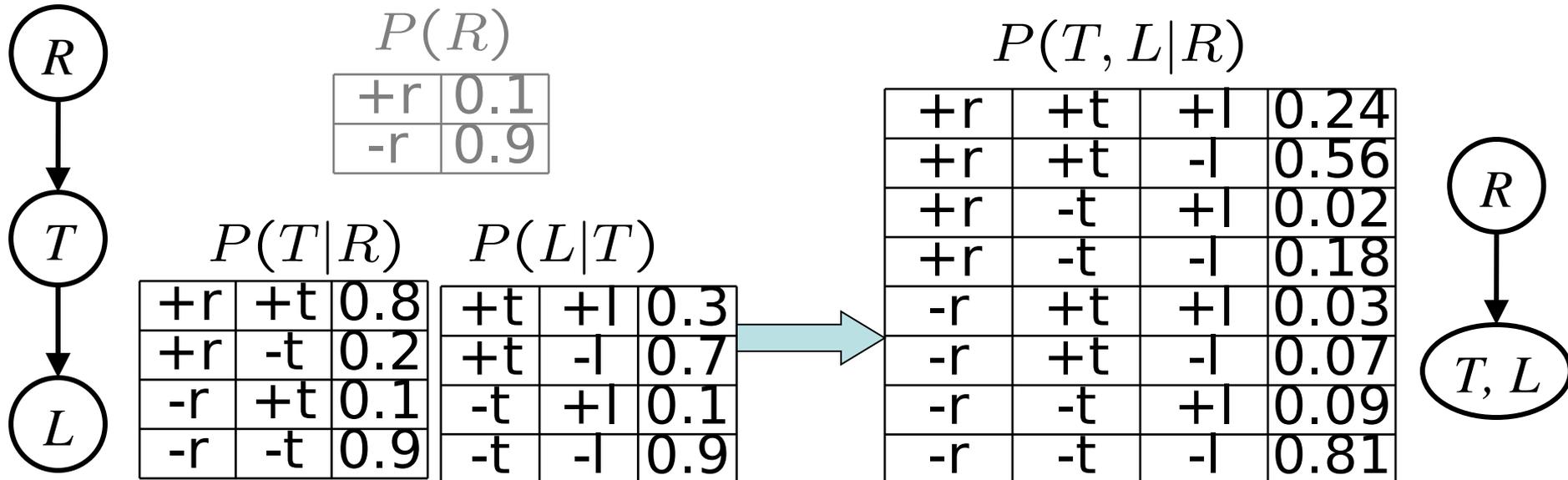
- First basic operation: **joining factors**
- Combining factors:
  - Just like a database join**
  - Get all factors over the joining variable
  - Build a new factor over the union of the variables involved
- Example: Join on R



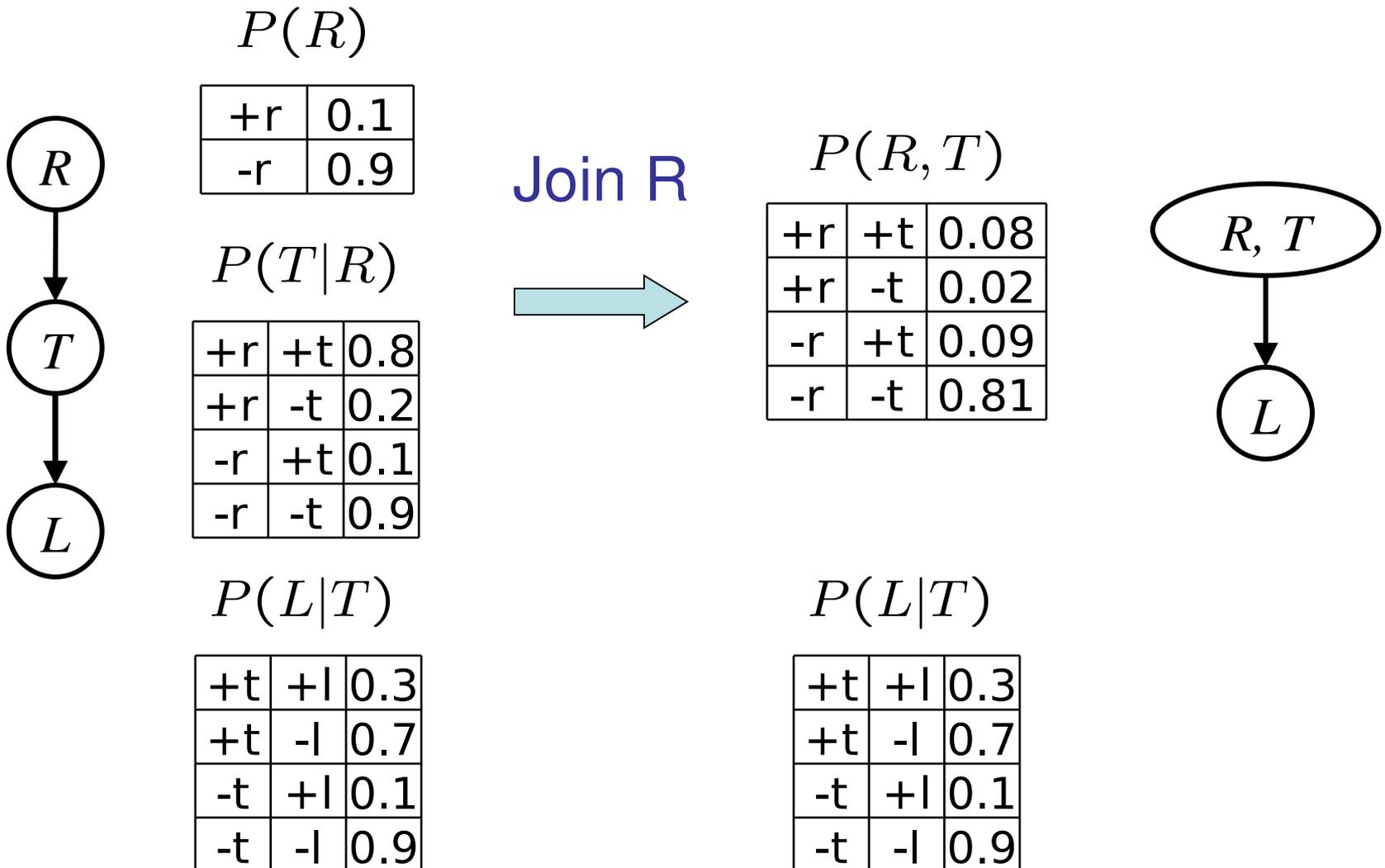
- Computation for each entry: pointwise products  
 $\forall r, t : P(r, t) = P(r) \cdot P(t|r)$

# Operation 1: Join Factors

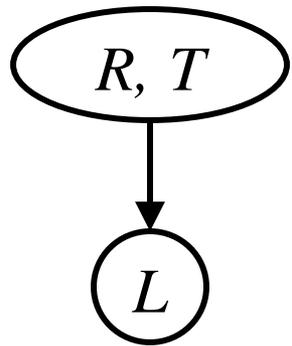
- In general, we **join on a variable**
  - Take all factors mentioning that variable
  - Join them all together with pointwise products
  - Result is  $P(\text{all LHS vars} \mid \text{all non-LHS vars})$
  - Leave other factors alone
- Example: Join on  $T$



# Example: Multiple Joins



# Example: Multiple Joins



$P(R, T)$

+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

Join T



$R, T, L$

$P(R, T, L)$

+r	+t	+l	0.024
+r	+t	-l	0.056
+r	-t	+l	0.002
+r	-t	-l	0.018
-r	+t	+l	0.027
-r	+t	-l	0.063
-r	-t	+l	0.081
-r	-t	-l	0.729

# Operation 2: Eliminate

---

- Second basic operation: **marginalization**
- Take a factor and sum out a variable
  - Shrinks a factor to a smaller one
  - A **projection** operation
- Example:

$P(R, T)$				$P(T)$	
+r	+t	0.08	sum $R$ 	+t	0.17
+r	-t	0.02		-t	0.83
-r	+t	0.09			
-r	-t	0.81			

# Multiple Elimination

$R, T, L$

$P(R, T, L)$

+r	+t	+l	0.024
+r	+t	-l	0.056
+r	-t	+l	0.002
+r	-t	-l	0.018
-r	+t	+l	0.027
-r	+t	-l	0.063
-r	-t	+l	0.081
-r	-t	-l	0.729

$T, L$

$P(T, L)$

Sum  
out R



+t	+l	0.051
+t	-l	0.119
-t	+l	0.083
-t	-l	0.747

Sum  
out T



$L$

$P(L)$

+l	0.134
-l	0.886

# P(L) : Marginalizing Early!

$P(R)$

+r	0.1
-r	0.9

Join R

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9



$P(R, T)$

+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81

Sum out R

$P(T)$

+t	0.17
-t	0.83



$P(L|T)$

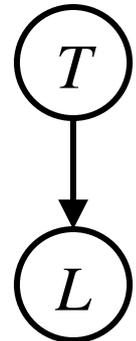
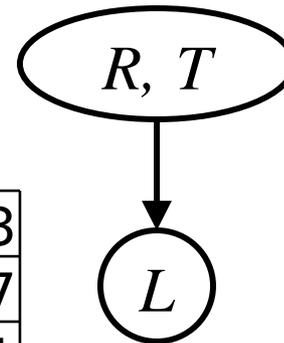
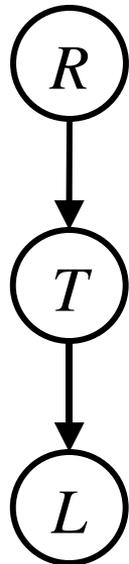
+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

$P(L|T)$

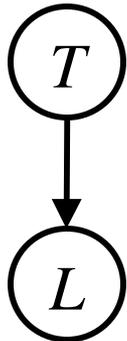
+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9



# Marginalizing Early (aka VE\*)



$P(T)$

+t	0.17
-t	0.83

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

Join T



$P(T, L)$

+t	+l	0.051
+t	-l	0.119
-t	+l	0.083
-t	-l	0.747

Sum out T



$P(L)$

+l	0.134
-l	0.886

\* VE is variable elimination

# Evidence

- If evidence, start with factors that select that evidence
  - No evidence uses these initial factors:

$$P(R)$$

+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

- Computing  $P(L|+r)$ , the initial factors become:

$$P(+r)$$

+r	0.1
----	-----

$$P(T|+r)$$

+r	+t	0.8
+r	-t	0.2

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

- We eliminate all vars other than query + evidence

# Evidence II

---

- Result will be a selected joint of query and evidence
  - E.g. for  $P(L \mid +r)$ , we'd end up with:

$$P(+r, L) \quad \text{Normalize} \quad P(L \mid +r)$$

+r	+l	0.026
+r	-l	0.074



+l	0.26
-l	0.74

- To get our answer, just normalize this!
- That's it!

# General Variable Elimination

---

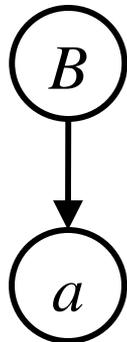
- Query:  $P(Q|E_1 = e_1, \dots, E_k = e_k)$
- Start with initial factors:
  - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
  - Pick a hidden variable H
  - Join all factors mentioning H
  - Eliminate (sum out) H
- Join all remaining factors and normalize

# Variable Elimination Bayes Rule

Start / Select

$P(B)$

B	P
+b	0.1
-b	0.9



$P(A|B) \rightarrow P(a|B)$

B	A	P
+b	+a	0.8
b	-a	0.2
-b	+a	0.1
-b	-a	0.9

Join on B



$P(a, B)$

A	B	P
+a	+b	0.08
+a	-b	0.09

Normalize

$P(B|a)$

A	B	P
+a	+b	8/17
+a	-b	9/17

# Example

---

$$P(B|j, m) \propto P(B, j, m)$$

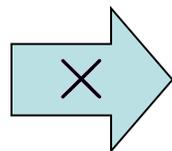
$P(B)$	$P(E)$	$P(A B, E)$	$P(j A)$	$P(m A)$
--------	--------	-------------	----------	----------

Choose A

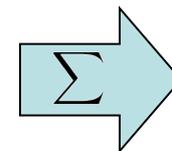
$$P(A|B, E)$$

$$P(j|A)$$

$$P(m|A)$$



$$P(j, m, A|B, E)$$



$$P(j, m|B, E)$$

$P(B)$	$P(E)$	$P(j, m B, E)$
--------	--------	----------------

# Example

$$P(B)$$

$$P(E)$$

$$P(j, m|B, E)$$

Choose E

$$\begin{array}{l} P(E) \\ P(j, m|B, E) \end{array} \xrightarrow{\times} P(j, m, E|B) \xrightarrow{\Sigma} P(j, m|B)$$

$$P(B)$$

$$P(j, m|B)$$

Finish with B

$$\begin{array}{l} P(B) \\ P(j, m|B) \end{array} \xrightarrow{\times} P(j, m, B) \xrightarrow{\text{Normalize}} P(B|j, m)$$

# Variable Elimination

---

- What you need to know:
  - Should be able to run it on small examples, understand the factor creation / reduction flow
  - Better than enumeration: saves time by marginalizing variables as soon as possible rather than at the end
- We will see special cases of VE later
  - On tree-structured graphs, variable elimination runs in polynomial time
  - You'll have to implement a tree-structured special case to track invisible ghosts (Project 4)

# Approximate Inference

---

- Simulation has a name: sampling
- Sampling is a hot topic in machine learning, and it's really simple
- Basic idea:
  - Draw  $N$  samples from a sampling distribution  $S$
  - Compute an approximate posterior probability
  - Show this converges to the true probability  $P$
- Why sample?
  - Learning: get samples from a distribution you don't know
  - Inference: getting a sample is faster than computing the right answer (e.g. with variable elimination)



# Prior Sampling

$$P(C)$$

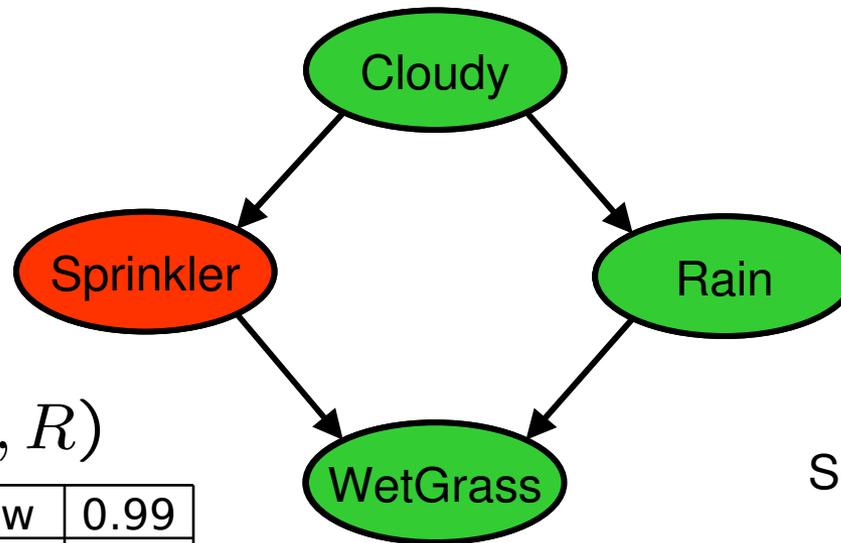
+c	0.5
-c	0.5

$$P(S|C)$$

+c	+s	0.1
	-s	0.9
-c	+s	0.5
	-s	0.5

$$P(R|C)$$

+c	+r	0.8
	-r	0.2
-c	+r	0.2
	-r	0.8



$$P(W|S, R)$$

+s	+r	+w	0.99
		-w	0.01
+s	-r	+w	0.90
		-w	0.10
-s	+r	+w	0.90
		-w	0.10
-s	-r	+w	0.01
		-w	0.99

Samples:

+c, -s, +r, +w

-c, +s, -r, +w

...

# Prior Sampling

---

- This process generates samples with probability:

$$S_{PS}(x_1 \dots x_n) = \prod_{i=1}^n P(x_i | \text{Parents}(X_i)) = P(x_1 \dots x_n)$$

...i.e. the BN's joint probability

- Let the number of samples of an event be  $N_{PS}(x_1 \dots x_n)$

- Then 
$$\begin{aligned} \lim_{N \rightarrow \infty} \hat{P}(x_1, \dots, x_n) &= \lim_{N \rightarrow \infty} N_{PS}(x_1, \dots, x_n) / N \\ &= S_{PS}(x_1, \dots, x_n) \\ &= P(x_1 \dots x_n) \end{aligned}$$

- I.e., the sampling procedure is **consistent**

# Example

- First: Get a bunch of samples from the BN:

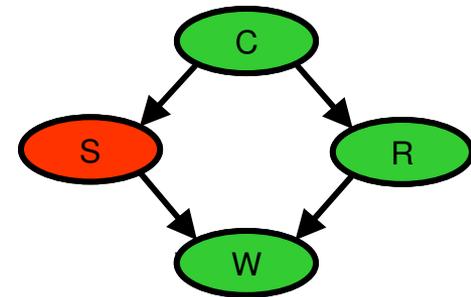
+C, -S, +r, +W

+C, +S, +r, +W

-C, +S, +r, -W

+C, -S, +r, +W

-C, -S, -r, +W

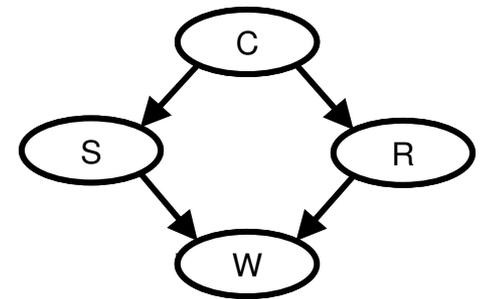


- Example: we want to know  $P(W)$

- We have counts  $\langle +w:4, -w:1 \rangle$
- Normalize to get approximate  $P(W) = \langle +w:0.8, -w:0.2 \rangle$
- This will get closer to the true distribution with more samples
- Can estimate anything else, too
- What about  $P(C| +w)$ ?  $P(C| +r, +w)$ ?  $P(C| -r, -w)$ ?
- Fast: can use fewer samples if less time (what's the drawback?)

# Rejection Sampling

- Let's say we want  $P(C)$ 
  - No point keeping all samples around
  - Just tally counts of  $C$  as we go
- Let's say we want  $P(C | +s)$ 
  - Same thing: tally  $C$  outcomes, but ignore (reject) samples which don't have  $S=+s$
  - This is called **rejection sampling**
  - It is also consistent for conditional probabilities (i.e., correct in the limit)



+C, -S, +r, +W  
+C, +S, +r, +W  
-C, +S, +r, -W  
+C, -S, +r, +W  
-C, -S, -r, +W

# Sampling Example

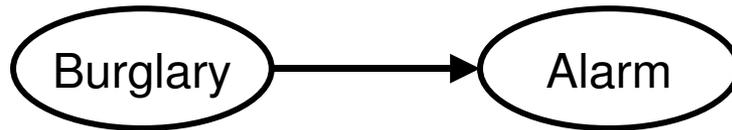
---

- There are 2 cups.
  - The first contains 1 penny and 1 quarter
  - The second contains 2 quarters
- Say I pick a cup uniformly at random, then pick a coin randomly from that cup. It's a quarter (yes!). What is the probability that the other coin in that cup is also a quarter?

# Likelihood Weighting

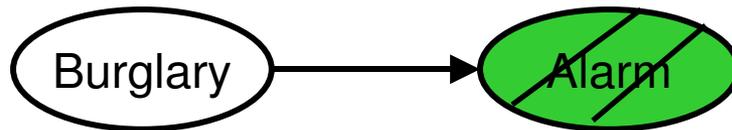
- Problem with rejection sampling:

- If evidence is unlikely, you reject a lot of samples
- You don't exploit your evidence as you sample
- Consider  $P(B|+a)$



-b, -a  
 -b, -a  
 -b, -a  
 -b, -a  
 +b, +a

- Idea: fix evidence variables and sample the rest



-b +a  
 -b, +a  
 -b, +a  
 -b, +a  
 +b, +a

- Problem: sample distribution not consistent!
- Solution: weight by probability of evidence given parents

# Likelihood Weighting

$$P(C)$$

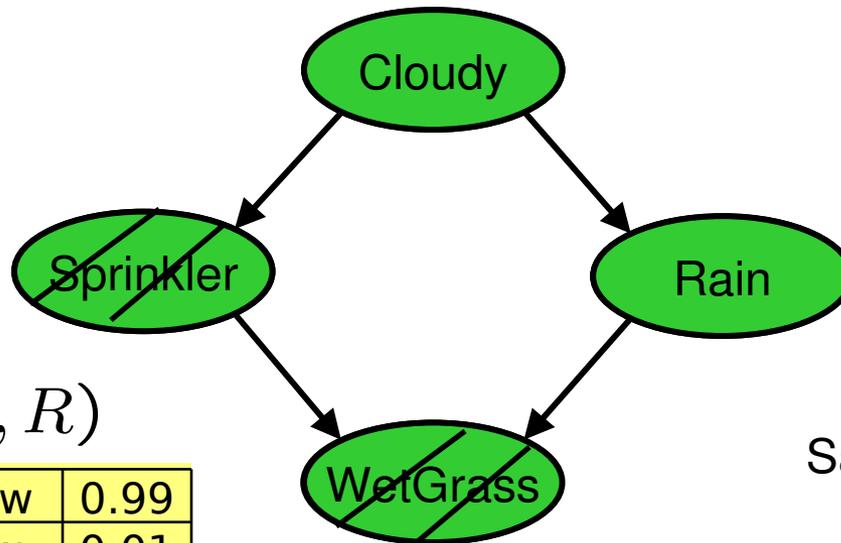
+c	0.5
-c	0.5

$$P(S|C)$$

+c	+s	0.1
	-s	0.9
-c	+s	0.5
	-s	0.5

$$P(R|C)$$

+c	+r	0.8
	-r	0.2
-c	+r	0.2
	-r	0.8



$$P(W|S, R)$$

+s	+r	+w	0.99
		-w	0.01
-s	-r	+w	0.90
		-w	0.10
	+r	+w	0.90
		-w	0.10
-r	+w	0.01	
	-w	0.99	

Samples:

+c, +s, +r, +w

...

$$w = 1.0 \times 0.1 \times 0.99$$

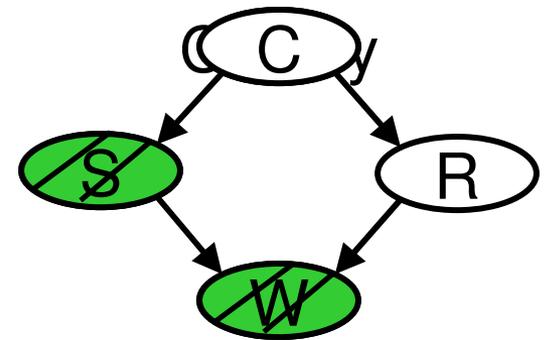
# Likelihood Weighting

- Sampling distribution if  $z$  sampled and  $e$  fixed evidence

$$S_{WS}(z, e) = \prod_{i=1}^l P(z_i | \text{Parents}(Z_i))$$

- Now, samples have weights

$$w(z, e) = \prod_{i=1}^m P(e_i | \text{Parents}(E_i))$$

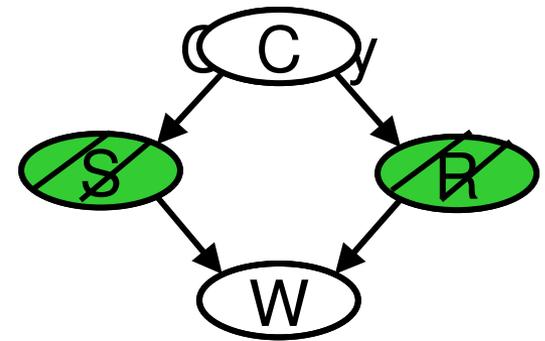


- Together, weighted sampling distribution is consistent

$$\begin{aligned} S_{WS}(z, e) \cdot w(z, e) &= \prod_{i=1}^l P(z_i | \text{Parents}(z_i)) \prod_{i=1}^m P(e_i | \text{Parents}(e_i)) \\ &= P(z, e) \end{aligned}$$

# Likelihood Weighting

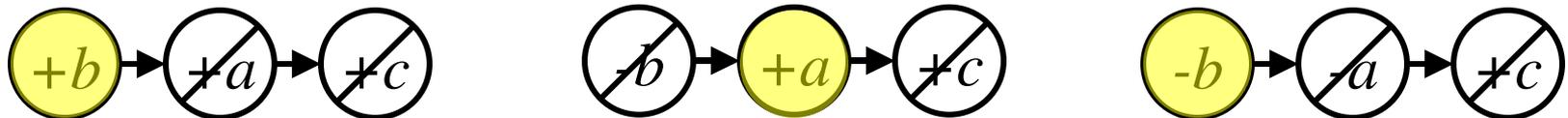
- Likelihood weighting is good
  - We have taken evidence into account **as we generate the sample**
  - E.g. here,  $W$ 's value will get picked based on the evidence values of  $S$ ,  $R$
  - More of our samples will reflect the state of the world suggested by the evidence
- Likelihood weighting doesn't solve all our problems
  - Evidence influences the choice of downstream variables, but not upstream ones ( $C$  isn't more likely to get a value matching the evidence)
- We would like to consider evidence when we sample every variable



# Markov Chain Monte Carlo\*

---

- *Idea*: instead of sampling from scratch, create samples that are each like the last one.
- *Procedure*: resample one variable at a time, conditioned on all the rest, but keep evidence fixed. E.g., for  $P(B|+c)$ :



- *Properties*: Now samples are not independent (in fact they're nearly identical), but sample averages are still consistent estimators!
- *What's the point*: both upstream and downstream variables condition on evidence.