

# **CS344M**

# **Autonomous Multiagent Systems**

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Department of Computer Science  
The University of Texas at Austin

# Good Afternoon, Colleagues

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Are there any questions?

# Logistics

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- Questions about the syllabus?

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  - Brooks' reactive robots
  - A more deliberative architecture
  - RoboCup challenge paper

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All proposed definitions include too much or leave gaps.

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But there are examples. . .



# Thermostats

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- Are they agents or not?
- How does Wooldridge resolve this?

# Intelligent (autonomous) Agents

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- Information gathering agent
  - Find me the cheapest?

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- Autonomous robot
- Information gathering agent
  - Find me the cheapest?
- E-commerce agents
  - Decides what to buy/sell and does it
- Air-traffic controller
- Meeting scheduler
- Computer-game-playing agent

# Not Intelligent Agents

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- Thermostat
- Telephone
- Answering machine
- Pencil
- Java object



# Your Agent Examples

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- **Automotive:** Stop light, Autonomous Car
- **Physical Control:** Roomba, Automatic sliding door
- **Software:** antivirus software, Google Now, Laptop battery management, Macbook light intensity controller, Parasolid
- **Game/entertainment:** StarCraft SCV, Counterstrike
- **Service:** Stock trading agent

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- You, as a class, act as a learning agent
- **Actions:** Wave, Stand, Clap
- **Observations:** colors, reward
- **Goal:** Find an optimal *policy*
  - Way of selecting actions that gets you the most reward



# How did you do it?

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- What is your policy?
- What does the world look like?

# Formalizing My Example

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Knowns:

# Formalizing My Example

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## Knowns:

- $\mathcal{O} = \{\text{Blue, Red, Green, Black, } \dots\}$
- Rewards in  $\mathbb{R}$
- $\mathcal{A} = \{Wave, Clap, Stand\}$

$$o_0, a_0, r_0, o_1, a_1, r_1, o_2, \dots$$

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- $\mathcal{R} : \mathcal{S} \times \mathcal{A} \mapsto \mathbb{R}$
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$$r_i = \mathcal{R}(s_i, a_i)$$

$$s_{i+1} = \mathcal{T}(s_i, a_i)$$