

# Translation Synchronization via Truncated Least Squares

Xiangru Huang<sup>1</sup>\*, Zhenxiao Liang<sup>2</sup>\*, Chandrajit Bajaj<sup>1</sup>, Qixing Huang<sup>1</sup>. (\* equally contributed)

<sup>1</sup> University of Texas at Austin. <sup>2</sup> Tsinghua University.

## Abstract

- ▶ 1D Translation Synchronization problem: recover global coordinates  $\{x_i\}$  from noisy relative measurements  $t_{ij} = x_i - x_j + \text{noise}$ .
- ▶ We introduce a robust algorithm *TranSync* for this problem by applying truncated least squares to **gradually prune out** noisy measurements.
- ▶ We provide analysis of our algorithm under both **deterministic** and **randomized** settings.
- ▶ In experiments, our algorithm achieved superior robustness and stability against state-of-the-art convex formulations on both **synthetic** and **real** datasets.

## Formulations

- ▶  $l_1$  minimization:

$$\arg \min_x \sum_{i,j \in \mathcal{E}} |t_{ij} - (x_i - x_j)|$$

- ▶ Least Squares:

$$\arg \min_x \sum_{i,j \in \mathcal{E}} |t_{ij} - (x_i - x_j)|^2$$

- ▶ Truncated Least Squares (ours):

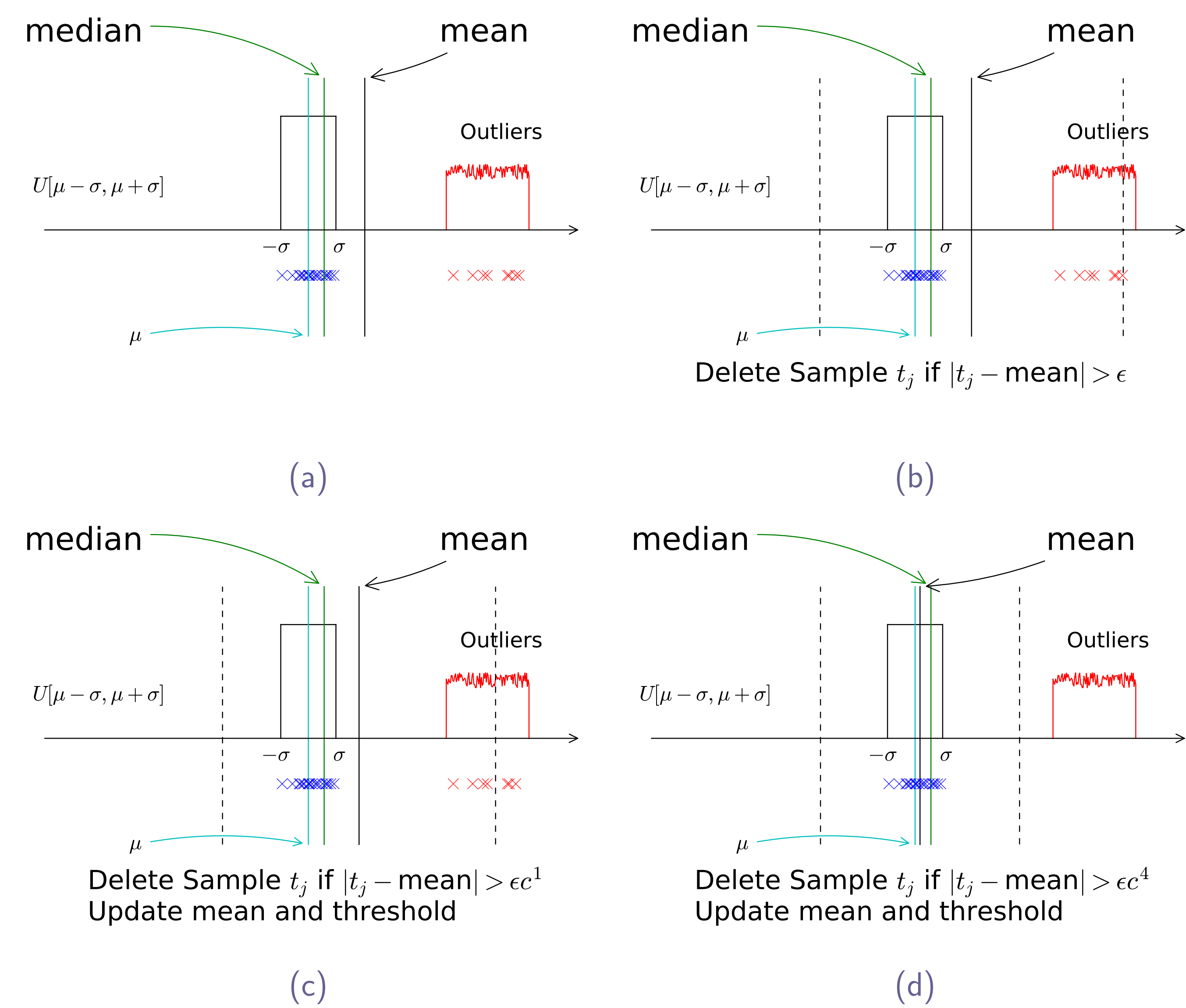
$$\arg \min_x \sum_{i,j \in \mathcal{E}} w_{ij}^{(k)} |t_{ij} - (x_i - x_j)|^2$$

## Our Algorithm

1.  $x^{(-1)} \leftarrow \mathbf{0}$ .  $\delta_{-1} \leftarrow \infty$ .  $c < 1$ .
- for  $k = 0, 1, 2, k_{\max}$  do
2. Obtain the truncated graph  $\mathcal{G}^{(k)}$  using  $x^{(k-1)}$  and  $\delta_{k-1}$ .
3. **Break** if  $\mathcal{G}^{(k)}$  is disconnected
4. Solve Truncated Least Squares w.r.t.  $\mathcal{G}^{(k)}$  to obtain  $x^{(k)}$ .
5.  $\delta_k = \min \left( \max_{(i,j) \in \mathcal{E}} |t_{ij} - (x_i^{(k)} - x_j^{(k)})|, c\delta_{k-1} \right)$ .

end for

**Output:**  $x^{(k)}$ .



## Deterministic Exact Recovery Condition

- ▶ **Biased Noise Model (Unbounded Outliers):**

$$t_{ij} = \begin{cases} x_i^{\text{gt}} - x_j^{\text{gt}} + U[-\sigma, \sigma] & \text{with probability } p \\ \text{Any real number} & \text{with probability } 1 - p \end{cases} \quad (1)$$

- ▶ For some constants  $p, q$  only depend on graph structure, during optimization we have

$$\|x^{(k)} - x^{\text{gt}}\|_{\infty} \leq q\sigma + 2p\epsilon c^{k-1}$$

and eventually we'll reach an  $\hat{x}$

$$\|\hat{x} - x^{\text{gt}}\|_{\infty} \leq \frac{2p + cq}{c - 4p} \sigma$$

where the RHS is independent of  $\epsilon$ .

## Randomized Case

**Biased Noise Model:**

$$t_{ij} = \begin{cases} x_i^{\text{gt}} - x_j^{\text{gt}} + U[-\sigma, \sigma] & \text{with probability } p \\ x_i^{\text{gt}} - x_j^{\text{gt}} + U[-a, b] & \text{with probability } 1 - p \end{cases} \quad (2)$$

**Theorem**

There exists a constant  $c$  so that if  $p > c/\sqrt{\log(n)}$ , then w.h.p,

$$\|x^{(k)} - x^{\text{gt}}\|_{\infty} \leq (1 - p/2)^k (b - a),$$

$$\forall k = 0, \dots, \lceil -\log(\frac{b+a}{2\sigma}) / \log(1 - p/2) \rceil.$$

## Experiments

**Synthetic Graphs in  $\{\text{Dense, Sparse}\} \times \{\text{Regular, Irregular}\}$**

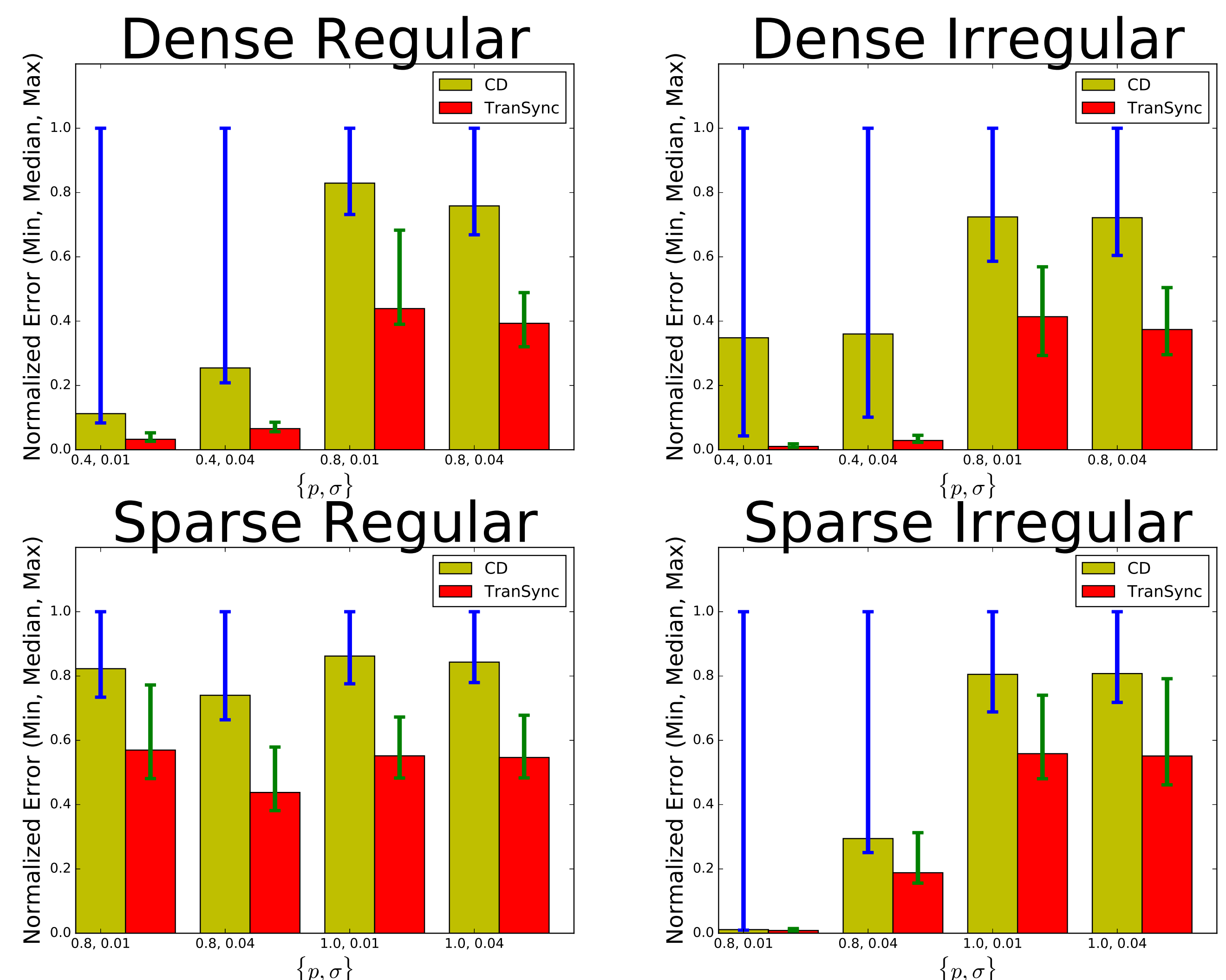


Figure: Experimental results comparing TranSync and Coordinate Descent (CD) under different settings. All statistics (min, median, max) are computed among 100 independent experiments with the same setting. Bars under the same setting are normalized for better display.

**Joint alignment of point clouds.**



Figure: The application of TranSync in joint alignment of 6K Lidar scans around a city block. (a) Snapshot of the underlying scanning trajectory. (b) Reconstruction using TranSync (c) Reconstruction using Coordinate Descent.

**Ranking from relative comparisons.**

| Movie                      | Global ranking (score) |             |             |              |            |           |
|----------------------------|------------------------|-------------|-------------|--------------|------------|-----------|
|                            | MRQE                   | Hodge-Diff. | Hodge-Ratio | Hodge-Binary | TS-Init    | TS-Final  |
| Shakespeare in Love        | 1(85)                  | 1(0.247)    | 2(0.078)    | 1 (0.138)    | 1(0.135)   | 1(0.219)  |
| Witness                    | 2(77)                  | 2(0.217)    | 1(0.088)    | 3(0.107)     | 3(0.076)   | 2(0.095)  |
| October Sky                | 3(76)                  | 3(0.213)    | 3(0.078)    | 2(0.111)     | 2(0.092)   | 3(0.0714) |
| The Waterboy               | 4(66)                  | 6(-0.464)   | 6(-0.162)   | 6(-0.252)    | 5(-0.134)  | 4(-0.112) |
| Interview with the Vampire | 5(65)                  | 4(-0.031)   | 4(-0.012)   | 4(-0.120)    | 4 (-0.098) | 5(-0.140) |
| Dune                       | 6(44)                  | 5(-0.183)   | 5(-0.069)   | 5(-0.092)    | 6(-0.216)  | 6(-0.281) |

Table: Global ranking of selected six movies via different methods: MRQE, HodgeRank[1] with 1) arithmetic mean score difference, 2) geometric mean score ratio and 3) and binary comparisons, and the initial and final predictions of TranSync. TranSync results in the most consistent result with MRQE.

## Reference

- ▶ Xiaoye Jiang, Lek-Heng Lim, Yuan Yao, and Yinyu Ye. Statistical ranking and combinatorial hodge theory. *Math. Program.*, 127(1):203–244, 2011.