B-Splines and OpenGL/GLU
Spline Curves

• Successive linear blend
• Basis polynomials
• Recursive evaluation
• Properties
• Joining segments

Tensor-product-patch Spline Surfaces

• Tensor product patches
• Recursive Evaluation
• Properties
• Joining patches

OpenGL and Glut Support
Splines

If give up on small support, get natural splines; every control point influences the whole curve.

If give up on interpolation, get cubic B-splines.
B-Splines

Need only one basis function, all $B_i(t)$ are obtained by shifts: $B_i(t) = B(t - i)$. The basis function is piecewise polynomial:

$$B(t) = \begin{cases} 
0 & t \leq -2 \\
\frac{1}{6}t^3 + 2t + \frac{4}{3} + t^2 & t \leq -1 \\
\frac{2}{3} - t^2 - \frac{1}{2}t^3 & t \leq 0 \\
\frac{2}{3} - t^2 + \frac{1}{2}t^3 & t \leq 1 \\
\frac{4}{3} - 2t + t^2 - \frac{1}{6}t^3 & t \leq 2 \\
0 & 2 \leq t 
\end{cases}$$
B-Splines

The curve with control points \( p_0, p_1, p_2, \ldots p_n \) is computed using

\[
p(t) = \sum_{i=0}^{n} p_i B(t - i)
\]

The allowed range of \( t \) is from 1 to \( n - 1 \); outside this interval our functions do not sum up to 1, which means in particular that if we move control points together in the same way, the curve outside the interval will not move rigidly.
B-Splines

The minimal number of points required is 4; this corresponds to the interval for $t$ of length 1.

This is inconvenient - but we can always add control points by reflection.
B-Splines

Adding control points by reflection:

\[ p_{-1} = 2p_0 - p_1; \quad p_{n+1} = 2p_n - p_{n-1} \]
Drawing B-Splines

Hardware typically can draw only line segments. Need to approximate B-spline with piecewise linear curve. Simplest approach:

Choose small $\Delta t$.
Compute points $p(0), p(\Delta t), p(2\Delta t), \ldots$.
Draw line segments connecting the points.

Not very efficient — have to evaluate a cubic polynomial (or several) at each point.

Can do better using a magic algorithm (subdivision). Next lecture!
Another Formulation: Discontinuities in Bézier Splines

Bézier Discontinuities:

• Two Bézier segments can be completely disjoint
• Two segments join if they share last/first control point
Common Parameterization and Blending Functions

- Joined curves can be given common parameterization
  - Parameterize first segment with $0 \leq t < 1$
  - Parameterize next segment with $1 \leq t \leq 2$, etc.
- Look at blending/basis polynomials under this parameterization
  - Combine those for common $P_j$ into a single piecewise polynomial

\[ \begin{array}{c}
  B_0 & B_1 & B_2 & B_3 & B_4 \\
  \hline
  0 & 1 & 2
\end{array} \]
Combined Curve Segments

- Curve is \( P(t) = P_0B_0(t) + P_1B_1(t) + P_2B_2(t) + P_3B_3(t) + P_4B_4(t) \), where

\[
\begin{align*}
B_0(t) & = \begin{cases} 
(1 - t)^2 & 0 \leq t < 1 \\
0 & 1 \leq t \leq 2 
\end{cases} \\
B_1(t) & = \begin{cases} 
2((1 - t)t & 0 \leq t < 1 \\
0 & 1 \leq t \leq 2 
\end{cases} \\
B_2(t) & = \begin{cases} 
t^2 & 0 \leq t < 1 \\
(2 - t)^2 & 1 \leq t \leq 2 
\end{cases} \\
B_3(t) & = \begin{cases} 
0 & 0 \leq t < 1 \\
2(2 - t)(t - 1) & 1 \leq t \leq 2 
\end{cases} \\
B_4(t) & = \begin{cases} 
0 & 0 \leq t < 1 \\
(t - 1)^2 & 1 \leq t \leq 2 
\end{cases}
\]
Curve Discontinuities from Basis Discontinuities

- $P_2$ is scaled by $B_2(t)$, which has a discontinuous derivative
- The corner in the curve results from this discontinuity
Spline Continuity

Smother Blending Functions:

- Can $B_0(t), \ldots, B_4(t)$ be replaced by smoother functions?
  - Piecewise polynomials on $0 \leq t \leq 2$
  - Continuous derivatives
- Yes, but we lose one degree of freedom
  - Curve has no corner if segments share a common tangent
  - Tangent is given by the chords $\overline{P_1P_2}$, $\overline{P_2P_3}$
  - An equation constrains $P_1, P_2, P_3$
    
    \[ P_3 - P_2 = P_2 - P_1 \implies P_2 = \frac{P_1 + P_3}{2} \]

- This equation leads to combinations:

\[
P_0B_0(t) + P_1 \left( B_1(t) + \frac{1}{2}B_2(t) \right) + P_3 \left( \frac{1}{2}B_2(t) + B_3(t) \right) + P_4B_4(t)
\]
Spline Basis:

- Combined functions form a smoother *spline basis*

\[
\begin{align*}
\bar{B}_0(t) &= B_0(t) \\
\bar{B}_1(t) &= \left( B_1(t) + \frac{1}{2} B_2(t) \right) \\
\bar{B}_2(t) &= \left( \frac{1}{2} B_2(t) + B_3(t) \right) \\
\bar{B}_3(t) &= B_4(t)
\end{align*}
\]
Smoother Curves:

- Control points used with this basis produce smoother curves.

General B-Splines:

- Nonuniform B-splines (NUBS) generalize this construction
- A B-spline, $B^d_i(t)$, is a piecewise polynomial:
  - each of its segments is of degree $\leq d$
  - it is defined for all $t$
  - its segmentation is given by knots $t = t_0 \leq t_1 \leq \cdots \leq t_N$
- it is zero for $T < T_i$ and $T > T_{i+d+1}$
- it may have a discontinuity in its $d - k + 1$ derivative at $t_j \in \{t_i, \ldots, t_{i+d+1}\}$, if $t_j$ has multiplicity $k$
- it is nonnegative for $t_i < t < t_{i+d+1}$
- $B_i^d(t) + \cdots + B_{i+d}(t) = 1$ for $t_{i+d} \leq t < t_{i+d+1}$, and all other $B_j^d(t)$ are zero on this interval
- Bézier blending functions are the special case where all knots have multiplicity $d + 1$
Example (Quadratic):

\[
B_i, B_{i+1}, B_{i+2}
\]

\[
t_i, t_{i+1}, t_{i+2}, t_{i+3}, t_{i+4}, t_{i+5}
\]
Evaluation:

- There is an efficient, recursive evaluation scheme for any curve point
- It generalizes the triangle scheme (deCasteljau) for Bézier curves
- Example (for cubics and \( t_{i+3} \leq t < t_{i+4} \)): 

Curves and Surfaces Programming using OpenGL and GLU

Quadrics support in GLU

Define a quadric object.

GLUquadricObj*p;
p=gluNewQuadric();

Specify a rendering Style of Quadric. Example as a wireframe.

gluQuadricDrawStyle(p,GLU_LINE);

Example a cylinder with its length along the y-axis

gluCylinder(p,BASE_RADIUS,BASE_RADIUS,BASE_HEIGHT,sample_circle,sample_height)

sample_circle = number of pieces of the base

sample_height = number of height pieces
**Bézier Curves and Surfaces**

Support is available through 1D, 2D, 3D, 4D *evaluators* to compute values for the polynomials used in Bézier and NURBS.

```c
glMaplf(type,u_min,u_max,stride,order,point_array)
```

- **type** = 3D points, 4D points, RGBA colors, normals, indexed colors, 1D to 4D texture coordinates
- **u_min** <= parameter u <= **u_max**
- **stride** = number of parameter values between curve segments
- **order** = degree of polynomial + 1
- **control polygon** = defined by **point_array**

Example an *evaluator* for a 3D cubic Bézier curve defined over (0,1) with a stride of 3 and order 4
point data[]={...}
glMap1f(GL_MAP_VERTEX_3, 0.0, 1.0, 3, 4, data);

Multiple evaluators can be active at the same time, and can be used to evaluate curves, normals, colors etc at the same time

To render the Bézier Curve over (0,1) with 100 line segments

glEnable(GL_MAP_VERTEX_3);
glBegin(GL_LINE_STRIP)
    for(i=0; i<100; i++) glEvalCoord1f((float) i/100.0);
glEnd();

The GLUT library has the teapot as an object. See pg 646-648, Chap 12 for display/render program a teapot using Bézier functions.

For lighting / shading using a NURBS surface, when additionally needs surface normals. These could be generated automatically, using

glEnable(GL_AUTO_NORMAL)
NURBS functions in GLU library

`gluNewNurbsRenderer()` - create a pointer to a NURBS object

`gluNurbsProperty()` - choose rendering values such as size of lines, polygons. Also enables a mode where the tesselated geometry can be retrieved through the callback interface

`gluNurbsCallBack()` - register the functions to call to retreive the tesselated geometric data or if you wish notification when an error is encountered

`gluNurbsCurve()` `gluNurbsSurface()` - to generate and render -specify control points, knot sequence, order, and/or normals, texture coordinates
Teapot using Bézier Patches: Wireframe Model

/* Enable evaluator */
glEnable( GL_MAP2_VERTEX_3 );

.glColor3f( 1.0, 1.0, 1.0 );
glRotatef( -90.0, 1.0, 0.0, 0.0 );
glScalef( 0.25, 0.25, 0.25 );

/* Draw wireframe */
for ( k=0; k< 32; k++ )
{
    glMap2f( GL_MAP2_VERTEX_3, 0, 1, 3, 4, 0, 1, 12
        &data[ k ][ 0 ][ 0 ] );

    for ( j = 0; j <= 4; j++ )
    {
        glBegin( GL_LINE_STRIP );
        for ( i = 0; i <= 20; i++ )
            glEvalCoord2f( ( GLfloat ) i / 20.0, ( GLfloat ) j / 4 );
        glEnd( );

        glBegin(GL_LINE_STRIP);
        for ( i = 0; i <=20; i++ )
            glEvalCoord2f( ( GLfloat ) j / 4.0, ( GLfloat ) i / 20 );
        glEnd( );
    }
}
/* Enable evaluators */
glEnable( GL_MAP2_VERTEX_3 );

/* Set up light */
GLfloat light_position[ ] = { 1.0, 1.0, 1.0, 0.0 };
GLfloat light_ambient[ ] = { 0.2, 0.2, 0.2, 1.0 };
GLfloat light_diffuse[ ] = { 0.6, 0.6, 0.6, 1.0 };
gLightfv( GL_LIGHT0, GL_POSITION, light_position );
gLightfv( GL_LIGHT0, GL_AMBIENT, light_ambient );
gLightfv( GL_LIGHT0, GL_DIFFUSE, light_diffuse );
gEnable( GL_LIGHTING );
gEnable( GL_LIGHT0 );
gEnable( GL_AUTO_NORMAL );

/* Set up material properties */
GLfloat mat_ambient[ ] = { 0.2, 0.2, 0.2, 1.0 };
GLfloat mat_specular[ ] = { 1.0, 1.0, 1.0 };
GLfloat mat_diffuse[ ] = { 0.6, 0.6, 0.6, 1.0 };
gMaterialfv( GL_FRONT_AND_BACK, GL_AMBIENT, mat_ambient );
gMaterialfv( GL_FRONT_AND_BACK, GL_DIFFUSE, mat_diffuse );
gMaterialfv( GL_FRONT_AND_BACK, GL_SPECULAR, mat_specular );
gMaterialf( GL_FRONT_AND_BACK, GL_SHININESS, 50.0 );

gRotatef( -90.0, 1.0, 0.0, 0.0 );
gScalef( 0.25, 0.25, 0.25 );

/* Draw solid model */
for ( k=0; k< 32; k++ ) {
    glMapGrid2f( 8, 0.0, 1.0, 8, 0.0, 1.0 );
}
Reading Assignment and News

Before the next class please review Chapter 10 and its practice exercises, of the recommended text. Also please see the midterm review questions.

(Recommended Text: Interactive Computer Graphics, by Edward Angel, Dave Shreiner, 6th edition, Addison-Wesley)

Please track Blackboard for the most recent Announcements and Project postings related to this course.

(http://www.cs.utexas.edu/users/bajaj/graphics2012/cs354/)