

Programming the Internet of Uncertain **<T>**hings

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Microsoft Research

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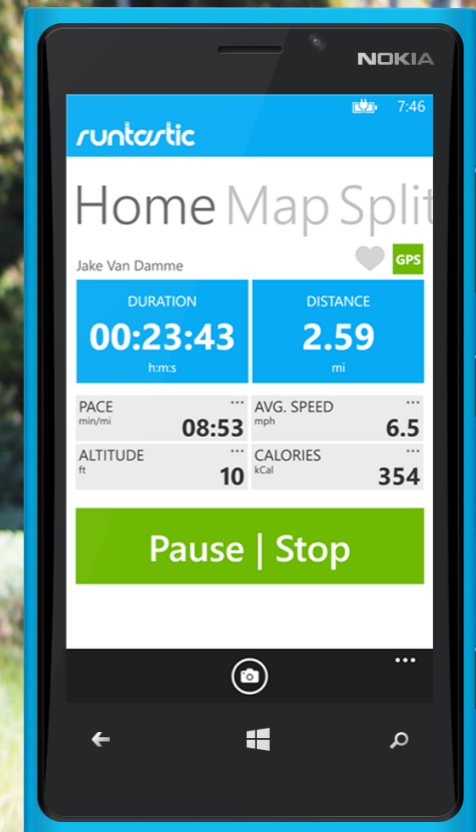
24 mph

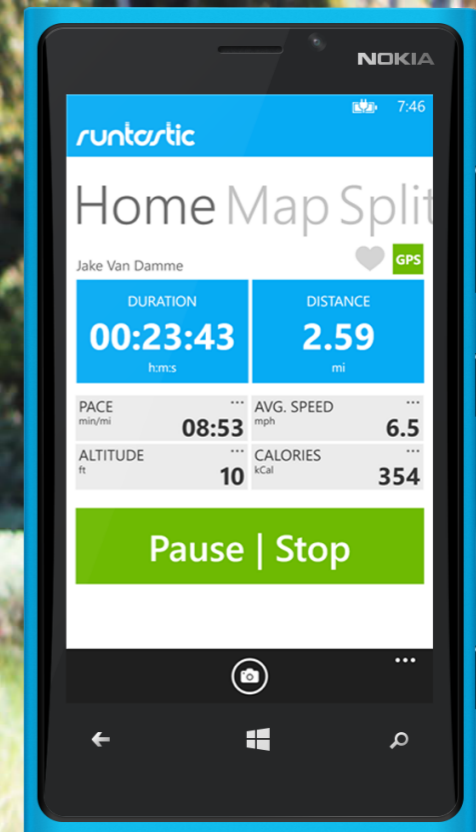


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```

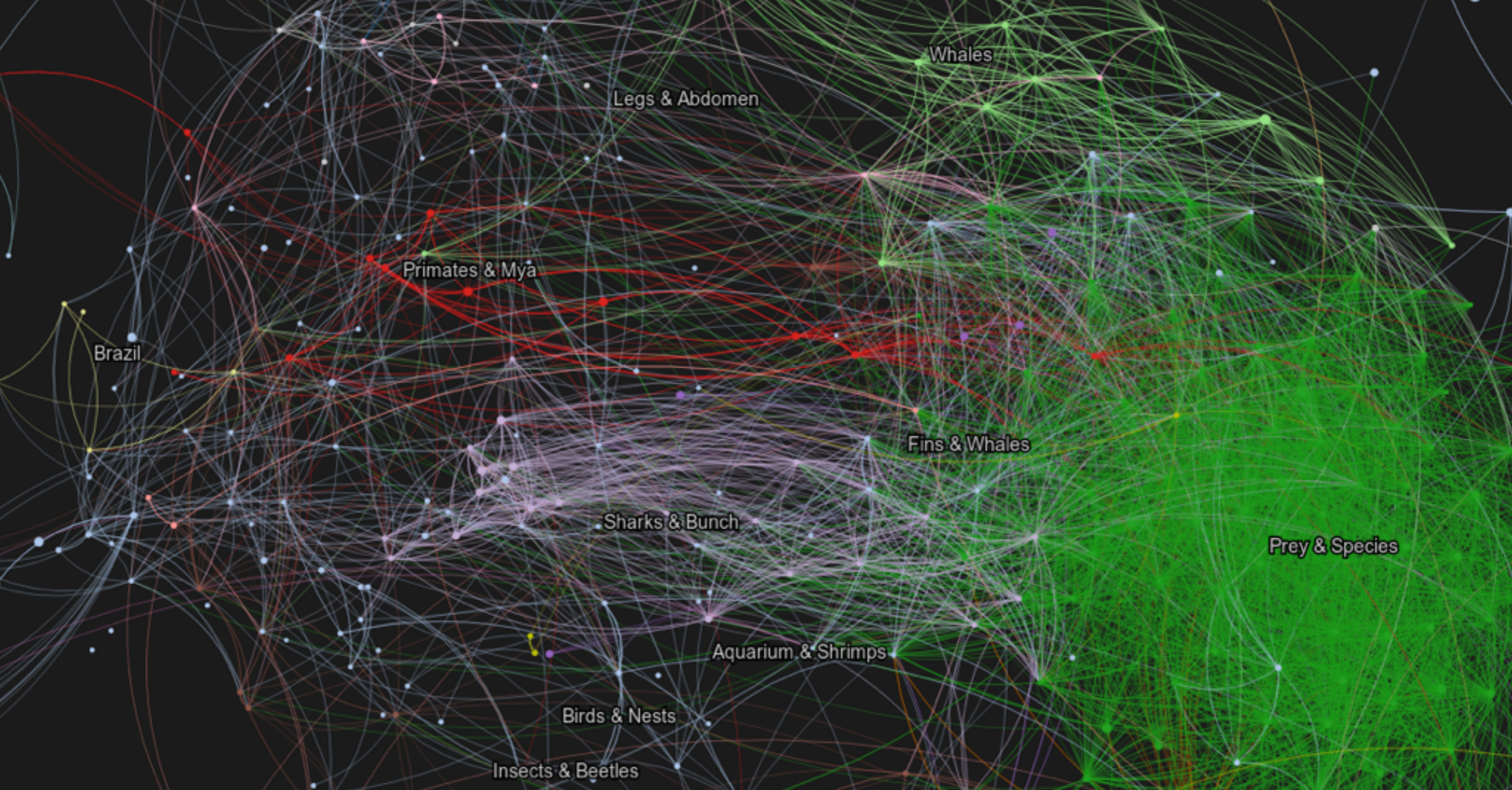
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double Dist =  
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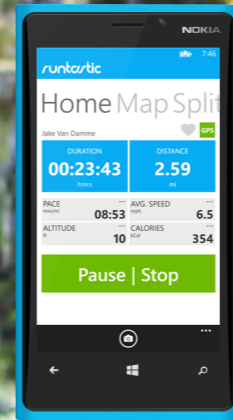
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if (Speed > 4)  
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```



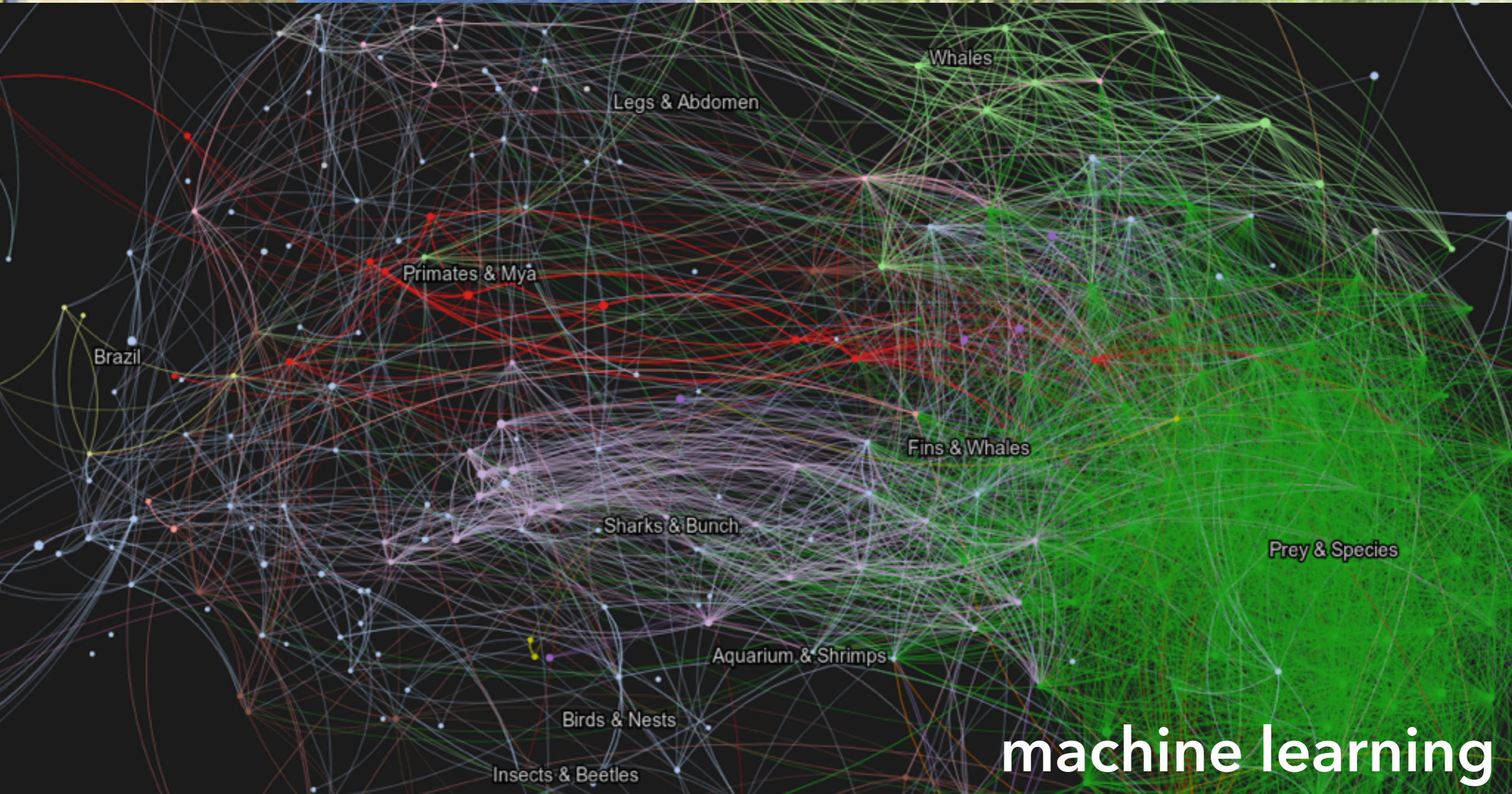


59 mph

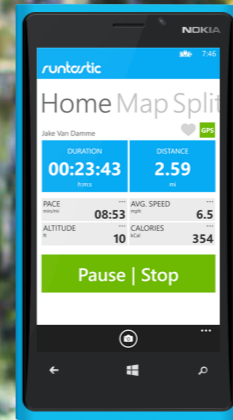




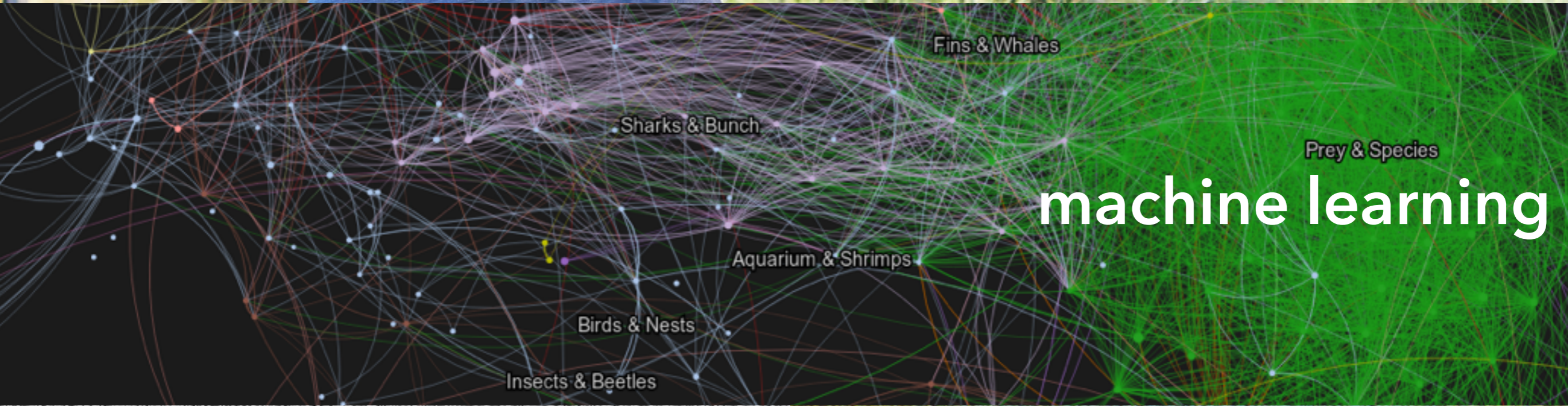
sensors



machine learning

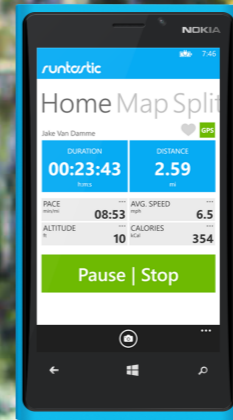


sensors

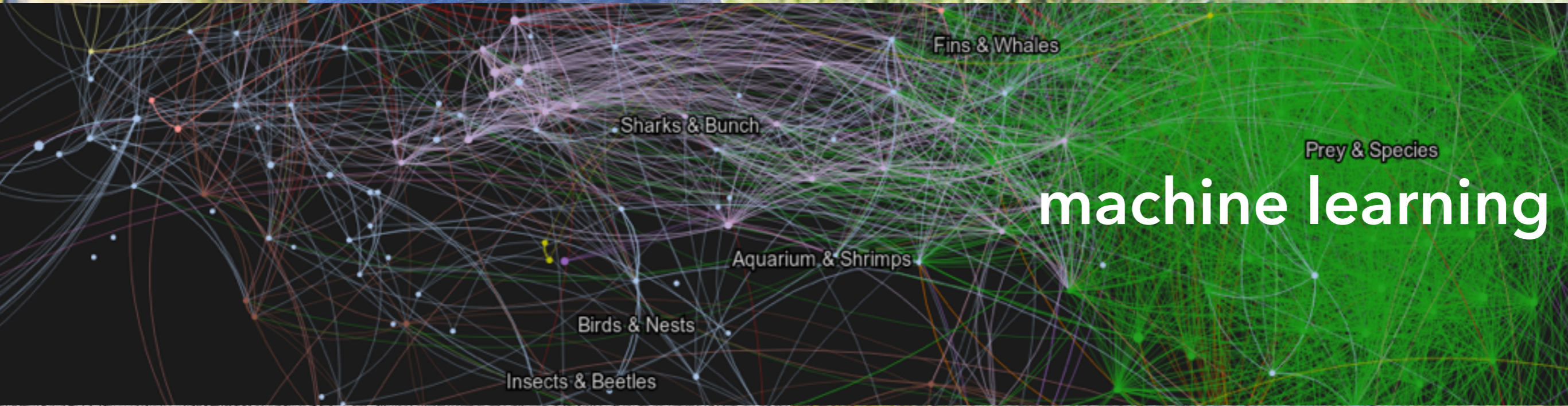


machine learning





sensors



machine learning



approximate
computing

Uncertain<T>

an abstraction for reasoning about noise [ASPLOS'14]

exploiting context

language constructs to make data more accurate

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86% fewer errors

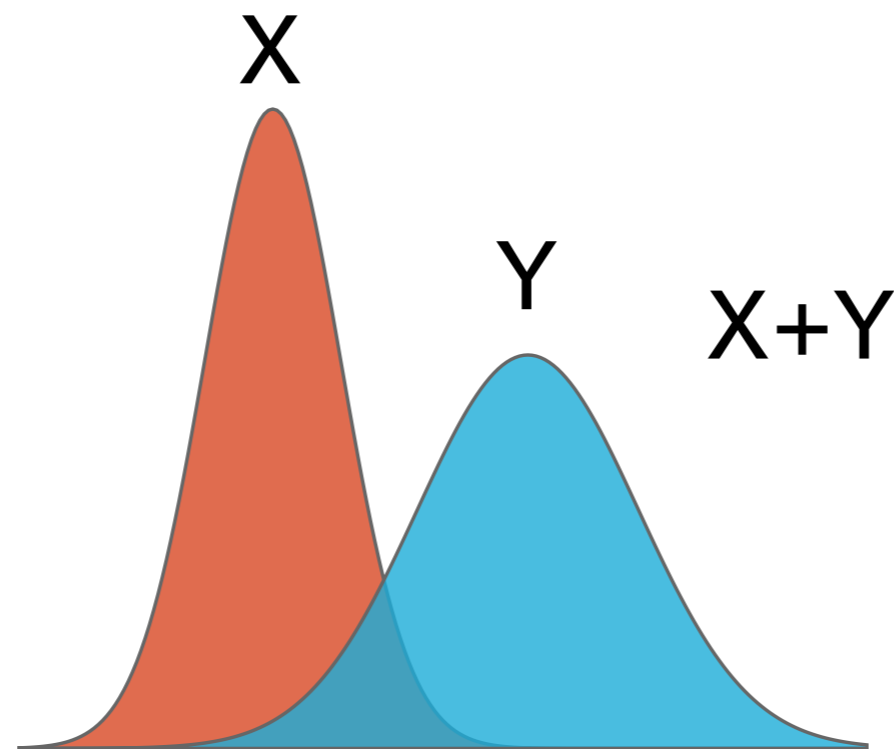
Semantics

Uncertain<T> encapsulates probability distributions and hides statistical complexity.

- Computing over random variables
- Deciding conditionals

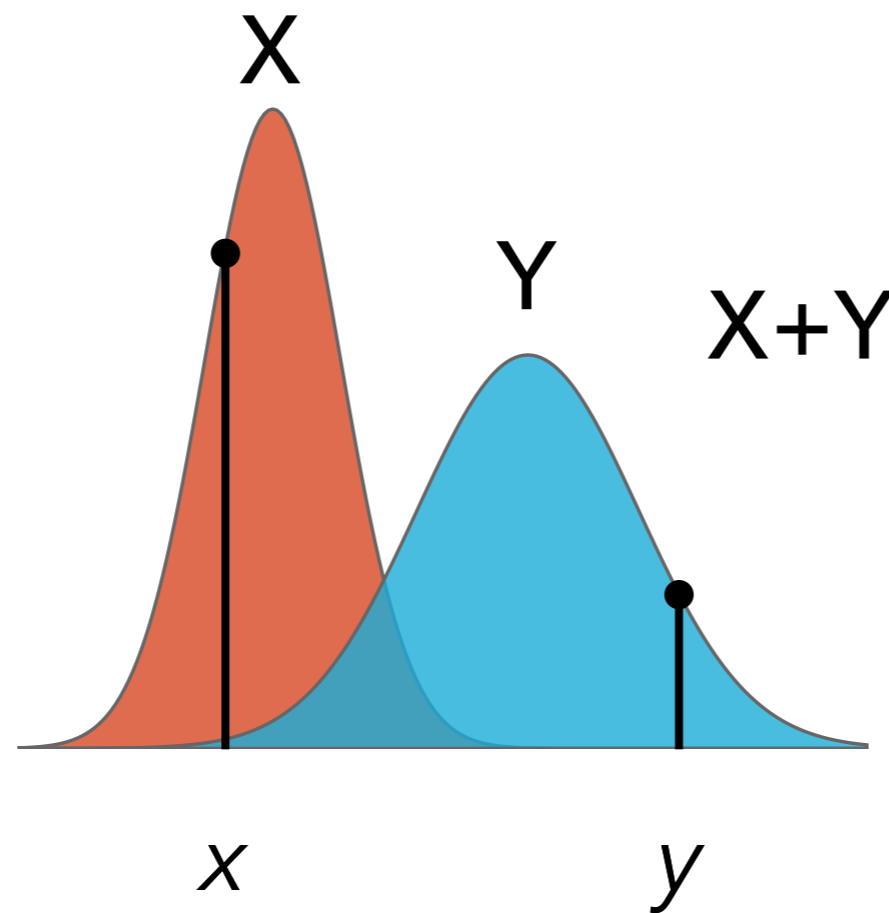
Computations

Represent distributions by random samples



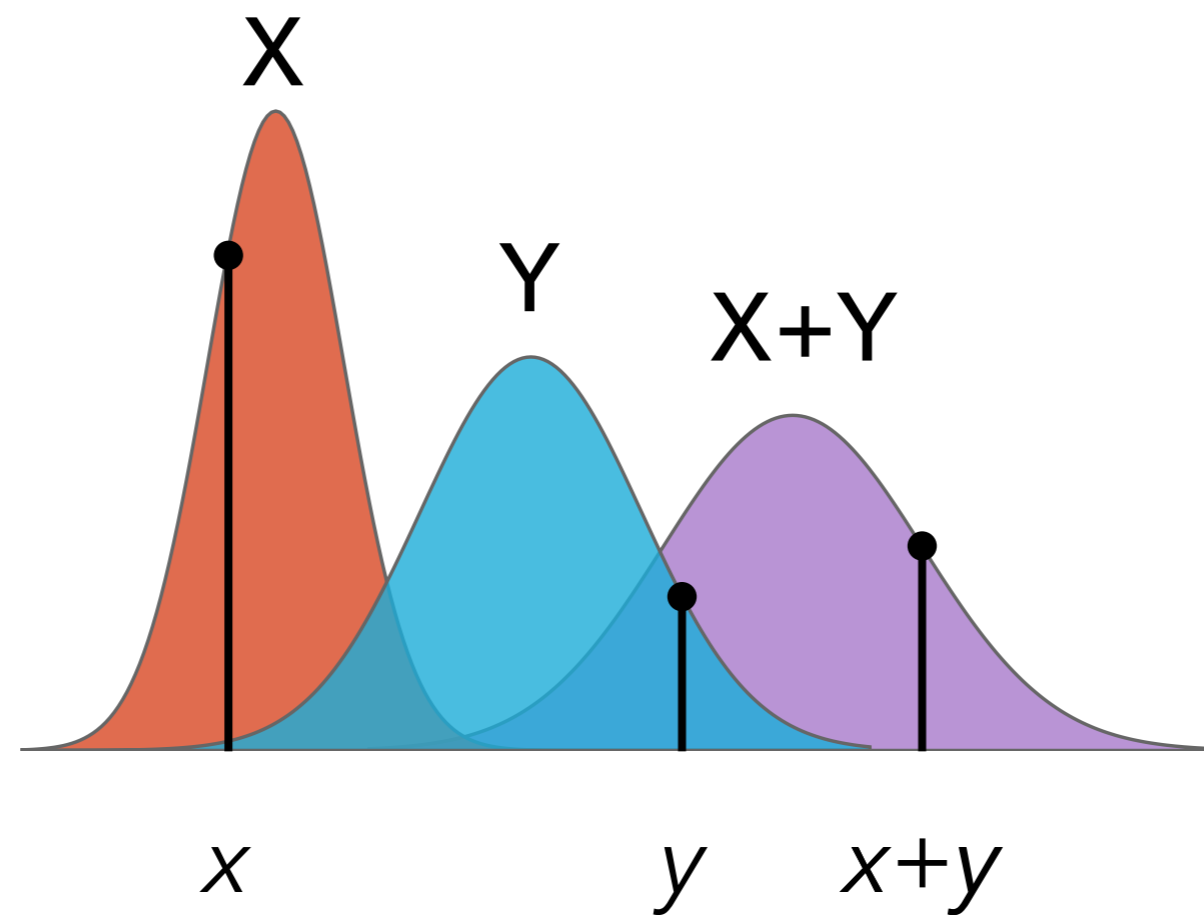
Computations

Represent distributions by random samples



Computations

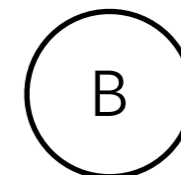
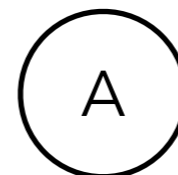
Represent distributions by random samples



Computations

Operators build a Bayesian network rather than evaluating immediately.

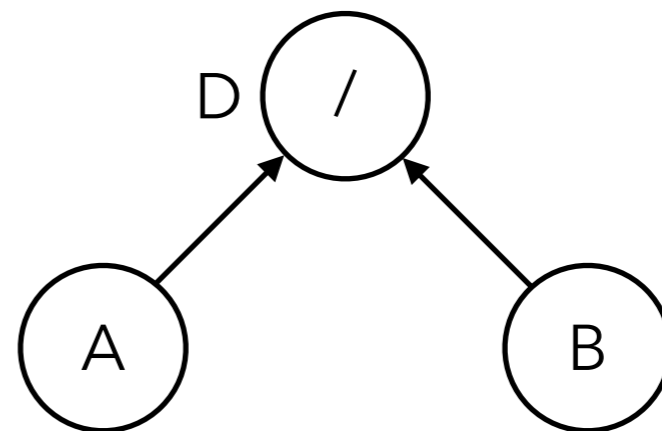
$$D = A / B$$



Computations

Operators build a Bayesian network rather than evaluating immediately.

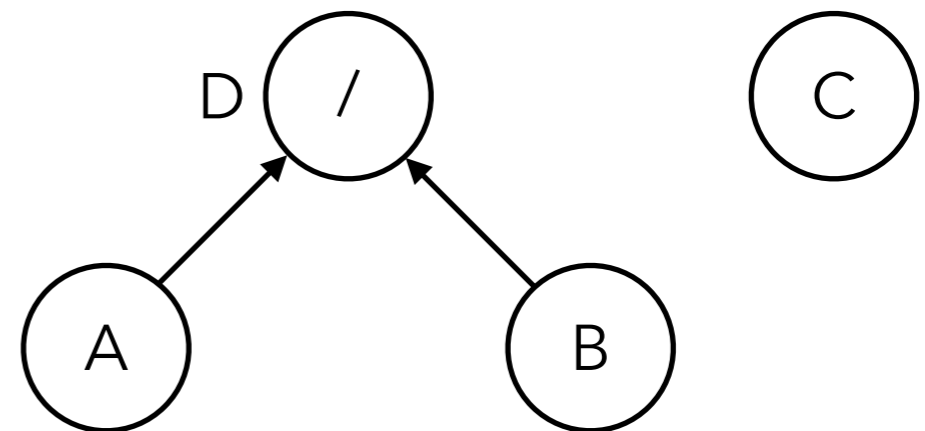
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Computations

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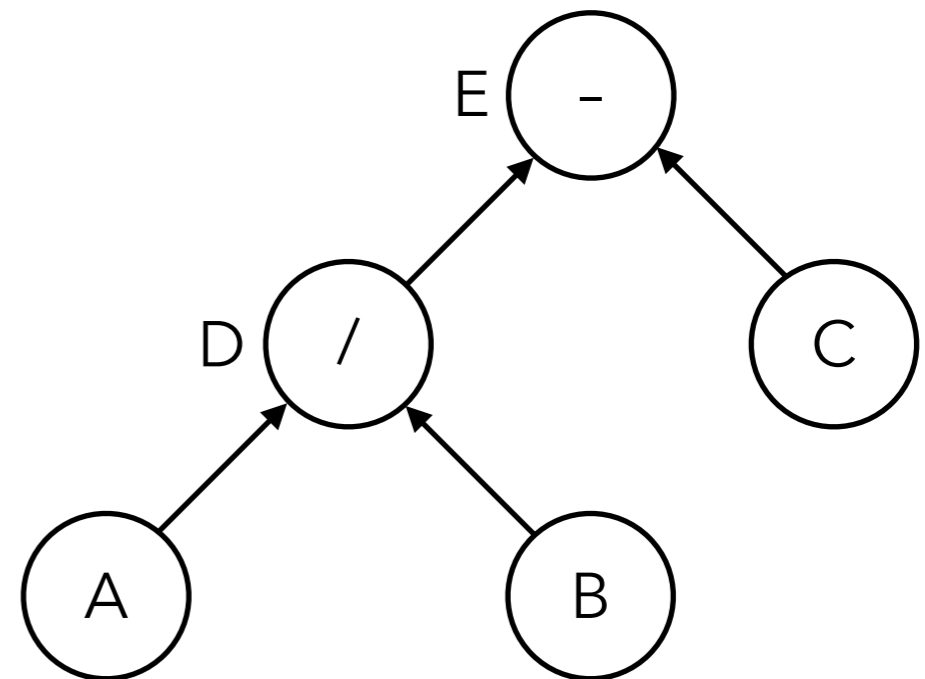
$$D = A / B$$
$$E = D - C$$



Computations

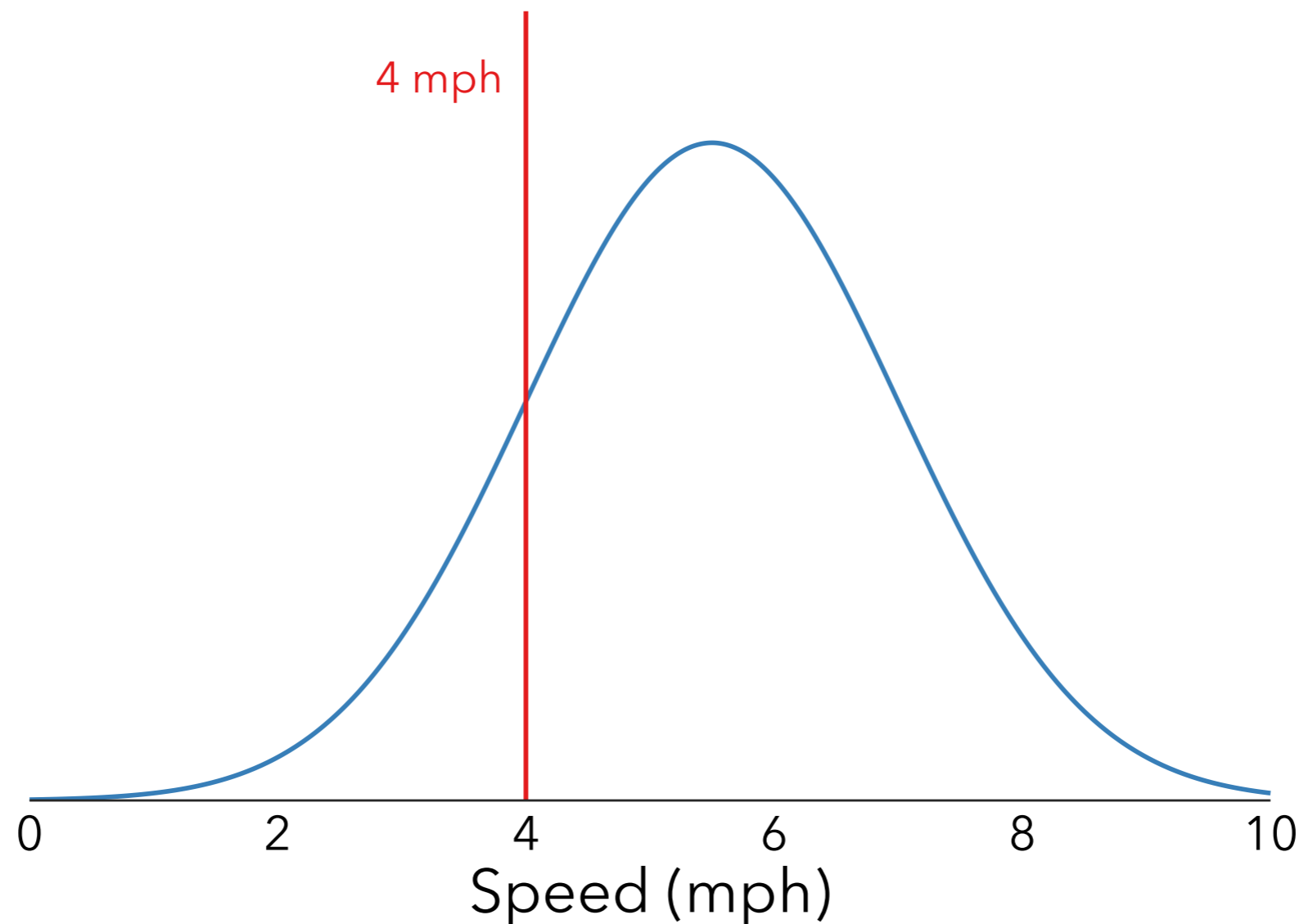
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$$D = A / B$$
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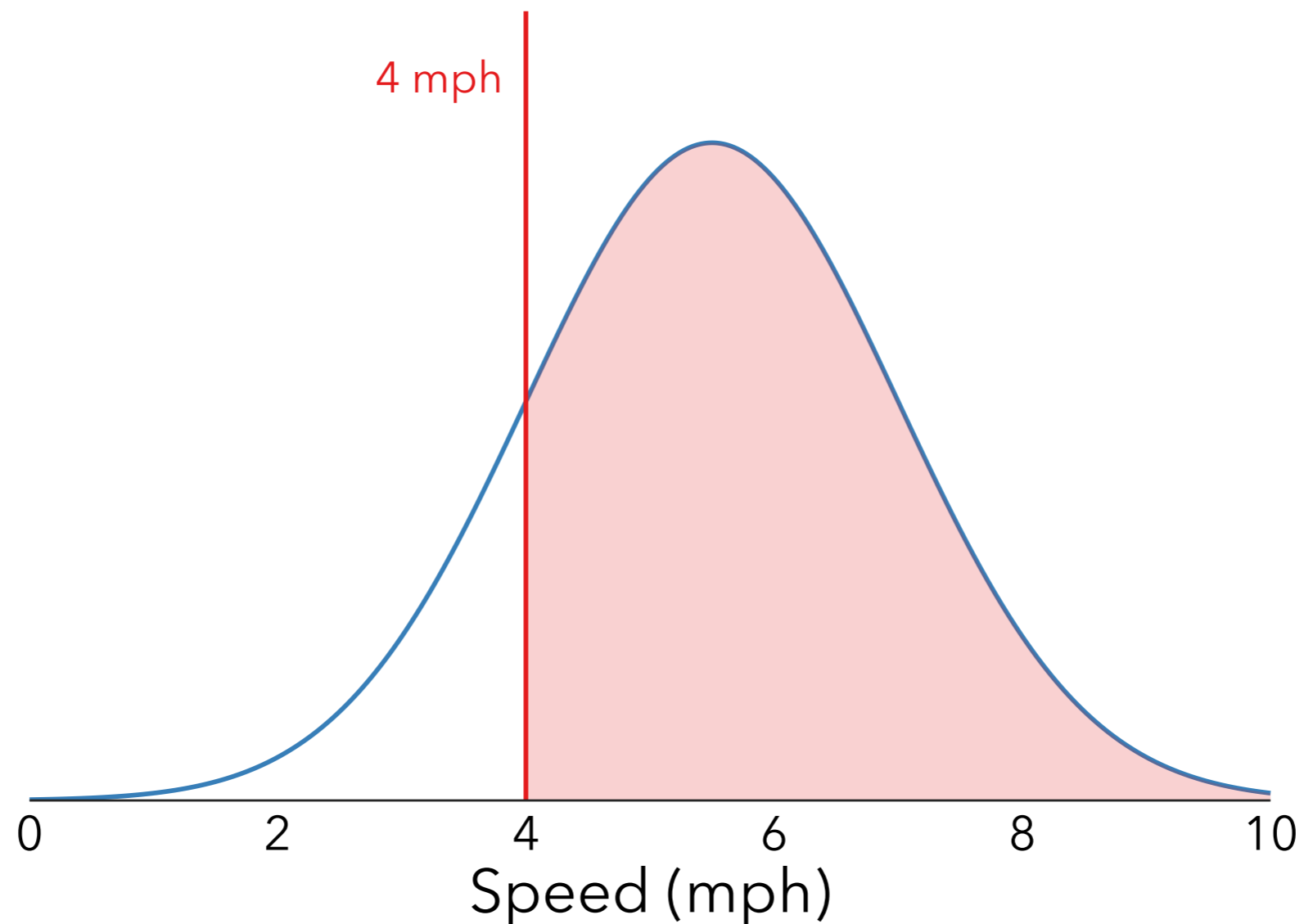
Deciding conditionals

```
if (Speed > 4)  
  Alert("Keep it up!");
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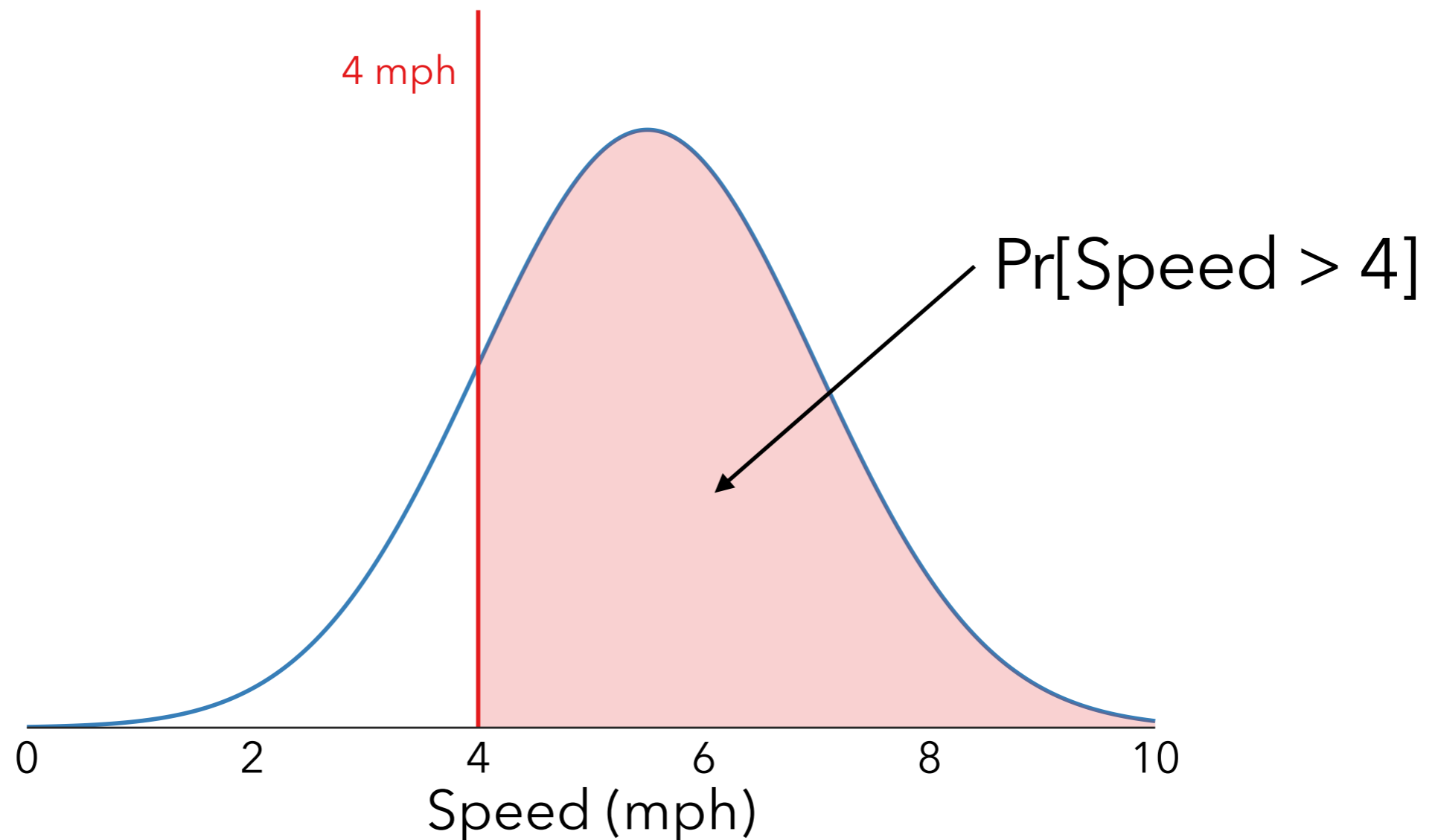
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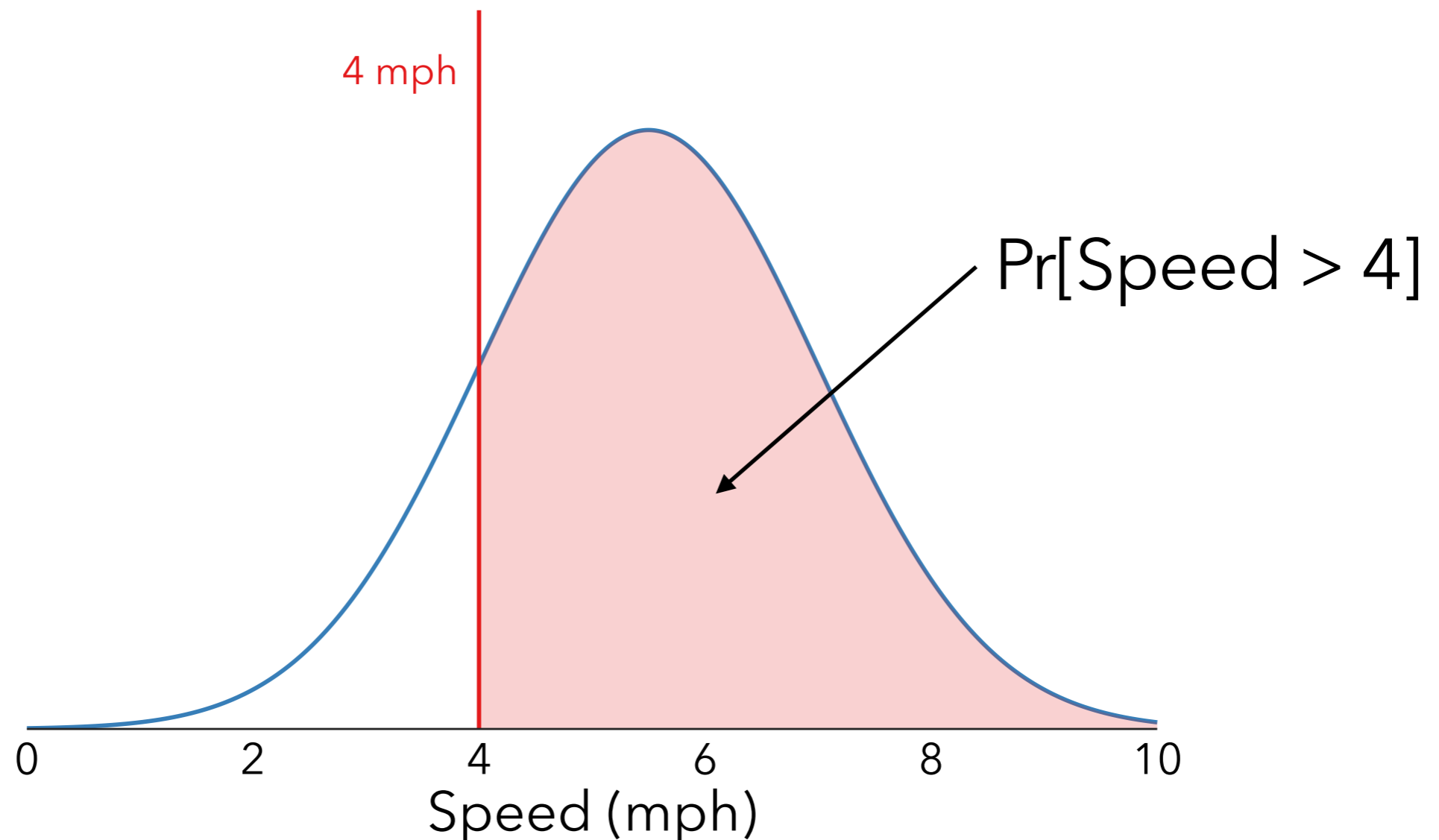
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Deciding conditionals

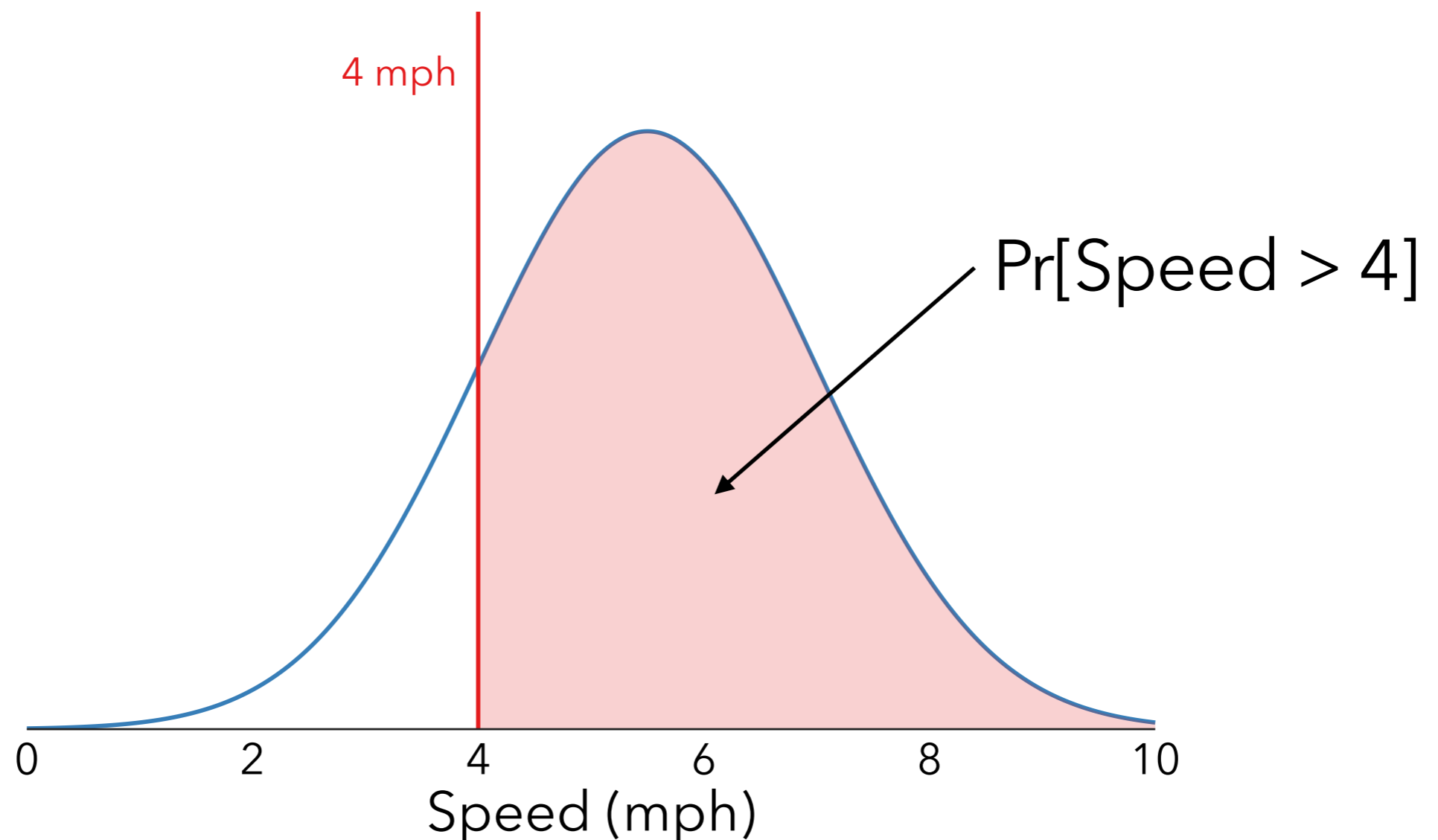
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if (Speed > 4)  
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More likely than not
that $\text{Speed} > 4$?



Deciding conditionals

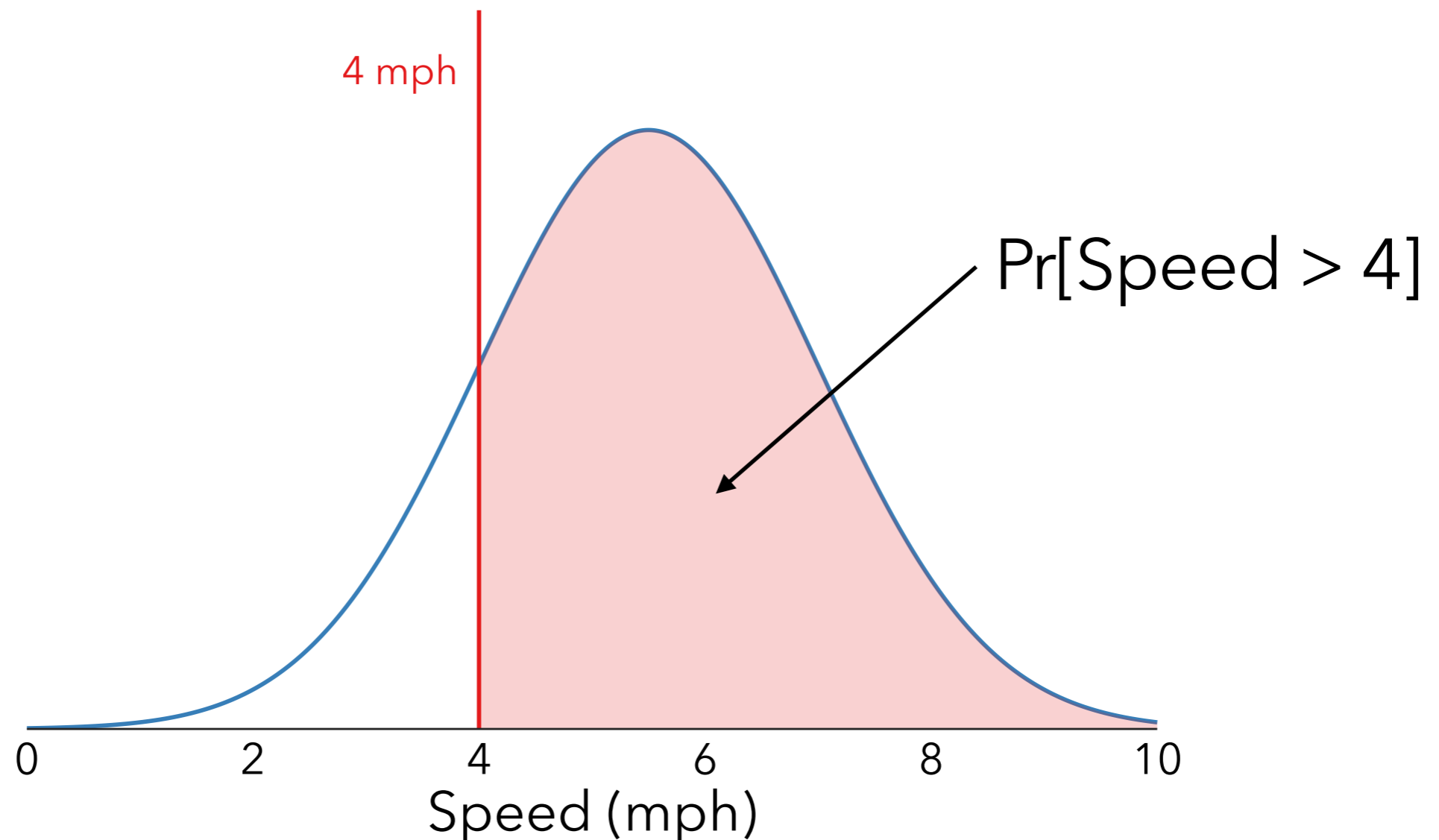
```
if ((Speed > 4).Pr(0.9))  
  Alert("Keep it up!");
```



Deciding conditionals

```
if ((Speed > 4).Pr(0.9))  
    Alert("Keep it up!");
```

At least 90% likely
that $\text{Speed} > 4$?



Identifying absurd data

```
GeoCoordinate PrevLocn = Get();  
Sleep(5);  
GeoCoordinate Location = Get();  
double Dist =  
    Distance(LastLocn, Location);  
double Speed = Dist / 5;  
  
if (Speed > 4) // 7 mph  
    Alert("That's crazy!");
```

Identifying absurd data

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GeoCoordinate PrevLocn = Get();  
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double Dist =  
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if (Speed > 4) // 7 mph           Naive: 30 times  
    Alert("That's crazy!");
```

Identifying absurd data

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if ((Speed > 4).Pr(0.9))  
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Naive: 30 times
50%: 4 times
90%: never

Uncertain<T>

an abstraction for reasoning about noise [ASPLOS'14]

exploiting context

language constructs to make data more accurate

Uncertain<

an abstraction for reasoning about noise

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```
if (RecognizeBeard(photo))  
    AddBeardToAvatar();
```



```
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```
City userCity = ...;
```

```
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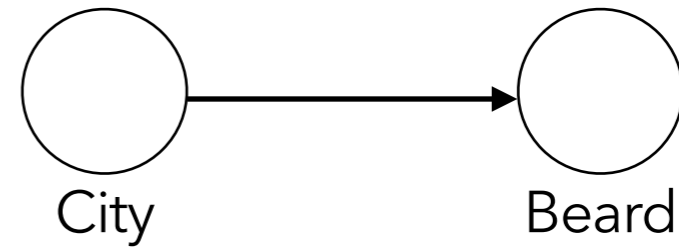
```
City userCity = ...;
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context

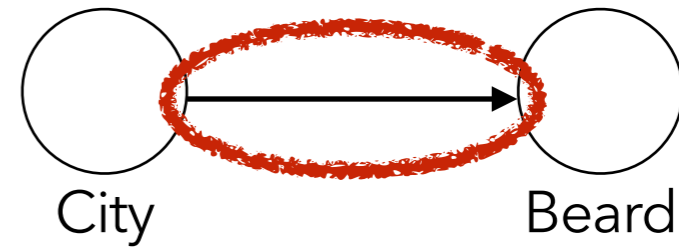
application-specific
domain knowledge

Static context



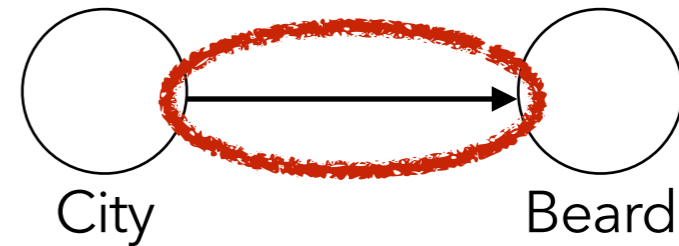
- How does city influence beards?

Static context



- How does city influence beards?

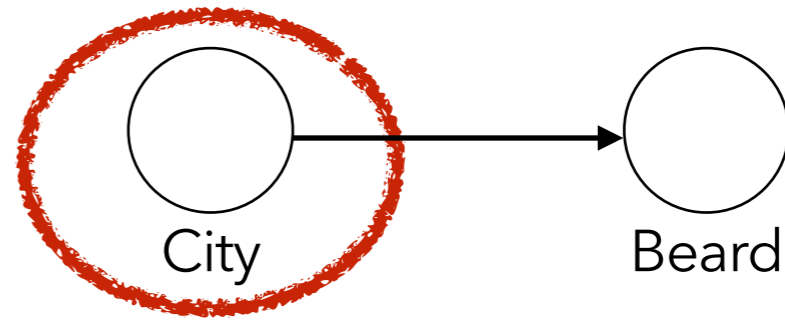
Static context



- How does city influence beards?

```
Bernoulli HasBeard_City(City c) {  
    if (c == "Seattle")  
        return new Bernoulli(0.4);  
    else  
        return new Bernoulli(0.2);  
}
```

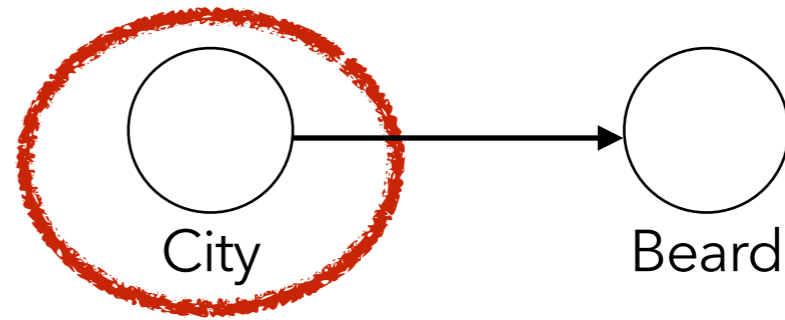
Static context



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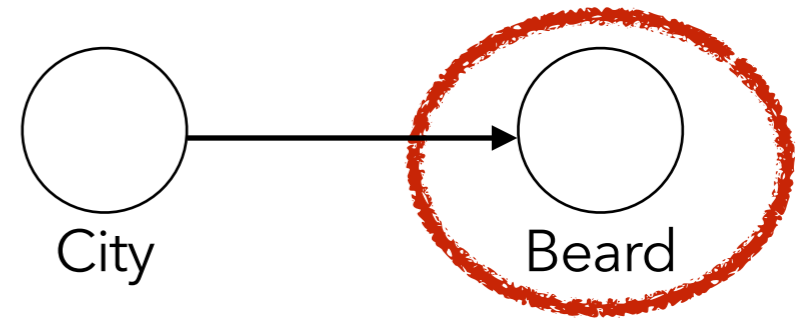


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}
```

```
var Cities = Uniform(...);
```

Static context

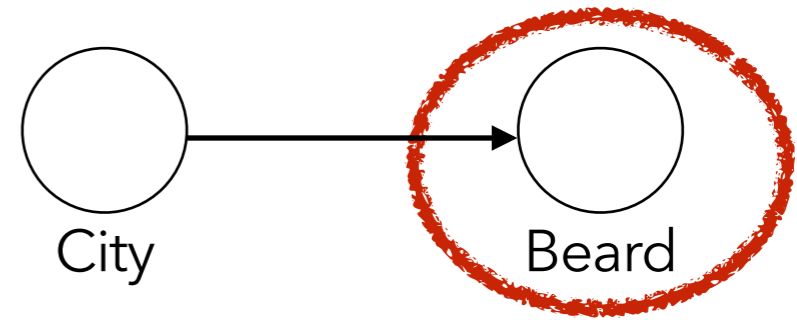


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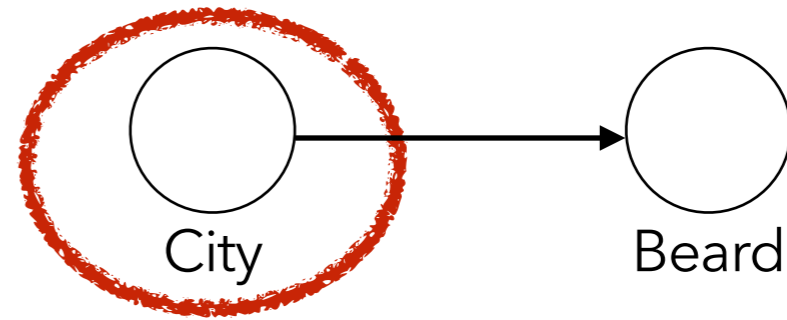
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```
var Cities = Uniform(...);
```

```
Bernoulli HasBeard =  
    HasBeard_City <| Cities;
```

Dynamic context



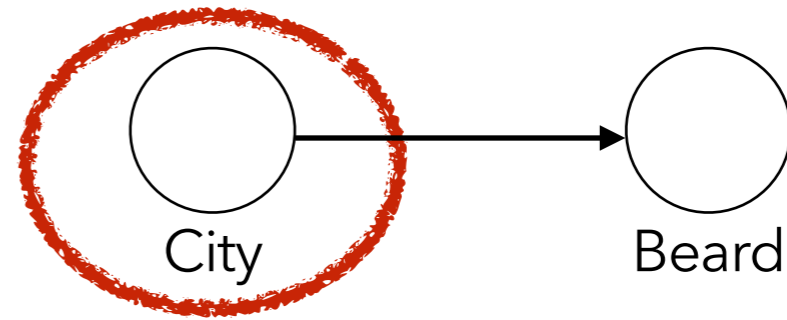
- Exploit knowledge about *this user*

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Bernoulli HasBeard =
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Dynamic context



- Exploit knowledge about *this user*

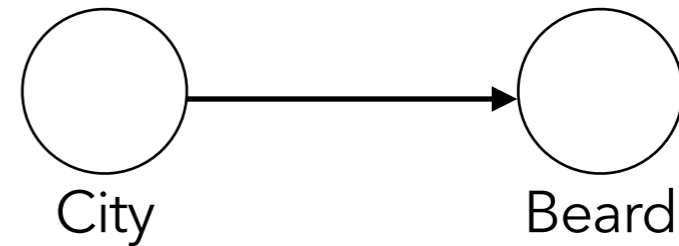
```
var Cities = Uniform(...);
```

```
Bernoulli HasBeard =
```

```
    HasBeard_City <| Cities;
```

```
Cities.Value = "Seattle";
```

Dynamic context



- Exploit knowledge about *this user*

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var Cities = Uniform(...);
```

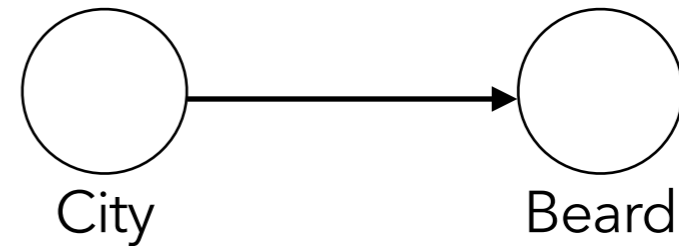
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Bernoulli HasBeard =
```

```
    HasBeard_City <| Cities;
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Cities.Value = "Seattle";
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```
Bernoulli oldHasBeard = BeardRecognizer(photo);
```


Dynamic context



- Exploit knowledge about *this user*

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```

```
Bernoulli HasBeard =
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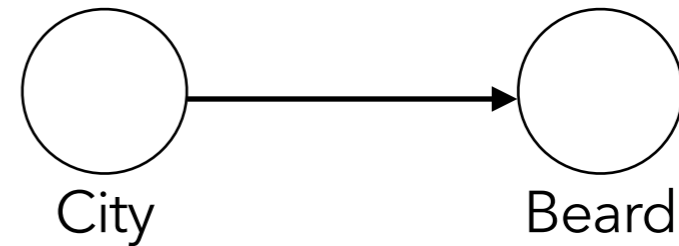
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Dynamic context



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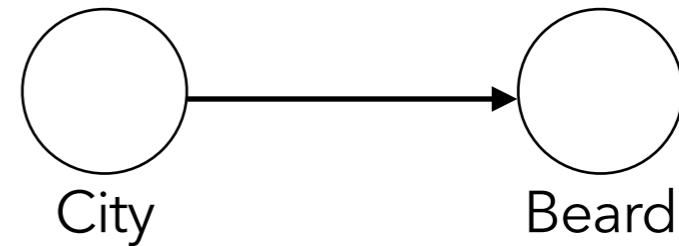
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Bernoulli oldHasBeard = BeardRecognizer(photo);
```

```
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```

```
if (newHasBeard)
```

```
    AddBeardToAvatar();
```

Dynamic context



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Bernoulli newHasBeard = oldHasBeard # HasBeard;
```

```
if (newHasBeard.Pr(0.9))  
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```

Two new constructs

<|

Building
probability
distributions
(conditional
probability)

#

Composing
context and
estimates
(Bayesian
inference)

Implementation

- We designed a *sequential likelihood reweighting* algorithm to implement this abstraction
- But we'd like to compile down to probabilistic programming languages, which have better inference



figaro



Simon Says



stomp your feet



touch your nose



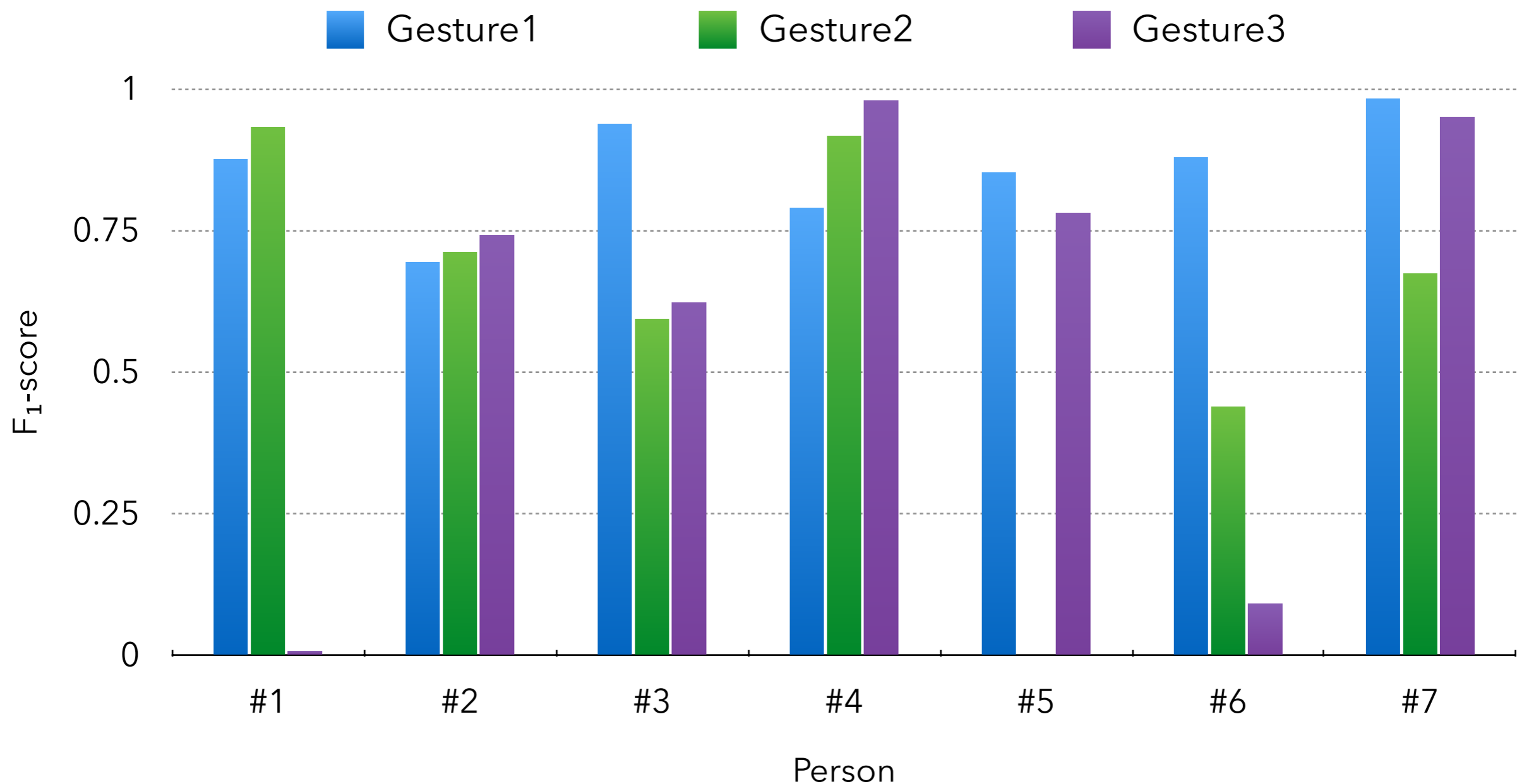
turn around



shake your head

Simon Says

- Xbox Kinect gesture recognition API



Simon Says

Local model

- Specific to our user
- Need lots of examples to avoid noise

Simon Says

Local model

- Specific to our user
- Need lots of examples to avoid noise

Global (API) model

- Trained over many users
- Generalises well

Simon Says

Local model

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- Need lots of examples to avoid noise

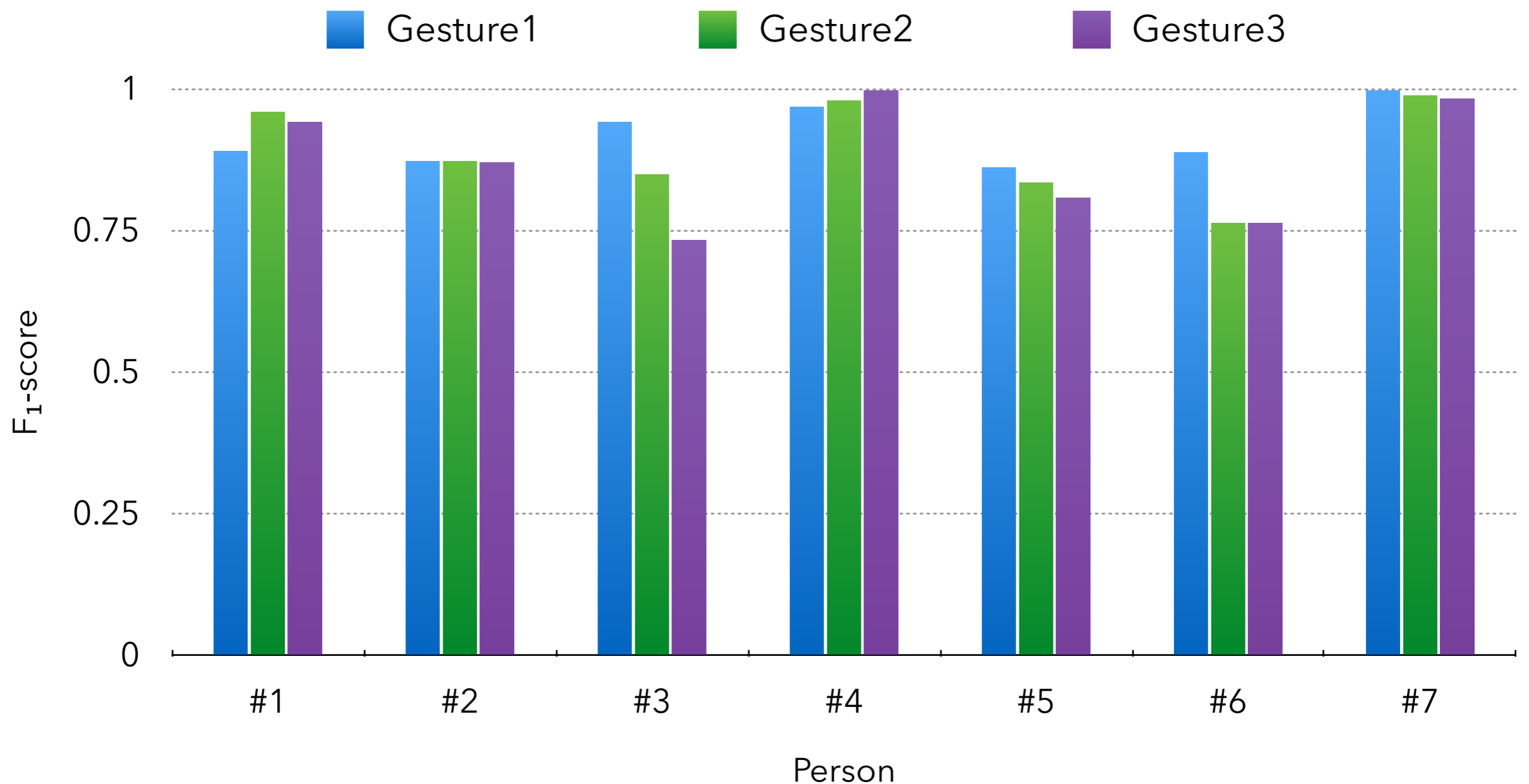
Global (API) model

- Trained over many users
- Generalises well

We'd like to keep both!

Simon Says

- Personalised gesture recognition model



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Uncertain<T>

an abstraction for reasoning about noise [ASPLOS'14]

Thanks!

exploiting context

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