

Figure 25: Dependencies in case $l_{ij} = x_k$

Similarly, it can be shown that $(V, E, D \cup \Delta, L)$ cannot contain any strong-cycles consistent with RT_1 and RT_2 if x_k is assigned *false*. Thus, $(V, E, D \cup \Delta, L)$ cannot contain any strong-cycles consistent with either RT_1 or RT_2 , and is strongly-acyclic with respect to R . \square

only if: Suppose there exists an assignment of truth values to literals such that C is satisfied. We show that there exists a set of dependencies Δ such that $D \cup \Delta$ is consistent and $(V, E, D \cup \Delta)$ is strongly-acyclic with respect to R . We specify the dependencies in the set Δ . For every literal dependency $(U_k, V_k) \rightarrow (V_k, W_k)$ is added to Δ if x_k is assigned *true*, else if \bar{x}_k is assigned *true*, then $(W_k, V_k) \rightarrow (V_k, U_k)$ is added to Δ (since only one of x_k or \bar{x}_k is *true* in the assignment, addition of dependencies to Δ does not make $D \cup \Delta$ inconsistent). Also, for all l_{ij} , if l_{ij} is *true* in the assignment then dependency $(N_{ij}, O_{ij}) \rightarrow (O_{ij}, P_{ij})$ is added to Δ , else dependency $(P_{ij}, O_{ij}) \rightarrow (O_{ij}, N_{ij})$ is added to Δ . From the construction of Δ , it trivially follows that $D \cup \Delta$ is consistent. We show that it is impossible for $(V, E, D \cup \Delta, L)$ to contain any strong-cycles that are consistent with either RT_1 or RT_2 .

We first show that $(V, E, D \cup \Delta, L)$ cannot contain any strong-cycles consistent with RT_1 . A strong-cycle consistent with RT_1 cannot contain nodes $R_{ijk}, S_{ijk}, T_{ijk}, F_{ijk}, G_{ijk}$ or H_{ijk} due to dependencies $(R_{ijk}, S_{ijk}) \rightarrow (S_{ijk}, T_{ijk})$ and $(H_{ijk}, G_{ijk}) \rightarrow (G_{ijk}, F_{ijk})$. Furthermore, since for every clause there exists a literal l_{ij} that is assigned *true*, dependency $(N_{ij}, O_{ij}) \rightarrow (O_{ij}, P_{ij})$ is added to Δ . Thus there cannot be any strong-cycle consistent with RT_1 in $(V, E, D \cup \Delta, L)$ involving nodes $N_{ij}, O_{ij}, P_{ij}, j = 1, 2, 3$. Thus, there are no strong-cycles consistent with RT_1 in $(V, E, D \cup \Delta, L)$.

we now show that $(V, E, D \cup \Delta, L)$ does not contain any strong-cycles consistent with RT_2 . A strong-cycle consistent with RT_2 cannot involve any of the nodes N'_{ij}, O'_{ij} or P'_{ij} due to the dependencies $(P'_{ij}, O'_{ij}) \rightarrow (O'_{ij}, N'_{ij})$, and must involve nodes $M_{ij}, P_{ij}, O_{ij}, N_{ij}, L_{ij}, F_{ijk}, G_{ijk}, H_{ijk}, X_k, U_k, V_k, W_k, Y_k, T_{ijk}, S_{ijk}, R_{ijk}$, for some literal $l_{ij} = x_k$ or \bar{x}_k . Let us assume that x_k is *true* in the assignment. We consider the following two cases:

$l_{ij} = \bar{x}_k$: In this case (as shown in Figure 24), since l_{ij} is *false* in the assignment, dependency $(P_{ij}, O_{ij}) \rightarrow (O_{ij}, N_{ij})$ is added to Δ and thus, it is impossible for there to be any strong-cycle consistent with RT_2 involving nodes P_{ij}, O_{ij}, N_{ij} .

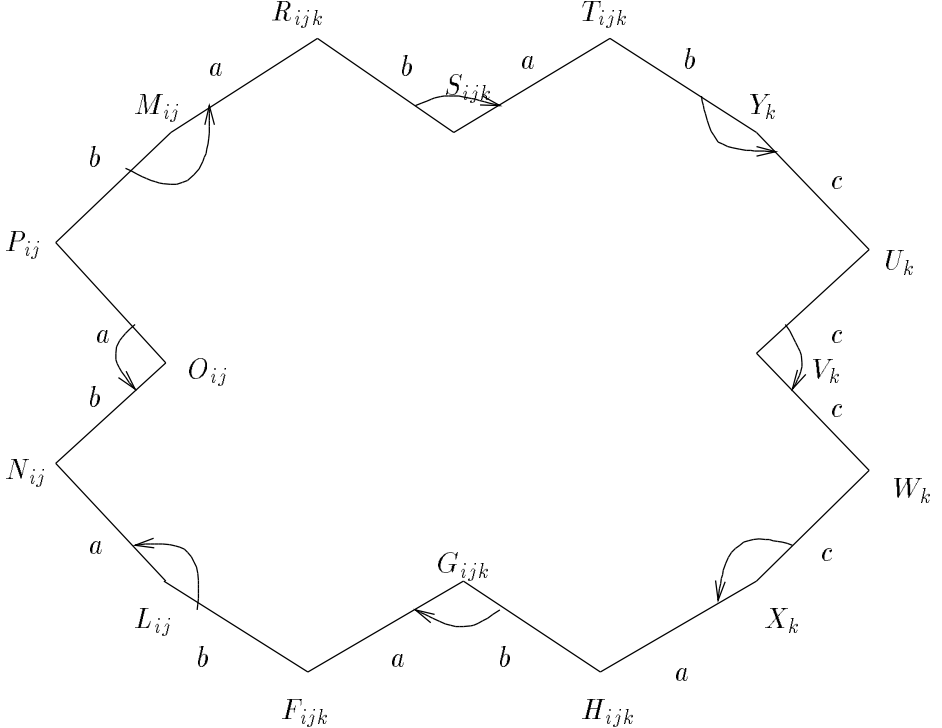


Figure 24: Dependencies in case $l_{ij} = \bar{x}_k$

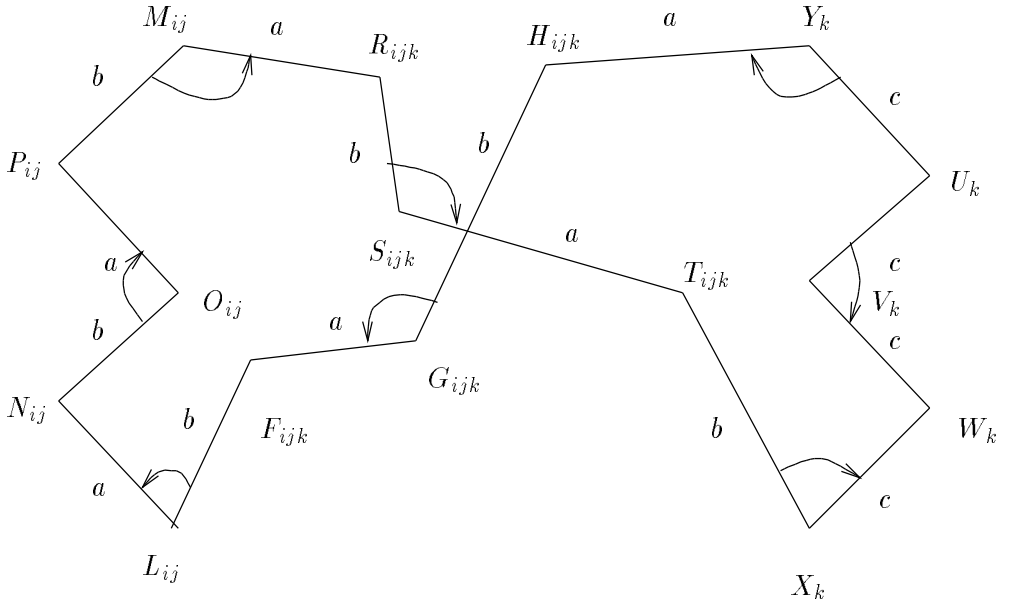


Figure 22: Dependencies in case $l_{ij} = x_k$

$l_{ij} = \bar{x}_k$: In this case (as shown in Figure 23), dependency $(W_k, V_k) \rightarrow (V_k, U_k)$ must belong to Δ , there would be a strong-cycle in the TSGD $(V, E, D \cup \Delta, L)$ consistent with RT_2 . Since Δ is consistent only one of $(W_k, V_k) \rightarrow (V_k, U_k)$ or $(U_k, V_k) \rightarrow (V_k, W_k)$ can belong to Δ . Thus, $(U_k, V_k) \rightarrow (V_k, W_k)$ does not belong to Δ , and x_k is assigned *false* (\bar{x}_k is assigned *true*).

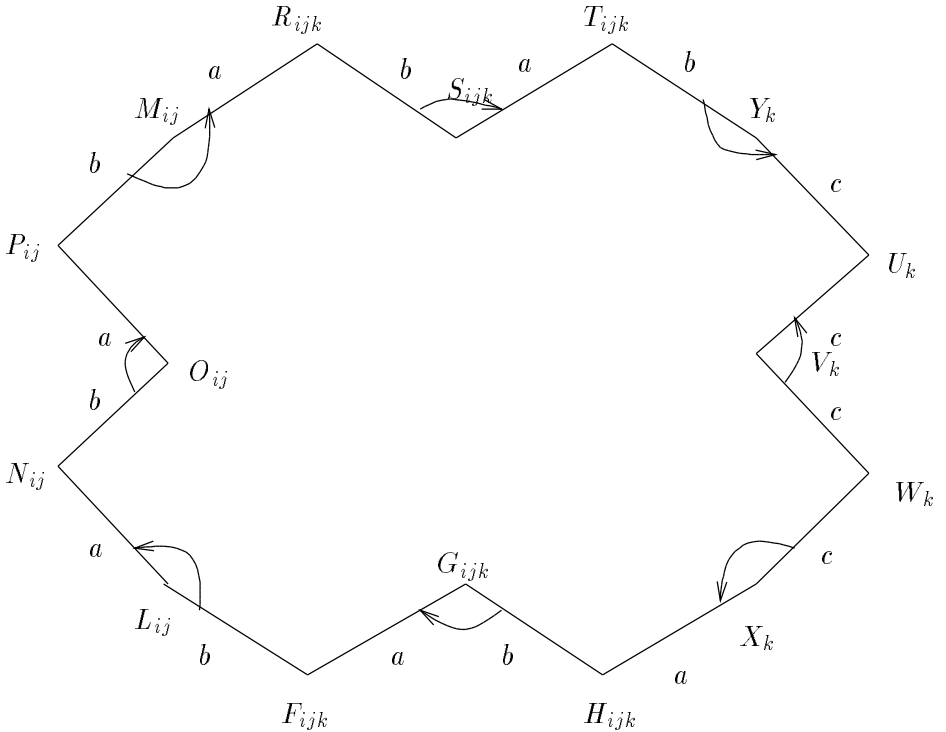


Figure 23: Dependencies in case $l_{ij} = \bar{x}_k$

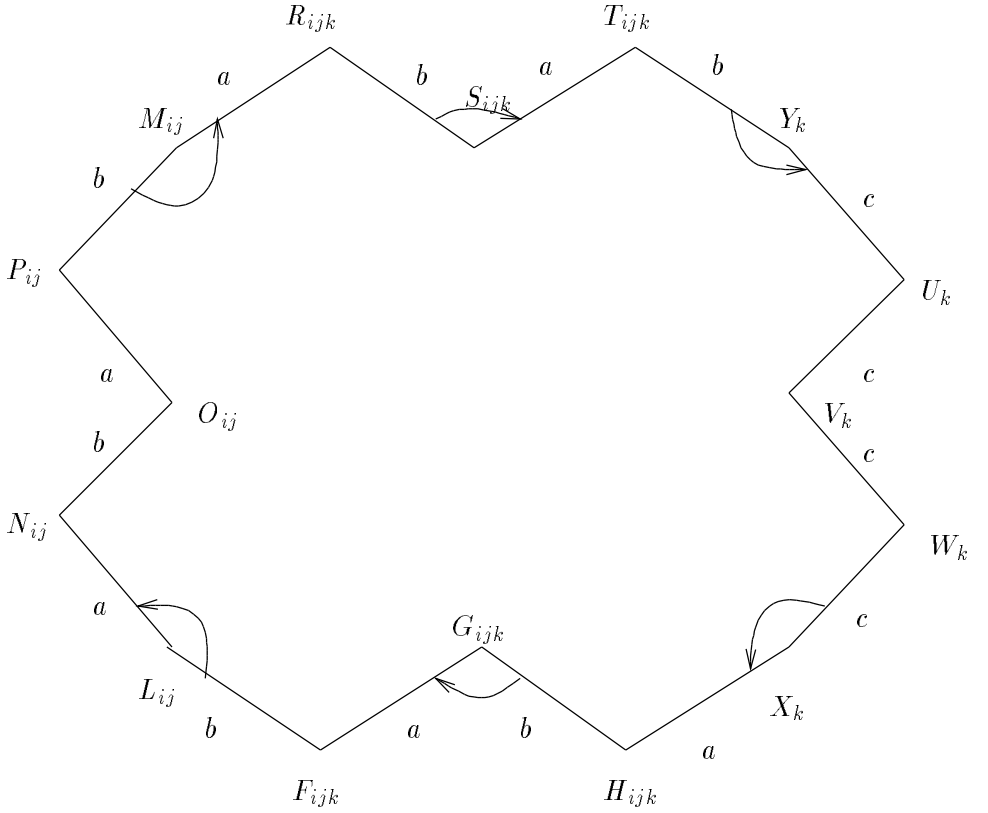


Figure 21: Nodes and edges if $l_{ij} = \bar{x}_k$

R_{ijk} , T_{ijk} , F_{ijk} and H_{ijk} are transaction nodes, while G_{ijk} and S_{ijk} are site nodes. Subtransactions of R_{ijk} , T_{ijk} , F_{ijk} and H_{ijk} at sites S_{ijk} , Y_k , L_{ij} and G_{ijk} respectively are of type b , while subtransactions of R_{ijk} , T_{ijk} , F_{ijk} and H_{ijk} at sites M_{ij} , S_{ijk} , G_{ijk} and X_k are of type a . Note that there are at most three edges incident on L_{ij} and M_{ij} . Also, there are two edges incident on each of P_{ij} , O_{ij} , N_{ij} , R_{ijk} , S_{ijk} , T_{ijk} , F_{ijk} , G_{ijk} , H_{ijk} , U_k , V_k , W_k , P'_{ij} , O'_{ij} , N'_{ij} . Note that the TSGD can be constructed in $O(p + q)$ steps.

The regular specification R contains two regular terms, RT_1 and RT_2 , $RT_1 = (A : a, b) : (A : a, b)$, $RT_2 = (A : c, c) : ((A : b, a) + (A : c, c))$. We show that C is satisfiable iff there exist a set of dependencies Δ such that $D \cup \Delta$ is consistent and $(V, E, D \cup \Delta, L)$ is strongly-acyclic with respect to R .

if: Let us assume there exists a set of dependencies Δ such that $(V, E, D \cup \Delta, L)$ is strongly-acyclic with respect to R and $D \cup \Delta$ is consistent. We need to show that there exists an assignment of truth values to literals such that C is satisfiable. We assign truth values to literals as follows. If dependency $(U_k, V_k) \rightarrow (V_k, W_k) \in \Delta$, then literal x_k is assigned *true*, else x_k is assigned *false* (\bar{x}_k is assigned *true*). Thus, only one of x_k or \bar{x}_k is assigned *true*.

We further need to show that in every clause C_i , there is at least one literal that is *true*. Since $(V, E, D \cup \Delta, L)$ is strongly-acyclic with respect to R , for every clause C_i , for some l_{ij} , $j = 1, \dots, p$, there must be a dependency $(N_{ij}, O_{ij}) \rightarrow (O_{ij}, P_{ij})$ (else there would be a strong-cycle in the TSGD $(V, E, D \cup \Delta, L)$ consistent with RT_1). We show that l_{ij} must be assigned *true*, for which we need to consider the following two cases:

$l_{ij} = x_k$: In this case (as shown in Figure 22), dependency $(U_k, V_k) \rightarrow (V_k, W_k)$ must belong to Δ , else there would be a strong-cycle in the TSGD $(V, E, D \cup \Delta, L)$ consistent with RT_2 . Thus, x_k

more understandable). For all $j = 1, 2, 3$, nodes P_{ij}, N_{ij}, P'_{ij} and N'_{ij} are transaction nodes while M_{ij}, O_{ij}, L_{ij} and O'_{ij} are site nodes. Subtransactions of P_{ij}, N_{ij}, P'_{ij} and N'_{ij} at sites O_{ij}, L_{ij}, M_{ij} and M_{ij} respectively are of type a ; while subtransactions of P_{ij}, N_{ij}, P'_{ij} and N'_{ij} at sites $M_{ij}, L_{i(j \bmod 3)+1}$ and O'_{ij} respectively are of type b . Furthermore, for every literal x_k , we include the nodes and edges shown in Figure 19 in the TSGD.

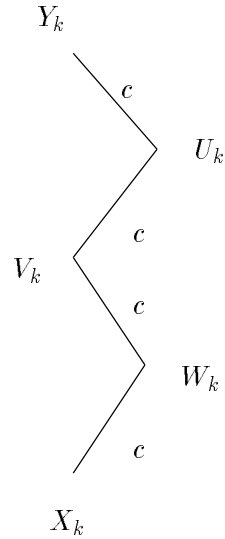


Figure 19: Nodes and edges for literal x_k

U_k and W_k are transaction nodes, while Y_k, V_k and X_k are site nodes. Subtransactions of U_k and W_k at sites Y_k, V_k and X_k are of type c . Also, we introduce additional edges and dependencies in the TSGD depending on whether $l_{ij} = x_k$ or $l_{ij} = \bar{x}_k$. If $l_{ij} = x_k$, then the nodes, edges and dependencies illustrated in Figure 20 are added to the TSGD.

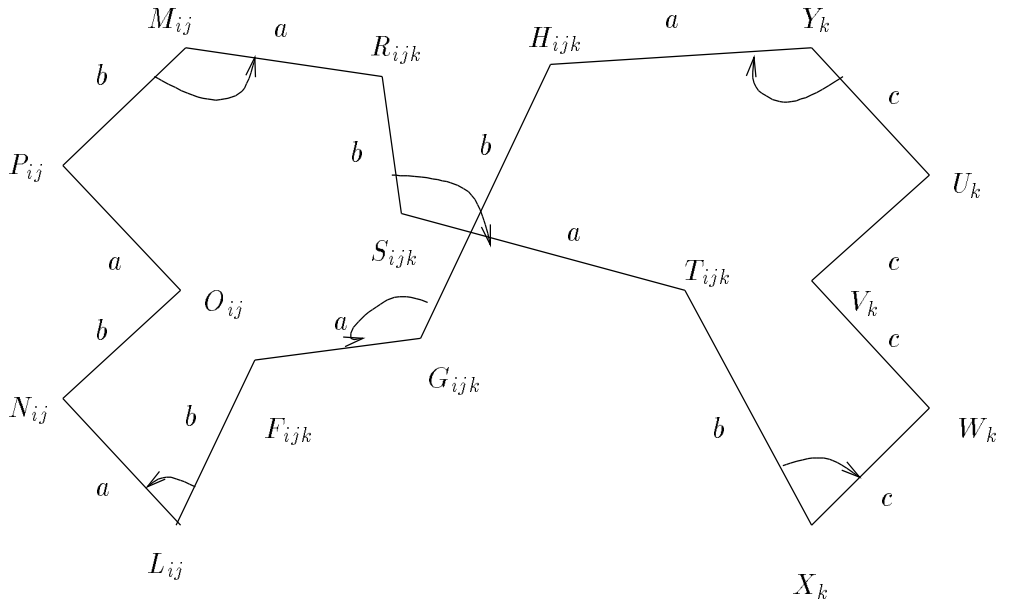


Figure 20: Nodes and edges if $l_{ij} = x_k$

On the other hand, if $l_{ij} = \bar{x}_k$, then we include nodes, edges and dependencies in the TSGD shown

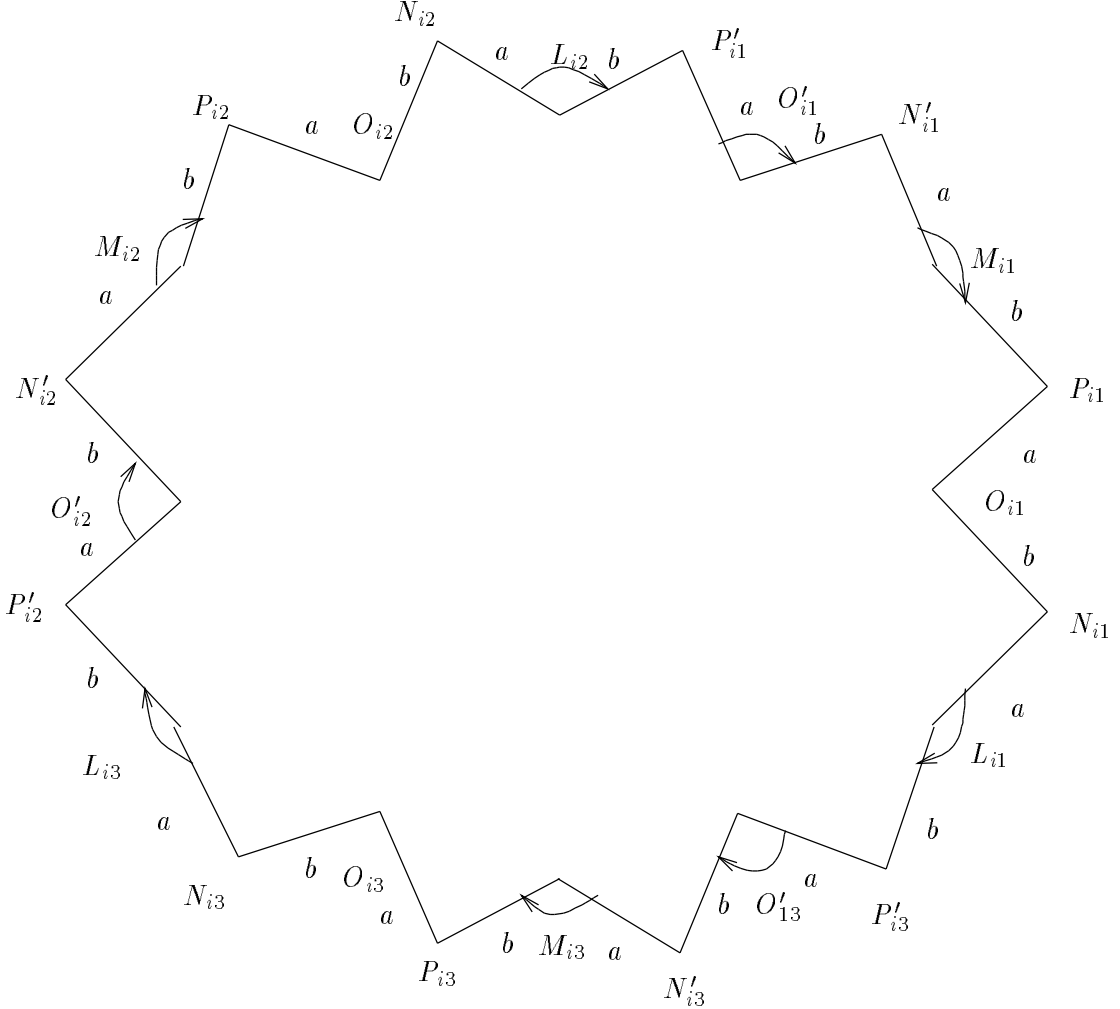


Figure 18: Structure for clause C_i

Proof of Theorem 8: The above problem is in NP since a non-deterministic algorithm only needs to guess a set Δ such that there are dependencies between any two edges in the TSGD. Δ can contain at most $|E|^2$ dependencies since there can be at most $|E|^2$ dependencies in the TSGD (V, E, D) . The algorithm then needs to check if (1) $D \cup \Delta$ is consistent, and (2) for every regular term RT in R and every node v in the TSGD, if there is a strong-cycle consistent with RT involving v in the TSGD. Step 1 can be performed in polynomial time and involves detecting cycles in a directed graph. Step 2, too, can be performed in polynomial time using an algorithm similar to Detect-Ins-Opt that guesses arguments a TSGD such that between any two edges there is a dependency, a node v in the TSGD and a regular term RT , precisely detects if the TSGD contains a strong-cycle involving v that is consistent with RT .

We show a polynomial transformation from 3-SAT to the above problem. Consider a 3-SAT formula $C = C_1 \wedge C_2 \wedge \dots \wedge C_p$ that is defined over literals x_1, x_2, \dots, x_q . Let l_{ij} denote the literal in clause C_i , $i = 1, 2, \dots, p$, in position j , $j = 1, 2, 3$ (l_{ij} could be either x_k or \bar{x}_k , for some $k = 1, 2, \dots, q$). We construct a TSGD (V, E, D, L) and a regular expression R such that C is satisfiable if and only if there exists a set of dependencies Δ such that $D \cup \Delta$ is consistent, and the TSGD $(V, E, D \cup \Delta, L)$ is strongly-acyclic with respect to R . Every global transaction in the MDDBS has type A , that is, $\text{type}(g\tau) = \{A\}$. Local DBMSs export procedures whose types are one of a, b or c , that is, $\text{type}(l\tau) = \{a, b, c\}$. We construct the TSGD as follows. For every clause C_i , the TSGD contains the structure shown in Figure 18.

- $(x_i, b'_i), (b'_i, N_{i1}), (N_{i1}, Z_{i1}), (Z_{i1}, Y_{i1}), (Y_{i1}, neg_i(1)), (neg_i(1), N_{i2}), (N_{i2}, Z_{i2}), \dots,$
 $(Y_{i|neg_i|}, neg_i(|neg_i|)), (neg_i(|neg_i|), N_{i(|neg_i|+1)}), (N_{i(|neg_i|+1)}, e'_i), (e'_i, x_{i+1}),$ if $|neg_i| > 0,$
- $(x_i, b'_i), (b'_i, N_{i1}), (N_{i1}, e'_i), (e'_i, x_{i+1}),$ if $|neg_i| = 0,$

This is mainly due to

- the dependency $(x_1, s_0) \rightarrow (s_0, C_{p+1}),$ and for all $i = 1, 2, \dots, p,$ dependencies (x_{i+1}, e_i)
 $(e_i, P_{i(|pos_i|+1)}), (x_{i+1}, e'_i) \rightarrow (e'_i, N_{i(|neg_i|+1)})$ in $D,$ and
- for all $l_{ij} = pos_r(k),$ only two edges are incident on each of P_{rk}, X_{rk} and $W_{rk},$ and dependen
 $(W_{rk}, l_{ij}) \rightarrow (l_{ij}, R_{ij}) \in D$ and $(B_{ij}, A_{ij}) \rightarrow (A_{ij}, C_i) \in D$ (a similar argument can be use
 $l_{ij} = neg_r(k)).$

Finally the strong-cycle contains the edges (x_{q+1}, s_2) and $(s_2, G_i).$ Note that no node in the strong-c
is visited more than once. Trivially, all the nodes other than l_{ij} appear only once in the strong-cy
Furthermore, if $l_{ij} = pos_r(k)$ (the argument if $l_{ij} = neg_r(k)$ is similar), then l_{ij} cannot be in the sequ
of edges between both C_i and C_{i+1} as well as x_r and x_{r+1} since $D \cup \{(R_{ij}, l_{ij}) \rightarrow (l_{ij}, B_{ij}), (P_{r(k+1)}, l_{ij}) \rightarrow (l_{ij}, W_{rk})\}$ is inconsistent, and the sequence of edges are in a strong-cycle.

We now show that there exists an assignment of truth values to x_k for all $k = 1, 2, \dots, q,$ s
that for all $i = 1, 2, \dots, p,$ for some $j = 1, 2, 3, l_{ij}$ is assigned *true*, and thus C is satisfiable. For
 $i = 1, 2, \dots, p,$ for all $j = 1, 2, 3, l_{ij}$ is assigned *true* iff the edges $(B_{ij}, l_{ij}), (l_{ij}, R_{ij})$ are in the stro
ng-cycle. This assignment causes C to be *true* since as shown earlier, for all $i = 1, 2, \dots, p,$ for s
 $j = 1, 2, 3,$ edges $(B_{ij}, l_{ij}), (l_{ij}, R_{ij})$ are in the strong-cycle.

Further, it is not possible that for some $k = 1, 2, \dots, q, x_k$ and \bar{x}_k are both assigned *true*. If x_k
 \bar{x}_k are both assigned *true*, then there must exist symbols l_{ij} and l_{rs} such that edges $(B_{ij}, l_{ij}), (l_{ij}, R_{ij}), (B_{rs}, l_{rs}), (l_{rs}, R_{rs})$ are in the strong-cycle, and $l_{ij} = x_k, l_{rs} = \bar{x}_k.$ Thus, $|neg_k| > 0, |pos_k| > 0,$
 $l_{ij} = pos_k(u),$ for some $u, u = 1, 2, \dots, |pos_k|,$ and $l_{rs} = neg_k(v),$ for some $v, v = 1, 2, \dots, |neg_k|.$
However, this is not possible, since as we showed earlier, one of l_{ij} and l_{rs} is also in the sequenc
edges between x_k and x_{k+1} in the strong-cycle, and the strong-cycle does not visit a node more t
once. \square

We now show that the problem of computing a set of dependencies, $\Delta,$ that is strongly-mini
with respect to (V, E, D, L) and $G_i,$ is NP-hard.

Proof of Theorem 7: We show that the NP-complete problem of determining if $\Delta' = \emptyset$
is not strongly-minimal with respect to G_i and (V, E, D, L) can be Turing-reduced to the problem
of computing a Δ such that $D \cup \Delta$ is consistent and Δ is strongly-minimal with respect to G_i
and $(V, E, D, L).$

Consider a subroutine $S((V, E, D, L), G_i)$ that returns a set of dependencies Δ such that $D \cup \Delta$
is consistent and Δ is strongly-minimal with respect to G_i and (V, E, D, L) (note that such a Δ al
ways exists if (V, E, D, L) satisfies the conditions mentioned in the theorem). An algorithm for solving
the problem of determining if $\Delta' = \emptyset$ is not strongly-minimal with respect to G_i and (V, E, D, L)
calls $S((V, E, D, L), G_i).$ If the set of dependencies Δ returned by S is non-empty, then the algori
thm responds “yes” (since if $\Delta' = \emptyset$ is strongly-minimal with respect to G_i and $(V, E, D, L),$ then a n
on-empty Δ cannot be strongly-minimal with respect to G_i and $(V, E, D, L),$ and S would return \emptyset)
on the other hand, the set of dependencies Δ returned by S is $\emptyset,$ then the algorithm responds “no”
(since $\Delta' = \emptyset$ is strongly-minimal with respect to (V, E, D, L) and $G_i).$ \square

cycle. Since C is satisfiable, there exists an assignment of truth values to x_k , for all $k = 1, 2, \dots$, such that for all $i = 1, 2, \dots, p$, for some $j = 1, 2, 3$, l_{ij} is assigned *true*. We now specify the edges in the strong-cycle. Edge sequence $(G_i, s_1)(s_1, C_1)$ is in the strong-cycle. For all $i = 1, 2, \dots, p$, edge sequence $(C_i, A_{ij})(A_{ij}, B_{ij})(B_{ij}, l_{ij})(l_{ij}, R_{ij})(R_{ij}, Q_{ij})(Q_{ij}, C_{i+1})$ is in the strong-cycle, for some $j = 1, 2, 3$ such that l_{ij} is *true* in the assignment. Edges $(C_{p+1}, s_0), (s_0, x_1)$ are also in the strong-cycle. For all $i = 1, 2, \dots, q$, if x_i is *false* in the assignment, then the following edges are in the strong-cycle

- $(x_i, b_i), (b_i, P_{i1}), (P_{i1}, X_{i1}), (X_{i1}, W_{i1}), (W_{i1}, pos_i(1)), (pos_i(1), P_{i2}), (P_{i2}, X_{i2}), \dots, (W_{i|pos_i|}, pos_i(|pos_i|)), (pos_i(|pos_i|), P_{i(|pos_i+1)}), (P_{i(|pos_i+1)}, e_i), (e_i, x_{i+1})$, if $|pos_i| > 0$,
- $(x_i, b_i), (b_i, P_{i1}), (P_{i1}, e_i), (e_i, x_{i+1})$, if $|pos_i| = 0$,

else if x_i is *true* in the assignment, the strong-cycle contains the edges:

- $(x_i, b'_i), (b'_i, N_{i1}), (N_{i1}, Z_{i1}), (Z_{i1}, Y_{i1}), (Y_{i1}, neg_i(1)), (neg_i(1), N_{i2}), (N_{i2}, Z_{i2}), \dots, (Y_{i|neg_i|}, neg_i(|neg_i|)), (neg_i(|neg_i|), N_{i(|neg_i+1)}), (N_{i(|neg_i+1)}, e'_i), (e'_i, x_{i+1})$, if $|neg_i| > 0$,
- $(x_i, b'_i), (b'_i, N_{i1}), (N_{i1}, e'_i), (e'_i, x_{i+1})$, if $|neg_i| = 0$,

Finally, the sequence of edges $(x_{p+1}, s_2)(s_2, G_i)$ are in the strong-cycle.

In the above choice of edges, we show that no node appears more than once in the strong-cycle. Nodes other than l_{ij} , trivially, appear only once. For any node l_{ij} , it is in the sequence of edges between nodes C_i and C_{i+1} only if l_{ij} is *true* in the assignment. If $l_{ij} = pos_r(k)$, then $l_{ij} = x_r$, and since x_r is *true* in the assignment, l_{ij} is not among the nodes in the sequence of edges between x_r and x_{r+1} . Similarly, if $l_{ij} = neg_r(k)$, then $l_{ij} = \bar{x}_r$, and since x_r is *false* in the assignment, l_{ij} is not among the nodes in the sequence of edges between x_r and x_{r+1} . Thus, since

- for any consecutive edges $(v_1, v_2), (v_2, v_3)$ in the sequence, $v_1 \neq v_3$ and dependency $(v_1, v_2) \rightarrow (v_2, v_3) \notin D$, and
- for all $l_{ij} = pos_r(k)$, $D \cup \{(R_{ij}, l_{ij}) \rightarrow (l_{ij}, B_{ij})\}$ is consistent and $D \cup \{(P_{r(k+1)}, l_{ij}) \rightarrow (l_{ij}, W_{rk})\}$ is consistent, and
- for all $l_{ij} = neg_r(k)$, $D \cup \{(R_{ij}, l_{ij}) \rightarrow (l_{ij}, B_{ij})\}$ is consistent and $D \cup \{(N_{r(k+1)}, l_{ij}) \rightarrow (l_{ij}, Y_{rk})\}$ is consistent,

the above sequence of edges constitute a strong-cycle involving G_i in the TSGD.

We now show that if there is a strong-cycle involving G_i in the TSGD, then there exists an assignment of truth values to literals such that C is satisfiable. Any strong-cycle involving G_i in the TSGD must contain the sequence of edges $(G_i, s_1)(s_1, C_1)$. Further, we claim that for all $i = 1, 2, \dots, p$, the sequence of edges $(C_i, A_{ij})(A_{ij}, B_{ij})(B_{ij}, l_{ij})(l_{ij}, R_{ij}), (R_{ij}, Q_{ij})(Q_{ij}, C_{i+1})$ are in the strong-cycle, for some $j = 1, 2, 3$. This follows from the fact that there are dependencies $(C_{r+1}, Q_{rs}) \rightarrow (Q_{rs}, R_{rs})$, for all $r = 1, 2, \dots, p$, for all $s = 1, 2, 3$ and also if $l_{ij} = pos_r(k)$, then the dependencies $(W_{rk}, X_{rk}) \rightarrow (X_{rk}, P_{rk}) \in D$ and $(B_{ij}, l_{ij}) \rightarrow (l_{ij}, P_{r(k+1)}) \in D$ (a similar set of dependencies can be identified in the case $l_{ij} = neg_r(k)$). Thus, the strong-cycle also contains edges $(C_{p+1}, s_0), (s_0, x_1)$.

Also, for all $i = 1, 2, \dots, q$, the strong-cycle contains either edges

- $(x_i, b_i), (b_i, P_{i1}), (P_{i1}, X_{i1}), (X_{i1}, W_{i1}), (W_{i1}, pos_i(1)), (pos_i(1), P_{i2}), (P_{i2}, X_{i2}), \dots, (W_{i|pos_i|}, pos_i(|pos_i|)), (pos_i(|pos_i|), P_{i(|pos_i+1)}), (P_{i(|pos_i+1)}, e_i), (e_i, x_{i+1})$, if $|pos_i| > 0$,
- $(x_i, b_i), (b_i, P_{i1}), (P_{i1}, e_i), (e_i, x_{i+1})$, if $|pos_i| = 0$,

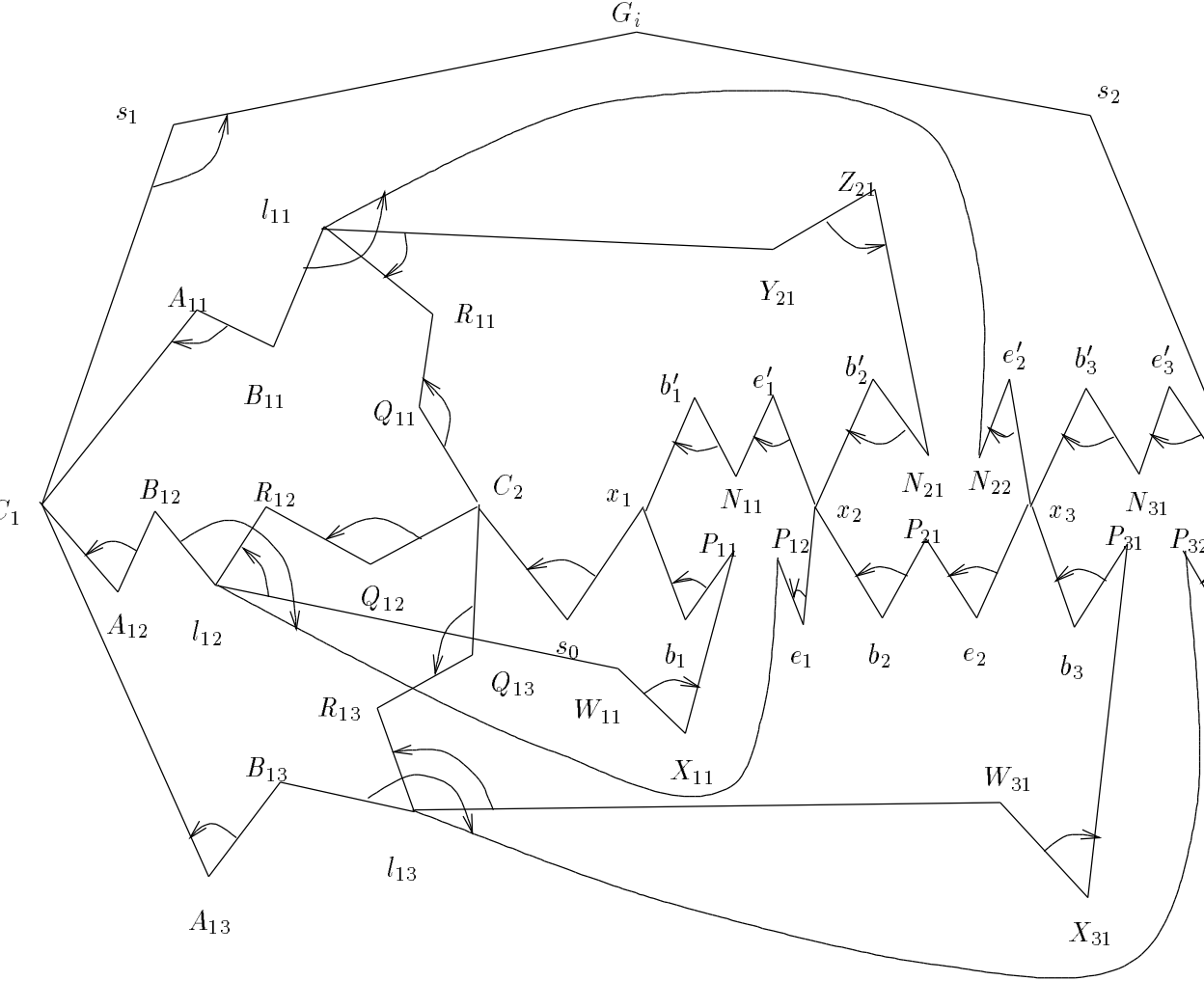


Figure 17: TSGD

only if $r < s$). In addition, there is no strong-cycle in (V', E', D', L') consisting of transaction nodes from both S_1 and S_2 since such a strong-cycle must contain the sequence of edges $(v_1, l_{ij})(l_{ij}, v_2)$, for some node l_{ij} , $v_1 \in S_2$ and $v_2 \in S_1$ (s_0 and l_{ij} are the only site nodes that have edges to transaction nodes in both S_1 and S_2 , and due to the dependency $(x_1, s_0) \rightarrow (s_0, C_{p+1})$, the sequence of edges $(x_1, s_0)(s_0, C_{p+1})$ cannot be in a strong-cycle). Let $l_{ij} = \text{pos}_r(k)$ (the argument if $l_{ij} = \text{neg}_r(k)$ is similar). Node v_1 can be $P_{r(k+1)}$ since if $k < |\text{pos}_r|$, then only two edges are incident on each of $P_{r(k+1)}$ and $X_{r(k+1)}$, and edges preceding (v_1, l_{ij}) in the strong-cycle must be the sequence $(W_{r(k+1)}, X_{r(k+1)})(X_{r(k+1)}, P_{r(k+1)})$. However, due to the dependency $(W_{r(k+1)}, X_{r(k+1)}) \rightarrow (X_{r(k+1)}, P_{r(k+1)})$, this is not possible. On the other hand, if $k = |\text{pos}_r|$, then since only two edges are incident on each of $P_{r(|\text{pos}_r|+1)}$ and e_r , edges preceding (v_1, l_{ij}) in the strong-cycle must be the sequence $(x_{r+1}, e_r)(e_r, P_{r(|\text{pos}_r|+1)})$. However, due to the dependency $(x_{r+1}, e_r) \rightarrow (e_r, P_{r(k+1)})$, this is not possible. Thus, $v_1 = W_{rk}$. However, due to the dependency $(W_{rk}, l_{ij}) \rightarrow (l_{ij}, R_{ij})$, $v_2 \neq R_{ij}$. Thus, it must be the case that $v_2 = B_{ij}$. However, since only two edges are incident on A_{ij} and B_{ij} , the sequence of edges immediately following B_{ij} in the cycle must be $(B_{ij}, A_{ij})(A_{ij}, C_i)$ which is not possible due to the dependency $(B_{ij}, A_{ij}) \rightarrow (A_{ij}, C_i)$. Thus, there can be no strong-cycle in (V', E', D', L') consisting of transaction nodes from both S_1 and S_2 , and (V', E', D', L') is strongly-acyclic.

We now show that C is satisfiable iff (V, E, D, L) contains a strong-cycle involving G_i . If C

- $(x_i, b'_i), (b'_i, N_{i1}), (N_{i1}, Z_{i1}), (Z_{i1}, Y_{i1}), (Y_{i1}, neg_i(1)), (neg_i(1), N_{i2}), (N_{i2}, Z_{i2}), \dots,$
 $(Y_{i|neg_i|}, neg_i(|neg_i|)), (neg_i(|neg_i|), N_{i(|neg_i|+1)}), (N_{i(|neg_i|+1)}, e'_i), (e'_i, x_{i+1}),$ if $|neg_i| > 0,$
- $(x_i, b'_i), (b'_i, N_{i1}), (N_{i1}, e'_i), (e'_i, x_{i+1}),$ if $|neg_i| = 0,$
- $(x_{q+1}, s_2), (s_2, G_i), (G_i, s_1), (s_1, C_1).$

Note that there are two edges incident on each of the symbols $e_i, e'_i, b_i, b'_i, A_{ij}, B_{ij}, Q_{ij}, R_{ij}, P_{ij}, W_{rk}, X_{ij}, N_{ij}, Y_{ij}$ and Z_{ij} . In addition, there are four edges incident on every symbol l_{ij} .

- If $l_{ij} = pos_r(k)$, there are edges $(B_{ij}, l_{ij}), (l_{ij}, R_{ij}), (W_{rk}, l_{ij})$ and $(l_{ij}, P_{r(k+1)})$ in the TSGD.
- If $l_{ij} = neg_r(k)$, there are edges $(B_{ij}, l_{ij}), (l_{ij}, R_{ij}), (Y_{rk}, l_{ij})$ and $(l_{ij}, N_{r(k+1)})$ in the TSGD.

The set of dependencies D consist of

- $(B_{ij}, A_{ij}) \rightarrow (A_{ij}, C_i), (C_{i+1}, Q_{ij}) \rightarrow (Q_{ij}, R_{ij}),$ for all $i = 1, 2, \dots, p,$ for all $j = 1, 2, 3,$
- $(x_1, s_0) \rightarrow (s_0, C_{p+1}),$
- for $i = 1, 2, \dots, q,$
 - $(P_{i1}, b_i) \rightarrow (b_i, x_i), (W_{i1}, X_{i1}) \rightarrow (X_{i1}, P_{i1}), (W_{i2}, X_{i2}) \rightarrow (X_{i2}, P_{i2}), \dots,$
 $(W_{i|pos_i|}, X_{i|pos_i|}) \rightarrow (X_{i|pos_i|}, P_{i|pos_i|}), (x_{i+1}, e_i) \rightarrow (e_i, P_{i(|pos_i|+1)}),$ if $|pos_i| > 0,$
 - $(P_{i1}, b_i) \rightarrow (b_i, x_i), (x_{i+1}, e_i) \rightarrow (e_i, P_{i1}),$ if $|pos_i| = 0,$
 - $(N_{i1}, b'_i) \rightarrow (b'_i, x_i), (Y_{i1}, Z_{i1}) \rightarrow (Z_{i1}, N_{i1}), (Y_{i2}, Z_{i2}) \rightarrow (Z_{i2}, N_{i2}), \dots,$
 $(Y_{i|neg_i|}, Z_{i|neg_i|}) \rightarrow (Z_{i|neg_i|}, N_{i|neg_i|}), (x_{i+1}, e'_i) \rightarrow (e'_i, N_{i(|neg_i|+1)}),$ if $|neg_i| > 0,$
 - $(N_{i1}, b'_i) \rightarrow (b'_i, x_i), (x_{i+1}, e'_i) \rightarrow (e'_i, N_{i1}),$ if $|neg_i| = 0,$
- for each symbol $l_{ij},$
 - if $l_{ij} = pos_r(k)$, then the following dependencies are in $D:$ $(W_{rk}, l_{ij}) \rightarrow (l_{ij}, R_{ij})$
 $(B_{ij}, l_{ij}) \rightarrow (l_{ij}, P_{r(k+1)}).$
 - if $l_{ij} = neg_r(k)$, then the following dependencies are in $D:$ $(Y_{rk}, l_{ij}) \rightarrow (l_{ij}, R_{ij})$ and $(B_{ij}, l_{ij}) \rightarrow (l_{ij}, N_{r(k+1)}).$
- $(C_1, s_1) \rightarrow (s_1, G_i),$

It is easy to see that the number of steps required to construct the TSGD (V, E, D, L) is $O(p + q)$. Let $C = \bar{x}_2 \vee x_1 \vee x_3$, then the constructed TSGD is as shown in Figure 17.

Our goal is to show that C is satisfiable iff (V, E, D, L) contains a strong-cycle involving G_i . We begin by showing that the TSGD (V, E, D, L) satisfies the conditions. In D , the only dependencies involving any of G_i 's edges is $(C_1, s_1) \rightarrow (s_1, G_i)$. Thus, in D , there are only dependencies into G_i 's edges. Also, the set of dependencies, D , is consistent. Further, we show that the TSGD (V', E', D') is strongly-acyclic, where $V' = V - G_i, E' = E - \{(G_i, s_1), (G_i, s_2)\},$ and $D' = D - \{(C_1, s_1) \rightarrow (s_1, G_i)\}.$ Let $S_1 = \{C_1, C_2, \dots, C_{p+1}\} \cup \{B_{ij}, R_{ij} : i = 1, 2, \dots, p, j = 1, 2, 3\},$ and $S_2 = \{x_1, x_2, \dots, x_{q+1}\} \cup \{N_{rk}, Y_{rk} : r = 1, 2, \dots, q, k = 1, 2, \dots, |neg_r|\} \cup \{P_{rk}, W_{rk} : r = 1, 2, \dots, q, k = 1, 2, \dots, |pos_r|\} \cup \{P_{r(|pos_r|+1)}, N_{r(|neg_r|+1)} : r = 1, 2, \dots, q\}.$ Note that there cannot exist a strong-cycle in (V', E', D') such that all the transaction nodes in the cycle are in S_1 (since there are dependencies $(B_{ij}, A_{ij}), (A_{ij}, C_i), (C_{i+1}, Q_{ij}) \rightarrow (Q_{ij}, R_{ij}),$ for all $i = 1, 2, \dots, p,$ for all $j = 1, 2, 3,$ a sequence of edges from C to C_s can be part of a strong-cycle only if $r < s$). Similarly, there can be no strong-cycle in (V', E', D') such that all the transaction nodes in the cycle are in S_2 (since there are dependencies $(P_{rk}, W_{rk}) \rightarrow (W_{rk}, X_{rk}), (X_{rk}, P_{rk}), (Y_{rk}, Z_{rk}) \rightarrow (Z_{rk}, N_{rk}),$ for all $r = 1, 2, \dots, q,$ a sequence of edges from C to C_s can be part of a strong-cycle only if $r < s$).

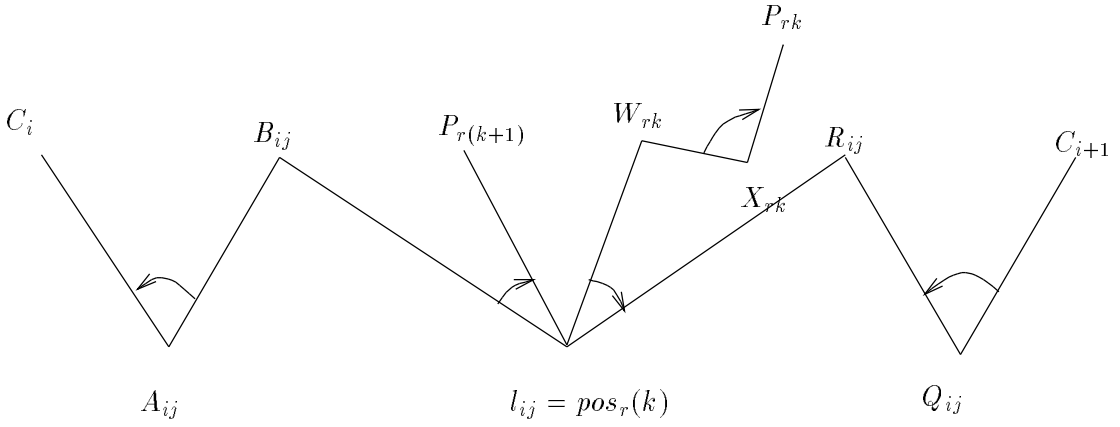


Figure 15: Edges and Dependencies if $l_{ij} = pos_r(k)$

On the other hand, if $l_{ij} = neg_r(k)$, then edges and dependencies shown in Figure 16 are introduced in the TSGD.

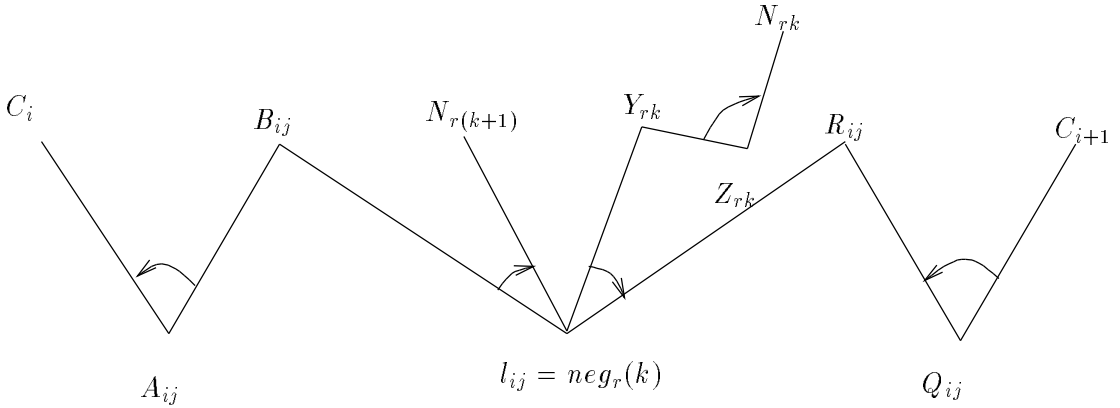


Figure 16: Edges and Dependencies if $l_{ij} = neg_r(k)$

We now describe the nodes, edges and dependencies in the TSGD. The set of nodes V consists of transaction and site nodes. The set of transaction nodes in the TSGD consists of $C_1, C_2, \dots, C_p, C_{p+1}, C_{p+2}, \dots, C_q, C_{q+1}, B_{ij}, R_{ij}, i = 1, 2, \dots, p, j = 1, 2, 3, G_i$ (C_{p+1}, C_{q+1} and G_i are new symbols in addition to $P_{r(|pos_r|+1)}, P_{rk}, W_{rk}$, for all $r = 1, 2, \dots, q, k = 1, 2, \dots, |pos_r|$, and for all $r = 1, 2, \dots, q, k = 1, 2, \dots, |neg_r|$. Site nodes consist of $l_{ij}, A_{ij}, Q_{ij}, i = 1, 2, \dots, p, j = 1, 2, 3, e_i, e'_i, b_i, b'_i, X_{rk}$ for all $r = 1, 2, \dots, q, k = 1, 2, \dots, |pos_r|$, and Z_{rk} for all $r = 1, 2, \dots, q, k = 1, 2, \dots, |neg_r|$ in addition to new symbols s_0, s_1, s_2 .

The set of edges E consist of

- $(C_i, A_{ij}), (A_{ij}, B_{ij}), (B_{ij}, l_{ij}), (l_{ij}, R_{ij}), (R_{ij}, Q_{ij})$ and (Q_{ij}, C_{i+1}) , for all $i = 1, 2, \dots, p$, for $j = 1, 2, 3$,
- $(C_{p+1}, s_0), (s_0, x_1)$,
- for $i = 1, 2, \dots, q$,
 - $(x_i, b_i), (b_i, P_{i1}), (P_{i1}, X_{i1}), (X_{i1}, W_{i1}), (W_{i1}, pos_i(1)), (pos_i(1), P_{i2}), (P_{i2}, X_{i2}), \dots,$
 $(W_{i(|pos_i|+1)}, pos_i(|pos_i|)), (pos_i(|pos_i|), P_{i(|pos_i|+1)}), (P_{i(|pos_i|+1)}, e_i), (e_i, x_{i+1})$, if $|pos_i| > 0$.

Appendix -E- : Intractability results

Theorem 7 is a consequence of the following NP-completeness result.

Theorem 9: The following problem is NP-complete: Given a TSGD (V, E, D, L) and a transaction node $G_i \in V$, such that D is consistent, and for all transactions $G_j \in V$, for all sites s_k , dependencies $(G_i, s_k) \rightarrow (s_k, G_j) \notin D$. Also, TSGD (V', E', D', L') resulting due to the deletion of G_i , its edges and dependencies from (V, E, D, L) , is strongly-acyclic. Is $\Delta = \emptyset$ not strongly-minimal with respect to TSGD and transaction G_i ?

Proof: We begin by showing that $\Delta = \emptyset$ is not strongly-minimal with respect to G_i and (V, E, D, L) iff (V, E, D, L) contains a strong-cycle involving transaction G_i . Since $\Delta = \emptyset$, and universal quantification over \emptyset is always *true*, by the definition of strong-minimality, Δ is strongly-minimal with respect to G_i and (V, E, D, L) iff (V, E, D, L) does not contain any strong-cycles involving G_i . As a result, it suffices to show that the following problem is NP-complete: Does (V, E, D, L) contain a strong-cycle involving G_i ?

The above problem is in NP since a non-deterministic algorithm only needs to guess a sequence of edges containing at most $2|E|^2 + 1$ edges and then check in polynomial time if the sequence of edges results in a strong-cycle involving G_i in the TSGD (V, E, D, L) . The algorithm only needs to guess a sequence of $2|E|^2 + 1$ edges since in any strong-cycle with more than $2|E|^2 + 1$ edges, a consecutive pair of edges must be repeated (the total number of distinct pairs of edges is $|E|^2$). Thus, the strong-cycle must be of the form $\cdots(v'_1, v_1)(v_1, v_2)(v_2, v_3) \cdots (v_1, v_2)(v_2, v_3)(v_3, v'_2) \cdots$ for some nodes $v_1, v_2, v_3, v'_1, v'_2$ in the TSGD. However, there exists a strong-cycle with fewer edges: $\cdots(v'_1, v_1)(v_1, v_2)(v_2, v_3)(v_3, v'_2)$. Thus, if (V, E, D, L) contains a strong-cycle involving G_i , then it contains a strong-cycle involving G_i with no more than $2|E|^2 + 1$ edges.

We show a polynomial transformation from 3-SAT. Consider a formula in *Conjunctive Normal Form* (CNF) $C = C_1 \wedge C_2 \wedge \cdots \wedge C_p$ that is defined over literals x_1, x_2, \dots, x_q . Let $l_{ij}, i = 1, 2, \dots, p, j = 1, 2, 3$ be a new symbol for the j^{th} literal in clause C_i . Each symbol l_{ij} is either x_k or $\bar{x}_k, k = 1, 2, \dots, q$. In addition, for every literal x_i , we introduce new symbols e_i, e'_i, b_i and b'_i , and for literal l_{ij} , we introduce new symbols A_{ij}, B_{ij}, Q_{ij} and R_{ij} . For $r = 1, 2, \dots, q, pos_r$ denotes the sequence of symbols l_{ij} in the order of increasing i , such that $l_{ij} = x_r$. For $r = 1, 2, \dots, q, neg_r$ denotes the sequence of symbols l_{ij} in the order of increasing i , such that $l_{ij} = \bar{x}_r$. Also $|pos_r|$ denotes the number of elements in the sequence pos_r and for $k = 1, 2, \dots, |pos_r|, pos_r(k)$ denotes the k^{th} element in the sequence pos_r ($|neg_r|$ and $neg_r(k)$ are similarly defined). For all $r = 1, 2, \dots, q$, we introduce new symbols P_{rk}, W_{rk}, Z_{rk} for each $pos_r(k), k = 1, 2, \dots, |pos_r|$, and $P_{r(|pos_r|+1)}$; for $r = 1, 2, \dots, q$, new symbols N_{rk}, Y_{rk}, Z_{rk} for each $neg_r(k), k = 1, 2, \dots, |neg_r|$, and $N_{r(|neg_r|+1)}$. We illustrate the notation by means of the following example (“ \cdot ” is the concatenation operator for sequences and “ ϵ ” is the empty sequence).

Example: Let $C = (x_1 \vee \bar{x}_3 \vee x_4) \wedge (\bar{x}_2 \vee \bar{x}_1 \vee x_3) \wedge (\bar{x}_2 \vee \bar{x}_4 \vee x_1)$.

$l_{1,1} = x_1, l_{2,2} = \bar{x}_1, l_{3,2} = \bar{x}_4$.

$pos_1 = l_{1,1} \cdot l_{3,3}, neg_1 = l_{2,2}, pos_2 = \epsilon$.

Also, $|pos_1| = 2, |pos_2| = 0, |neg_2| = 2$.

$pos_1(1) = l_{1,1}, pos_1(2) = l_{3,3}, neg_1(1) = l_{2,2}, neg_2(2) = l_{3,1}$. \square

We now construct the TSGD as follows. The main components in the TSGD are the edges and dependencies that we introduce for literals l_{ij} . If $l_{ij} = pos_r(k)$, then edges and dependencies shown in Figure 15 are included in the TSGD.

We further use Lemma 3 to show that, for $F = FA(RT_2)$, $state_F(init_st_F, edge(t_1) \cdots edge(t_n, sfirst(t_0), G_0))$ is an accept state. Let $edge(t_1) \cdots edge(t_{n-1})(sfirst(t_0), G_0) = (v_1, v_2) \cdots (v_{2m-1}, v_{2m})$. In order to use Lemma 3, we need to show that there exists a sequence $g_1 \cdots g_{m-1}$ such that

- if $v_{2i} = v_{2i+1}$, then $g_i = L(v_{2i-1}, v_{2i})$, and
- if $v_{2i-1} = v_{2i+1}$, then $g_i = \overline{L(v_{2i-1}, v_{2i})}$, and

$st_F(init_st_F, g_1 \cdots g_{m-1})$ is an accept state. We construct the sequence $g_1 \cdots g_{m-1}$ with the above properties as follows. For all $i = 1, \dots, n-1$, let $f_i = \overline{(type(hdr(t_i)), type(first(t_i)))}$, if $arity(t_i) = 2$, else, $f_i = (type(hdr(t_i)), type(first(t_i)))(type(hdr(t_i)), type(last(t_i)))$. Since $type(t_1) \cdots type(t_{n-1})$ is a string in $L(reg_exp)$, by the construction of $FA(RT_2)$, it follows that $st_F(init_st_F, f_1 \cdots f_{n-1})$ is an accept state. Let $g_1 \cdots g_{m-1} = f_1 \cdots f_{n-1}$, such that every $g_i \in \Sigma_F$. Furthermore, from the definition of $edge$ and f_j , it follows that, if for some $i = 1, \dots, m-1$, if $(v_{2i-1}, v_{2i}) \in edge(t_k)$ and $arity(t_k) = 2$, then $g_i = L(v_{2i-1}, v_{2i})$, else $g_i = \overline{L(v_{2i-1}, v_{2i})}$.

In order to show that $state_F(init_st_F, (v_1, v_2), \dots, (v_{m-1}, v_m))$ is an accept state, we need to show that for all $i, i = 1, 2, \dots, m-1$, if $v_{2i} = v_{2i+1}$, then $g_i = L(v_{2i-1}, v_{2i})$ and if $v_{2i-1} = v_{2i+1}$, then $g_i = \overline{L(v_{2i-1}, v_{2i})}$. We first show that if $v_{2i} = v_{2i+1}$, and $(v_{2i-1}, v_{2i}) \in edge(t_k)$ for some $k, k = 1, 2, \dots, n-1$, then $arity(t_k) = 2$. Suppose $arity(t_k) = 1$. Since $last(t_k)$ and $first(t_{(k+1) \bmod n})$ execute at the same site, $slast(t_k) = v_{2i-1}$, $sfirst(t_{(k+1) \bmod n}) = v_{2i+1}$, it follows that $v_{2i-1} = v_{2i+1}$, which leads to a contradiction. Thus, $arity(t_k) = 2$, and $g_i = L(v_{2i-1}, v_{2i})$. Also, it can be shown that if $v_{2i-1} = v_{2i+1}$, and $(v_{2i-1}, v_{2i}) \in edge(t_k)$, then $arity(t_k) = 1$. Suppose $arity(t_k) = 2$, $v_{2i} = G_k$, then $v_{2i} = v_{2i+1} = G_k$, which leads to a contradiction. If $v_{2i-1} = G_k$, then since $last(t_k)$ and $first(t_{(k+1) \bmod n})$ execute at the same site, $slast(t_k) = v_{2i}$, $sfirst(t_{(k+1) \bmod n}) = v_{2i+1}$, it follows that $v_{2i} = v_{2i+1}$, which leads to a contradiction. Thus, $arity(t_k) = 1$, and, $g_i = \overline{L(v_{2i-1}, v_{2i})}$.

Thus, by Lemma 3, $state_F(init_st_F, edge(t_1) \cdots edge(t_{n-1})(sfirst(t_0), G_0))$ is an accept state. Thus, by corollaries 8 and 10, during the execution of $Detect_Ins_TSGD?(V, E, D, L, G_0, slast(t_0), set_1, RT_2)$, dependency $(prev_anc(sfirst(t_0)), sfirst(t_0)) \rightarrow (sfirst(G_0), G_0)$ is added to Δ , and $(prev_anc(sfirst(t_0)), sfirst(t_0)) \rightarrow (sfirst(t_0), G_0) \in \Delta_F$. However, this leads to a contradiction since we showed earlier that $(prev_anc(sfirst(t_0)), sfirst(t_0)) \rightarrow (sfirst(t_0), G_0) \notin \Delta_F$. Thus, every schedule S is correct. \square

When $init_0$ is processed, the procedure `Detect_Ins_TSGD?` is invoked with arguments that include the TSGD (V, E, D, L) , G_0 , $slast(t_0)$, set_1 , and RT_2 since $type(G_0) = hdr(e_0)$ and $type(last(t_0)) = last(e_0)$. Also, $sfirst(t_0) \in set_1$ (if $arity(t_0) = 1$, then since $sfirst(t_0) = slast(t_0)$, $sfirst(t_0) \in set_1$; if $binary(t_0)$, then since $sfirst(t_0) \neq slast(t_0)$, and $type(first(t_0)) = first(e_0)$, $sfirst(t_0) \in set_1$). Furthermore, all the edges belonging to G_0, \dots, G_{n-1} are in the TSGD when `Detect_Ins_TSGD?` is invoked. In order to show this, we first show that G_j 's edges cannot be deleted from the TSGD before $G_{(j+1) \bmod n}$'s edges are deleted from the TSGD, for all $j, j = 1, 2, \dots, n-1$. Suppose, for some $j, j = 1, 2, \dots, n-1$, G_j 's edges are deleted from the TSGD before $G_{(j+1) \bmod n}$'s edges are deleted from the TSGD. Let $slast(t_j) = s_k$. Since G_{j_k} is serialized after $G_{((j+1) \bmod n)k}$, at site $ser_k(G_{(j+1) \bmod n})$ executes before $ser_k(G_j)$. Thus, since $G_{(j+1) \bmod n}$'s edges are inserted into the TSGD before $ser_k(G_{(j+1) \bmod n})$ executes, while G_j 's edges are deleted after $ser_k(G_j)$ executes, $G_{(j+1) \bmod n}$'s edges must be in the TSGD when G_j 's edges are deleted (since we have assumed that G_j 's edges are deleted before $G_{(j+1) \bmod n}$'s edges are deleted). Furthermore, since $ser_k(G_j)$ and $ser_k(G_{(j+1) \bmod n})$ must have both executed when G_j 's edges are deleted, $G_{(j+1) \bmod n}$ is serialized before G_j when G_j 's edges are deleted. However, this leads to a contradiction, since edges belonging to G_j and $G_{(j+1) \bmod n}$ are deleted together when fin_l for some transaction G_l is processed (since $G_{(j+1) \bmod n}$ is serialized before G_j , if for every transaction $G_k \in V$ serialized before G_j , val_k has been processed, then for every transaction $G_k \in V$ serialized before $G_{(j+1) \bmod n}$ also, val_k must have been processed). Thus, G_j 's edges are not deleted from the TSGD before G_2 's edges are deleted, \dots , G_{n-1} 's edges are not deleted from the TSGD before G_0 's edges are deleted. By transitivity and since G_0 's edges are deleted only after $init_0$ has been processed, when `Detect_Ins_TSGD?` is invoked during the processing of $init_0$, the TSGD contains all the edges belonging to transactions G_0, G_1, \dots, G_{n-1} .

Let Δ_F be the set of dependencies returned by `Detect_Ins_TSGD?`. We now show that $(G_0, slast(t_0)) \rightarrow edge(t_1) \cdots edge(t_{n-1})(sfirst(t_0), G_0)$ is a path in the TSGD $(V, E, D \cup \Delta_F)$. We begin by showing that any two consecutive edges in the path have a common node. Consecutive edges in the path can be one of the following:

- $(sfirst(G_j), G_j)(G_j, slast(G_j)), j = 1, 2, \dots, n-1$, where $arity(t_j) = 2$ (G_j is the common node).
- $(G_j, slast(t_j))(sfirst(t_{(j+1) \bmod n}), G_{(j+1) \bmod n}), j = 0, 1, \dots, n-1$, where $arity(t_j) = 2$ or $j = 0$ and $arity(t_{(j+1) \bmod n}) = 1$ or 2 (since for all $j, j = 0, 1, \dots, n-1$, $last(t_j)$ and $first(t_{(j+1) \bmod n})$ execute at the same site, $slast(t_j) = sfirst(t_{(j+1) \bmod n})$ is the common node).
- $(sfirst(t_j), G_j)(sfirst(t_{(j+1) \bmod n}), G_{(j+1) \bmod n}), j = 1, 2, \dots, n-1$, where $arity(t_j) = 1$, and $arity(t_{(j+1) \bmod n}) = 1$ or 2 (since $arity(t_j) = 1$ implies that $sfirst(t_j) = slast(t_j)$, and $slast(t_j) = sfirst(t_{(j+1) \bmod n})$, it follows that $sfirst(t_j) = sfirst(t_{(j+1) \bmod n})$ is the common node).

Also, for the sequence of edges $(sfirst(t_j), G_j)(G_j, slast(t_j))$ in the path, $j = 1, 2, \dots, n-1$, it must be the case that $arity(t_j) = 2$, and thus $sfirst(t_j) \neq slast(t_j)$. Also, if for some $j, k, j = 0, 1, \dots, n-1, j < k \leq n$, the sequence of edges $(G_j, slast(t_j))(sfirst(t_{(j+1) \bmod n}), G_{(j+1) \bmod n}), \dots, (sfirst(t_{k \bmod n}), G_{k \bmod n})$ is in the path, then it must be the case that for all $j < l < k$, $arity(t_l) = 2$. Thus, by Property 1, it follows that $slast(t_j) = sfirst(t_{(j+1) \bmod n}) = \dots = sfirst(t_{k \bmod n})$, and for all $r, s, j \leq r < s \leq k$,

- $G_r \neq G_{s \bmod n}$, and
- G_r is serialized after $G_{s \bmod n}$ at site $sfirst(G_{s \bmod n})$. Thus, by Lemma 14, dependency $(G_r, sfirst(G_{s \bmod n})) \rightarrow (sfirst(G_{s \bmod n}), G_{s \bmod n})$ does not belong to $D \cup \Delta_F$ (since Δ_F is added to the set of dependencies D in the TSGD immediately after $init_0$ is processed).

Thus, $(G_0, slast(t_0)) \rightarrow edge(t_1) \cdots edge(t_{n-1})(sfirst(t_0), G_0)$ is a path in the TSGD $(V, E, D \cup \Delta_F)$. The path starts at $sfirst(t_0)$ and ends at $slast(t_0)$. For all $j, j = 1, 2, \dots, n-1$, $sfirst(t_j) = sfirst(t_{(j+1) \bmod n})$ and $slast(t_j) = slast(t_{(j+1) \bmod n})$.

However, since in state St'_k , no forward transition can be made due to edge $(St'_k.v, v_{2m+2})$, it must be the case that

- if $v_{2m+2} = v_{2m+3}$, then $St'_k.V_set(v_{2m+2})$ already contains $(st_{m+1}, (St'_k.v, St'_k.v))$. Thus, since $St'_k.v = v_{2m+1}$, $prev(v_{2m+3}) = v_{2m+1}$, $prev_anc(v_{2m+3}) = v_{2m+1}$, $(st_{m+1}, (prev_anc(v_{2m+3}), prev(v_{2m+3})))$ is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_TSGD2.
- if $v_{2m+1} = v_{2m+3}$, then $St'_k.V_set(St'_k.v)$ already contains $(st_{m+1}, (prev_anc(v_{2m+1}), v_{2m+1}))$. Thus, since $St'_k.v = v_{2m+1}$, $prev(v_{2m+3}) = v_{2m+2}$, $prev_anc(v_{2m+3}) = prev_anc(v_{2m+1})$, $(st_{m+1}, (prev_anc(v_{2m+3}), prev(v_{2m+3})))$ is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_TSGD2. \square

Corollary 10: Let $\text{Detect_Ins_TSGD2}((V, E, D, L), v_1, v_2, set_1, RT)$ return the set of dependencies Δ_F . If the TSGD $(V, E, D \cup \Delta_F)$ contains a path $(v_1, v_2) \cdots (v_{2n-1}, v_{2n})(v_{2n+1}, v_1)$, $v_2 = v_3$, such that for the regular term RT , $F = FA(RT)$, $st = state_F(\text{init_st}_F, (v_3, v_4) \cdots (v_{2n-1}, v_{2n})(v_{2n+1}, v_1))$ is an accept state and $v_{2n+1} \in set_1$, then during the execution of Detect_Ins_TSGD2 , dependency $(prev_anc(v_{2n+1}), v_{2n+1}) \rightarrow (v_{2n+1}, v_1)$ is added to Δ .

Proof: By Lemma 13, $(st, (prev_anc(v_{2n+1}), prev(v_{2n+1})))$ is added to $V_set(v_{2n+1})$. Since $prev(v_{2n+1}) \neq v_1$ and $prev_anc(v_{2n+1}) \neq v_1$ (by definition of path), Detect_Ins_TSGD2 makes a forward state transition when $(st, (prev_anc(v_{2n+1}), prev(v_{2n+1})))$ is added to $V_set(v_{2n+1})$. However, just before $(st, (prev_anc(v_{2n+1}), prev(v_{2n+1})))$ is added to $V_set(v_{2n+1})$, since st is an accept state, $prev_anc(v_{2n+1}) \neq v_1$, $prev(v_{2n+1}) \neq v_1$ and $v_{2n+1} \in set_1$, dependency $(prev_anc(v_{2n+1}), v_{2n+1}) \rightarrow (v_{2n+1}, v_1)$ is added to Δ . \square

We are now in a position to prove that the TSGD scheme ensures the correctness of S . Before we present the proof, we prove the following lemma.

Lemma 14: If, in the TSGD scheme, for some site s_k , transactions G_i, G_j, G_{ik} is serialized before G_{jk} at site s_k , then there does not exist a dependency $(G_j, s_k) \rightarrow (s_k, G_i)$ in the TSGD.

Proof: Suppose there exists a dependency $(G_j, s_k) \rightarrow (s_k, G_i)$ in the TSGD. The dependency can be added to the TSGD once $act(ser_k(G_i))$ has executed. Thus, dependency $(G_j, s_k) \rightarrow (s_k, G_i)$ must be added to the TSGD before $act(ser_k(G_i))$ executes. However, if this were the case, $act(ser_k(G_i))$ would not execute until $act(ack(ser_k(G_j)))$ completes execution (the dependency $(G_j, s_k) \rightarrow (s_k, G_i)$ is deleted from the TSGD only after $ack(ser_k(G_j))$ is processed). Thus, $ser_k(G_j)$ would execute before $ser_k(G_i)$ and G_{jk} would be serialized before G_{ik} at site s_k , which leads to a contradiction. \square

Proof of Theorem 5: Suppose S is not correct. Thus, there exists a regular term RT in R and an instantiation I of RT in S . Let G_0 be the transaction in I such that $init_0$ is processed after $init_1$ and every other transaction G_i in I is processed. By Lemma 1, since R is complete, there exists a regular term $RT_2 = e_0 : reg_exp$ and an instantiation $t_0 : t_1 t_2 \cdots t_{n-1}$ of RT_2 in S such that $hdr(t_0) = G_0$. Thus,

- for all j , $j = 0, 1, \dots, n-1$,
 1. $t_j \in \Sigma_S$ (without loss of generality, let $hdr(t_j) = G_j$), and
 2. $last(t_j)$ and $first(t_{(j+1) \bmod n})$ execute at the same site, and $last(t_j)$ is serialized after $first(t_{(j+1) \bmod n})$ at the site, and

or $St_j.v = prev_anc(v_{2m+1})$, or due to Step 1). Thus, $St_k.v = v_{2m+1}$, $St_k.cur_st = st_m$ and in St_k , $head(St_k.anc(St_k.v)) = prev_anc(v_{2m+1})$. Furthermore, it follows from Lemma 10 that after a finite number of steps, Detect_Ins_TSGD1 is in a state St'_k such that $St'_k \equiv St_k$ and no further forward transitions can be made from St'_k . Thus, in state St'_k ,

- Since $prev_anc(v_{2m+1}) \neq v_{2m+2}$ (by the definition of path), $head(St'_k.anc(St'_k.v)) \neq v_{2m+2}$,
- Since $St'_k.\Delta \subseteq \Delta_F$, and $(v_1, v_2) \cdots (v_{2m+1}, v_{2m+2})$ is a path in $(V, E, D \cup \Delta_F)$, there is no dependency $(prev_anc(v_{2m+1}), v_{2m+1}) \rightarrow (v_{2m+1}, v_{2m+2})$ in $D \cup \Delta_F$; thus, there is no dependency $(head(St'_k.anc(St'_k.v)), St'_k.v) \rightarrow (St'_k.v, v_{2m+2})$ in $D \cup St'_k.\Delta$,
- Since $state_F(init_st_F, (v_3, v_4) \cdots (v_{2m+1}, v_{2m+2})(v_{2m+3}, v_{2m+4}))$ is defined, if $v_{2m+2} = v_{2m+3}$, then $st_{m+1} = st_F(St'_k.cur_st, L(St'_k.v, v_{2m+2}))$ is defined, else if $v_{2m+1} = v_{2m+3}$, then $st_{m+1} = st_F(St'_k.cur_st, L(St'_k.v, v_{2m+2}))$ is defined.

However, since in state St'_k , no forward transition can be made due to edge $(St'_k.v, v_{2m+2})$, it must be the case that

- if $v_{2m+2} = v_{2m+3}$, then $St'_k.V_set(v_{2m+2})$ already contains $(st_{m+1}, St'_k.v)$. Thus, since $St'_k.v = v_{2m+1}$, $prev_anc(v_{2m+3}) = v_{2m+1}$, $(st_{m+1}, prev_anc(v_{2m+3}))$ is added to $V_set(v_{2m+3})$ during execution of Detect_Ins_TSGD1.
- if $v_{2m+1} = v_{2m+3}$, then $St'_k.V_set(St'_k.v)$ already contains $(st_{m+1}, prev_anc(v_{2m+1}))$. Thus, since $St'_k.v = v_{2m+1}$, $prev_anc(v_{2m+3}) = prev_anc(v_{2m+1})$, $(st_{m+1}, prev_anc(v_{2m+3}))$ is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_TSGD1. \square

Corollary 8: Let $Detect_Ins_TSGD1((V, E, D, L), v_1, v_2, set_1, RT)$ return the set of dependencies Δ_F . If the TSGD $(V, E, D \cup \Delta_F)$ contains a path $(v_1, v_2) \cdots (v_{2n-1}, v_{2n})(v_{2n+1}, v_1)$, $v_2 = v_3$, st is an accept state and $v_{2n+1} \in set_1$, then during the execution of Detect_Ins_TSGD1, dependency $(prev_anc(v_{2n+1}), v_{2n+1}) \rightarrow (v_{2n+1}, v_1)$ is added to Δ .

Proof: By Lemma 11, $(st, prev_anc(v_{2n+1}))$ is added to $V_set(v_{2n+1})$. Since $prev_anc(v_{2n+1}) \neq v_1$, Detect_Ins_TSGD1 makes a forward state transition when $(st, prev_anc(v_{2n+1}))$ is added to $V_set(v_{2n+1})$. However, just before $(st, prev_anc(v_{2n+1}))$ is added to $V_set(v_{2n+1})$, since st is an accept state, $prev_anc(v_{2n+1}) \neq v_1$ and $v_{2n+1} \in set_1$, dependency $(prev_anc(v_{2n+1}), v_{2n+1}) \rightarrow (v_{2n+1}, v_1)$ is added to Δ . \square

We now show that Detect_Ins_TSGD2 terminates in $O(n_G^2 m v_S)$ steps, for which we need to prove the following lemma.

Lemma 12: If during its execution, Detect_Ins_TSGD2 is in state St_k , then after a finite number of steps, it enters a state $St'_k \equiv St_k$ such that no forward transitions from St'_k are possible.

Proof: Similar to proof of Lemma 8. \square

Corollary 9: Procedure Detect_Ins_TSGD2 terminates in $O(n_G^3 m n_S)$ steps.

Proof: Detect_Ins_TSGD2 can be shown to terminate as a result of Lemma 12 using a similar argument as in Corollary 3.

The number of steps Detect_Ins_TSGD2 terminates in is equal to the product of the number of times Detect_Ins_TSGD2 checks if an edge satisfies the conditions in Step 2 and the number of

Appendix -D- : TSGD Schemes

In this appendix, we prove Theorem 5. We begin by showing that Detect_Ins_TSGD1 and Detect_Ins_TSGD2 detect instantiations of regular terms in S . States St_k between the execution of two steps of Detect_Ins_TSGD1 and Detect_Ins_TSGD2 are as defined earlier for Detect_Ins_Opt.

Lemma 10: If during its execution, Detect_Ins_TSGD1 is in state St_k , then after a finite number of steps, it enters a state $St'_k \equiv St_k$ such that no forward transitions from St'_k are possible.

Proof: Similar to proof of Lemma 2. \square

Corollary 7: Procedure Detect_Ins_TSGD1 terminates in $O(n_G^2 mn_S)$ steps.

Proof: Detect_Ins_TSGD1 can be shown to terminate as a result of Lemma 10 using a similar argument as in Corollary 3.

The number of steps Detect_Ins_TSGD1 terminates in is equal to the product of the number of times Detect_Ins_TSGD1 checks if an edge satisfies the conditions in Step 2 and the number of steps required to check if an edge satisfies the conditions in Step 2. Every time a transaction node is visited, the conditions in Step 2 need to be checked, on an average, for v_S edges (the average number of steps a global transaction executes at is v_S), while every time a site node is visited, the conditions in Step 2 need to be checked for at most n_G edges (since the number of transaction nodes in the TSGD is at most n_G). Furthermore, every transaction node can be visited at most $v_S n_S$ times, while every site node can be visited at most $n_G n_S$ times (every node v in the TSGD can be visited in a state st at most once for every node w such that edge (v, w) is in the TSGD, and F has at most n_S states). Since there are m site nodes and at most n_G transaction nodes in the TSGD, the number of times Detect_Ins_TSGD1 checks if an edge satisfies the conditions in Step 2 is $n_G^2 mn_S + n_G v_S^2 n_S$. Since each of the conditions in Step 2 can be checked in constant time and $v_S \ll n_G, v_S < m$, Detect_Ins_TSGD1 terminates in $O(n_G^2 mn_S)$ steps. \square

We now show that Detect_Ins_TSGD1 traverses edges in the TSGD in a manner that ensures it detects instantiations of regular terms.

Lemma 11: Let $\text{Detect_Ins_TSGD1}((V, E, D, L), v_1, v_2, \text{set}_1, RT)$ return the set of dependent edges Δ_F . If the TSGD $(V, E, D \cup \Delta_F)$ contains a path $(v_1, v_2), (v_3, v_4), \dots, (v_{2n-3}, v_{2n-2}), (v_{2n-1}, v_{2n}), (v_{2n+1}, v_{2n+2}), \dots, (v_{2m-1}, v_{2m})$, such that for the regular term $RT, F = FA(RT)$, $\text{state}_F(\text{init_st}_F, (v_3, v_4), \dots, (v_{2n-1}, v_{2n}))$ is defined, then during the execution of Detect_Ins_TSGD1, for all $i, i = 1, 2, 3, \dots, n-1$, $(st, \text{prev_anc}(v_{2i+1}))$ is added to $V_set(v_{2i+1})$, where $st = \text{state}_F(\text{init_st}_F, (v_3, v_4) \cdots (v_{2i-1}, v_{2i})(v_{2i+1}, v_{2i+2}))$.

Proof: We prove the above lemma by induction on i . We prove that for all $i, i = 1, 2, \dots, n-1$, $(st, \text{prev_anc}(v_{2i+1}))$ is added to $V_set(v_{2i+1})$, where $st = \text{state}_F(\text{init_st}_F, (v_3, v_4) \cdots (v_{2i-1}, v_{2i})(v_{2i+1}, v_{2i+2}))$.
Basis ($i = 1$): In Step 1 of Detect_Ins_TSGD1, $(\text{init_st}_F, v_1)$ is added to $V_set(v_2)$. Since $v_2 = \text{prev_anc}(v_3) = v_1$, and $\text{state}_F(\text{init_st}_F, (v_3, v_4)) = \text{init_st}_F$, the lemma is true for $i = 1$ ($(\text{init_st}_F, \text{prev_anc}(v_3))$ is added to $V_set(v_3)$).

Induction: Let us assume that the lemma is true for $i = m, 1 \leq m < n-1$. Thus, $(st_m, \text{prev_anc}(v_{2m+1}))$ is added to $V_set(v_{2m+1})$, where $st_m = \text{state}_F(\text{init_st}_F, (v_3, v_4) \cdots (v_{2m-1}, v_{2m})(v_{2m+1}, v_{2m+2}))$. We show the lemma to be true for $i = m + 1$. Thus, we need to show that $(st_{m+1}, \text{prev_anc}(v_{2m+3}))$ is added to $V_set(v_{2m+3})$, where $st_{m+1} = \text{state}_F(\text{init_st}_F, (v_3, v_4) \cdots (v_{2m+1}, v_{2m+2})(v_{2m+3}, v_{2m+4}))$. By the definition of state_F , $st_{m+1} = st_F(st_m, L(v_{2m+1}, v_{2m+2}))$, if $v_{2m+2} = v_{2m+3}$ and $st_{m+1} = st_F(st_m, \overline{L}(v_{2m+1}, v_{2m+2}))$, if $v_{2m+1} = v_{2m+3}$.

$j < k \leq n$, the sequence of edges $(G_j, \text{slast}(t_j))(\text{sfirst}(t_{(j+1) \bmod n}), G_{(j+1) \bmod n}), \dots, (\text{sfirst}(t_{k \bmod n}), G_{k \bmod n})$ is in the path, then it must be the case that for all $j < l < k$, $\text{arity}(t_l) = 2$. Thus, by Property 1, it follows that $\text{slast}(t_j) = \text{sfirst}(t_{(j+1) \bmod n}) = \dots = \text{sfirst}(t_{k \bmod n})$, and all $r, s, j \leq r < s \leq k$, $G_r \neq G_{s \bmod n}$. Thus, $(G_0, \text{slast}(t_0))\text{edge}(t_1) \cdots \text{edge}(t_{n-1})(\text{sfirst}(t_0), G_0)$ is a path in the TSG (V, E, L) . Furthermore, if Δ_F is the set of site nodes returned by Detect_Ins_TS, then for some $j = 0, 1, \dots, n-1$, if $\text{sfirst}(t_{(j+1) \bmod n}) \in \text{set}_2 \cup \Delta_F$, then $G_{(j+1) \bmod n} \neq G_0$, $s_k = \text{sfirst}(t_{(j+1) \bmod n}) = \text{slast}(t_j)$. If $s_k \in \text{set}_2 \cup \Delta_F$ and $G_{(j+1) \bmod n} = G_0$, then $\text{ser}_k(G_{(j+1) \bmod n})$ in the queue is marked when init_0 is processed. Since init_0 is processed after init_j , $\text{ser}_k(G_{(j+1) \bmod n})$ is inserted into the queue for site s_k before $\text{ser}_k(G_{(j+1) \bmod n})$ is inserted into the queue for s_k . Thus, $\text{ser}_k(G_{(j+1) \bmod n})$ executes after $\text{ser}_k(G_j)$, and $\text{first}(t_{(j+1) \bmod n}) = G_{((j+1) \bmod n)k}$ must be serializable after $\text{last}(t_j) = G_{jk}$ at site s_k , which leads to a contradiction. Thus, $\text{sfirst}(t_0) \notin \text{set}_2 \cup \Delta_F$. Thus, the path $(G_0, \text{slast}(t_0))\text{edge}(t_1) \cdots \text{edge}(t_{n-1})(\text{sfirst}(t_0), G_0)$ is consistent with respect to $\text{set}_2 \cup \Delta_F$. We further use Lemma 3 to show that, for $F = FA(RT_2)$, $\text{state}_F(\text{init_st}_F, \text{edge}(t_1) \cdots \text{edge}(t_{n-1})(\text{sfirst}(t_0), G_0))$ is an accept state. Let $\text{edge}(t_1) \cdots \text{edge}(t_{n-1})(\text{sfirst}(t_0), G_0) = (v_1, v_2) \cdots (v_{2m-1}, v_{2m})$. In order to use Lemma 3, we need to show that there exists a sequence $g_1 \cdots g_{m-1}$ such that

- if $v_{2i} = v_{2i+1}$, then $g_i = L(v_{2i-1}, v_{2i})$, and
- if $v_{2i-1} = v_{2i+1}$, then $g_i = \overline{L(v_{2i-1}, v_{2i})}$, and

$\text{state}_F(\text{init_st}_F, g_1 \cdots g_{m-1})$ is an accept state. We construct the sequence $g_1 \cdots g_{m-1}$ with the above properties as follows. For all $i = 1, \dots, m-1$, let $f_i = (\text{type}(\text{hdr}(t_i)), \text{type}(\text{first}(t_i)))$, if $\text{arity}(t_i) = 2$, else, $f_i = (\text{type}(\text{hdr}(t_i)), \text{type}(\text{first}(t_i)))(\text{type}(\text{hdr}(t_i)), \text{type}(\text{last}(t_i)))$. Since $\text{type}(t_1) \cdots \text{type}(t_{n-1})$ is a string in $L(\text{reg_exp})$, by the construction of $FA(RT_2)$, it follows that $\text{state}_F(\text{init_st}_F, f_1 \cdots f_{n-1})$ is an accept state. Let $g_1 \cdots g_{m-1} = f_1 \cdots f_{n-1}$, such that every $g_i \in \Sigma_F$. Furthermore, from the definition of edge and f_j , it follows that, if for some $i = 1, \dots, m-1$, if $(v_{2i-1}, v_{2i}) \in \text{edge}(t_k)$ and $\text{arity}(t_k) = 2$, then $g_i = L(v_{2i-1}, v_{2i})$, else $g_i = \overline{L(v_{2i-1}, v_{2i})}$.

In order to show that $\text{state}_F(\text{init_st}_F, (v_1, v_2), \dots, (v_{m-1}, v_m))$ is an accept state, we need to show that for all $i, i = 1, 2, \dots, m-1$, if $v_{2i} = v_{2i+1}$, then $g_i = L(v_{2i-1}, v_{2i})$ and if $v_{2i-1} = v_{2i+1}$, then $g_i = \overline{L(v_{2i-1}, v_{2i})}$. We first show that if $v_{2i} = v_{2i+1}$, and $(v_{2i-1}, v_{2i}) \in \text{edge}(t_k)$ for some $k, k = 1, 2, \dots, n-1$, then $\text{arity}(t_k) = 2$. Suppose $\text{arity}(t_k) = 1$. Since $\text{last}(t_k)$ and $\text{first}(t_{(k+1) \bmod n})$ execute at the same site, $\text{slast}(t_k) = v_{2i-1}$, $\text{sfirst}(t_{(k+1) \bmod n}) = v_{2i+1}$, it follows that $v_{2i-1} = v_{2i+1}$, which leads to a contradiction. Thus, $\text{arity}(t_k) = 2$, and $g_i = L(v_{2i-1}, v_{2i})$. Also, it can be shown that if $v_{2i-1} = v_{2i+1}$, and $(v_{2i-1}, v_{2i}) \in \text{edge}(t_k)$, then $\text{arity}(t_k) = 1$. Suppose $\text{arity}(t_k) = 2$. If $v_{2i} = G_k$, then $v_{2i} = v_{2i+1} = G_k$, which leads to a contradiction. If $v_{2i-1} = G_k$, then since $\text{last}(t_k) = v_{2i-1}$ and $\text{first}(t_{(k+1) \bmod n}) = v_{2i+1}$ execute at the same site, $\text{slast}(t_k) = v_{2i}$, $\text{sfirst}(t_{(k+1) \bmod n}) = v_{2i+1}$, it follows that $v_{2i} = v_{2i+1}$, which leads to a contradiction. Thus, $\text{arity}(t_k) = 1$, and, $g_i = \overline{L(v_{2i-1}, v_{2i})}$.

Thus, by Lemma 3, $\text{state}_F(\text{init_st}_F, \text{edge}(t_1) \cdots \text{edge}(t_{n-1})(\text{sfirst}(t_0), G_0))$ is an accept state. Thus, by corollaries 4 and 6, during the execution of Detect_Ins_TSG? $((V, E, L), G_0, \text{slast}(t_0), \text{set}_1, \text{set}_2, R)$, $\text{sfirst}(t_0)$ is added to Δ , and thus $\text{sfirst}(t_0) \in \Delta_F$. However, this leads to a contradiction since we showed earlier that $\text{sfirst}(t_0) \notin \text{set}_2 \cup \Delta_F$. Thus, every schedule S is correct. \square

Proof of Theorem 3: Suppose S is not correct. Thus, there exists a regular term RT in R an instantiation I of RT in S . Let G_0 be the transaction in I such that $init_0$ is processed after $init_0$, every other transaction G_i in I is processed. By Lemma 1, since R is complete, there exists a regular term $RT_2 = e_0 : reg_exp$ and an instantiation $t_0 : t_1 t_2 \cdots t_{n-1}$ of RT_2 in S such that $hdr(t_0) =$ Thus,

- for all $j, j = 0, 1, \dots, n-1$,
 1. $t_j \in \Sigma_S$ (without loss of generality, let $hdr(t_j) = G_j$), and
 2. $last(t_j)$ and $first(t_{(j+1) \bmod n})$ execute at the same site, and $last(t_j)$ is serialized after $first(t_{(j+1) \bmod n})$ at the site, and
- $type(t_0) = e_0$ and $type(t_1) \cdots type(t_{n-1})$ is a string in $L(reg_exp)$.

When $init_0$ is processed, the procedure Detect_Ins_TSG? is invoked with arguments that include TSG (V, E, L) , G_0 , $slast(t_0)$, set_1 , set_2 and RT_2 since $type(G_0) = hdr(e_0)$ and $type(last(t_0)) = last(t_0)$. Also, $sfirst(t_0) \in set_1$ (if $arity(t_0) = 1$, then since $sfirst(t_0) = slast(t_0)$, $sfirst(t_0) \in set_1$). If $arity(t_0) > 1$, then since $sfirst(t_0) \neq slast(t_0)$, and $type(sfirst(t_0)) = first(e_0)$, $sfirst(t_0) \in set_2$. Furthermore, all the edges belonging to G_0, \dots, G_{n-1} are in the TSG when Detect_Ins_TSG? is invoked. In order to show this, we first show that G_j 's edges cannot be deleted from the TSG before $G_{(j+1) \bmod n}$'s edges are deleted from the TSG, for all $j, j = 1, 2, \dots, n-1$. Suppose, for some $j, j = 1, 2, \dots, n-1$, G_j 's edges are deleted from the TSG before $G_{(j+1) \bmod n}$'s edges are deleted from the TSG. Let $slast(t_j) = G_j$. Since G_{j_k} is serialized after $G_{((j+1) \bmod n)_k}$, at site s_k , $ser_k(G_{(j+1) \bmod n})$ executes before $ser_k(G_j)$. Thus, since $G_{(j+1) \bmod n}$'s edges are inserted into the TSG before $ser_k(G_{(j+1) \bmod n})$ executes, while G_j 's edges are deleted after $ser_k(G_j)$ executes, $G_{(j+1) \bmod n}$'s edges must be in the TSG when G_j 's edges are deleted (since we have assumed that G_j 's edges are deleted before $G_{(j+1) \bmod n}$'s edges are deleted). However, this leads to a contradiction, since edges belonging to G_j and $G_{(j+1) \bmod n}$ are deleted together when fin_l for some transaction G_l is processed (due to the sequence of edges between G_j and $G_{(j+1) \bmod n}$ in the TSG). Thus, G_j 's edges are not deleted from the TSG before $G_{(j+1) \bmod n}$'s edges are deleted. Thus, G_1 's edges are not deleted from the TSG before G_2 's edges are deleted, \dots , G_{n-1} 's edges are not deleted from the TSG before G_0 's edges are deleted. By transitivity and since G_0 's edges are deleted only after $init_0$ has been processed, when Detect_Ins_TSG? is invoked during the processing of $init_0$, the TSG (V, E, L) contains all the edges belonging to transactions G_0, G_1, \dots, G_{n-1} .

We now show that $(G_0, slast(t_0))edge(t_1) \cdots edge(t_{n-1})(sfirst(t_0), G_0)$ is a path in the TSG (V, E, L) . We begin by showing that any two consecutive edges in the path have a common node. Consecutive edges in the path could be one of the following:

- $(sfirst(G_j), G_j)(G_j, slast(G_j))$, $j = 1, 2, \dots, n-1$, where $arity(t_j) = 2$ (G_j is the common node).
- $(G_j, slast(t_j))(sfirst(t_{(j+1) \bmod n}), G_{(j+1) \bmod n})$, $j = 0, 1, \dots, n-1$, where $arity(t_j) = 2$ or $j = n-1$ and $arity(t_{(j+1) \bmod n}) = 1$ or 2 (since for all $j, j = 0, 1, \dots, n-1$, $last(t_j)$ and $first(t_{(j+1) \bmod n})$ execute at the same site, $slast(t_j) = sfirst(t_{(j+1) \bmod n})$ is the common node).
- $(sfirst(t_j), G_j)(sfirst(t_{(j+1) \bmod n}), G_{(j+1) \bmod n})$, $j = 1, 2, \dots, n-1$, where $arity(t_j) = 1$, and $arity(t_{(j+1) \bmod n}) = 1$ or 2 (since $arity(t_j) = 1$ implies that $sfirst(t_j) = slast(t_j)$, and $slast(t_j) = sfirst(t_{(j+1) \bmod n})$, it follows that $sfirst(t_j) = sfirst(t_{(j+1) \bmod n})$ is the common node).

Also, for the sequence of edges $(sfirst(t_i), G_i)(G_i, slast(t_i))$ in the path, $i = 1, 2, \dots, n-1$, it

or $St_j.v = prev_anc(v_{2m+1})$, or due to Step 1). Thus, $St_k.v = v_{2m+1}$, $St_k.cur_st = st_m$ and in St_k , $head(St_k.anc(St_k.v)) = (prev_anc(v_{2m+1}), v_j)$. Furthermore, it follows from Lemma 8 that after a finite number of steps, Detect_Ins_TSG2 is in a state St'_k such that $St'_k \equiv St_k$ and no further forward transitions can be made from St'_k . Thus, in state St'_k ,

- Since $prev_anc(v_{2m+1}) \neq v_{2m+2}$ and $v_j \neq v_{2m+2}$, $head(St'_k.anc(St'_k.v))[1] \neq v_{2m+2}$, $head(St'_k.anc(St'_k.v))[2] \neq v_{2m+2}$,
- Since $state_F(init_st_F, (v_3, v_4) \cdots (v_{2m+1}, v_{2m+2})(v_{2m+3}, v_{2m+4}))$ is defined, if $v_{2m+2} = v_{2m+3}$ then $st_{m+1} = st_F(St'_k.cur_st, L(St'_k.v, v_{2m+2}))$ is defined, else if $v_{2m+1} = v_{2m+3}$, then $st_{m+1} = st_F(St'_k.cur_st, L(St'_k.v, v_{2m+2}))$ is defined.
- Since $St'_k.\Delta \subseteq \Delta_F$, and $(v_3, v_4) \cdots (v_{2m+1}, v_{2m+2})$ is consistent with $set_2 \cup \Delta_F$, $(v_3, v_4) \cdots (v_{2m+1}, v_{2m+2})$ is consistent with $set_2 \cup St'_k.\Delta$; thus, if $St'_k.v \in (set_2 \cup St'_k.\Delta)$, then $v_{2m+2} \neq v_{2m+3}$.

However, since in state St'_k , no forward transition can be made due to edge $(St'_k.v, v_{2m+2})$, it must be the case that

- if $v_{2m+2} = v_{2m+3}$, then either
 1. $St'_k.V_set(v_{2m+2})$ already contains $(st_{m+1}, (St'_k.v, St'_k.v))$. Thus, since $St'_k.v = v_{2m+1}$, $v_{2m+1} \neq v_{2m+4}$, $prev_anc(v_{2m+3}) = v_{2m+1}$, $(st_{m+1}, (prev_anc(v_{2m+3}), v'_j))$ is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_TSG2, $v'_j \neq v_{2m+4}$.
 2. $St'_k.V_set(v_{2m+2})$ already contains $(st_{m+1}, (St'_k.v, u_2))$ and $(st_{m+1}, (St'_k.v, u_3))$, $u_2 \neq u_3$. Thus, since $St'_k.v = v_{2m+1}$, either $u_2 \neq v_{2m+4}$ or $u_3 \neq v_{2m+4}$ (since $u_2 \neq u_3$), $prev_anc(v_{2m+3}) = v_{2m+1}$, $(st_{m+1}, (prev_anc(v_{2m+3}), v'_j))$ is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_TSG2, $v'_j \neq v_{2m+4}$.
- if $v_{2m+1} = v_{2m+3}$, then either
 1. $St'_k.V_set(St'_k.v)$ already contains $(st_{m+1}, (prev_anc(v_{2m+1}), v_{2m+2}))$. Thus, since $St'_k.v = v_{2m+1}$, $v_{2m+1} \neq v_{2m+4}$, $prev_anc(v_{2m+3}) = prev_anc(v_{2m+1})$, $(st_{m+1}, (prev_anc(v_{2m+3}), v'_j))$ is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_TSG2, $v'_j \neq v_{2m+4}$.
 2. $St'_k.V_set(St'_k.v)$ already contains $(st_{m+1}, (prev_anc(v_{2m+1}), u_2))$ and $(st_{m+1}, (prev_anc(v_{2m+1}), u_3))$, $u_2 \neq u_3$. Thus, since $St'_k.v = v_{2m+1}$, either $u_2 \neq v_{2m+4}$ or $u_3 \neq v_{2m+4}$ (since $u_2 \neq u_3$), $prev_anc(v_{2m+3}) = prev_anc(v_{2m+1})$, $(st_{m+1}, (prev_anc(v_{2m+3}), v'_j))$ is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_TSG2, $v'_j \neq v_{2m+4}$. \square

Corollary 6: Let $\text{Detect_Ins_TSG2}((V, E, L), v_1, v_2, set_1, set_2, RT)$ return the set of sites Δ_F . If the TSG (V, E, L) contains a path $(v_1, v_2)(v_3, v_4) \cdots (v_{2n-1}, v_{2n})(v_{2n+1}, v_1)$, $v_2 = v_3$, consistent with $set_2 \cup \Delta_F$, such that for the regular term RT , $F = FA(RT)$, $st = state_F(init_st_F, (v_3, v_4) \cdots (v_{2n-1}, v_{2n})(v_{2n+1}, v_1))$ is an accept state and $v_{2n+1} \in set_1$, then during the execution of Detect_Ins_TSG2, v_{2n+1} is added to Δ .

Proof: By Lemma 9, $(st, (prev_anc(v_{2n+1}), v_j))$ is added to $V_set(v_{2n+1})$, where $v_j \neq v_1$. Since $prev_anc(v_{2n+1}) \neq v_1$ and $v_j \neq v_1$, Detect_Ins_TSG2 makes a forward state transition when $(st, (prev_anc(v_{2n+1}), v_j))$ is added to $V_set(v_{2n+1})$. However, just before $(st, (prev_anc(v_{2n+1}), v_j))$ is added to $V_set(v_{2n+1})$, since st is an accept state, $prev_anc(v_{2n+1}) \neq v_1$, $v_j \neq v_1$ and $v_{2n+1} \in set_1$, v_{2n+1} is added to Δ . \square

Corollary 5: Procedure Detect_Ins-TSG2 terminates in $O(n_G^2 mn_S)$ steps.

Proof: Detect_Ins-TSG2 can be shown to terminate as a result of Lemma 8 using a similar argument as in Corollary 3.

The number of steps Detect_Ins-TSG2 terminates in is equal to the product of the number of times Detect_Ins-TSG2 checks if an edge satisfies the conditions in Step 2 and the number of steps required to check if an edge satisfies the conditions in Step 2. Every time a transaction node is visited, the conditions in Step 2 need to be checked, on an average, for v_S edges (the average number of sites a global transaction executes at is v_S), while every time a site node is visited, the conditions in Step 2 need to be checked for at most n_G edges (since the number of transaction nodes in the TSG is at most n_G). Furthermore, every transaction node can be visited at most $2v_S n_S$ times, while every site node can be visited at most $2n_G n_S$ times (every node v in the TSG can be visited in a state st of F at most twice every node w such that edge (v, w) is in the TSG, and F has at most n_S states). Since there are m edges and at most n_G transaction nodes in the TSG, the number of times Detect_Ins-TSG2 checks if an edge satisfies the conditions in Step 2 is $2n_G^2 mn_S + 2n_G v_S^2 n_S$. Since each of the conditions in Step 2 can be checked in constant time and $v_S \ll n_G, v_S < m$, Detect_Ins-TSG2 terminates in $O(n_G^2 mn_S)$ steps.

In order to show that Detect_Ins-TSG2 traverses edges in the TSG in a manner that ensures it detects instantiations of regular terms, we define the following.

Definition 13: Consider a TSG/TSGD containing a path $(v_1, v_2)(v_3, v_4) \cdots (v_{2n-1}, v_{2n})$, $v_2 = v_3$. For all $i = 1, 2, \dots, n-1$, $prev_anc(v_{2i+1})$ is defined as follows.

$$prev_anc(v_{2i+1}) = \begin{cases} prev_anc(v_{2i-1}) & \text{if } v_{2i-1} = v_{2i+1} \\ v_{2i-1} & \text{if } v_{2i} = v_{2i+1} \quad \square \end{cases}$$

Note that, by the definition of path, it follows that for all $i, i = 1, 2, \dots, n-1$, $v_{2i+2} \neq prev_anc(v_{2i+1})$ and dependency $(prev_anc(v_{2i+1}), v_{2i+1}) \rightarrow (v_{2i+1}, v_{2i+2})$ does not belong to the TSGD.

Lemma 9: Let $Detect_Ins_TSG2(TSG, v_1, v_2, set_1, set_2, RT)$ return the set of nodes Δ_F . If the TSG (V, E, L) contains a path $(v_1, v_2), (v_3, v_4), \dots, (v_{2n-3}, v_{2n-2}), (v_{2n-1}, v_{2n})$, $v_2 = v_3$, consistent with respect to $set_2 \cup \Delta_F$, such that for the regular term RT , $F = FA(RT)$, $state_F(init_st_F, (v_3, v_4), \dots, (v_{2n-1}, v_{2n}))$ is defined, then during the execution of Detect_Ins-TSG2, for all $i, i = 1, 2, 3, \dots, n$, there exists a node v_j , $v_j \neq v_{2i+2}$, $(st, (prev_anc(v_{2i+1}), v_j))$ is added to $V_set(v_{2i+1})$, where $st = state_F(init_st_F, (v_3, v_4) \cdots (v_{2i-1}, v_{2i})(v_{2i+1}, v_{2i+2}))$.

Proof: We prove the above lemma by induction on i . We prove that for all $i, i = 1, 2, \dots, n$, there exists a $v_j \neq v_{2i+2}$, such that $(st, (prev_anc(v_{2i+1}), v_j))$ is added to $V_set(v_{2i+1})$, where $st = state_F(init_st_F, (v_3, v_4) \cdots (v_{2i-1}, v_{2i})(v_{2i+1}, v_{2i+2}))$.

Basis ($i = 1$): In Step 1 of Detect_Ins-TSG2, $(init_st_F, (v_1, v_1))$ is added to $V_set(v_2)$. Since $v_2 = v_3$, $prev_anc(v_3) = v_1$, $v_1 \neq v_4$, and $state_F(init_st_F, (v_3, v_4)) = init_st_F$, the lemma is true for $i = 1$. (($init_st_F, (prev_anc(v_3), v_j)$) is added to $V_set(v_3)$, $v_j \neq v_4$).

Induction: Let us assume that the lemma is true for $i = m$, $1 \leq m < n-1$. Thus, $(st_m, (prev_anc(v_{2m+1}), v_j))$ is added to $V_set(v_{2m+1})$, where $v_j \neq v_{2m+2}$, $st_m = state_F(init_st_F, (v_3, v_4) \cdots (v_{2m-1}, v_{2m})(v_{2m+1}, v_{2m+2}))$. We show the lemma to be true for $i = m+1$. Thus, we need to show that $(st_{m+1}, (prev_anc(v_{2m+3}), v'_j))$ is added to $V_set(v_{2m+3})$, where $v'_j \neq v_{2m+4}$, $st_{m+1} = state_F(init_st_F, (v_3, v_4) \cdots (v_{2m+1}, v_{2m+2})(v_{2m+3}, v_{2m+4}))$. By the definition of $state_F$, $st_{m+1} = st_F(st_m, L(v_{2m+1}, v_{2m+2}))$, if $v_{2m+2} = v_{2m+3}$ and $st_{m+1} = st_F(st_m, L(v_{2m+1}, v_{2m+2}))$, if $v_{2m+1} = v_{2m+3}$.

Let St_m be the resulting state of Detect_Ins-TSG2 after $(st_m, (prev_anc(v_{2m+1}), v_j))$ is added.

Corollary 4: Let $\text{Detect_Ins_TSG1}((V, E, L), v_1, v_2, \text{set}_1, \text{set}_2, RT)$. return the set of site no Δ_F . If the TSG (V, E, L) contains a path $(v_1, v_2)(v_3, v_4) \cdots (v_{2n-1}, v_{2n})(v_{2n+1}, v_1)$, $v_2 = v_3$, consist with $\text{set}_2 \cup \Delta_F$, such that for the regular term RT , $F = FA(RT)$, $st = \text{state}_F(\text{init_st}_F, (v_3, v_4) \cdots (v_{2n-1}, v_{2n})(v_{2n+1}, v_1))$ is an accept state and $v_{2n+1} \in \text{set}_1$, then during the execution of Detect_Ins_TSG1 , v_{2n+1} is added to Δ .

Proof: By Lemma 7, (st, v_j) is added to $V_set(v_{2n+1})$, where $v_j \neq \text{foll}(v_{2n+1})$. Since $\text{foll}(v_{2n+1}) = v_1$, $v_j \neq v_1$ and Detect_Ins_TSG1 makes a forward state transition when (st, v_j) is added to $V_set(v_{2n+1})$. However, just before (st, v_j) is added to $V_set(v_{2n+1})$, since st is an accept state, $v_j \neq v_1$ and $v_{2n+1} \in \text{set}_1$, v_{2n+1} is added to Δ . \square

We now show that Detect_Ins_TSG2 terminates in $O(n_G^2 m v_S)$ steps, for which we need to prove the following lemma.

Lemma 8: If during its execution, Detect_Ins_TSG2 is in state St_k , then after a finite number of steps, it enters a state $St'_k \equiv St_k$ such that no forward transitions from St'_k are possible.

Proof: We prove the lemma by induction on num , the number of elements in $\{(st, v_1, v_2, v_3) \mid (st \text{ is a state of } F) \wedge (v_1, v_2, v_3 \in V) \wedge ((st, (v_1, v_2)) \notin V_set(v_3))\}$ in state St_k .

Basis ($num = 0$): If $num = 0$ in state St_k , then, in state St_k , for every edge $(St_k.v, u)$, if $st_F(St_k.cur_st, L(St_k.v, u))$ is defined, then $(st, (St_k.v, St_k.v)) \in St_k.V_set(u)$ (alternatively, if $st_F(St_k.cur_st, L(St_k.v, u))$ is defined, then $(st', (\text{head}(St_k.anc(St_k.v))[1], u)) \in St_k.V_set(St_k.v)$). no forward transition can be made from state St_k (since every edge $(St_k.v, u)$ satisfies the third condition in Step 2).

Induction: Let us assume the lemma is true for $num \leq m$, $m \geq 0$. We show that the lemma is true if $num \leq m + 1$ in state St_k . We show that after a finite number of moves, Detect_Ins_TSG2 enters a state St'_k such that $St'_k \equiv St_k$ and no forward transitions can be made from state St'_k .

Let St''_k be any state equivalent to St_k such that in St''_k , $num \leq m + 1$. If Detect_Ins_TSG2 makes the forward transition $St''_k \rightarrow St_l$ due to some edge $(St''_k.v, u)$ and $L(St''_k.v, u)$, then it must be the case that $St_l.v = u$, $St_l.cur_st = st_F(St''_k.cur_st, L(St''_k.v, u))$. Furthermore, in state St_l , $(St_l.cur_st, (St''_k.v, St''_k.v)) \notin St''_k.V_set(u)$ and in state St_l , $(St_l.cur_st, (St''_k.v, St''_k.v)) \in St_l.V_set(u)$ (since the transition $St''_k \rightarrow St_l$ causes $(St_l.cur_st, (St''_k.v, St''_k.v))$ to be added to $V_set(u)$). Note that since before the transition is made, $(St_l.cur_st, (St''_k.v, St''_k.v))$ does not belong to $V_set(u)$ and $num \leq m + 1$ in St''_k , after the transition $St''_k \rightarrow St_l$ is made, $num \leq m$ in St_l . By IH, after a finite number of steps, Detect_Ins_TSG2 enters a state $St'_l \equiv St_l$, such that no forward transitions are possible from St'_l . Thus, Detect_Ins_TSG2 makes the reverse transition $St'_l \rightarrow St''_k$ after a finite number of steps where $St''_k \equiv St''_k \equiv St_k$. Furthermore, in state St''_k , $(St_l.cur_st, (St''_k.v, St''_k.v)) \in St''_k.V_set(u)$ and $St''_k.v = St''_k.v$, and thus, no forward transition can be made from state St''_k due to edge $(St''_k.v, u)$ and $L(St''_k.v, u)$ (edge $(St''_k.v, u)$ does not satisfy the condition in Step 3(b)). Using a similar argument can be shown that if Detect_Ins_TSG2 makes a forward transition $St''_k \rightarrow St_l$ due to edge $(St''_k.v, u)$ and $L(St''_k.v, u)$, then in a finite number of steps, Detect_Ins_TSG2 enters a state $St'''_k \equiv St''_k$ such that no forward transitions are possible from St'''_k due to edge $(St'''_k.v, u)$ and $L(St'''_k.v, u)$.

Thus, once a forward transition is made by Detect_Ins_TSG2 due to an edge e and $L(e)/\overline{L(e)}$ from a state equivalent to St_k , then no further forward transitions can be made by Detect_Ins_TSG2 due to e and $L(e)/\overline{L(e)}$ from any state equivalent to St_k . Furthermore, everytime a forward transition is made from a state St''_k that is equivalent to St_k such that $num \leq m + 1$ in St''_k , a reverse transition is made by Detect_Ins_TSG2 to a state St'''_k equivalent to St_k such that $num \leq m + 1$ in St'''_k . Since there are a finite number of edges incident on each node and in state St_k , $num \leq m + 1$, eventually Detect_Ins_TSG2 would be in a state $St'_k \equiv St_k$ such that no further forward transitions can be made

1, there exists a node v_j , $v_j \neq foll(v_{2i+1})$, such that (st, v_j) is added to $V_set(v_{2i+1})$, where $st = state_F(omit_st_F, (v_3, v_4) \cdots (v_{2i-1}, v_{2i})(v_{2i+1}, v_{2i+2}))$.

Proof: We prove the above lemma by induction on i . We prove that for all i , $i = 1, 2, \dots, n$, there exists a $v_j \neq foll(v_{2i+1})$, such that (st, v_j) is added to $V_set(v_{2i+1})$, where $st = state_F(omit_st_F, (v_3, v_4) \cdots (v_{2i-1}, v_{2i})(v_{2i+1}, v_{2i+2}))$.

Basis ($i = 1$): In Step 1 of Detect_Ins_TSG1, $(omit_st_F, v_1)$ is added to $V_set(v_2)$. Since $v_2 = v_1 \neq foll(v_3)$, and $state_F(omit_st_F, (v_3, v_4)) = omit_st_F$, the lemma is true for $i = 1$ ($(omit_st_F, v_1)$ added to $V_set(v_3)$, $v_j \neq foll(v_3)$).

Induction: Let us assume that the lemma is true for $i = m$, $1 \leq m < n - 1$. Thus, (st_m, v_j) is added to $V_set(v_{2m+1})$, where $v_j \neq foll(v_{2m+1})$, $st_m = state_F(omit_st_F, (v_3, v_4) \cdots (v_{2m+1}, v_{2m+2}))$. We show the lemma to be true for $i = m + 1$. Thus, we need to show that (st_{m+1}, v'_j) is added to $V_set(v_{2m+3})$ where $v'_j \neq foll(v_{2m+3})$, $st_{m+1} = state_F(omit_st_F, (v_3, v_4) \cdots (v_{2m+3}, v_{2m+4}))$. By the definition of $state_F$, $st_{m+1} = st_F(st_m, L(v_{2m+1}, v_{2m+2}))$, if $v_{2m+2} = v_{2m+3}$ and $st_{m+1} = st_F(st_m, \overline{L(v_{2m+1}, v_{2m+2})})$ if $v_{2m+1} = v_{2m+3}$.

Let St_k be the resulting state of Detect_Ins_TSG1 after (st_m, v_j) is added to $V_set(v_{2m+1})$. The resulting state St_k results either due to the forward transition $St_j \rightarrow St_k$, either $St_j.v = v_{2m+1}$ or $St_j.v = v_j$ (due to Step 1). Thus, $St_k.v = v_{2m+1}$, $St_k.cur_st = st_m$ and in state St_k , $head(St_k.anc(St_k.v)) = st_m$. Furthermore, it follows from Lemma 6 that after a finite number of steps, Detect_Ins_TSG1 is in a state St'_k such that $St'_k \equiv St_k$ and no further forward transitions can be made from St'_k . Thus, in state St'_k ,

- Since $state_F(omit_st_F, (v_3, v_4) \cdots (v_{2m+1}, v_{2m+2})(v_{2m+3}, v_{2m+4}))$ is defined, if $v_{2m+2} = v_{2m+3}$, then $st_{m+1} = st_F(\overline{St'_k.cur_st}, L(St'_k.v, v_{2m+2}))$ is defined, else if $v_{2m+1} = v_{2m+3}$, then $st_{m+1} = st_F(St'_k.cur_st, L(St'_k.v, v_{2m+2}))$ is defined.
- Since $St'_k.\Delta \subseteq \Delta_F$, and $(v_3, v_4) \cdots (v_{2m+1}, v_{2m+2})$ is consistent with $set_2 \cup \Delta_F$, $(v_3, v_4) \cdots (v_{2m+1}, v_{2m+2})$ is consistent with $set_2 \cup St'_k.\Delta$; thus, if $St'_k.v \in (set_2 \cup St'_k.\Delta)$, then $v_{2m+2} \neq foll(v_{2m+1})$.

However, since in state St'_k , no forward transition can be made due to edge $(St'_k.v, v_{2m+2})$, it must be the case that

- if $v_{2m+2} = v_{2m+3}$, then $foll(v_{2m+1}) = v_{2m+2}$ and since $v_j \neq foll(v_{2m+1})$ (by the definition of $foll$), $head(St'_k.anc(St'_k.v)) \neq v_{2m+2}$, and thus, either
 1. $St'_k.V_set(v_{2m+2})$ already contains $(st_{m+1}, St'_k.v)$. Thus, since $St'_k.v = v_{2m+1}$, $v_{2m+2} = v_{2m+3}$, (st_{m+1}, v'_j) is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_TSG1, $v'_j \neq foll(v_{2m+3})$.
 2. $St'_k.V_set(v_{2m+2})$ already contains (st_{m+1}, u_2) and (st_{m+1}, u_3) , $u_2 \neq u_3$. Thus, since either $u_2 \neq foll(v_{2m+3})$ or $u_3 \neq foll(v_{2m+3})$ (since $u_2 \neq u_3$), (st_{m+1}, v'_j) is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_TSG1, $v'_j \neq foll(v_{2m+3})$.
- if $v_{2m+1} = v_{2m+3}$, then either
 1. $St'_k.V_set(St'_k.v)$ already contains (st_{m+1}, v_j) . Thus, since $St'_k.v = v_{2m+1}$, $foll(v_{2m+1}) = v_{2m+2}$, $v_j \neq foll(v_{2m+1})$, (st_{m+1}, v'_j) is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_TSG1, $v'_j \neq foll(v_{2m+3})$.
 2. $St'_k.V_set(St'_k.v)$ already contains (st_{m+1}, u_2) and (st_{m+1}, u_3) , $u_2 \neq u_3$. Thus, since either $u_2 \neq foll(v_{2m+3})$ or $u_3 \neq foll(v_{2m+3})$ (since $u_2 \neq u_3$), (st_{m+1}, v'_j) is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_TSG1, $v'_j \neq foll(v_{2m+3})$. \square

Appendix -C- : TSG Schemes

In this appendix, we prove Theorem 3. We begin by showing that Detect_Ins_TSG1 and Detect_Ins_TSG2 detect instantiations of regular terms in S . States St_k between the execution of any steps of Detect_Ins_TSG1 and Detect_Ins_TSG2 are as defined earlier for Detect_Ins_Opt.

Lemma 6: If during its execution, Detect_Ins_TSG1 is in state St_k , then after a finite number of steps, it enters a state $St'_k \equiv St_k$ such that no forward transitions from St'_k are possible.

Proof: Similar to proof of Lemma 2. \square

Corollary 3: Procedure Detect_Ins_TSG1 terminates in $O(n_G m n_S)$ steps.

Proof: We first show that Detect_Ins_TSG1 terminates in a finite number of steps. Let St_1 denote the state immediately after the execution of Step 1 of algorithm Detect_Ins_TSG1. By Lemma 6, after a finite number of steps, Detect_Ins_TSG1 is in a state $St'_1 \equiv St_1$ such that no further forward transitions can be made from St'_1 . Detect_Ins_TSG1, thus executes Step 4 and since, in state St'_1 , $head(St'_1.F_List(St'_1.v)) = (s*, G_i)$, Detect_Ins_TSG1 terminates in a finite number of steps.

The number of steps Detect_Ins_TSG1 terminates in is equal to the product of the number of times Detect_Ins_TSG1 checks if an edge satisfies the conditions in Step 2 and the number of steps required to check if an edge satisfies the conditions in Step 2. Every time a transaction node is visited, the conditions in Step 2 need to be checked, on an average, for v_S edges (the average number of sites a global transaction executes at is v_S), while every time a site node is visited, the conditions in Step 2 need to be checked for at most n_G edges (since the number of transaction nodes in the TSG is at most n_G). Furthermore, every transaction and site node can be visited at most $2n_S$ times (every node in the TSG can be visited in a state st of F at most twice, and F has at most n_S states). Since there are at most n_S site nodes and at most n_G transaction nodes in the TSG, the number of times Detect_Ins_TSG1 checks if an edge satisfies the conditions in Step 2 is $2n_G m n_S + 2n_G v_S n_S$. Since each of the conditions in Step 2 can be checked in constant time and $v_S < m$, Detect_Ins_TSG1 terminates in $O(n_G m n_S)$ steps.

In order to show that Detect_Ins_TSG1 traverses edges in the TSG in a manner that ensures it detects instantiations of regular terms, we define the following.

Definition 11: Consider a TSG containing a path $(v_1, v_2)(v_3, v_4) \cdots (v_{2n-1}, v_{2n})$. For all $i = 1, 2, \dots, n-1$, we define $foll(v_{2i-1})$ as follows.

$$foll(v_{2i-1}) = \begin{cases} foll(v_{2i+1}) & \text{if } i < n \text{ and } v_{2i-1} = v_{2i+1} \\ v_{2i} & \text{if } i = n \text{ or } v_{2i} = v_{2i+1} \quad \square \end{cases}$$

Note that, by the definition of path, for all $i = 1, 2, \dots, n-1$, if $v_{2i} = v_{2i+1}$, then $v_{2i-1} \neq foll(v_{2i-1})$.

Definition 12: Consider a TSG containing a path $(v_1, v_2) \cdots (v_{2n-1}, v_{2n})$. The path is said to be *consistent* with a set of nodes set if for all $i, i = 1, \dots, n$, if $v_{2i-1} \in set$, then $v_{2i} \neq v_1$. \square

Lemma 7: Let $\text{Detect_Ins_TSG1}((V, E, L), v_1, v_2, set_1, set_2, RT)$ return the set of site nodes set . If the TSG (V, E, L) contains a path $(v_1, v_2), (v_3, v_4), \dots, (v_{2n-3}, v_{2n-2}), (v_{2n-1}, v_{2n}), v_2 = v_3$, consistent with $set_2 \cup \Delta_F$ such that for the regular term $RT, F = FA(RT), state_F(init_st_F, (v_3, v_4), \dots, (v_{2n-1}, v_{2n}))$ is defined, then during the execution of Detect_Ins_TSG1, for all $i, i = 1, 2, 3, \dots,$

- $(sfirst(G_j), G_j)(G_j, slast(G_j))$, $j = 1, 2, \dots, n-1$, where $arity(t_j) = 2$ (G_j is the common node).
- $(G_j, slast(t_j))(sfirst(t_{(j+1) \bmod n}), G_{(j+1) \bmod n})$, $j = 0, 1, \dots, n-1$, where $arity(t_j) = 2$ or $j = 0$ and $arity(t_{(j+1) \bmod n}) = 1$ or 2 (since for all j , $j = 0, 1, \dots, n-1$, $last(t_j)$ and $first(t_{(j+1) \bmod n})$ execute at the same site, $slast(t_j) = sfirst(t_{(j+1) \bmod n})$ is the common node).
- $(sfirst(t_j), G_j)(sfirst(t_{(j+1) \bmod n}), G_{(j+1) \bmod n})$, $j = 1, 2, \dots, n-1$, where $arity(t_j) = 1$, $arity(t_{(j+1) \bmod n}) = 1$ or 2 (since $arity(t_j) = 1$ implies that $sfirst(t_j) = slast(t_j)$, and $slast(t_j) = sfirst(t_{(j+1) \bmod n})$, it follows that $sfirst(t_j) = sfirst(t_{(j+1) \bmod n})$ is the common node).

Also, for the sequence of edges $(sfirst(t_j), G_j)(G_j, slast(t_j))$ in the path, $j = 1, 2, \dots, n-1$, it may be the case that $arity(t_j) = 2$, and thus $sfirst(t_j) \neq slast(t_j)$. Also, if for some j, k , $j = 0, 1, \dots, n-1$, $j < k \leq n$, the sequence of edges $(G_j, slast(t_j))(sfirst(t_{(j+1) \bmod n}), G_{(j+1) \bmod n}), \dots, (sfirst(t_{k \bmod n}), G_{k \bmod n})$ is in the path, then it must be the case that for all $j < l < k$, $arity(t_l) = 2$. Thus, by Property 1, it follows that $slast(t_j) = sfirst(t_{(j+1) \bmod n}) = \dots = sfirst(t_{k \bmod n})$, and for all r, s , $j \leq r < s \leq k$,

- $G_r \neq G_{s \bmod n}$, and
- G_r is serialized after $G_{s \bmod n}$ at site $sfirst(G_{s \bmod n})$. Thus, by Lemma 5, dependency $(G_r, sfirst(G_{s \bmod n})) \rightarrow (sfirst(G_{s \bmod n}), G_{s \bmod n})$ does not belong to D' .

Thus, $(G_0, slast(t_0))edge(t_1) \cdots edge(t_{n-1})(sfirst(t_0), G_0)$ is a path in the TSGD (V', E', D', L') .

We further use Lemma 3 to show that, for $F = FA(RT_2)$, $state_F(init_st_F, edge(t_1) \cdots edge(t_{n-1})(sfirst(t_0), G_0))$ is an accept state. Let $edge(t_1) \cdots edge(t_{n-1})(sfirst(t_0), G_0) = (v_1, v_2) \cdots (v_{2m-1}, v_{2m})$. In order to use Lemma 3, we need to show that there exists a sequence $g_1 \cdots g_{m-1}$ such that

- if $v_{2i} = v_{2i+1}$, then $g_i = L(v_{2i-1}, v_{2i})$, and
- if $v_{2i-1} = v_{2i+1}$, then $g_i = \overline{L(v_{2i-1}, v_{2i})}$, and

$state_F(init_st_F, g_1 \cdots g_{m-1})$ is an accept state. We construct the sequence $g_1 \cdots g_{m-1}$ with the above properties as follows. For all $i = 1, \dots, m-1$, let $f_i = \overline{(type(hdr(t_i)), type(first(t_i)))}$, if $arity(t_i) = 2$; else, $f_i = (type(hdr(t_i)), type(first(t_i)))(type(hdr(t_i)), type(last(t_i)))$. Since $type(t_1) \cdots type(t_{n-1})$ is a string in $L(reg_exp)$, by the construction of $FA(RT_2)$, it follows that $state_F(init_st_F, f_1 \cdots f_{m-1})$ is an accept state. Let $g_1 \cdots g_{m-1} = f_1 \cdots f_{m-1}$, such that every $g_i \in \Sigma_F$. Furthermore, from the definition of $edge$ and f_j , it follows that, if for some $i = 1, \dots, m-1$, if $(v_{2i-1}, v_{2i}) \in edge(t_k)$ and $arity(t_k) = 2$, then $g_i = L(v_{2i-1}, v_{2i})$; else $g_i = \overline{L(v_{2i-1}, v_{2i})}$.

In order to show that $state_F(init_st_F, (v_1, v_2), \dots, (v_{m-1}, v_m))$ is an accept state, we need to show that for all i , $i = 1, 2, \dots, m-1$, if $v_{2i} = v_{2i+1}$, then $g_i = L(v_{2i-1}, v_{2i})$ and if $v_{2i-1} = v_{2i+1}$, then $g_i = \overline{L(v_{2i-1}, v_{2i})}$. We first show that if $v_{2i} = v_{2i+1}$, and $(v_{2i-1}, v_{2i}) \in edge(t_k)$ for some k , $k = 1, 2, \dots, n-1$, then $arity(t_k) = 2$. Suppose $arity(t_k) = 1$. Since $last(t_k)$ and $first(t_{(k+1) \bmod n})$ execute at the same site, $slast(t_k) = v_{2i-1}$, $sfirst(t_{(k+1) \bmod n}) = v_{2i+1}$, it follows that $v_{2i-1} = v_{2i+1}$, which leads to a contradiction. Thus, $arity(t_k) = 2$, and $g_i = L(v_{2i-1}, v_{2i})$. Also, it can be shown that if $v_{2i-1} = v_{2i+1}$, and $(v_{2i-1}, v_{2i}) \in edge(t_k)$, then $arity(t_k) = 1$. Suppose $arity(t_k) = 2$. If $v_{2i} = G_k$, then $v_{2i} = v_{2i+1} = G_k$, which leads to a contradiction. If $v_{2i-1} = G_k$, then since $last(t_k)$ and $first(t_{(k+1) \bmod n})$ execute at the same site, $slast(t_k) = v_{2i}$, $sfirst(t_{(k+1) \bmod n}) = v_{2i+1}$, it follows that $v_{2i} = v_{2i+1}$, which leads to a contradiction. Thus, $arity(t_k) = 1$, and, $g_i = \overline{L(v_{2i-1}, v_{2i})}$.

Thus, by Lemma 3, $state_F(init_st_F, edge(t_1) \cdots edge(t_{n-1})(sfirst(t_0), G_0))$ is an accept state. Thus, by Corollary 2, $Detect_Ins_Opt((V', E', D', L'), G_0, slast(t_0), set_1, RT_2)$ returns abort and G_0 is aborted by the optimistic scheme. However, this leads to a contradiction since G_0 is a transaction in I .

dependency is added during the execution of $act(ser_k(G_i))$, then $act(ser_k(G_j))$ must have already executed. On the other hand, if the dependency were added to the TSGD before $act(ser_k(G_i))$ executed, then $act(ser_k(G_i))$ would not execute until $act(ack(ser_k(G_j)))$ completes execution (the dependency $(G_j, s_k) \rightarrow (s_k, G_i)$ is deleted from the TSGD only after $ack(ser_k(G_j))$ is processed). Thus, in both cases $act(ser_k(G_j))$ executes before $ser_k(G_i)$, and thus, G_{jk} is serialized before G_{ik} at site s_k , which leads to a contradiction. \square

For an element $t_i \in \Sigma_S$, we denote by $slast(t_i)$ and $sfirst(t_i)$, the sites at which $last(t_i)$ and $first(t_i)$ execute, respectively. Also, if $arity(t_i) = 1$, then $edge(t_i) = (sfirst(t_i), hdr(t_i))$, and if $arity(t_i) = 2$, then $edge(t_i) = (sfirst(t_i), hdr(t_i))(hdr(t_i), slast(t_i))$.

Proof of Theorem 1: Suppose S is not correct. Thus, there exists a regular term RT in R and an instantiation I of RT in S . Let G_0 be the transaction in I such that val_0 is processed after val_i for every other transaction G_i in I is processed. By Lemma 1, since R is complete, there exists a regular term $RT_2 = e_0 : reg_exp$ and an instantiation $t_0 : t_1 t_2 \cdots t_{n-1}$ of RT_2 in S such that $hdr(t_0) = val_0$. Thus,

- for all j , $j = 0, 1, \dots, n-1$,
 1. $t_j \in \Sigma_S$ (without loss of generality, let $hdr(t_j) = G_j$), and
 2. $last(t_j)$ and $first(t_{(j+1) \bmod n})$ execute at the same site, and $last(t_j)$ is serialized after $first(t_{(j+1) \bmod n})$ at the site, and
- $type(t_0) = e_0$ and $type(t_1) \cdots type(t_{n-1})$ is a string in $L(reg_exp)$.

When val_0 is processed, Detect_Ins_Opt is invoked with arguments that include the TSGD (V', E', D', L') , G_0 , $slast(t_0)$, set_1 , and RT_2 since $type(G_0) = hdr(e_0)$ and $type(last(t_0)) = last(e_0)$. Also, $sfirst(t_0) \in set_1$ (if $arity(t_0) = 1$, then since $sfirst(t_0) = slast(t_0)$, $sfirst(t_0) \in set_1$; if $arity(t_0) = 2$, then since $sfirst(t_0) \neq slast(t_0)$, and $type(first(t_0)) = first(e_0)$, $sfirst(t_0) \in set_1$). Furthermore, the edges belonging to G_0, \dots, G_{n-1} are in the TSGD when Detect_Ins_Opt is invoked. In order to show this, we first show that G_j 's edges cannot be deleted from the TSGD before $G_{(j+1) \bmod n}$'s edges are deleted from the TSGD, for all j , $j = 1, 2, \dots, n-1$. Suppose, for some j , $j = 1, 2, \dots, n-1$, that G_j 's edges are deleted from the TSGD before $G_{(j+1) \bmod n}$'s edges are deleted from the TSGD. Since $last(t_j) = s_k$. Since G_{jk} is serialized after $G_{((j+1) \bmod n)k}$, at site s_k , $ser_k(G_{(j+1) \bmod n})$ executes before $ser_k(G_j)$. Thus, since $G_{(j+1) \bmod n}$'s edges are inserted into the TSGD before $ser_k(G_{(j+1) \bmod n})$ executes, while G_j 's edges are deleted after $ser_k(G_j)$ executes, $G_{(j+1) \bmod n}$'s edges must be in the TSGD when G_j 's edges are deleted (since we have assumed that G_j 's edges are deleted before $G_{(j+1) \bmod n}$'s edges are deleted). Furthermore, since $ser_k(G_j)$ and $ser_k(G_{(j+1) \bmod n})$ must have both executed when G_j 's edges are deleted, $G_{(j+1) \bmod n}$ is serialized before G_j when G_j 's edges are deleted. However, this leads to a contradiction, since edges belonging to G_j and $G_{(j+1) \bmod n}$ are deleted together when $act(f)$ for some transaction G_l executes (since $G_{(j+1) \bmod n}$ is serialized before G_j , if for every transaction $G_k \in V$ serialized before G_j , val_k has been processed, then for every transaction $G_k \in V$ serialized before $G_{(j+1) \bmod n}$ also, val_k must have been processed). Thus, G_1 's edges are not deleted from the TSGD before G_2 's edges are deleted, \dots , G_{n-1} 's edges are not deleted from the TSGD before G_n 's edges are deleted. By transitivity and since G_0 's edges are deleted only after val_0 has been processed when Detect_Ins_Opt is invoked during the processing of val_0 , the TSGD (V', E', D', L') contains all the edges belonging to transactions G_0, G_1, \dots, G_{n-1} (since for all $i = 1, \dots, n-1$, val_i is processed before val_0 is processed).

We now show that $(G_0, slast(t_0))edge(t_1) \cdots edge(t_{n-1})(sfirst(t_0), G_0)$ is a path in the TSGD.

By the definition of $state_F$, $st_{m+1} = st_F(st_m, L(v_{2m+1}, v_{2m+2}))$, if $v_{2m+2} = v_{2m+3}$ and $st_{m+1} = st_F(st_m, L(v_{2m+1}, v_{2m+2}))$, if $v_{2m+1} = v_{2m+3}$.

Let St_k be the resulting state of Detect_Ins_Opt after $(st_m, prev(v_{2m+1}))$ is added to $V_set(v_{2m+1})$ (the state St_k results either due to the forward transition $St_j \rightarrow St_k$, either $St_j.v = v_{2m+1}$ or $St_j.prev(v_{2m+1})$, or due to Step 1). Thus, $St_k.v = v_{2m+1}$, $St_k.cur_st = st_m$ and in state St_k , $head(St_k.(St_k.v))[2] = prev(v_{2m+1})$. Furthermore, since Detect_Ins_Opt does not return abort, it follows from Lemma 2 that after a finite number of steps, Detect_Ins_Opt is in a state St'_k such that $St'_k \equiv St_k$ and no further forward transitions can be made from St'_k . Thus, in state St'_k ,

- Since $prev(v_{2m+1}) \neq v_{2m+2}$ (by the definition of path), $head(St'_k.anc(St'_k.v)) \neq v_{2m+2}$,
- Since $(v_1, v_2) \cdots (v_{2m+1}, v_{2m+2})$ is a path in (V, E, D) , there is no dependency $(prev(v_{2m+1}), v_{2m+1}, v_{2m+2})$ in D ; thus, there is no dependency $(head(St'_k.anc(St'_k.v)), St'_k.v) \rightarrow (St'_k.v, v_{2m+2})$ in D ,
- Since $state_F(init_st_F, (v_3, v_4) \cdots (v_{2m+1}, v_{2m+2})(v_{2m+3}, v_{2m+4}))$ is defined, if $v_{2m+2} = v_{2m+3}$ then $st_{m+1} = st_F(St'_k.cur_st, L(St'_k.v, v_{2m+2}))$ is defined, else if $v_{2m+1} = v_{2m+3}$, then $st_{m+1} = st_F(St'_k.cur_st, L(St'_k.v, v_{2m+2}))$ is defined.

However, since in state St'_k , no forward transition can be made due to edge $(St'_k.v, v_{2m+2})$ and Detect_Ins_Opt does not return abort, it must be the case that

- if $v_{2m+2} = v_{2m+3}$, then $St'_k.V_set(v_{2m+2})$ already contains $(st_{m+1}, St'_k.v)$. Thus, since $St'_k.v = v_{2m+1}$, $prev(v_{2m+3}) = v_{2m+1}$, $(st_{m+1}, prev(v_{2m+3}))$ is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_Opt.
- if $v_{2m+1} = v_{2m+3}$, then $St'_k.V_set(St'_k.v)$ already contains (st_{m+1}, v_{2m+2}) . Thus, since $St'_k.v = v_{2m+1}$, $prev(v_{2m+3}) = v_{2m+2}$, $(st_{m+1}, prev(v_{2m+3}))$ is added to $V_set(v_{2m+3})$ during the execution of Detect_Ins_Opt. \square

Corollary 2: Consider a TSGD (V, E, D, L) containing a path $(v_1, v_2) \cdots (v_{2n-1}, v_{2n})(v_{2n+1}, v_{2n+2}, v_{2n+3})$. If, for a regular term $RT, F = FA(RT)$, $st = state_F(init_st_F, (v_3, v_4) \cdots (v_{2n-1}, v_{2n})(v_{2n+1}, v_{2n+2}, v_{2n+3}))$ is an accept state, and $v_{2n+1} \in set_1$, then Detect_Ins_Opt $((V, E, D, L), v_1, v_2, set_1, RT)$ returns abort.

Proof: Suppose Detect_Ins_Opt does not return abort. By Lemma 4, $(st, prev(v_{2n+1}))$ is added to $V_set(v_{2n+1})$. Since $prev(v_{2n+1}) \neq v_1$, Detect_Ins_Opt makes a forward state transition with $(st, prev(v_{2n+1}))$ is added to $V_set(v_{2n+1})$. However, just before $(st, prev(v_{2n+1}))$ is added to $V_set(v_{2n+1})$, since st is an accept state, $prev(v_{2n+1}) \neq v_1$, $v_{2n+1} \in set_1$, and dependency $(prev(v_{2n+1}), v_{2n+1}, v_{2n+2}, v_{2n+3})$ does not belong to D , Detect_Ins_Opt returns abort. This leads to a contradiction, thus, it must be the case that Detect_Ins_Opt returns abort. \square

We are now in a position to prove Theorem 1. Before we present the proof, we introduce some additional notation and the following lemma.

Lemma 5: If, in the optimistic scheme, for some site s_k , transactions G_i, G_j, G_{ik} is serializable before G_{jk} at site s_k , then there does not exist a dependency $(G_j, s_k) \rightarrow (s_k, G_i)$ in the TSGD.

Proof: Suppose there exists a dependency $(G_j, s_k) \rightarrow (s_k, G_i)$ in the TSGD. The dependency cannot have been added to the TSGD after $act(ser_k(G_i))$ has executed. Thus, dependency (G_j, s_k)

The above definition of $state_F$ is recursive. In the following lemma, we show that an alternative non-recursive definition of $state_F$ is possible.

Lemma 3: Consider a TSGD containing a path $(v_1, v_2)(v_3, v_4) \cdots (v_{2n-1}, v_{2n})$. If $e_1 e_2 \cdots e_n$ is a sequence such that

- if $v_{2i} = v_{2i+1}$, then $e_i = L(v_{2i-1}, v_{2i})$, and
- if $v_{2i-1} = v_{2i+1}$, then $e_i = \overline{L(v_{2i-1}, v_{2i})}$,

then for a regular term RT and a state st of $F = FA(RT)$, $state_F(st, (v_1, v_2)(v_3, v_4) \cdots (v_{2n-1}, v_{2n})) = st_F(st, e_1 \cdots e_{n-1})$.

Proof: We use induction on i to prove that for all $i = 1, \dots, n$, $state_F(st, (v_1, v_2) \cdots (v_{2i-1}, v_{2i})) = st_F(st, e_1 \cdots e_{i-1})$.

Basis ($i = 1$): $state_F(st, (v_1, v_2)) = st_F(st, \epsilon) = st$.

Induction: Assume true for $i = m$, $1 \leq m < n$, that is, $state_F(st, (v_1, v_2) \cdots (v_{2m-1}, v_{2m})) = st_F(st, e_1 \cdots e_{m-1})$. We prove the claim for $i = m + 1$, that is, we need to show that $state_F(st, (v_1, v_2) \cdots (v_{2m+1}, v_{2m+2})) = st_F(st, e_1 \cdots e_m)$. By the definition of $state_F$,

$$state_F(st, (v_1, v_2) \cdots (v_{2m+1}, v_{2m+2})) = \begin{cases} st_F(st', \frac{L(v_{2m-1}, v_{2m})}{L(v_{2m-1}, v_{2m})}) & \text{if } v_{2m} = v_{2m+1} \\ st_F(st', \overline{L(v_{2m-1}, v_{2m})}) & \text{if } v_{2m-1} = v_{2m+1} \end{cases}$$

where $st' = state_F(st, (v_1, v_2) \cdots (v_{2m-1}, v_{2m}))$. Thus,

$$state_F(st, (v_1, v_2) \cdots (v_{2m+1}, v_{2m+2})) = \begin{cases} st_F(st, e_1 \cdots e_{m-1} \frac{L(v_{2m-1}, v_{2m})}{L(v_{2m-1}, v_{2m})}) & \text{if } v_{2m} = v_{2m+1} \\ st_F(st, e_1 \cdots e_{m-1} \overline{L(v_{2m-1}, v_{2m})}) & \text{if } v_{2m-1} = v_{2m+1} \end{cases}$$

Thus, $state_F(st, (v_1, v_2) \cdots (v_{2m+1}, v_{2m+2})) = st_F(st, e_1 \cdots e_m)$. \square

For every instantiation of a regular term RT , there is a corresponding path in the TSG/TSGD which $state_F$ ($F = FA(RT)$) with respect to the initial state $init_st_F$ is an accept state. The following lemma lays the groundwork for showing that Detect_Ins_Opt detects instantiation by detecting appropriate paths in the TSGD.

Lemma 4: Consider a TSGD (V, E, D, L) containing a path $(v_1, v_2) \cdots (v_{2n-3}, v_{2n-2}), (v_{2n-1}, v_{2n})$, such that for a regular term RT , $F = FA(RT)$, $state_F(init_st_F, (v_3, v_4) \cdots (v_{2n-1}, v_{2n}))$ is defined. If Detect_Ins_Opt $((V, E, D, L), v_1, v_2, set_1, RT)$ does not return abort, then during the execution of Detect_Ins_Opt (before it returns commit), for all i , $i = 1, 2, 3, \dots, n - 1$, $(st, prev(v_{2i+1}))$ is added to $V_set(v_{2i+1})$, where $st = state_F(init_st_F, (v_3, v_4) \cdots (v_{2i-1}, v_{2i})(v_{2i+1}, v_{2i+2}))$.

Proof: We prove the above lemma by induction on i . We prove that if Detect_Ins_Opt does not return abort, then for all i , $i = 1, 2, \dots, n - 1$, $(st, prev(v_{2i+1}))$ is added to $V_set(v_{2i+1})$, where $st = state_F(init_st_F, (v_3, v_4) \cdots (v_{2i-1}, v_{2i})(v_{2i+1}, v_{2i+2}))$.

Basis ($i = 1$): In Step 1 of Detect_Ins_Opt, $(init_st_F, v_1)$ is added to $V_set(v_2)$. Since $v_2 = prev(v_3) = v_1$, and $state_F(init_st_F, (v_3, v_4)) = init_st_F$, the lemma is true for $i = 1$ ($(init_st_F, prev(v_3))$ is added to $V_set(v_3)$).

Induction: Let us assume that the lemma is true for $i = m$, $1 \leq m < n - 1$. Thus, if Detect_Ins_Opt does not return abort, then $(st_m, prev(v_{2m+1}))$ is added to $V_set(v_{2m+1})$, where $st_m = state_F(init_st_F, (v_3, v_4) \cdots (v_{2m-1}, v_{2m})(v_{2m+1}, v_{2m+2}))$. We show the lemma to be true for $i = m + 1$. The state $st_{m+1} = state_F(st_m, prev(v_{2m+1}))$ is added to $V_set(v_{2m+2})$. Since $v_{2m+2} = prev(v_{2m+3}) = st_m$, and $state_F(st_m, prev(v_{2m+1})) = st_m$, the lemma is true for $i = m + 1$.

node can be visited at most $n_G n_S$ times (every node v in the TSGD can be visited in a state st at most once for every node w such that edge (v, w) is in the TSGD, and F has at most n_S states). Since there are m site nodes and at most n_G transaction nodes in the TSGD, the number of times Detect_Ins_Opt checks if an edge satisfies the conditions in Step 2 is $n_G^2 m n_S + n_G v_S^2 n_S$. Since each of the conditions in Step 2 can be checked in constant time and $v_S \ll n_G, v_S < m$, Detect_Ins_Opt terminates in $O(n_G^2 m n_S)$ steps. \square

Before we show that Detect_Ins_Opt detects instantiations, we define the notion of a path in order to capture the notion of instantiations in the TSGD. Corresponding to every instantiation, there is a path, defined below, in the TSGD (paths are similarly defined for a TSG; the requirement that there are no dependencies between certain edges is trivially satisfied in a TSG).

Definition 9: Consider a TSG/TSGD containing the sequence of edges $(v_1, v_2)(v_3, v_4) \cdots (v_{2n-1}, v_{2n})$, $n > 1$. The sequence of edges is a path if

- for every pair of consecutive edges $(v_{2i-1}, v_{2i}), (v_{2i+1}, v_{2i+2})$, $i = 1, \dots, n-1$, either $v_{2i} = v_{2i+1}$ or $v_{2i-1} = v_{2i+1}$, and
- if for some $j, k = 1, 2, \dots, n$, $j \leq k$, $v_{2j-1} = v_{2j+1} = v_{2j+3} = \cdots = v_{2k-1}$, then
 1. if $j < k$, then $v_{2j} \neq v_{2j+2} \neq v_{2j+4} \neq \cdots \neq v_{2k}$, and for all l, m , $j \leq l < m \leq k$, there is no dependency $(v_{2l}, v_{2l-1}) \rightarrow (v_{2m-1}, v_{2m})$ in the TSG/TSGD, and
 2. if $j > 1$ and $v_{2j-2} = v_{2j-1}$, then for all $l = j, j+1, \dots, k$, $v_{2j-3} \neq v_{2l}$, and there is no dependency $(v_{2j-3}, v_{2j-2}) \rightarrow (v_{2l-1}, v_{2l})$ in the TSG/TSGD. \square

Thus, it follows from the definition of path that for every pair of consecutive edges $(v_{2i-1}, v_{2i})(v_{2i+1}, v_{2i+2})$, $i = 1, \dots, n-1$, either

- $v_{2i} = v_{2i+1}$, $v_{2i-1} \neq v_{2i+2}$, and dependency $(v_{2i-1}, v_i) \rightarrow (v_{2i+1}, v_{2i+2})$ is not in the TSGD, or
- $v_{2i-1} = v_{2i+1}$, $v_{2i} \neq v_{2i+2}$ and dependency $(v_{2i}, v_{2i-1}) \rightarrow (v_{2i+1}, v_{2i+2})$ is not in the TSGD.

Furthermore, for the path $(v_1, v_2)(v_3, v_4) \cdots (v_{2n-1}, v_{2n})$, for $i = 1, 2, \dots, n-1$, we define $prev(v_{2i+1})$ as follows.

$$prev(v_{2i+1}) = \begin{cases} v_{2i-1} & \text{if } v_{2i} = v_{2i+1} \\ v_{2i} & \text{if } v_{2i-1} = v_{2i+1} \end{cases}$$

Note that, by the definition of path, $prev(v_{2i+1}) \neq v_{2i+2}$ and there is no dependency $(prev(v_{2i+1}), v_{2i+1}) \rightarrow (v_{2i+1}, v_{2i+2})$ in the TSGD. Only certain paths in the TSG/TSGD in which the sequence of transaction types are a string in $L(reg_exp)$ correspond to instantiations of $RT = e_0 : reg_exp$ in S . In order to ensure that transaction type information can be taken into account when detecting paths in the TSG/TSGD, we define $state_F$ below.

Definition 10: Consider a TSG/TSGD containing a path $(v_1, v_2) \cdots (v_{2n-1}, v_{2n})$. Let RT be a regular term and $F = FA(RT)$. We define $state_F$ for the sequence of edges in the path and a state st of F , using st_F , as follows.

$$state_F(st, (v_1, v_2) \cdots (v_{2i-1}, v_{2i})) = \begin{cases} st & \text{if } i = 1 \\ st_F(st', L(v_{2i-3}, v_{2i-2})) & \text{if } i > 1 \text{ and } v_{2i-2} = v_{2i-1} \\ st_F(st', L(v_{2i-3}, v_{2i-2})) & \text{if } i > 1 \text{ and } v_{2i-3} = v_{2i-1} \end{cases}$$

Basis ($num = 0$): If $num = 0$ in state St_k , then in state St_k , for every edge $(St_k.v, u)$, if $st_F(St_k.cur_st, L(St_k.v, u))$ is defined, then $(st, St_k.v) \in St_k.V_set(u)$ (alternatively, if $st' = (St_k.cur_st, \overline{L(St_k.v, u)})$ is defined, then $(st', u) \in St_k.V_set(St_k.v)$). Thus, no forward transition can be made from state St_k (since every edge $(St_k.v, u)$ satisfies the last condition in Step 2).

Induction: Let us assume the lemma is true if $num \leq m$ in state St_k , $m \geq 0$. We show that lemma is true if $num \leq m + 1$ in state St_k . We show that if Detect_Ins_Opt does not return abort, then after a finite number of moves, Detect_Ins_Opt is in a state St'_k such that $St'_k \equiv St_k$ and no forward transitions can be made from state St'_k .

Let St''_k be any state equivalent to St_k such that in St''_k , $num \leq m + 1$. If Detect_Ins_Opt makes the forward transition $St''_k \rightarrow St_l$ due to some edge $(St''_k.v, u)$ and $L(St''_k.v, u)$, then it may be the case that $St_l.v = u$, $St_l.cur_st = st_F(St''_k.cur_st, L(St''_k.v, u))$. Furthermore, in state St_l , $(St_l.cur_st, St''_k.v) \notin St''_k.V_set(u)$ and in state St_l , $(St_l.cur_st, St''_k.v) \in St_l.V_set(u)$ (since the transition $St''_k \rightarrow St_l$ causes $(St_l.cur_st, St''_k.v)$ to be added to $V_set(u)$). Note that, since before the transition is made, $(St_l.cur_st, St''_k.v)$ does not belong to $V_set(u)$ and $num \leq m + 1$ in St''_k , after the transition $St''_k \rightarrow St_l$ is made, $num \leq m$ in St_l . By IH, since Detect_Ins_Opt does not return abort, after a finite number of steps, Detect_Ins_Opt enters a state $St'_l \equiv St_l$, such that no forward transitions are possible from St'_l . Thus, since it does not return abort, Detect_Ins_Opt makes the reverse transition $St'_l \rightarrow St'''_k$ after a finite number of steps, where $St'''_k \equiv St''_k \equiv St_k$. Furthermore, in state St'''_k , $(St_l.cur_st, St''_k.v) \in St'''_k.V_set(u)$ and $St'''_k.v = St''_k.v$, and thus, no forward transition can be made from state St'''_k due to edge $(St'''_k.v, u)$ and $L(St'''_k.v, u)$ (edge $(St'''_k.v, u)$ does not satisfy the condition in Step 3(c)). Using a similar argument, it can be shown that if Detect_Ins_Opt makes a forward transition $St''_k \rightarrow St_l$ due to edge $(St''_k.v, u)$ and $\overline{L(St''_k.v, u)}$, then in a finite number of steps, Detect_Ins_Opt enters a state $St'''_k \equiv St''_k$ such that no forward transitions are possible from St'''_k due to edge $(St'''_k.v, u)$ and $\overline{L(St'''_k.v, u)}$.

Thus, once a forward transition is made by Detect_Ins_Opt due to an edge e and $L(e)/\overline{L(e)}$ from a state equivalent to St_k , then no further forward transitions can be made by Detect_Ins_Opt due to e and $L(e)/\overline{L(e)}$ from any state equivalent to St_k . Furthermore, everytime a forward transition is made from a state St''_k that is equivalent to St_k such that $num \leq m + 1$ in St''_k , a reverse transition is made by Detect_Ins_Opt to a state St'''_k equivalent to St_k such that $num \leq m + 1$ in St'''_k . Since there are a finite number of edges incident on each node, Detect_Ins_Opt does not return abort, and in state St_k , $num \leq m + 1$, eventually, Detect_Ins_Opt would be in a state $St'_k \equiv St_k$ such that no further forward transitions can be made. \square

Corollary 1: Procedure Detect_Ins_Opt terminates in $O(n_G^2 mn_S)$ steps.

Proof: We first show that Detect_Ins_Opt terminates in a finite number of steps. Let St_1 denote the state immediately after the execution of Step 1 of algorithm Detect_Ins_Opt. If Detect_Ins_Opt does not return abort, then by Lemma 1, after a finite number of steps, Detect_Ins_Opt is in a state $St'_1 \equiv St_1$ such that no further forward transitions can be made from St'_1 . Detect_Ins_Opt, then, executes Step 4 and since, in state St'_1 , $head(St'_1.F_list(St'_1.v)) = (s^*, G_i)$, Detect_Ins_Opt terminates in a finite number of steps. If, on the other hand, Detect_Ins_Opt returns abort, then it trivially terminates in a finite number of steps.

The number of steps Detect_Ins_Opt terminates in is equal to the product of the number of times Detect_Ins_Opt checks if an edge satisfies the conditions in Step 2 and the number of steps required to check if an edge satisfies the conditions in Step 2. Every time a transaction node is visited, the conditions in Step 2 need to be checked, on an average, for v_S edges (the average number of sites a global transaction executes at is v_S), while every time a site node is visited, the conditions in Step 2 need to be checked for at most n_G edges (since the number of transaction nodes in the TSGD is

Appendix -B- : Optimistic Scheme

Before we prove Theorem 1, we need to prove certain lemmas. In the following lemma, we state the implications of complete regular specifications.

Lemma 1: Let RT_1 be a regular term in the regular specification R , I be an instantiation of RT_1 in the global schedule S , and G_0 be a transaction in I . If R is complete, then there exists a regular term RT_2 and an instantiation $t_0 : t_1 \cdots t_{m-1}$ of RT_2 in S such that $hdr(t_0) = G_0$.

Proof: Let $RT_1 = e'_0 : reg_exp_1$ and $I = t'_0 : t'_1 \cdots t'_{n-1}$, $n > 1$. Since I is an instantiation of RT_1 in S ,

- for all j , $j = 0, 1, \dots, n - 1$,
 1. $t'_j \in \Sigma_S$, and
 2. $last(t'_j)$ and $first(t'_{(j+1) \bmod n})$ execute at the same site, and $last(t'_j)$ is serialized after $first(t'_{(j+1) \bmod n})$ at the site, and
- $type(t'_0) = e'_0$ and $type(t'_1) \cdots type(t'_{n-1})$ is a string in $L(reg_exp_1)$.

Let $G_0 = hdr(t'_k)$, for some k , $k = 0, 1, \dots, n - 1$. Since R is complete, there exists a regular term $RT_2 = type(t'_k) : reg_exp_2$ such that

$$type(t'_{(k+1) \bmod n}) \cdots type(t'_{(k+n-1) \bmod n})$$

is a string in $L(reg_exp_2)$. Thus,

$$t'_k : t'_{(k+1) \bmod n} \cdots t'_{(k+n-1) \bmod n}$$

is the required instantiation of RT_2 in S . \square

We next show that the manner in which Detect_Ins_Opt traverses edges in the TSGD ensures that it detects instantiations of regular terms in the TSGD. We first introduce the following additional notation.

Between the execution of any two steps³ of Detect_Ins_Opt, the contents of v , cur_st , Δ , and $anc(v_i)$ for all $v_i \in V$ constitute a state St_k of Detect_Ins_Opt. We denote the contents of v , cur_st , Δ , $anc(v_i)$, $V_set(v_i)$, and $F_List(v_i)$ for any $v_i \in V$ in state St_k by $St_k.v$, $St_k.cur_st$, $St_k.\Delta$, $St_k.anc(v_i)$, $St_k.V_set(v_i)$ and $St_k.F_List(v_i)$ respectively. State changes in Detect_Ins_Opt caused by steps 1, 3 and 4. We refer to state transition $St_j \rightarrow St_k$ due to Step 3 as a *forward transition* while a state transition $St_j \rightarrow St_k$ due to Step 4 is referred to as a *reverse transition*. Also, two states St_j and St'_j are said to be equivalent (denoted by $St_j \equiv St'_j$) if $St_j.v = St'_j.v$, $St_j.cur_st = St'_j.cur_st$, and for all $v_i \in V$, $St_j.anc(v_i) = St'_j.anc(v_i)$, $St_j.F_List(v_i) = St'_j.F_List(v_i)$. Detect_Ins_Opt has the following interesting property: if it makes a forward transition $St_j \rightarrow St_k$ and for a state $St'_k \equiv St_k$ it makes a reverse transition $St'_k \rightarrow St'_j$, then $St_j \equiv St'_j$.

Lemma 2: If Detect_Ins_Opt does not return abort and during its execution, Detect_Ins_Opt is in state St_k , then after a finite number of steps, it enters a state $St'_k \equiv St_k$ such that no forward transitions from St'_k are possible.

Proof: We prove the lemma by induction on num , the number of elements in $\{(st, v_1, v_2) \mid (st \text{ is a state of } F) \wedge (v_1, v_2 \in V) \wedge ((st, v_1) \notin V_set(v_2))\}$ in state St_k .

procedure Detect_Ins_TSGD2($(V, E, D, L), G_i, s_k, set_1, RT$):

1. For all nodes v in the TSGD, set $F_list(v) = []$, $anc(v) = []$, $V_set(v) = \emptyset$.
 $v = s_k$, $F_list(s_k) = [(st*, G_i)]$, $anc(s_k) = [(G_i, G_i)]$, $F = FA(RT)$, $V_set(s_k) = \{(init_st_F, (G_i, G_i))\}$ and $cur_st = init_st_F$. Set $\Delta = \emptyset$.
2. If, for every edge (v, u) one of the following is true:
 - $head(anc(v))[1] = u$.
 - $head(anc(v))[2] = u$.
 - There is a dependency $(head(anc(v))[1], v) \rightarrow (v, u)$ in $D \cup \Delta$.
 - There is a dependency $(head(anc(v))[2], v) \rightarrow (v, u)$ in $D \cup \Delta$.
 - If $st = st_F(cur_st, L(v, u))$ is defined then $(st, (v, v)) \in V_set(u)$, and
if $st' = st_F(cur_st, L(v, u))$ is defined then $(st', (head(anc(v))[1], u)) \in V_set(v)$.

then go to Step 4.

3. Choose an edge (v, u) such that

- (a) $head(anc(v))[1] \neq u$, and
- (b) $head(anc(v))[2] \neq u$, and
- (c) there is no dependency $(head(anc(v))[1], v) \rightarrow (v, u)$ in $D \cup \Delta$, and
- (d) there is no dependency $(head(anc(v))[2], v) \rightarrow (v, u)$ in $D \cup \Delta$, and
- (e) $st = st_F(cur_st, L(v, u))$ is defined and $(st, (v, v)) \notin V_set(u)$, or
 $st' = st_F(cur_st, L(v, u))$ is defined and $(st', (head(anc(v))[1], u)) \notin V_set(v)$.

If st is defined and $(st, (v, v)) \notin V_set(u)$, then do

- If st is an accept state, $u \in set_1$ and $v \neq G_i$, then $\Delta := \Delta \cup \{(v, u) \rightarrow (u, G_i)\}$.
- $F_list(u) := (cur_st, v) \circ F_list(u)$, $anc(u) := (v, v) \circ anc(u)$, $cur_st := st$, $V_set(u) := V_set(u) \cup \{(st, (v, v))\}$, $v := u$. Go to Step 2.

If st' is defined and $(st', (head(anc(v))[1], u)) \notin V_set(v)$ then do

- If st' is an accept state, $v \in set_1$, $u \neq G_i$ and $head(anc(v))[1] \neq G_i$, then $\Delta := \Delta \cup \{(head(anc(v))[1], v) \rightarrow (v, G_i)\}$.
- $F_list(v) := (cur_st, v) \circ F_list(v)$, $anc(v) := (head(anc(v))[1], u) \circ anc(v)$, $cur_st := st'$, $V_set(v) := V_set(v) \cup \{(st', (head(anc(v))[1], u))\}$. Go to Step 2.

4. If $head(F_list(v)) \neq (st*, G_i)$, then $temp1 := head(F_list(v))[1]$, $temp2 := head(F_list(v))[2]$, $F_list(v) := tail(F_list(v))$, $anc(v) = tail(anc(v))$, $cur_st := temp1$, $v := temp2$ and go to Step 2.

5. **return**(Δ).

Figure 14: Procedure Detect_Ins_TSGD2

procedure Detect_Ins_TSGD1($(V, E, D, L), G_i, s_k, set_1, RT$):

1. For all nodes v in the TSGD, set $F_list(v) = []$, $anc(v) = []$, $V_set(v) = \emptyset$. Set $v = s_k$, $F_list(s_k) = [(st^*, G_i)]$, $anc(s_k) = [G_i]$, $F = FA(RT)$, $V_set(s_k) = \{(init_st_F, G_i)\}$, $cur_st = init_st_F$. Set $\Delta = \emptyset$.
2. If, for every edge (v, u) one of the following is true:
 - $head(anc(v)) = u$.
 - There is a dependency $(head(anc(v)) \rightarrow (v, u))$ in $D \cup \Delta$.
 - If $st = st_F(cur_st, L(v, u))$ is defined then $(st, v) \in V_set(u)$, and if $st' = st_F(cur_st, L(v, u))$ is defined then $(st', head(anc(v))) \in V_set(v)$.

then go to Step 4.

3. Choose an edge (v, u) such that

- (a) $head(anc(v)) \neq u$, and
- (b) there is no dependency $(head(anc(v)) \rightarrow (v, u))$ in $D \cup \Delta$, and
- (c) $st = st_F(cur_st, L(v, u))$ is defined and $(st, v) \notin V_set(u)$, or $st' = st_F(cur_st, L(v, u))$ is defined and $(st', head(anc(v))) \notin V_set(v)$.

If st is defined and $(st, v) \notin V_set(u)$, then do

- if st is an accept state, $u \in set_1$ and $v \neq G_i$, then $\Delta := \Delta \cup \{(v, u) \rightarrow (u, G_i)\}$.
- $F_list(u) := (cur_st, v) \circ F_list(u)$, $anc(u) := v \circ anc(u)$, $cur_st := st$, $V_set(u) := V_set(u) \cup \{(st, v)\}$, $v := u$. Go to Step 2.

If st' is defined and $(st', head(anc(v))) \notin V_set(v)$, then do

- if st' is an accept state, $v \in set_1$ and $head(anc(v)) \neq G_i$, then $\Delta := \{(head(anc(v)), v) \rightarrow (v, G_i)\}$.
- $F_list(v) := (cur_st, v) \circ F_list(v)$, $anc(v) := head(anc(v)) \circ anc(v)$, $cur_st := st'$, $V_set(v) := V_set(v) \cup \{(st', head(anc(v)))\}$. Go to Step 2.

4. If $head(F_list(v)) \neq (st^*, G_i)$, then $temp1 := head(F_list(v))[1]$, $temp2 := head(F_list(v))[2]$, $F_list(v) := tail(F_list(v))$, $anc(v) = tail(anc(v))$, $cur_st := temp1$, $v := temp2$ and goto Step 2.

5. **return**(Δ).

Figure 13: Procedure Detect_Ins_TSGD1

procedure Detect_Ins_TSG2($(V, E, L), G_i, s_k, set_1 set_2, RT$):

1. For all nodes v in the TSG, set $F_list(v) = []$, $anc(v) = []$, $V_set(v) = \emptyset$. Set $v = s_k$, $F_list(v) := [(st^*, G_i)]$, $anc(s_k) = [(G_i, G_i)]$, $F = FA(RT)$, $V_set(s_k) = \{(init_st_F, (G_i, G_i))\}$ and $cur_st := init_st_F$. Set $\Delta = \emptyset$.
2. If, for every edge (v, u) one of the following is true:
 - $head(anc(v))[1] = u$ or $head(anc(v))[2] = u$.
 - If $st = st_F(cur_st, L(v, u))$ is defined then
 - (a) there exist nodes u_2, u_3 , $u_2 \neq u_3$, such that $(st, (v, u_2)) \in V_set(u)$, $(st, (v, u_3)) \in V_set(u)$ or
 - (b) $(st, (v, v)) \in V_set(u)$,
 and if $st' = st_F(cur_st, \overline{L(v, u)})$ is defined then
 - (a) there exist nodes u_2, u_3 , $u_2 \neq u_3$, such that $(st', (head(anc(v))[1], u_2)) \in V_set(v)$, $(st', (head(anc(v))[1], u_3)) \in V_set(v)$, or
 - (b) $(st', (head(anc(v))[1], u)) \in V_set(v)$.
 - $v \in (set_2 \cup \Delta)$ and $u = G_i$.

then go to Step 4.

3. Choose an edge (v, u) such that
 - $head(anc(v))[1] \neq u$ and $head(anc(v))[2] \neq u$, and
 - $st = st_F(cur_st, L(v, u))$ is defined and
 - (a) there do not exist nodes u_2, u_3 , $u_2 \neq u_3$, such that $(st, (v, u_2)) \in V_set(u)$, $(st, (v, u_3)) \in V_set(u)$, and
 - (b) $(st, (v, v)) \notin V_set(u)$,
 or $st' = st_F(cur_st, \overline{L(v, u)})$ is defined and
 - (a') there do not exist nodes u_2, u_3 , $u_2 \neq u_3$, such that $(st', (head(anc(v))[1], u_2)) \in V_set(v)$, $(st', (head(anc(v))[1], u_3)) \in V_set(v)$, and
 - (b') $(st', (head(anc(v))[1], u)) \notin V_set(v)$, and
 - $v \notin (set_2 \cup \Delta)$ or $u \neq G_i$.

If st is defined, 3(a) and 3(b) then do

- If st is an accept state, $u \in set_1$ and $v \neq G_i$, then $\Delta := \Delta \cup \{u\}$.
- $F_list(u) := (cur_st, v) \circ F_list(u)$, $anc(u) := (v, v) \circ anc(u)$, $cur_st := st$, $V_set(u) = V_set(u) \cup \{(st, (v, v))\}$, $v := u$. Go to Step 2.

If st' is defined, 3(a') and 3(b') then do

- If st' is an accept state, $v \in set_1$, $u \neq G_i$ and $head(anc(v))[1] \neq G_i$, then $\Delta := \Delta \cup \{v\}$.
- $F_list(v) := (cur_st, v) \circ F_list(v)$, $anc(v) := (head(anc(v))[1], u) \circ anc(v)$, $cur_st := st'$, $V_set(v) = V_set(v) \cup \{(st', (head(anc(v))[1], u))\}$. Go to Step 2.

4. If $head(F_list(v)) \neq (st^*, G_i)$, then $temp1 := head(F_list(v))[1]$, $temp2 := head(F_list(v))[2]$, $F_list(v) := tail(F_list(v))$, $anc(v) = tail(anc(v))$, $cur_st := temp1$, $v := temp2$ and go to Step 2.
5. **return**(Δ).

Figure 12: Procedure Detect_Ins_TSG2

procedure Detect_Ins_TSG1($(V, E, L), G_i, s_k, set_1, set_2, RT$):

1. For all nodes v in the TSG, set $F_list(v) = []$, $anc(v) = []$, $V_set(v) = \emptyset$. Set $v = s_k$, $F_list([st*, G_i])$, $anc(s_k) = [G_i]$, $F = FA(RT)$, $V_set(s_k) = \{(init_st_F, G_i)\}$ and $cur_st = init_st_F$, $\Delta = \emptyset$.
2. If, for every edge (v, u) one of the following is true:
 - If $st = st_F(cur_st, L(v, u))$ is defined then either
 - (a) $head(anc(v)) = u$ or
 - (b) $(st, v) \in V_set(u)$ or
 - (c) there exist two distinct nodes v_1, v_2 such that $(st, v_1) \in V_set(u)$ and $(st, v_2) \in V_set(u)$ and if $st' = st_F(cur_st, \overline{L(v, u)})$ is defined then either
 - (a) $(st', head(anc(v))) \in V_set(v)$, or
 - (b) there exist two distinct nodes v_1, v_2 such that $(st', v_1) \in V_set(v)$ and $(st', v_2) \in V_set(v)$
 - $v \in (set_2 \cup \Delta)$ and $u = G_i$.

then go to Step 4.

3. Choose an edge (v, u) such that
 - $st = st_F(cur_st, L(v, u))$ is defined and
 - (a) $head(anc(v)) \neq u$, and
 - (b) $(st, v) \notin V_set(u)$, and
 - (c) there do not exist two distinct nodes v_1, v_2 such that $(st, v_1) \in V_set(u)$ and $(st, v_2) \in V_set(u)$,
 or $st' = st_F(cur_st, \overline{L(v, u)})$ is defined and
 - (a') $(st', head(anc(v))) \notin V_set(v)$, and
 - there do not exist two distinct nodes v_1, v_2 such that $(st', v_1) \in V_set(v)$ and $(st', v_2) \in V_set(v)$, and
 - $v \notin (set_2 \cup \Delta)$ or $u \neq G_i$.

If st is defined, 3(a), 3(b) and 3(c), then do

- If st is an accept state, $u \in set_1$ and $v \neq G_i$, then $\Delta := \Delta \cup \{u\}$.
- $F_list(u) := (cur_st, v) \circ F_list(u)$, $anc(u) := v \circ anc(u)$, $cur_st := st$, $V_set(u) = V_set(u) \cup \{(st, v)\}$, $v := u$. Go to Step 2.

If $st' = st_F(cur_st, \overline{L(v, u)})$ is defined, 3(a') and 3(b'), then do

- If st' is an accept state, $v \in set_1$ and $head(anc(v)) \neq G_i$, then $\Delta := \Delta \cup \{v\}$.
- $F_list(v) := (cur_st, v) \circ F_list(v)$, $anc(v) := head(anc(v)) \circ anc(v)$, $cur_st := st'$, $V_set(v) = V_set(v) \cup \{(st', head(anc(v)))\}$. Go to Step 2.

4. If $head(F_list(v)) \neq (st*, G_i)$, then $temp1 := head(F_list(v))[1]$, $temp2 := head(F_list(v))$, $F_list(v) := tail(F_list(v))$, $anc(v) = tail(anc(v))$, $cur_st := temp1$, $v := temp2$, and go to Step 2.
5. **return**(Δ).

Figure 11: Procedure Detect_Ins_TSG1

Appendix -A- : Procedures

procedure Detect_Ins_Opt($(V, E, D, L), G_i, s_k, set_1, RT$):

1. For all nodes v in the TSGD, set $F_list(v) = []$ ($[]$ is the empty list), $anc(v) = []$, $V_set(v)$
 Set $v = s_k$, $F_list(s_k) = [(st^*, G_i)]$ (st^* is a special termination state), $anc(s_k) =$
 $F = FA(RT)$, $V_set(s_k) = \{(init_st_F, G_i)\}$ and $cur_st = init_st_F$.

2. If, for every edge (v, u) one of the following is true:

- $head(anc(v)) = u$.
- There is a dependency $(head(anc(v)), v) \rightarrow (v, u)$ in D .
- if $st = st_F(cur_st, L(v, u))$ is defined then $(st, v) \in V_set(u)$, and
 if $st' = st_F(cur_st, L(v, u))$ is defined then $(st', u) \in V_set(v)$.

then go to Step 4.

3. Choose an edge (v, u) such that

- (a) $head(anc(v)) \neq u$, and
- (b) there is no dependency $(head(anc(v)), v) \rightarrow (v, u)$ in D , and
- (c) $st = st_F(cur_st, L(v, u))$ is defined and $(st, v) \notin V_set(u)$, or
 $st' = st_F(cur_st, L(v, u))$ is defined and $(st', u) \notin V_set(v)$.

If st is defined and $(st, v) \notin V_set(u)$ then do

- If st is an accept state, $u \in set_1$, $v \neq G_i$ and there is no dependency $(v, u) \rightarrow (u, G_i)$ in D , then **return**(abort).
- $F_list(u) := (cur_st, v) \circ F_list(u)$, $anc(u) = v \circ anc(u)$, $cur_st := st$, $V_set(u) := (st, v) \cup V_set(u)$, $v := u$. Go to Step 2.

If st' is defined and $(st', u) \notin V_set(v)$ then do

- If st' is an accept state, $v \in set_1$, $u \neq G_i$ and there is no dependency $(u, v) \rightarrow (v, G_i)$ in D , then **return**(abort).
- $F_list(v) := (cur_st, v) \circ F_list(v)$, $anc(v) = u \circ anc(v)$, $cur_st := st'$, $V_set(v) := (st', u) \cup V_set(v)$. Go to Step 2.

4. If $head(F_list(v)) \neq (st^*, G_i)$, then $temp1 := head(F_list(v))[1]$, $temp2 := head(F_list(v))[2]$, $anc(v) = tail(anc(v))$, $F_list(v) := tail(F_list(v))$, $cur_st := temp1$, $v := temp2$ and go to Step 2.

5. **return**(commit).

Figure 10: Procedure Detect_Ins_Opt