



# Texture Mapping

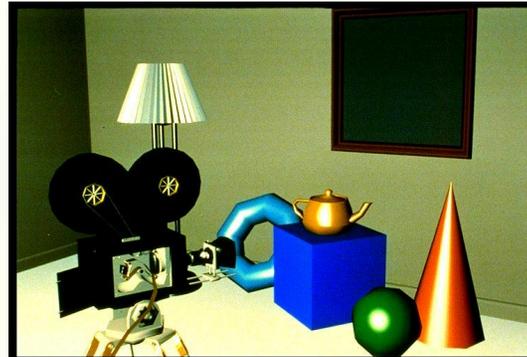




# What adds visual realism?



*Geometry only*



*Phong shading*



*Phong shading +  
Texture maps*



# Textures Supply Rendering Detail



*Without texture*

*With texture*



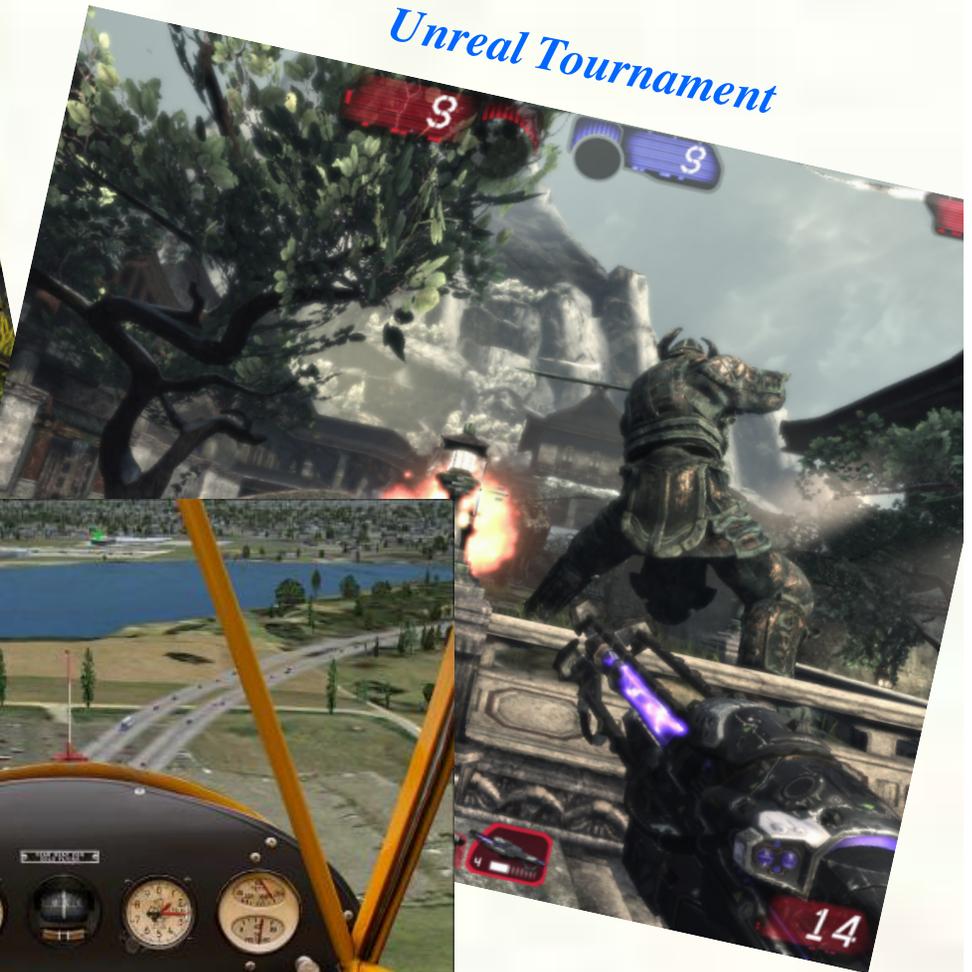


# Textures Make Graphics Pretty

*Sacred 2*



*Unreal Tournament*



*Texture → detail,  
detail → immersion,  
immersion → fun*



*Microsoft Flight Simulator X*



# Texture mapping

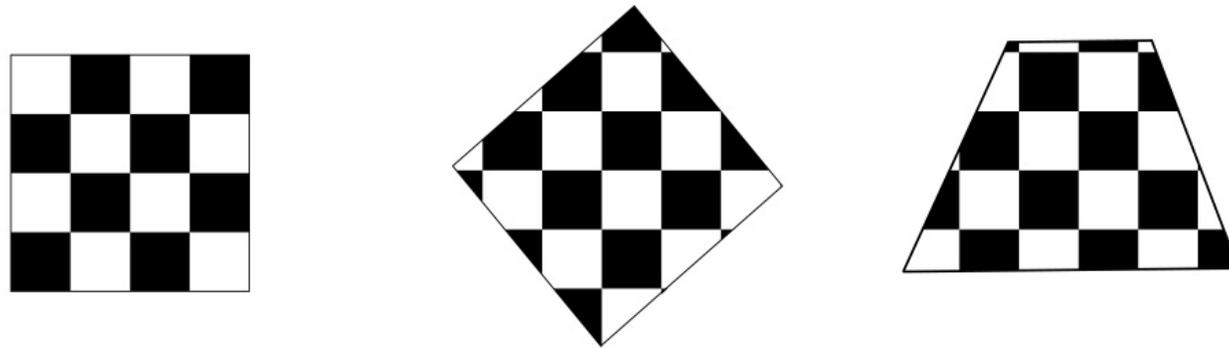


*Texture mapping (Woo et al., fig. 9-1)*

- Texture mapping allows you to take a simple polygon and give it the appearance of something much more complex.
  - Due to Ed Catmull, PhD thesis, 1974
  - Refined by Blinn & Newell, 1976
- Texture mapping ensures that “all the right things” happen as a textured polygon is transformed and rendered.



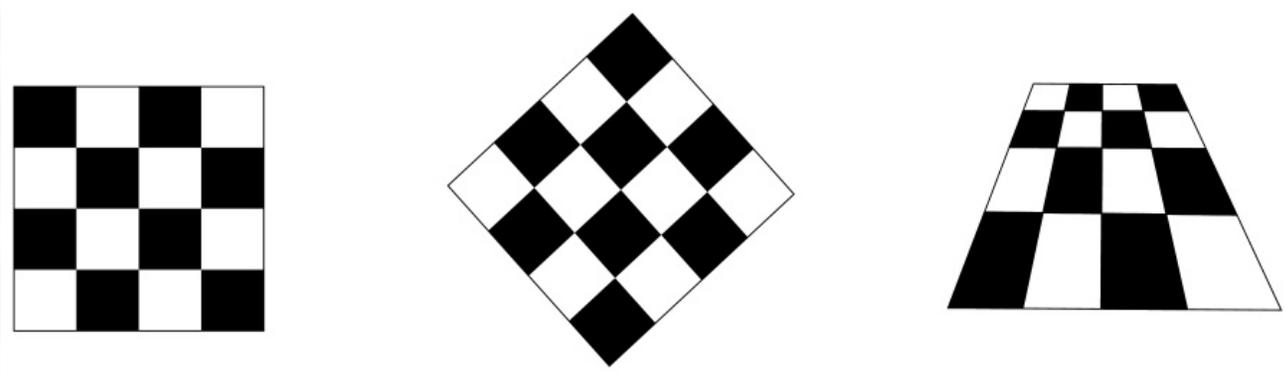
# Non-parametric texture mapping



- With “non-parametric texture mapping”:
  - Texture size and orientation are fixed
  - They are unrelated to size and orientation of polygon
  - Gives cookie-cutter effect



# Parametric texture mapping

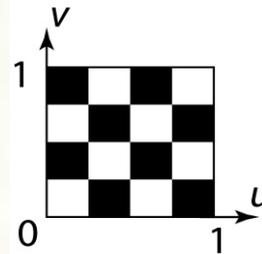


- With “parametric texture mapping,” texture size and orientation are tied to the polygon.
- Idea:
  - Separate “texture space” and “screen space”
  - Texture the polygon as before, but in texture space
  - Deform (render) the textured polygon into screen space
- A texture can modulate just about any parameter – diffuse color, specular color, specular exponent, ...

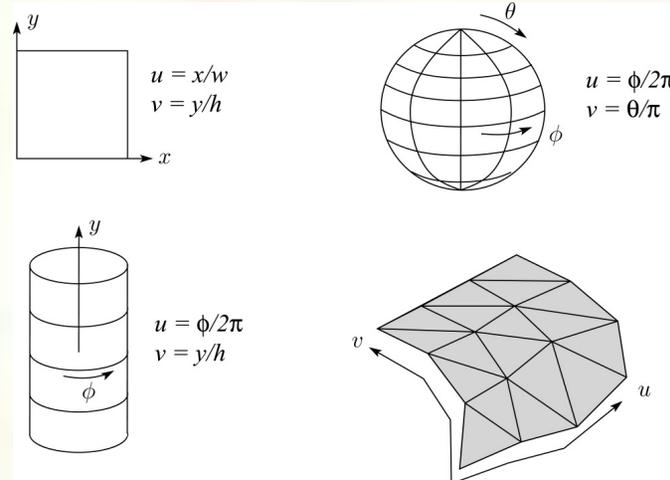


# Implementing texture mapping

- A texture lives in its own abstract image coordinates parameterized by  $(u, v)$  in the range  $([0..1], [0..1])$ :



- It can be wrapped around many different surfaces:



- Computing  $(u, v)$  texture coordinates in a ray tracer is fairly straightforward.
- Note: if the surface moves/deforms, the texture goes with it.



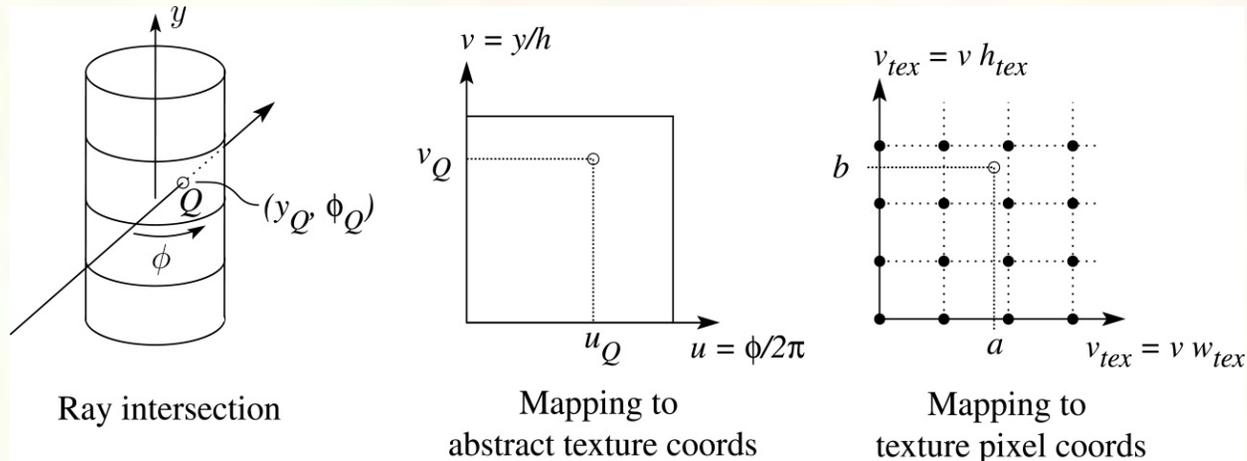
# Mapping to texture image coords

- The texture is usually stored as an image. Thus, we need to convert from abstract texture coordinate:

$(u, v)$  in the range  $([0..1], [0..1])$

to texture image coordinates:

$(u_{tex}, v_{tex})$  in the range  $([0.. w_{tex}], [0.. h_{tex}])$

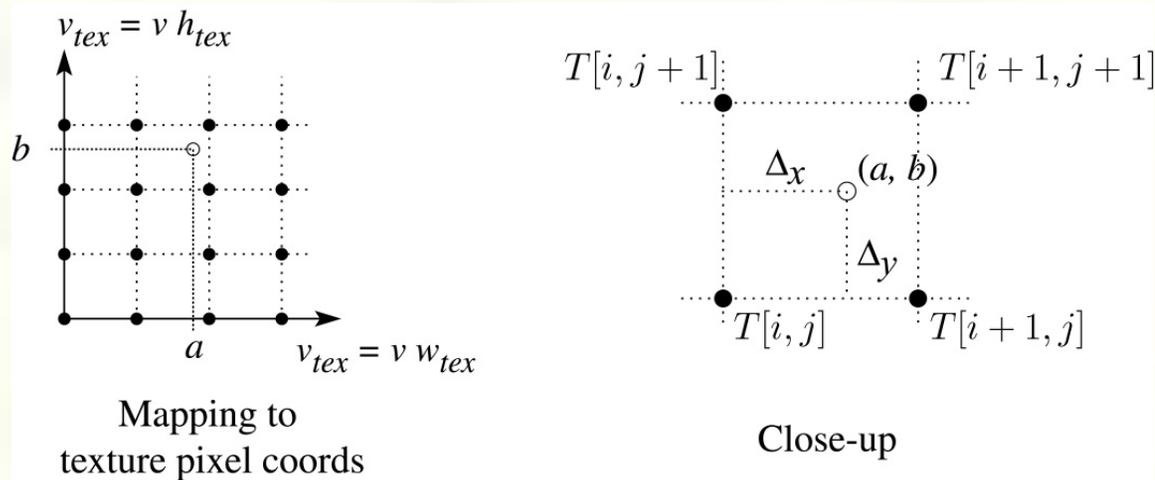


- **Q:** What do you do when the texture sample you need lands between texture pixels?



# Texture resampling

- We need to resample the texture:



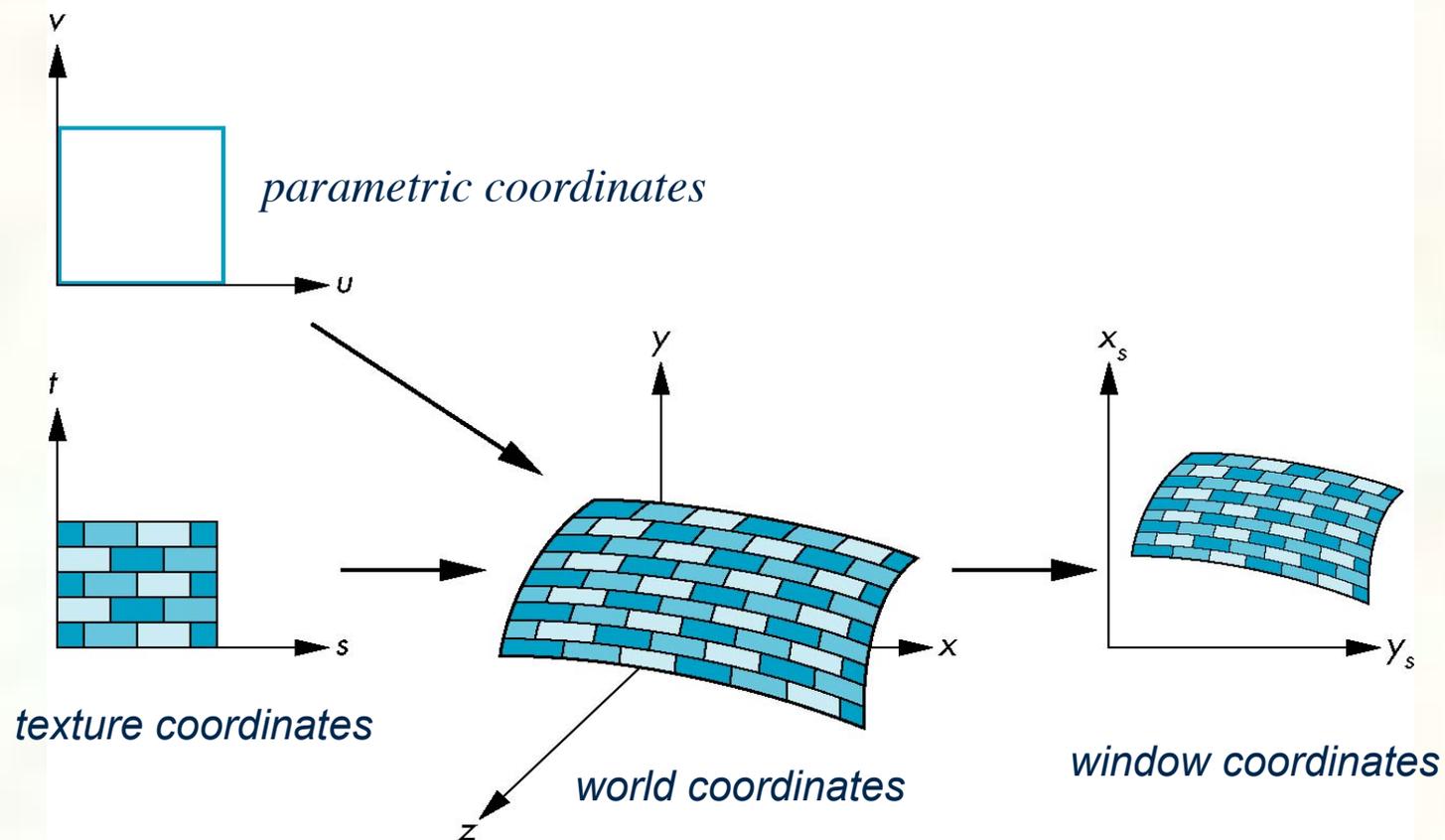
- A common choice is **bilinear interpolation**:

$$\begin{aligned} T(a,b) &= T[i + \Delta_x, j + \Delta_y] \\ &= (1 - \Delta_x)(1 - \Delta_y)T[i, j] + \Delta_x(1 - \Delta_y)T[i + 1, j] \\ &\quad + (1 - \Delta_x)\Delta_y T[i, j + 1] + \Delta_x\Delta_y T[i + 1, j + 1] \end{aligned}$$



# Texture Coordinates

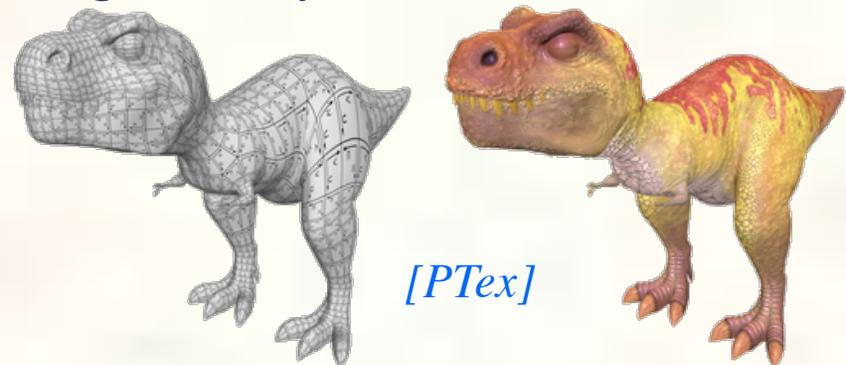
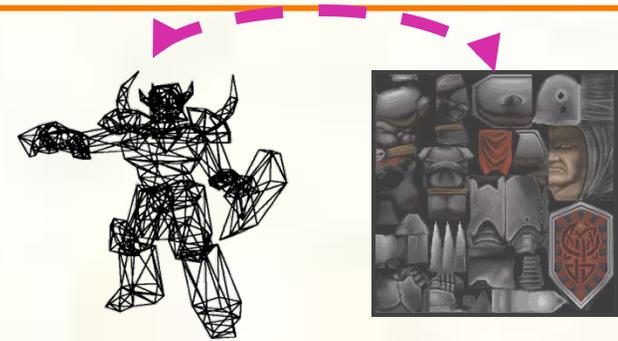
- Interpolated over rasterized primitives





# Source of texture coordinates?

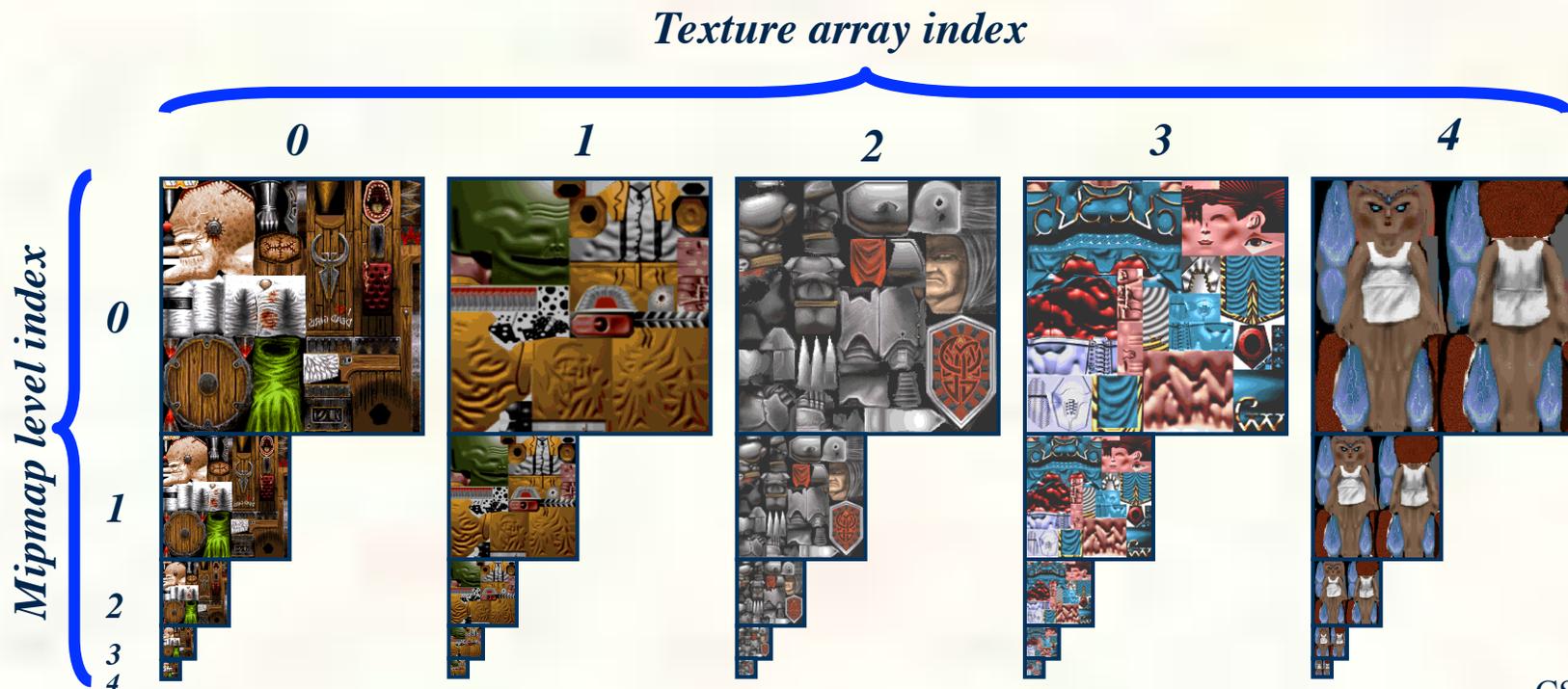
- Assigned ad-hoc by artist
  - Tedious!
  - Has gift wrapping problem
- Computed based on XYZ position
  - Texture coordinate generation (“texgen”)
  - Hard to map to “surface space”
  - Function maps  $(x,y,z)$  to  $(s,t,r,q)$
- From bi-variate parameterization of geometry
  - Good when geometry is generated from patches
  - So  $(u,v)$  of patch maps to  $(x,y,z)$  and  $(s,t)$





# Texture Arrays

- **Multiple skins packed in texture array**
  - Motivation: binding to one multi-skin texture array avoids texture bind per object





# Textured Polygonal Models



*Key-frame  
model  
geometry*



*Decal  
skin*



*Result*

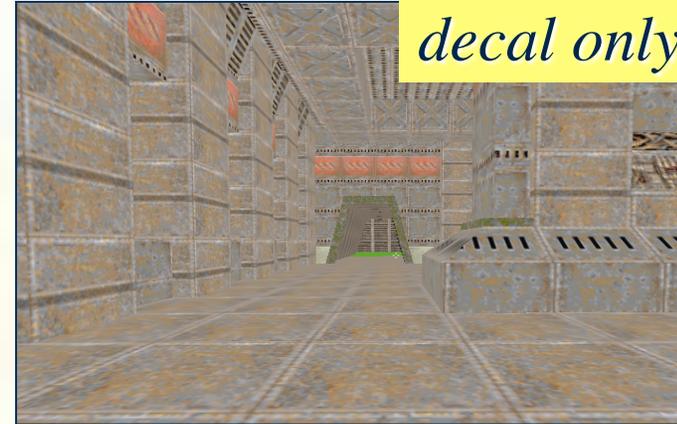


# Multiple Textures



*lightmaps only*

×  
(modulate)



*decal only*

=



*combined scene*

*\* Id Software's Quake 2  
circa 1997*



# Can define material by program

- A 'surface shader' computes the color of each ray that hits the surface.
- Example: Renderman surface shader

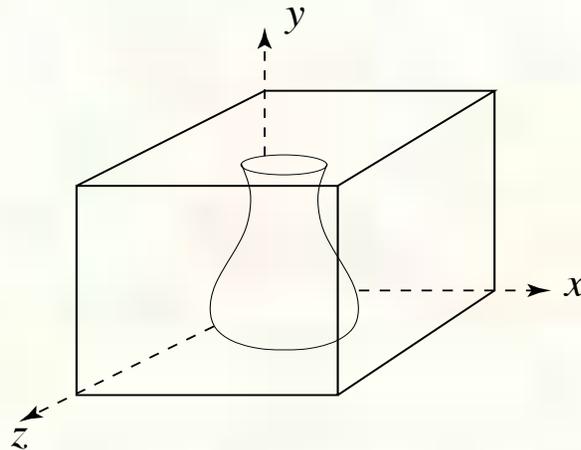
```
/*  
 * Checkerboard  
 */  
surface checker(float Kd=.5, Ka=.1) {  
    float smod = mod(10*s, 1);  
    float tmod = mod(10*t, 1);  
    if (smod < 0.5) {  
        if (tmod < 0.5) Ci=Cs; else Ci=color(0,0,0);  
    } else {  
        if (tmod < 0.5) Ci=color(0,0,0); else Ci=Cs;  
    }  
    Oi = Os;  
    Ci = Oi*Ci*(  
        Ka*ambient() +  
        Kd*diffuse(faceforward(normalize(N),I)));  
}
```





# Solid textures

- **Q:** What kinds of artifacts might you see from using a marble veneer instead of real marble?



- One solution is to use **solid textures**:
  - Use model-space coordinates to index into a 3D texture
  - Like “carving” the object from the material
- One difficulty of solid texturing is coming up with the textures.



# Solid textures (cont'd)

- Here's an example for a vase cut from a solid marble texture:

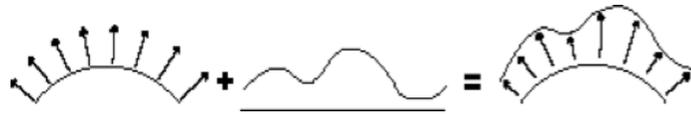


- *Solid marble texture by Ken Perlin, (Foley, IV-21)*



# Displacement and Bump Mapping

- Use surface offsets stored in texture
  - Perturb or displace the surface
  - Shade on the resulting surface normals



$$\mathbf{P}(u,v)$$

$$\mathbf{S}(u,v) = \frac{\partial \mathbf{P}(u,v)}{\partial u} \quad \mathbf{T}(u,v) = \frac{\partial \mathbf{P}(u,v)}{\partial v}$$

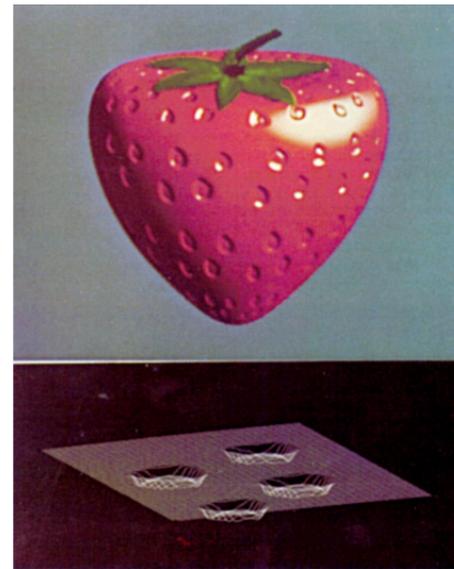
$$\mathbf{N}(u,v) = \mathbf{S} \times \mathbf{T}$$

- **Displacement**

$$\mathbf{P}'(u,v) = \mathbf{P}(u,v) + h(u,v)\mathbf{N}(u,v)$$

- **Perturbed normal**

$$\begin{aligned} \mathbf{N}'(u,v) &= \mathbf{P}'_u \times \mathbf{P}'_v \\ &= \mathbf{N} + h_u(\mathbf{T} \times \mathbf{N}) + h_v(\mathbf{S} \times \mathbf{N}) \end{aligned}$$



From Blinn 1976



# Normal Mapping

- Bump mapping via a normal map texture
  - Normal map – x,y,z components of actual normal
  - Instead of a height field 1 value per pixel
  - The normal map can be generated from the height field
  - Otherwise have to orient the normal coordinates to the surface



*diffuse*



*decal*



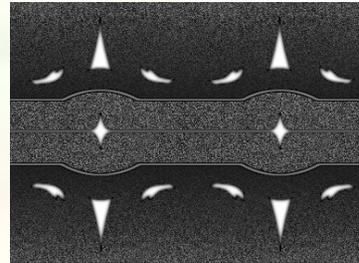
*specular*



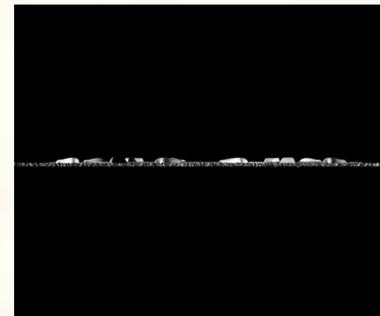
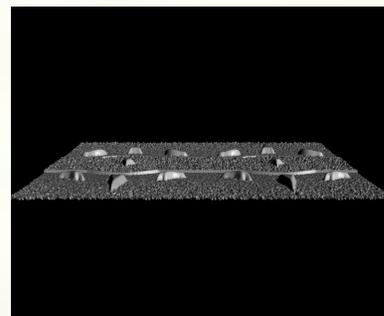
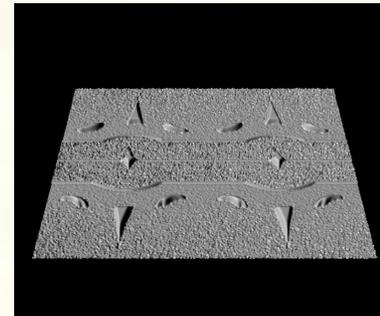
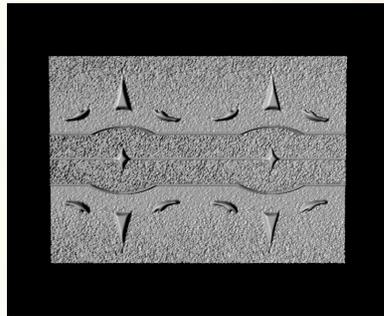


# Displacement vs. bump mapping

- Input texture

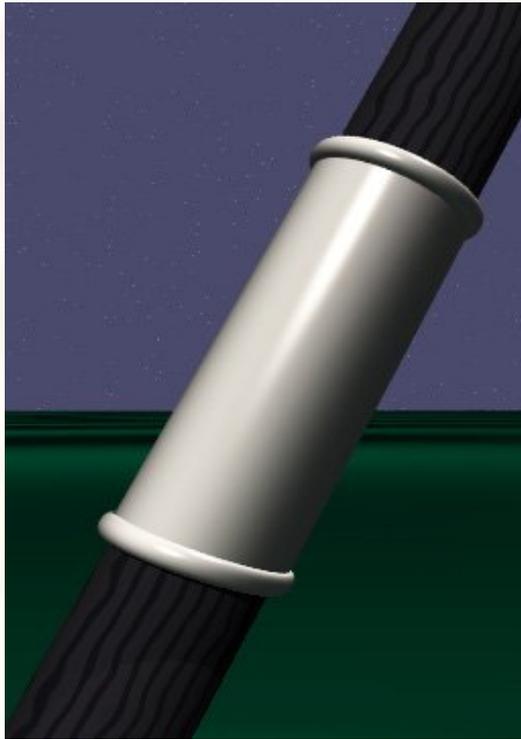


- Rendered as displacement map over a rectangular surface





# Displacement vs. bump mapping (cont'd)



Original rendering

cylinder



Rendering with bump map  
wrapped around a

*Bump map and rendering by Wyvern Aldinger*

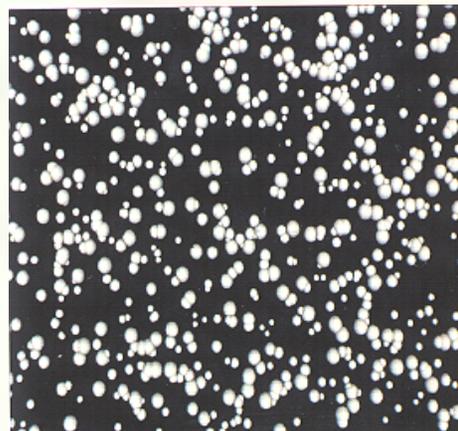


# Bump mapping example

Texture #1  
(diffuse color)



Texture #2  
(bump map)



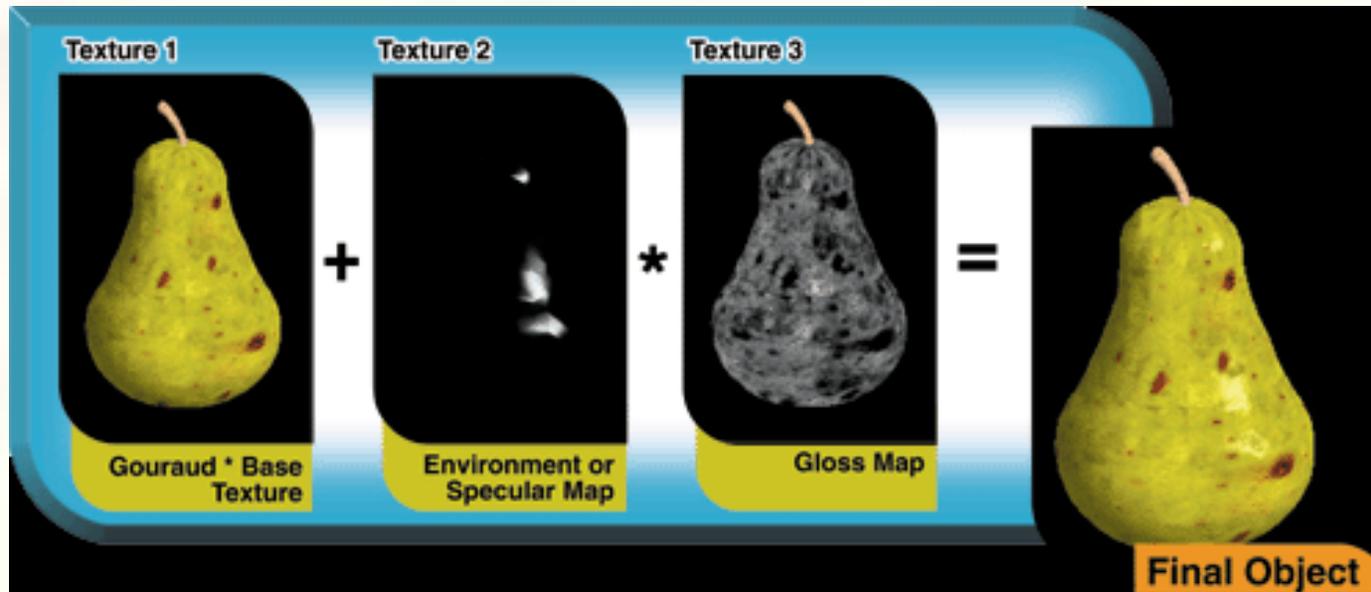
Rendered Image





# Combining texture maps

- Using texture maps in combination gives even better effects.



*Diffuse  
color*

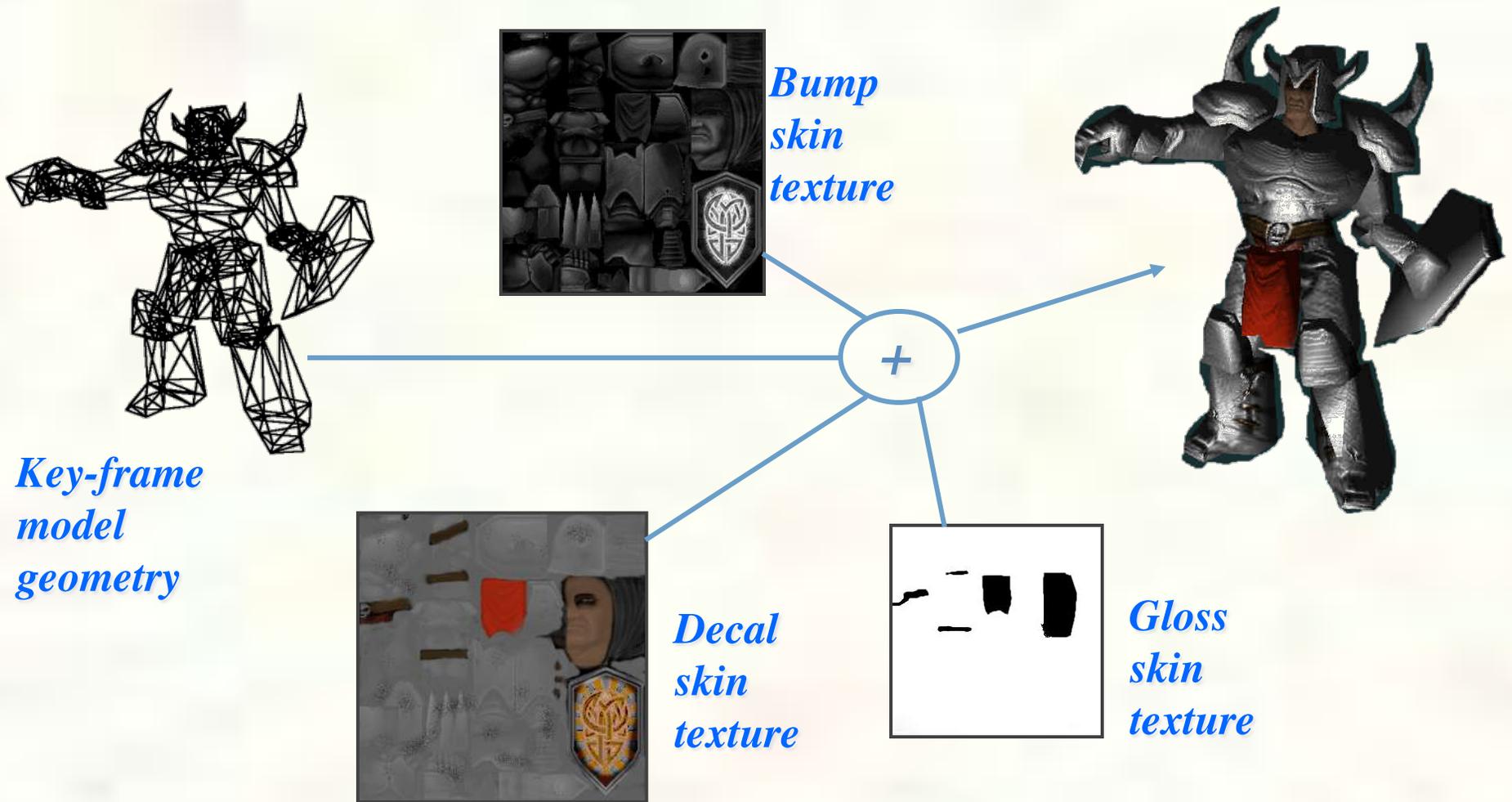
*Environment map  
(not necessary  
in ray tracer)*

*Specular  
coefficient*

*Material  
properties  
(coefficients  
in shading  
equation)*



# Multiple Textures





# Multitexturing

$$\left( \text{Diffuse} \times \text{Decal} \right) + \left( \text{Specular} \times \text{Gloss} \right) =$$

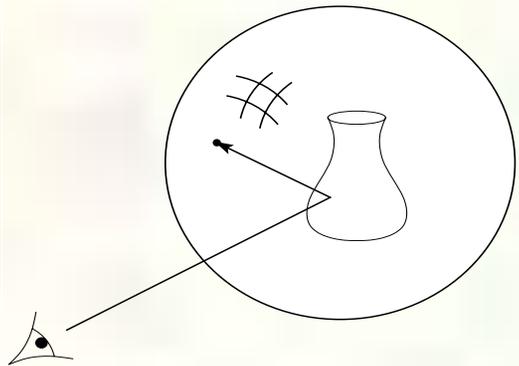
*Diffuse*      *Decal*      *Specular*      *Gloss*



*Final result!*



# Environment mapping

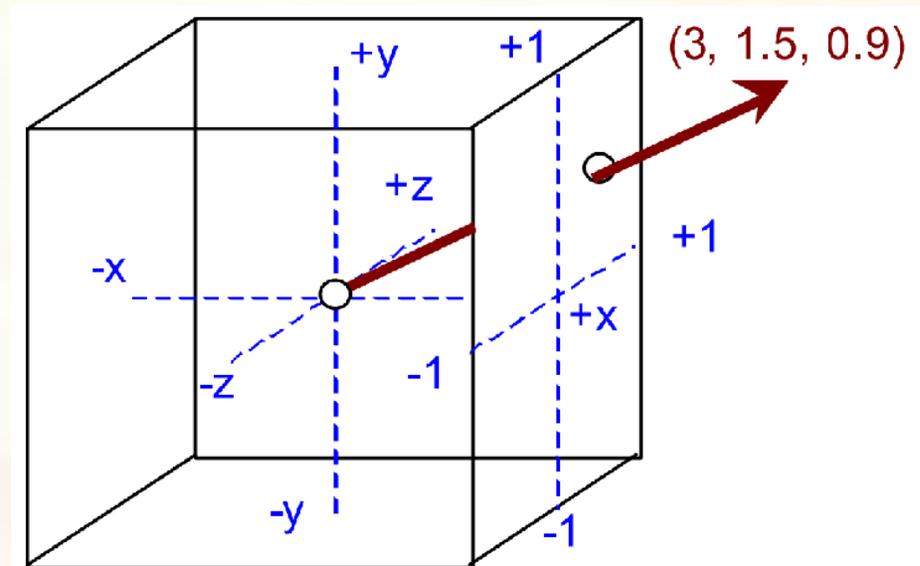
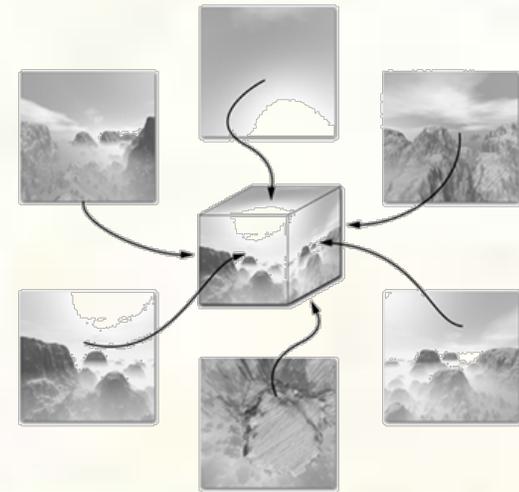


- In **environment mapping** (also known as **reflection mapping**), a texture is used to model an object's environment:
  - Rays are bounced off objects into environment
  - Color of the environment used to determine color of the illumination
  - Really, a simplified form of ray tracing
  - Environment mapping works well when there is just a single object – or in conjunction with ray tracing
- Under simplifying assumptions, environment mapping can be implemented in hardware.
- With a ray tracer, the concept is easily extended to handle refraction as well as reflection.



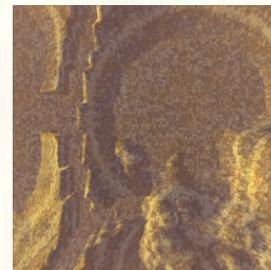
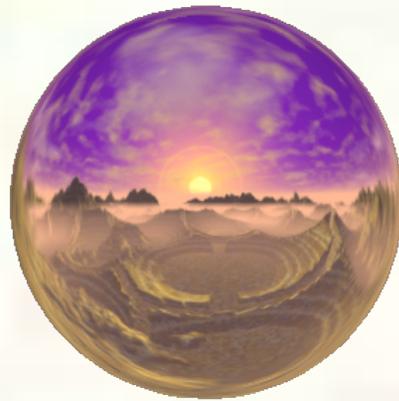
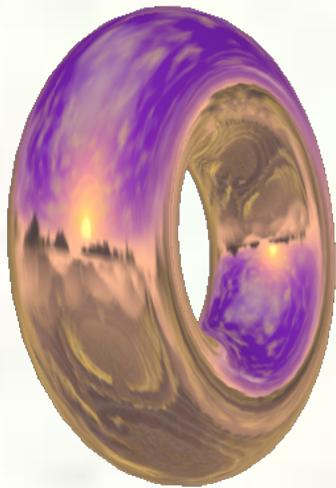
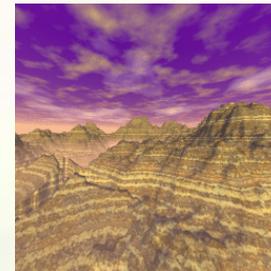
# Cube Map Textures

- Instead of one 2D images
  - Six 2D images arranged like the faces of a cube
    - +X, -X, +Y, -Y, +Z, -Z
- Indexed by 3D  $(s, t, r)$  un-normalized vector
  - Instead of 2D  $(s, t)$
  - Where on the cube images does the vector “poke through”?
    - That’s the texture result



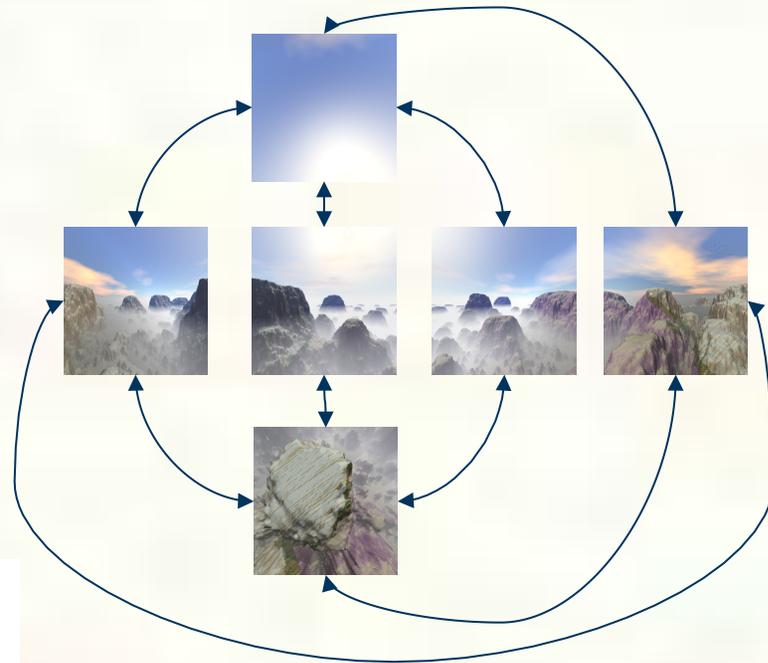
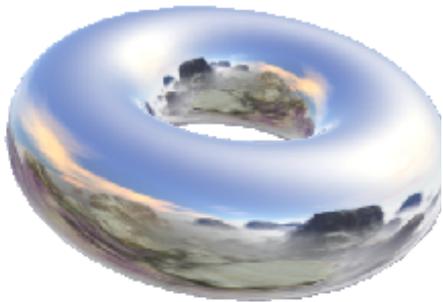


# More Cube Mapping





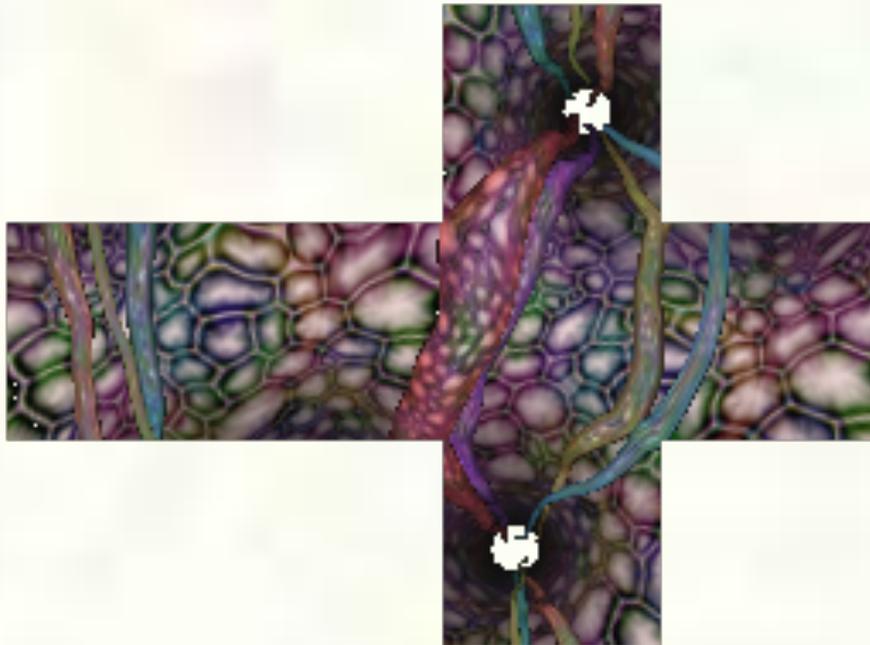
# Omni-directional Lighting



*Access texture  
by surface reflection  
vector*



# Dynamic Cube Map Textures

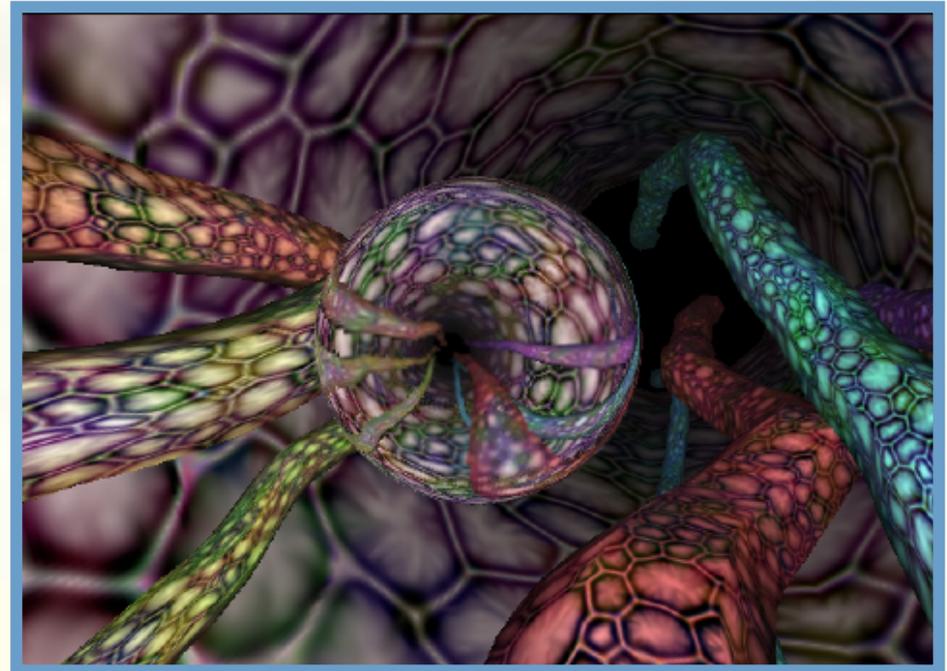


*Dynamically created  
cube map image*

*Image credit:*

*“Guts” GeForce 2 GTS demo,  
Thant Thessman*

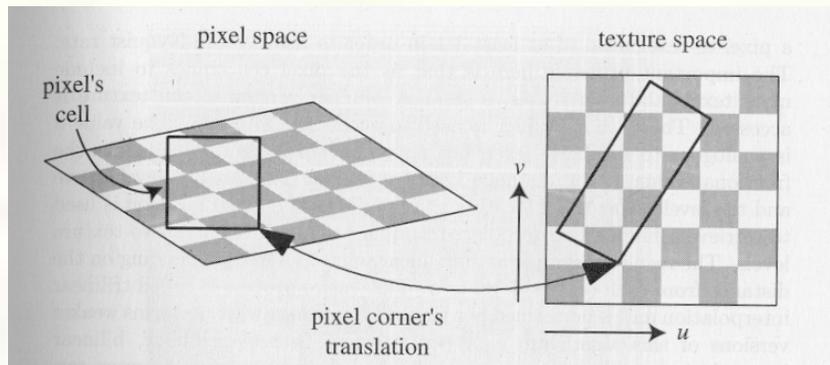
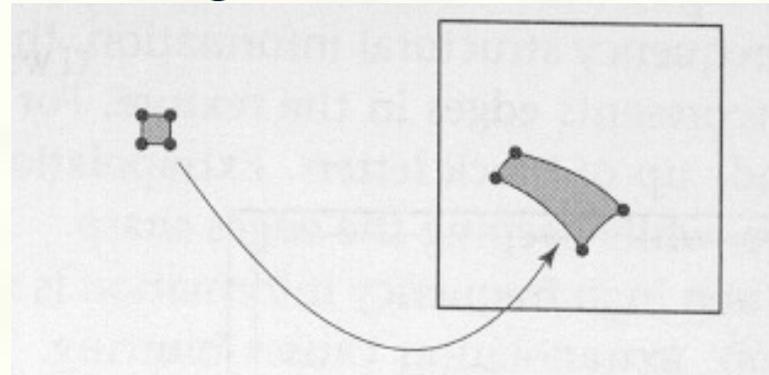
*Rendered scene*





# How do we anti-alias textures?

- We could just super-sample.
- But textures (and shader programs) are a special case; we can use true area integration!



- *Approximate footprint as parallelogram*
- *Determine this approximate footprint using discrete differences*



# Pre-filtered Image Versions

- Base texture image is say 256x256
  - Then down-sample 128x128, 64x64, 32x32, all the way down to 1x1



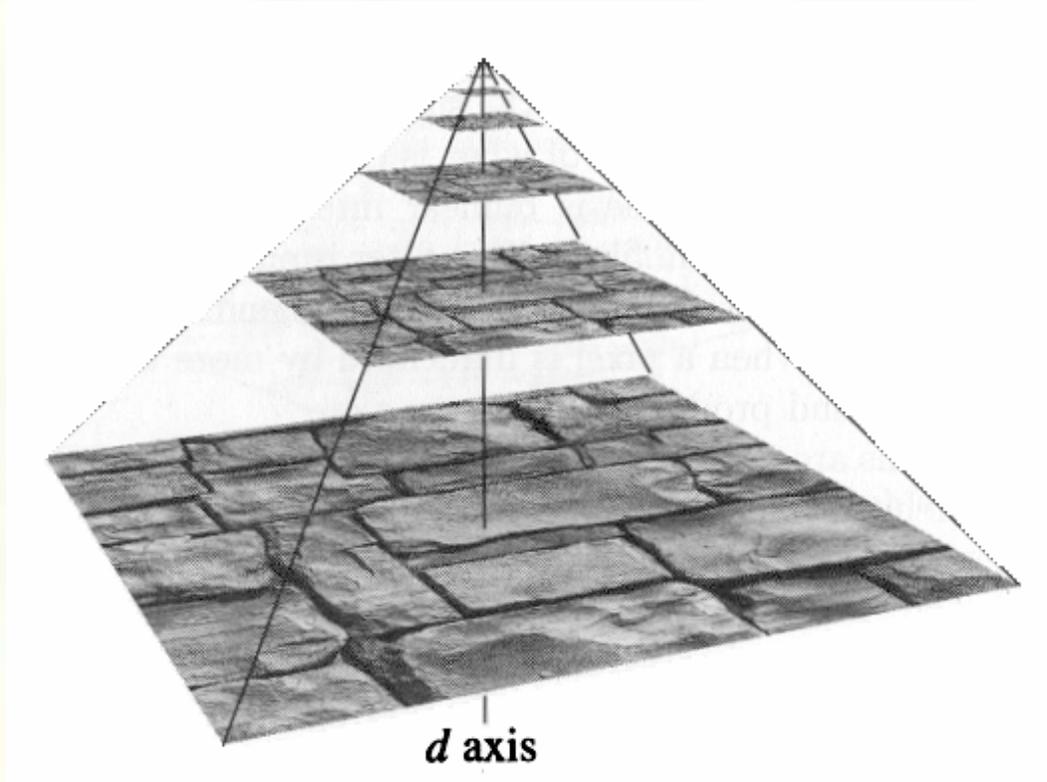
*Trick:* When sampling the texture, pixel the mipmap level with the closest mapping of pixel to texel size

*Why?* Hardware wants to sample just a small (1 to 8) number of samples for every fetch—and want constant time access



# Cost of filtering can be reduced

- Store a pyramid of pre-filtered images:

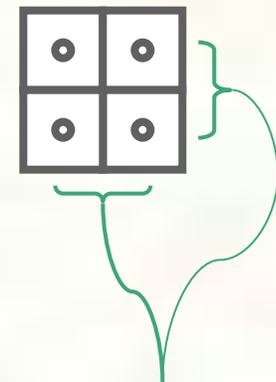


- During texture lookup, read from appropriate level of the pyramid.



# Mipmap LOD Selection

- Tri-linear mip-mapping means compute appropriate mipmap level
- Hardware rasterizes in 2x2 pixel entities
  - Typically called quad-pixels or just *quad*
  - Finite difference with neighbors to get change in  $u$  and  $v$  with respect to window space
    - Approximation to  $\partial u/\partial x$ ,  $\partial u/\partial y$ ,  $\partial v/\partial x$ ,  $\partial v/\partial y$
    - Means 4 subtractions per quad (1 per pixel)
- Now compute approximation to gradient length
  - $p = \max(\text{sqrt}((\partial u/\partial x)^2 + (\partial u/\partial y)^2), \text{sqrt}((\partial v/\partial x)^2 + (\partial v/\partial y)^2))$



*one-pixel separation*



# LOD Bias and Clamping

---

- Convert  $p$  length to power-of-two level-of-detail and apply LOD bias
  - $\lambda = \log_2(p) + \text{lodBias}$
- Now clamp  $\lambda$  to valid LOD range
  - $\lambda' = \max(\text{minLOD}, \min(\text{maxLOD}, \lambda))$



# Determine Levels and Interpolant

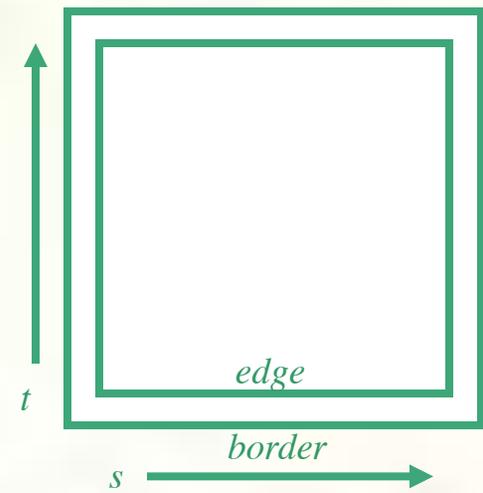
---

- Determine lower and upper mipmap levels
  - $b = \text{floor}(\lambda')$  is bottom mipmap level
  - $t = \text{floor}(\lambda' + 1)$  is top mipmap level
- Determine filter weight between levels
  - $w = \text{frac}(\lambda')$  is filter weight



# Determine Texture Sample Point

- Get  $(u,v)$  for selected top and bottom mipmap levels
  - Consider a level  $l$  which could be either level  $t$  or  $b$ 
    - With  $(u,v)$  locations  $(u_l, v_l)$
- Perform `GL_CLAMP_TO_EDGE` wrap modes
  - $u_w = \max(1/2 * \text{widthOfLevel}(l), \min(1 - 1/2 * \text{widthOfLevel}(l), u))$
  - $v_w = \max(1/2 * \text{heightOfLevel}(l), \min(1 - 1/2 * \text{heightOfLevel}(l), v))$
- Get integer location  $(i,j)$  within each level
  - $(i,j) = ( \text{floor}(u_w * \text{widthOfLevel}(l)), \text{floor}(v_w * \text{heightOfLevel}(l)) )$





# Determine Texel Locations

---

- Bilinear sample needs 4 texel locations
  - $(i_0, j_0), (i_0, j_1), (i_1, j_0), (i_1, j_1)$
- With integer texel coordinates
  - $i_0 = \text{floor}(i-1/2)$
  - $i_1 = \text{floor}(i+1/2)$
  - $j_0 = \text{floor}(j-1/2)$
  - $j_1 = \text{floor}(j+1/2)$
- Also compute fractional weights for bilinear filtering
  - $a = \text{frac}(i-1/2)$
  - $b = \text{frac}(j-1/2)$



# Determine Texel Addresses

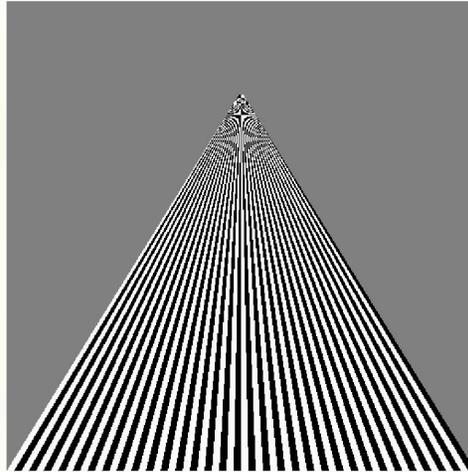
---

- Assuming a texture level image's base pointer, compute a texel address of each texel to fetch
  - Assume  $\text{bytesPerTexel} = 4$  bytes for RGBA8 texture
- Example
  - $\text{addr00} = \text{baseOfLevel}(l) + \text{bytesPerTexel} * (i_0 + j_0 * \text{widthOfLevel}(l))$
  - $\text{addr01} = \text{baseOfLevel}(l) + \text{bytesPerTexel} * (i_0 + j_1 * \text{widthOfLevel}(l))$
  - $\text{addr10} = \text{baseOfLevel}(l) + \text{bytesPerTexel} * (i_1 + j_0 * \text{widthOfLevel}(l))$
  - $\text{addr11} = \text{baseOfLevel}(l) + \text{bytesPerTexel} * (i_1 + j_1 * \text{widthOfLevel}(l))$
- More complicated address schemes are needed for good texture locality!

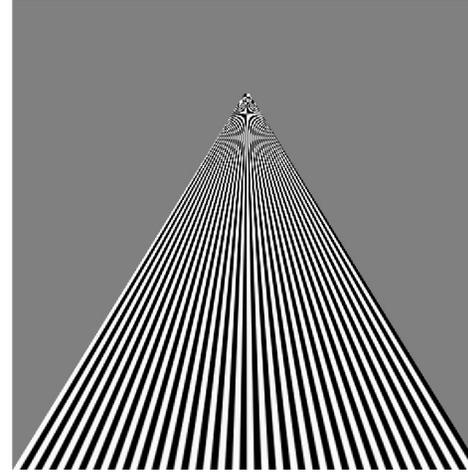


# Mipmap Texture Filtering

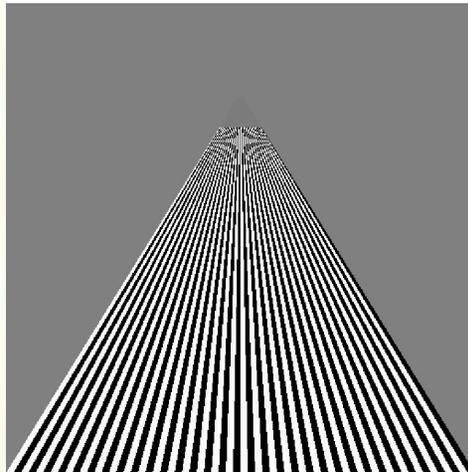
*point  
sampling*



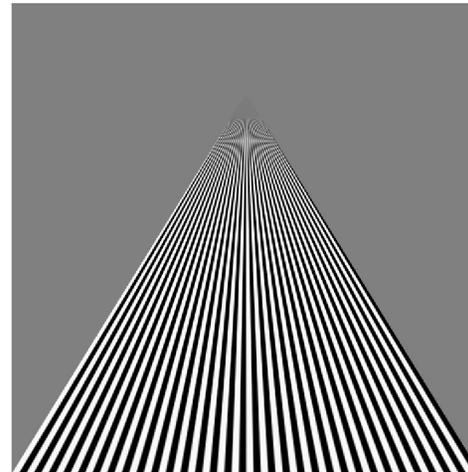
*linear  
filtering*



*mipmapped  
point  
sampling*



*mipmapped  
linear  
filtering*





# Anisotropic Texture Filtering

- Standard (isotropic) mipmap LOD selection
  - Uses magnitude of texture coordinate gradient (not direction)
  - Tends to spread blurring at shallow viewing angles
- Anisotropic texture filtering considers gradients direction
  - Minimizes blurring



*Isotropic*



*Anisotropic*