

Progress–Safety–Safety

Notes on UNITY: 05-89

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4/20/89

The PSP rule (PSP is an abbreviation for Progress–Safety–Progress) is a fundamental rule for deriving a progress property from a progress and a safety property. We had no analogous rule for deriving a nontrivial safety property from a progress and a safety property. This note contains such a rule.

Theorem:

$$\frac{p \mapsto q, \neg r \wedge \neg q \text{ is stable}}{p \Rightarrow q \vee r, \quad p \text{ unless } (\neg p \wedge r) \vee q}$$

Proof of $p \Rightarrow q \vee r$

$$\begin{array}{ll} p \mapsto q & , \text{ antecedent} \\ \neg r \wedge \neg q \text{ is stable} & , \text{ antecedent} \\ p \wedge \neg r \wedge \neg q \mapsto \text{false} & , \text{ PSP rule on the above two} \\ \neg(p \wedge \neg r \wedge \neg q) & , \text{ impossibility rule on the above} \\ p \Rightarrow q \vee r & , \text{ rewriting the above} \end{array}$$

Proof of $p \text{ unless } (\neg p \wedge r) \vee q$:

Crucial to this proof is a recent result due to Ambuj Singh [1] which says that given $p \mapsto q$ there is a predicate s such that

$$\begin{array}{ll} p \Rightarrow s, & (1) \\ s \text{ unless } q & (2) \\ s \mapsto q & (3) \end{array}$$

Also we have from the antecedent

$$\neg r \wedge \neg q \text{ is stable} \quad (4)$$

Now

*This work was partially supported by ONR Contracts N00014-87-K-0510 and N00014-86-0763, by a grant from the John Simon Guggenheim Foundation.

$$\begin{aligned}
& s \wedge \neg r \wedge \neg q \mapsto \text{false} \\
& \quad , \text{PSP on (3) and (4)} \\
& s \Rightarrow q \vee r \\
& \quad , \text{impossibility theorem on the above and then rewriting} \\
& p \text{ unless } \neg p \\
& \quad , \text{property of } \textit{unless} \\
& s \text{ unless } q \\
& \quad , \text{repeating (2)} \\
& p \wedge s \text{ unless } (p \wedge q) \vee (\neg p \wedge s) \vee (\neg p \wedge q) \\
& \quad , \text{conjunction of the above two} \\
& p \wedge s \text{ unless } (\neg p \wedge s) \vee q \\
& \quad , \text{rewriting the rhs of the above} \\
& p \text{ unless } (\neg p \wedge s) \vee q \\
& \quad , \text{simplifying the lhs using (1)} \\
& p \text{ unless } [\neg p \wedge (q \vee r)] \vee q \\
& \quad , \text{weakening the rhs using (5)} \\
& p \text{ unless } (\neg p \wedge r) \vee q \\
& \quad , \text{simplifying the rhs}
\end{aligned} \tag{5}$$

□

The following corollary was proven in [1]. Now we have a trivial proof.
Corollary 1:

$$\frac{p \mapsto q, \neg p \wedge \neg q \text{ is stable}}{p \text{ unless } q}$$

Proof: Replace r by p in the second consequent of the theorem. □

Corollary 2:

$$\frac{\begin{array}{l} p \mapsto q, \\ \neg r \wedge \neg q \text{ is stable}, \\ p \text{ unless } \neg r \end{array}}{p \text{ unless } q}$$

Proof:

$$\begin{aligned}
& p \text{ unless } (\neg p \wedge r) \vee q \\
& \quad , \text{from the second consequent of the theorem} \\
& p \text{ unless } \neg r \\
& \quad , \text{from the antecedent of the corollary} \\
& p \text{ unless } (p \wedge \neg r) \vee (p \wedge q) \vee (q \wedge \neg r) \\
& \quad , \text{conjunction of the above two} \\
& p \text{ unless } (p \wedge \neg r) \vee q \\
& \quad , \text{weakening the rhs of the above} \\
& p \text{ unless } q \\
& \quad , \text{weakening the rhs using } p \wedge \neg r \Rightarrow q \\
& \quad \quad (\text{from the first consequent of the theorem})
\end{aligned}$$

□

References

1. Jayadev Misra, "A Theorem Relating *leads-to* and *unless*," *Notes on UNITY: 04-88*, The University of Texas, Austin, Texas, December 1988.