

## Motivation

Sequence-to-sequence models are widely used for *editing* tasks in which most of the input text is preserved. Prevailing token-level copying techniques require the decoder to make several predictions to reproduce long spans of the input.

Editing natural language (e.g., Grammatical error correction):

Its **there** decision to make. → It's **their** decision to make.

Editing source code (e.g., Bug fixing):

while(i <= arr.Length) → while(i <= arr.Length-1)

**Goal:** Learn to copy long spans of the input.

## Evaluation Task #1: Bug Fixing

Given faulty code, generate the corrected version.

**Table 1:** Accuracy on BFP Dataset (Tufano et al., 2019)

	BFP <sub>small</sub>		BFP <sub>medium</sub>	
	@1	@20	@1	@20
Tufano et al. (2019)	9.2	43.5	3.2	22.2
Seq2Seq + Token Copying	14.8	42.0	7.0	23.8
Seq2Seq + Span Copying	<b>17.7</b>	<b>45.0</b>	<b>8.0</b>	<b>25.4</b>
Always Copy Longest Span	14.2	33.7	7.2	20.0
No Marginalization	16.9	43.4	2.5	11.1

Heuristic *Copy* action selection fails to capture entire spectrum of correct actions.

Equipping Seq2Seq w/ span copying achieves state-of-the-art on BFP datasets.

Marginalization incentivizes model to use as few actions as possible.

**Table 2:** Statistics on Lengths of Copied Spans

	BFP <sub>small</sub>	BFP <sub>medium</sub>
	$\mu$	9.6
Median	7.0	19.0
% of <i>Copy</i> actions yielding spans of length > 1	88.8	72.9

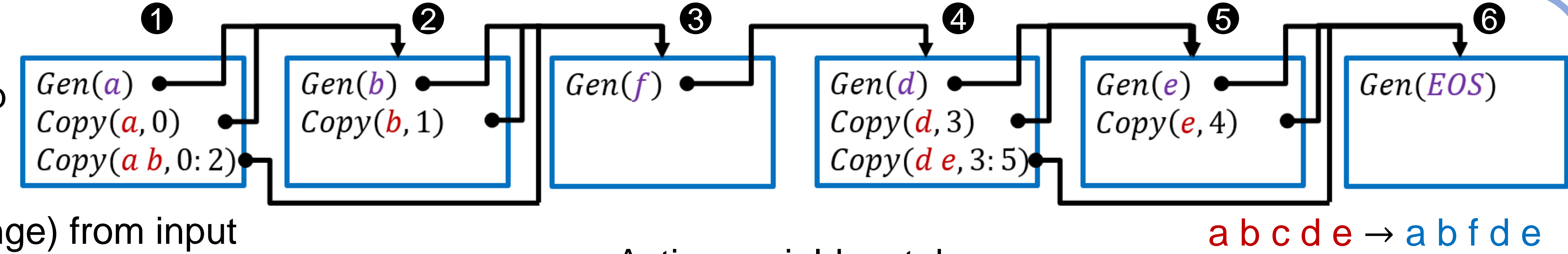
*Copy* actions tend to yield long copy spans.

## Model Overview

Correct actions  $\alpha \in A_k$  at  $k^{\text{th}}$  step

Kinds of actions ( $\alpha$ ):

- *Gen(token)* from vocabulary
- *Copy(span of tokens, pos range)* from input



### Training

**Marginalize over all possible action sequences leading to correct output sequence.**

- Maximize  $p(o_0 \dots o_m | \mathbf{in})$  defined recursively:

$$p(o_k \dots o_m | \mathbf{in}, o_0 \dots o_{k-1}) = \sum_{\substack{\alpha \in A_k \\ l = \llbracket \alpha \rrbracket}} q(\alpha | \mathbf{in}, o_0 \dots o_{k-1}) \times p(o_{k+l} \dots o_m | o_0 \dots o_{k+l-1})$$

- Probability of generating correct suffix conditioned only on subsequence generated so far, not the concrete actions
- Encourages copying longer spans through fewer # of actions

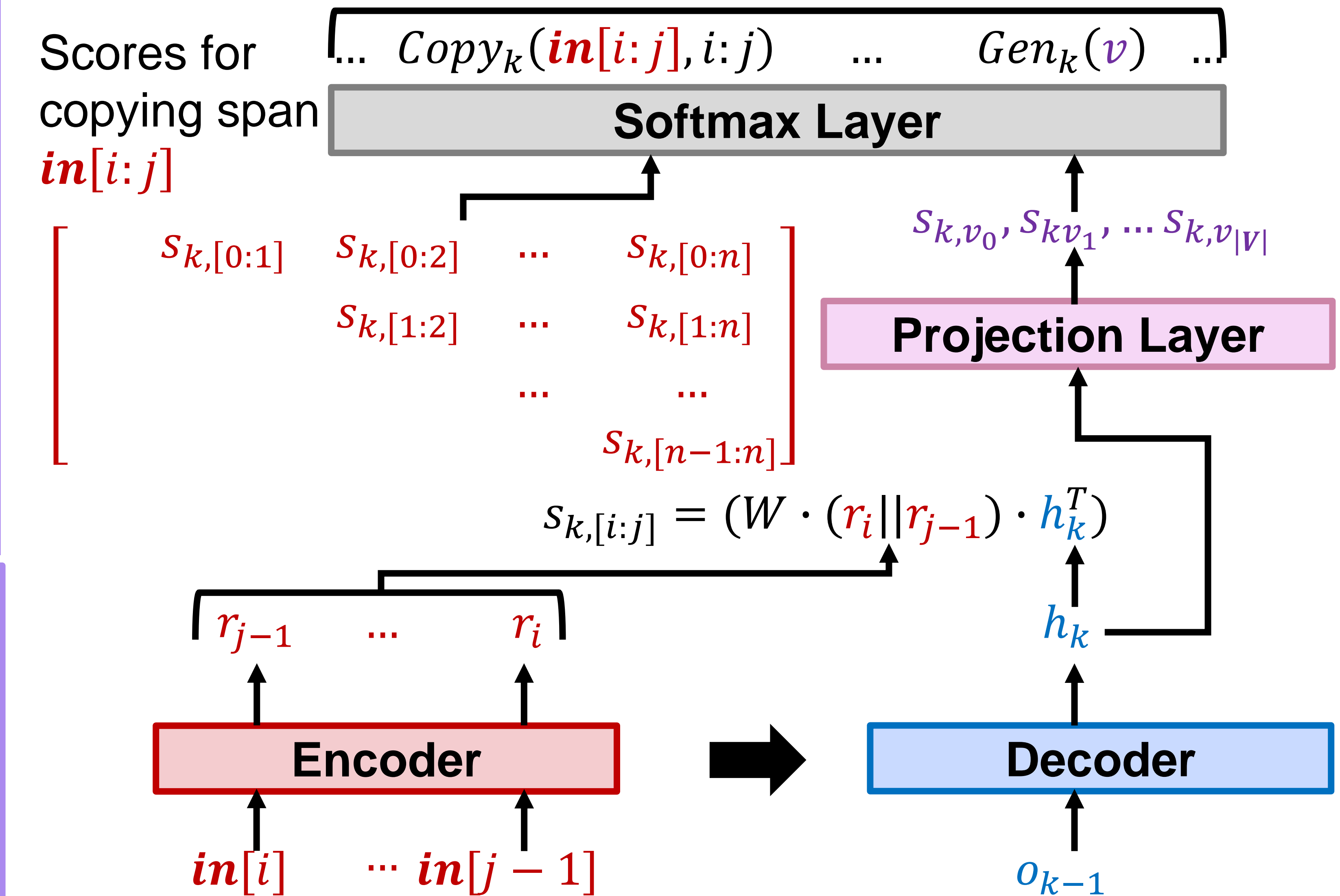
### Inference

**Generate likely action sequences through a beam search variant that is more compatible with the training objective.**

- Pause expansion when token sequence length exceeds action sequence length
- Merge rays yielding identical token sequences

Action  $\alpha$  yields a token

sequence of length  $l$   $\alpha \rightarrow o_k \dots o_{k+l}$



## Evaluation Task #2: Learning Edit Representations

Learn to embed similar edit patterns nearby in a vector space.

Span copying leads to more accurate predictions of edited text and code.

Alice Rumph was a painter, etcher, and teacher. **1**  
Alice **Edith** Rumph was a painter, etcher, and teacher.

... To the west of the Reiner crater. **3**  
... To the west of the Reiner crater **on the moon**.



Mark Taufa is an Australian professional rugby league player. **2**  
Mark **Larry** Taufa is an Australian professional rugby league player.

... had a heart attack after he was pushed by a mugger. **4**  
... had a heart attack after he was pushed by a mugger **in the market**.

**Table 3:** Accuracy on Predicting Edits

	WikiAtomicEdits	GitHubEdits
	Yin et al. (2019)	72.9
Seq2Seq + Token Copying	67.8	64.4
Seq2Seq + Span Copying	<b>78.1</b>	<b>67.4</b>

**Table 4:** Accuracy on One-Shot Transfer Task

	C# Fixers
	Seq2Seq + Token Copying
Seq2Seq + Span Copying	<b>24.2</b>

Span copying facilitates learning more generalizable edit representations.