



# Stacking With Auxiliary Features

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→ Vision



# Slot Filling

org: Microsoft

1. city\_of\_headquarters:
2. website:
3. subsidiaries:
4. employees:
5. shareholders:
- ⋮

Microsoft is a technology company,  
headquartered in Redmond, Washington  
that develops ...

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**provenance:**



**confidence score:**

1.0



# Entity Discovery and Linking (EDL)

## Source Corpus Document:

*Hillary Clinton* Not Talking  
About '92 *Clinton*-Gore  
Confederate Campaign  
Button..

## FreeBase entry:

Hillary Diane Rodham Clinton is a US Secretary of State, U.S. Senator, and First Lady of the United States. From 2009 to 2013, she was the 67th Secretary of State, serving under President Barack Obama. She previously represented New York in the U.S. Senate.

## FreeBase entry:

William Jefferson "Bill" Clinton is an American politician who served as the 42nd President of the United States from 1993 to 2001. Clinton was Governor of Arkansas from 1979 to 1981 and 1983 to 1992, and Arkansas Attorney General from 1977 to 1979.



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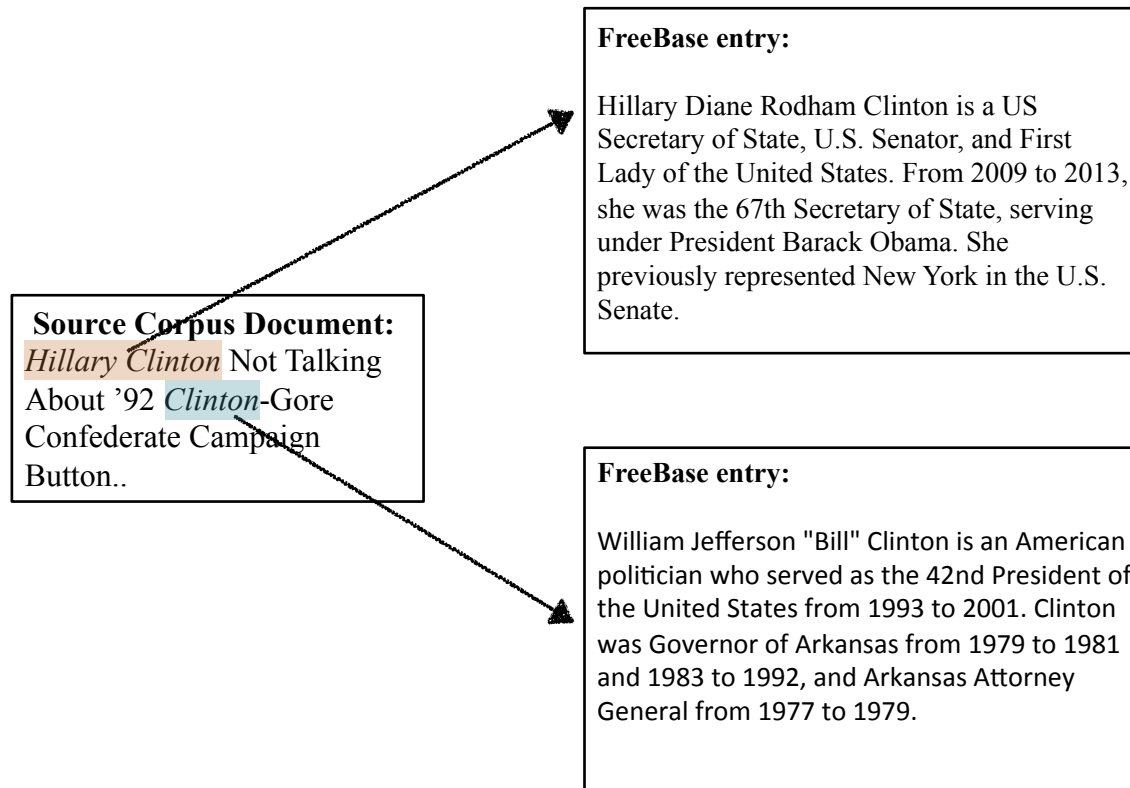
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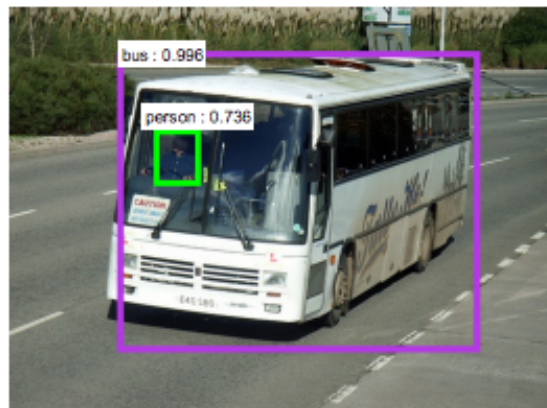
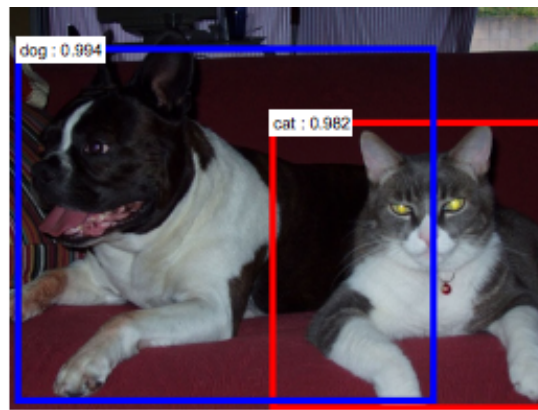
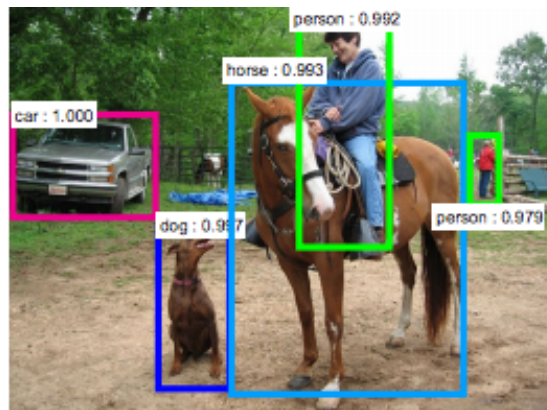
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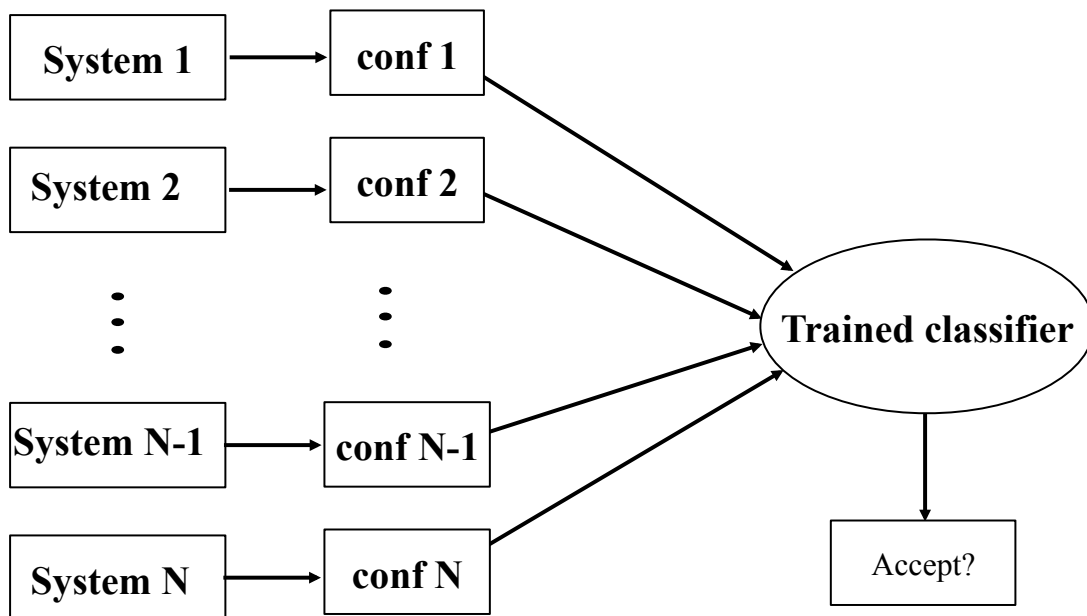


# ImageNet Object Detection



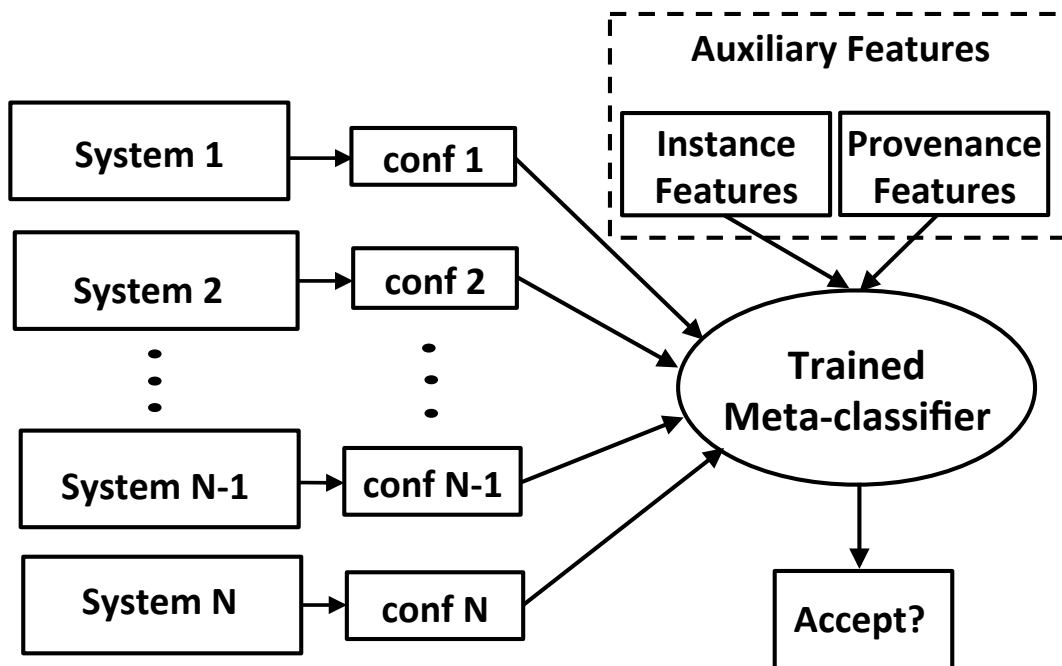
# Ensemble Algorithms

- Stacking (Wolpert, 1992)



# Stacking With Auxiliary Features (SWAF)

- Stacking using two types of auxiliary features:





# Instance Features



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- Some systems are better at certain input types
- SF — slot type (per: age)
- EDL — entity type (PER/ORG/GPE/FAC/LOC)
- Object detection — object category and VGGNet's fc7 features



# Provenance Features



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- Output is reliable if systems agree on source



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- SF and EDL — document and offset provenance
- Object detection — bounding box provenance

# Document Provenance Feature

- For a given query and slot, for each system,  $i$ , there is a feature  $DP_i$ :
  - $N$  systems provide a fill for the slot.
  - Of these,  $n$  give same provenance *docid* as  $i$ .
  - $DP_i = n/N$  is the document provenance score.
- Measures extent to which systems agree on document provenance of the slot fill.

# Offset Provenance Feature

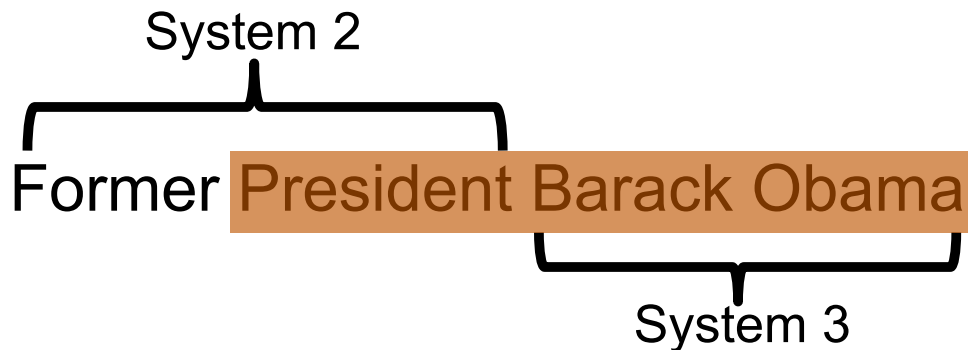
- Degree of overlap between systems' provenance strings.
- Uses Jaccard similarity coefficient.

$$OP(n) = \frac{1}{|N|} \times \sum_{i \in N, i \neq n} \frac{|substring(i) \cap substring(n)|}{|substring(i) \cup substring(n)|}$$

- Systems with different *docid* have zero OP

# Offset Provenance Feature

Offsets	System 1	System 2	System 3
Start	8	1	18
End	29	16	29

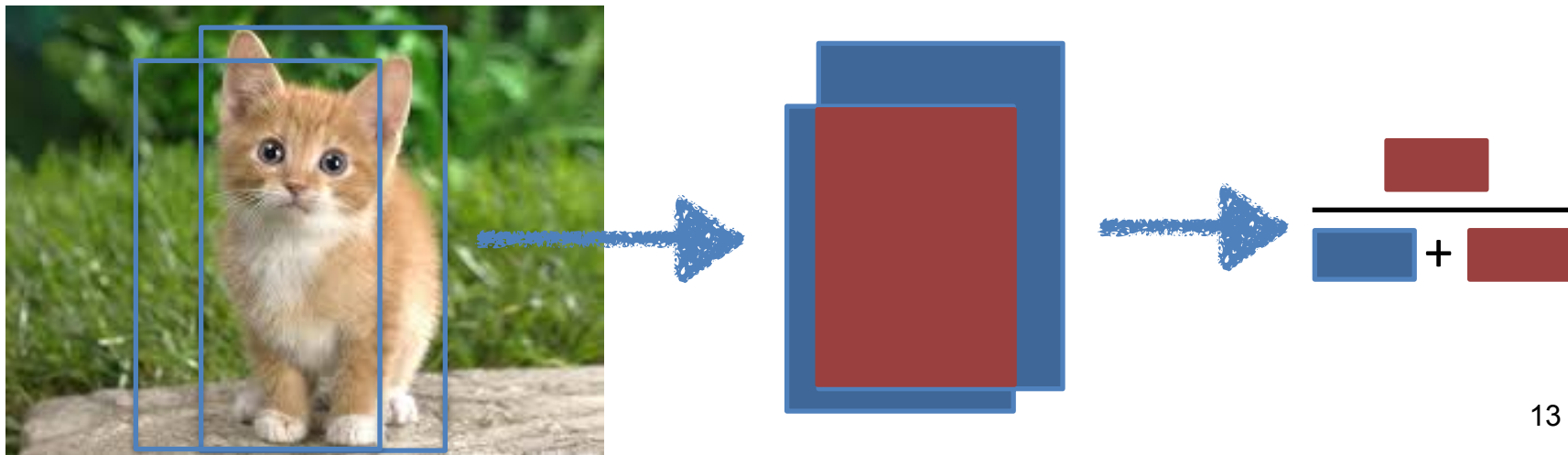


$$OP_1 = \frac{1}{2} \times \left( \frac{9}{29} + \frac{12}{21} \right)$$

# Provenance Features

- Object detection — measure BB overlap

$$BBO(n) = \frac{1}{|N|} \times \sum_{i \in N, i \neq n} \frac{|\text{Area}(i) \cap \text{Area}(n)|}{|\text{Area}(i) \cup \text{Area}(n)|}$$



# Baselines

- Mixtures of Experts (MoE) (Jacobs et al., 1991)
  - same intuition as instance auxiliary features
  - partition the problem into sub-spaces
  - learn to switch experts based on input using a gating network
- Oracle Voting
  - Vary the number of systems from 1 to  $n$  and use the one that results in best performance
  - Upper-bound on voting



# Results

- 2016 SF — 8 component systems



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- 2016 EDL — 6 component systems

Approach	Precision	Recall	F1
Oracle voting ( $\geq 4$ )	0.588	0.412	0.485
Mixtures of Experts (Jacobs et al., 1991)	0.721	0.494	0.587
Top ranked system (Sil et al., 2016)	0.717	0.517	0.601
Stacking	0.723	0.537	0.616
Stacking + instance features	0.752	0.542	0.630
Stacking + provenance features	<b>0.767</b>	0.544	0.637
SWAF	0.739	<b>0.600</b>	<b>0.662</b>

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# Results

- 2015 ImageNet object detection—  
3 component systems

Approach	Mean AP	Median AP
Oracle voting ( $\geq 1$ )	0.366	0.368
Best standalone system (VGG + selective search)	0.434	0.430
Stacking	0.451	0.441
Stacking + instance features	0.461	0.45
Mixtures of Experts (Jacobs et al., 1991)	0.494	0.489
Stacking + provenance features	0.502	0.494
<b>SWAF</b>	<b>0.506</b>	<b>0.497</b>

# Takeaways

- SWAF produced SOTA on SF and EDL
- Significant improvements on ImageNet object detection
- Our approach is more robust than MoE in terms of number of component systems
- For object detection — works well for images with multiple instances of the same object