

Generic Theories as Proof Strategies

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Outline of Talk

- Background
- Loop Invariant Theory
- Tail Recursion Theory
- Alternative Induction Theory
- An Example
- Concluding Remarks

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A Floyd-Hoare Triple

```
{ N>0 }
         X := N
         A := 0
LOOP: A := A + X
         X := X - 1
         X>0 => GO TO LOOP
         \{ A = N*(N+1)/2 \}
```

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A Floyd-Hoare Proof

Find a loop invariant R(A,X)

$$X \ge 0 \land A + X^*(X+1)/2 = N^*(N+1)/2$$

- Prove: (1) N>0 => R(0,N) (2) X>0 Λ R(A,X) => R(A+X,X-1) (3) X≤0 Λ R(A,X) => A=N*(N+1)/2
- Use identity X*(X+1)/2=X+(X-1)*X/2

Weakest Precondition Model

- Denote the postcondition by Q(A,X,N)
- Mechanically derive

$$wp(A,X,N)$$
=
if X>1 wp(A+X,X-1,N) else Q(A+X,X-1,N)

• Prove: N > 0 = > wp(0, N, N)

Attempted Weakest Precondition Proof

- Induction patterned after wp yields:
- Base case: N=1 => wp(0,N,N)
- Induction step: $N>1 \land wp(0,N-1,N-1) => wp(0,N,N)$
- Expansion of wp(0,N,N) to wp(N,N-1,N) does not match the hypothesis.



Capturing Proof Strategies

- We can prove weakest preconditions with the same ease as Floyd-Hoare.
- We will identify alternative strategies to deal with finding suitable inductions when recursive functions are applied to specialized arguments.
- We will use generic theories to capture and apply these strategies.

Loop Invariant Theory

The most general weakest precondition may be represented by:

(wp s) = (if (b s) (qp s) (wp (sigma s)))

where b is the loop exit predicate, sigma represents the loop body, and qp is the postcondition.

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Loop Invariant Theory

We constrain wp by:

$$(b s) => (wp s)=(qp s)$$

 $(not (b s)) => (wp (sigma s))=(wp s)$

 Since these are treated as rewrite rules the order of the equalities matters.

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Loop Invariant Theory

We constrain a measure function:

```
(o-p (measure s))
(not (b s)) =>
(o< (measure (sigma s)) (measure s))
```

in order to allow inductive proofs about wp.

Loop Invariant Theory

Finally, we constrain a loop invariant r by:

(not (b s))
$$\Lambda$$
 (r s) => (r (sigma s)) (2)
(b s) Λ (r s) => (qp s) (3)

from which we prove

$$(r s) => (wp s) \tag{1}$$

 This characterizes wp as the weakest loop invariant.



 Our goal in this theory is to remove the "a" component of state from the tail recursive function

```
(g a s) = (if (bb s)
(qt a s)
(g (rho a s) (tau s)))
```

where tau is measure decreasing.

Summary of the Tail Recursion Theory

 We introduce an invariant rt to capture underlying assumptions of the theory.

```
(not (bb s)) \Lambda (rt a s) =>
(rt (rho a s) (tau s))
```

Summary of the Tail Recursion Theory

 We introduce functions op, h and hs with properties that allow us to prove



Summary of the Alternative Induction Theory

This theory uses two tail recursive functions

together with a mapping id-alt from the domain of fn1 to the domain of fn2, and a loop invariant p on the domain of fn1.



Summary of the Alternative Induction Theory

The key requirement in this theory is

(not (b1 s))
$$\Lambda$$
 (p s) =>
(id-alt (sigma1 s))=(sigma2 (id-alt s))

When fn1 and fn2 are identical, this property states that id-alt and sigma1 commute.



Summary of the Alternative Induction Theory

This theory allows us to prove

$$(p s) => (fn1 s)=(fn2 (id-alt s))$$

 Notice that when fn1 and fn2 are the same and id-alt is measure decreasing, id-alt defines an alternative induction.



State consists of bytes A, N and flag C.

```
{ N>0 \( \text{NS=N \( \text{N*}(N+1)/2<256 \)} \\ \text{LDA \( \text{#0} \) load \( \text{A immediate with 0} \\ \text{CLC} \quad \text{clear the carry flag} \\ \text{LOOP:} \quad \( \text{ADC \( \text{N} \) add with carry \( \text{N to A} \) \\ \text{DEC \( \text{N} \) decrement \( \text{N by 1} \) \\ \text{BNE LOOP branch if N>0 to LOOP} \\ \{ \text{A=NS*}(NS+1)/2 \} \end{array}
```



The weakest precondition at LOOP is



Where dec is defined by

```
(defun dec (n)
(if (zp n) 255 (1- n)))
```

 The weakest precondition at the beginning of the program is

```
(defun wp-1 (n ns)
(wp-loop n 0 0 ns))
```



The proof goal is

The Automated Loop Invariant Proof

```
;;; Define the loop invariant
(defun sum-invariant (n a c ns)
 (and (not (zp n))
      (< (+ a (floor (* n (1+ n)) 2)) 256)
      (natp a)
      (equal c 0)
      (natp ns)
      (equal (+ a (floor (* n (1+ n)) 2))
             (floor (* ns (1+ ns)) 2))))
```

The Automated Loop Invariant Proof

```
;;; Instantiate the theory
(defthm wp-sum-loop-invariant
 (implies (sum-invariant n a c ns)
          (wp-loop n a c ns))
 :hints ((loop-invariant-hint; computed hint
        'wp-loop
                             ; concrete weakest precondition
        '(sum-invariant n a c ns))))
(defthm wp-loop-is-correct
 (implies (and (not (zp n))
               (equal ns n)
               (< (floor (* n (1+ n)) 2) 256))
         (wp-1 n ns)))
```



A Comparison of the Theories

We compare the theories on the sum program and the following multiply program.

```
\{ F1 = F1SAVE \land F1 < 256 \land F2 < 256 \land LOW < 256 \}
       LDX #8
                    load the X register immediate with 8
       LDA #0
                    load the A register immediate with 0
                    rotate F1 right circular through carry
LOOP
       ROR F1
       BCC ZCOEF branch on carry clear to ZCOEF
                    clear the carry flag
       CLC
                    add with carry F2 to the contents of A
       ADC F2
ZCOEF ROR A
                    rotate A right circular through carry
                    rotate LOW right circular through carry decrement the X register by 1
       ROR LOW
       DEX
       BNE LOOP branch if X is non-zero to LOOP
       \{ LOW + 256*A = F1SAVE*F2 \}
```



A Comparison of the Theories

• We count the number of supporting lemmas needed to prove the two programs with each of the generic theories. We use Robert Krug's September 2003 modified ACL2 and arithmetic-4 proof library as well as NQTHM with my modularithmetic-98 proof library.



A Comparison of the Theories

Theorem Count for the Sum Program

	Generalization	Loop Invariant	Tail Recursion	Alt. Induction
ACL2	3	4	5	4
NQTHM	2	4	4	3

Theorem Count for the Multiply Program

	Generalization	Loop Invariant	Tail Recursion	Alt. Induction
ACL2	6	12	18	11
NQTHM	8	11	19	11



Conclusions

- Without automation generic theories are cumbersome to use compared with straight forward generalization.
- With automation they are effective means for high level proof structuring.
- Based upon these examples, ACL2 and NQTHM are roughly comparable in their ability to support arithmetic proofs over the naturals.