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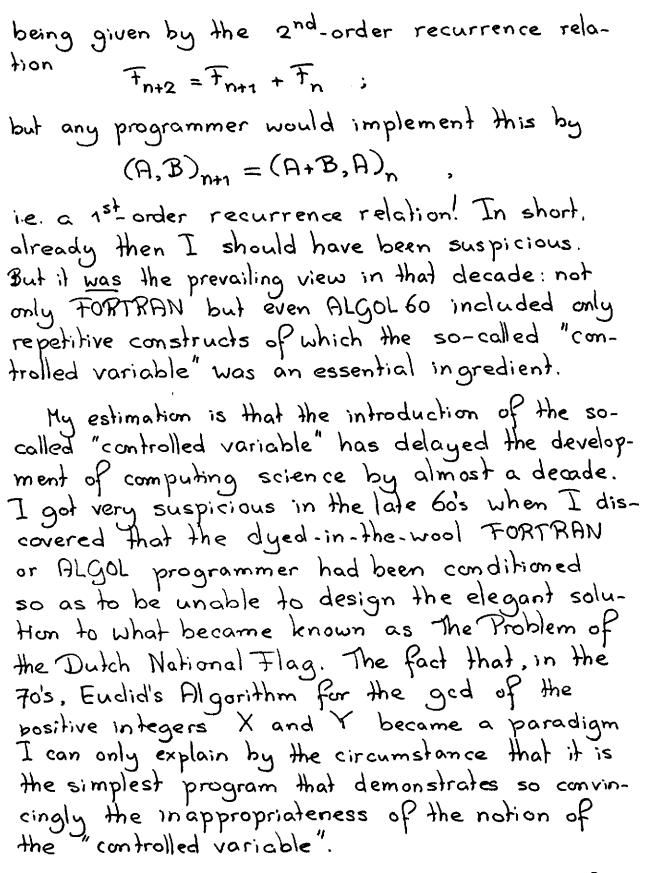
## Invariance and Nondeterminacy

An accident introduced me 32 years ago to automatic computing, a topic that has fascinated me ever since. As the years go by, I am beginning to appreciate the length of my involvement more and more, since I owe to it a very lively picture of a sizeable part of the history of the growth of a science. I have observed profound changes in our thinking habits, and I have found those observations interesting and instructive.

I do remember, for instance, one of my first efforts - in the mid 50's - to come to grips with what we would call now "repetition". It was profoundly inadequate, and in the course of this talk I hope to explain to you why. Very operationally, I tried to deal with it as a recurrence relation: one instructs the machine to start with an initial value Xo and to generate from there enough values from the sequence further defined by the recurrence relation

$$x_{i+1} = f(x_i)$$

Why did I do that? I think because I was glad to recognize something familiar, and in those days familiarity was more important than significance. The knowledge I had at the time was already sufficient to doubt the significance, but I don't remember I did. You see, a well-known concept was the "order" of a recurrence relation, the Fibonacci sequence



(Euclid's Algorithm became known in the form:

|| x,y: int ; x,y = X,Y  $; \underline{do} \times y \rightarrow x = x - y$ l y> x → y=y-x ]| ]|

This is evidently a repetition in which there is no place for a "controlled variable" counting something of relevance and/or controlling termination.)

Another accident \_ A.W. Dek's invention of the real-time interrupt - introduced me 25 years ago to nondeterminacy. My first major concern was to show that saving register contents at program inter-ruption and restoring them at program resumption could not be corrupted by the occurrence of a next interrupt. The arguments required were very tricky, so tricky as a matter of fact that I was not surprised at all when I found flaws in the designs of the interrupt facilities of later machines such as the CDC 165 and the IBM 360. I experienced the problems caused by the unpredictable interleaving as completely novel ones, not suspect-ing that, about a decade later, they would be tackled by the same techniques that would then be used for reasoning about repetitions. I am, of course, referring to the technique

of the so-called "invariant" as illustrated in the following type of annotation of a repetition -assertions being written within braces-{P}

do B→{PAB} S {P} <u>od</u> {PA3B}

In words: if assertion P, guard B, and statement S are such that the additional init. ial validity of B guarantees that execution of S does not destroy the validity of P, then the whole repetition do  $B \rightarrow S$  and will not destroy the validity of P, <u>no matter</u> <u>how often</u> the repeatable statement S is repeated.

Now, if we have, instead of a single  $B \rightarrow S$ , a bunch of those, none of which destroys the validity of P, the validity of P will not be destroyed <u>no matter how often and in</u> <u>what order</u> they are repeated. In other words, the pattern appropriate for reasoning about repetitions is straightforwardly able to cope with the nondeterminacy that has to be absorbed by the operating system for, say, a multiprogrammed installation.

The technique has been used rather constructively in the design of the THE Multiprogramming System to derive the synchronization conditions" (i.e. guards) that would ensure, for instance, that no buffer would become emptier than empty or fuller than full. At the time we did not know the Axiom of Assignment; we only knew what it entailed for simple assignment statements, such as n:=n+1, and equally simple P, such as n < N. This was in the first half of the 60's.

In the second half of the 60's, the method was formalized for deterministic sequential programs formalized for deterministic sequential programs by R.W. Floyd and by C.A.R. Hoare. Floyd in-cluded proofs of termination, but addressed him-self to programs as could be expressed by arbi-trary flow charts. (This latter generality was not too attractive. In the control graph one had to select a set of so-called "cutting edges", i.e. a set of edges such that their removal would leave a and the each cutting leave a graph with no cycles, and to each cutting edge a proof obligation corresponded. The awkward thing is that for an arbitrary control graph, the problem of determining a minimum set of cutting edges is most unattractive.) Hoare's subsequent contribution was twofold: on account of the structure of the Axiom of Assignment he definitely decided in favour of so-called "barkwards reason-ing" -Floyd had left this choice open- and he tied the proof obligations in with syntactic constructs for the flow of control. (Ironically, he confined himself to partial correctness, though the problem of finding a minimum set of cutting

edges - which are required for termination proofshad been reduced to triviality by the sequencing discipline he had adopted.) All this was synthesized in the early 70's by Edogor W. Dykstra, whose "guarded commands", besides forming a basis for a calculus for the derivation of programs, reintroduced nondeterminacy again.

Central to this game was the formal expression of so-called "assertions" or "conditions", i.e. predicates that contained the coordinates of the program's state space as free variables, and the formal manipulation of such expressions, e.g. in order to derive for a program fragment the precondition corresponding to a given postcondition. (It is this direction of the functional dependence to which the term "backwards reasoning" refers. The prognatic advantages of backwards reasoning are twofold. It circumvents undefined values, since for any program fragment the precondition is a total function of the postcondition, whereas the postcondition is, in general, a partial function of the precondition. Turthermore, the calculus includes nondeterminacy at no extra cost at all.)

For the formulation and manipulation of these conditions, the predicate calculus became a vital tool, so much so that during the last decade it became for many a programming computing scientist an indispensable tool for his

daily reasoning. (In passing I may mention my strong impression that those computing scientists may very well have been the first to use the predicate calculus regularly. Mathematicians, and even logicians, for whom, for instance, the facts that equivalence is associative, that disfacts that equivalence is associative, that dis-junction distributes over equivalence and that conjunction distributes over nonequivalence, belong to their active knowledge are extreme-ly rare. I never met one. Without intimate knowledge of such basic properties of the logical connectives one can hardly be expected to be a very effective user of the predicate cal-culus. Itence my strong impression. In retrospect I found the conclusion, so to speak, that as far as the mathematical community is concerned George Boole has lived in vain, rather shocking.)

The extensive use of the predicate calculus in program derivation during the last decade has had a profound influence, the consequences of which are still unfathomed. It turned program development into a calculational activity (and the idea of program correctness into a calculational notion). The consequences are unfathomed because suddenly we find ourselves urgently invited to apply formal techniques on a much more grandiose scale than we were used to. It turns out that the predicate calculus only solves the problem "in principle": without careful choice of our extra-logical primitives

and their notation, the formulae to be manipulated have a tendency of becoming unmanageably complicated. As a result, each specific problem may pose a new conceptual and notational challenge. By way of illustration, I shall show an extreme example from the field of distributed programming; the example is extreme in the sense that almost all the manipulations of the derivation belong to the extra-logical calculus.

We consider a network of machines that can send messages to each other. Each machine is in 1 of 3 states, viz.

n for "neutrally engaged", d for "delayed", or c for "critically engaged"

A critical engagement lasts only a finite period and is immediately followed by a neutral engagement of the machine in question. Between a neutral and the subsequent critical engagement a delay may occur in view of the requirement that at any moment at most 1 machine be critthat at any moment at most 1 machine be critically engaged (so-called "mutual exclusion"). The implied synchronization has to be implemented in such a manner that no delay lasts forever (socalled "fairness").

We introduce a single <u>token</u>, either held by one of the machines or being sent from one machine to another. Mutual exclusion is then achieved by maintaining

a critically engaged machine holds the token. The machines maintain this by (i) not initiating a critical engagement unless holding the token, and (ii) not sending the token to another machine while being critically engaged.

Furthermore each machine maintains

the machine holding the token is not delayed by (i) skipping the delay upon termination of a neutral engagement while holding the token, and (ii) initiating a critical engagement upon receipt of the token while delayed. Tairness is therefore ensured when each delayed machine receives the token within a finite period of time.

The rest of this example deals with the control of the movement of the token. To this end the machines are arranged in a ring, the two circular directions in which are called "to the left" and "to the right" respectively. The token is sent to the left, so-called <u>signals</u> are sent to the right. Each link connecting two neighbouring machines in the ring is in 1 of 3 states, viz.

u for "unused"
 t for "carrying the token to the left"
 s for "carrying a signal to the right"
 The latter two states are postulated to last only a finite period of time.

The computation will be broken up in so-called "atomic actions". (An "atomic action" is the same type of idealization as the "point mass" in physics.) Each atomic action is performed by one of the machines and involves a state change for that machine and for its link(s). There are four atomic actions to be designed:

(n) upon completion of a neutral engagement
(c) upon completion of a critical engagement
(s) upon arrival of a signal
(t) upon arrival of the token.

(We need not bother about "completion of a delay" since this will be subsumed by the arrival of the token; similarly, the "completion" of the state "unused" for a link is subsumed in sending either the token or a signal over that link.)

Our invariant for the whole system is, loosely speaking, "the ring is in a permissible state", but this is only helpful provided we have a very precise characterization of the set of permissible states. This set of permissible states will be derived as the transitive closure of the atomic transitions from a given initial state, say: all machines neutrally engaged, all the links unused, and the token residing in one of the machines.

Immediately the question arises how to characterize sets of ring states. Since a string of the appropriate length, in which machine states and link states alternate, characterizes a ring state -by lying the string around-, we can characterize a set of ring states by writing down a grammar for representative strings. In this example we shall use the grammar of so-called "regular expressions".

It will turn out to be handy to give machines one of two colours, either black (b) or white (w), and a machine state will be coded by prefixing one of three states n, d, or c, by one of the colours b or w. The machine holding the token will be identified by writing its colour with the corresponding capital letter. Initially all machines being white, we can characterize the initial state by the regular expression

(o)  $-(wn u)^*$  Wn u -

<u>Note</u>. If a regular expression is used to characterize a set of ring states, we shall surround it by a pair of dashes. This implies, for instance, that (0) is equivalent with

(End of Note.)

In (0), the star \* denotes "a succession of zero or more instances of the enclosed".

In (0), only completion of neutral engagements is possible. For the time being we confine our attention to the more interesting case of such completions taking place in machines not holding the token, and propose the transition (n.0) wn  $u \rightarrow wd s$ , i.e. a white machine without the token completes its neutral engagement by becoming delayed and sending a signal over the link to its right. (Transition n.0 only caters for the situation that a wn has a u to its right.)

The transitive closure of (0) under (n.o) is (1)  $-(wn u \| wd s)^*$  Wn u -

in which 1 - which syntactically has been given the lowest binding power - should be read as "or".

For the arrival of a signal at a white neutral machine (note that (1) is equivalent to

-(wn u [] wd s [] wd s wn u)\* Wn u \_ ) We propose the transition

(s.0) swn  $u \rightarrow u bn s$ 

i.e. the machine transmits the signal and blackens itself. The transitive closure of (0) under (n.0) and

(s.0) is given by - (wn u [] wd (u bn) \* s) \* Wn u-Closing this furthermore under  $u bn \rightarrow u bd$ (n.1)(5.1)  $s wd \rightarrow u bd$ yields  $-(wn u \| wd (u bn \| u bd)^* s)^* Wn u - ,$ which we record as (2) -H\* Wn u- with (3)  $H = wn u \square Q s$  with (4) Q = wd (u bn [] u bd)\* We note that the grammars H, H\*, and H\*Q - note the absence of dashes: these grammars correspond to sets of strings - are also closed under the four transitions considered so far. [The reader is not expected to see this at a glance: the formal verification of the above requires a -be it short- calculation.] Furthermore we note that under the transitions given so far the transitive closure of the string wn u H\* equals H H\*

Let us now look at the more interesting case that a signal arrives at the machine

holding the token. The only way in which we can make in (2) the substring s Wn explicit is by adding the superfluous term Q 5 Wn u  $-H^*(Wnu [Qs Wnu) - ,$ which we can close under (s.2) s Wn u -> t wn u by applying (s.2) now as rewrite rule: - H\* (Wn u [] Q + wn u) -As a result of the emergence of a new instance of wn u, this is no longer closed under the previous transformations, but we have seen that the closure yields (5) -H\* (Wn u ] Q + H) -Closing (5) under (n.2)  $Wn u \rightarrow Wc u$ obviously yields (6)  $-H^*(Wn u \| Wc u \| Q + H)$ which is also closed under the inverse (c.0) We u → Wn u

With the introduction of the term Wc u we have created the possibility of a signal

arriving at the critically engaged machine (that holds the token). Observing that in (6) the substring 5 We can only occur in Q s We u, adding this as superfluous term, and applying the transition s We u -> u Be u (s.3)as rewrite rule, we derive the closure (7) - H\* (Wn u ]] We u ]] Q + H ]] Q u Beu)-The introduction of the term Bc intro-duces a new form of critical engagement, which may terminate, for which we suggest the transition (c.1) u Bc u -> + wn u Since the resulting Q + wn u is subsumed by the preceding Q+H, (7) is closed under (C.1) as well. We leave to the reader the verification that (7) is also closed under the remaining three transitions that enumerate how the token can arrive wd + -> Wc u (1.0) (t.1) u bn t -> t wn u ubd + - > u Bc u (1.2)

Since (7) tells us that t has a string Q to its left, which may end in three different ways,

the construction of the closure and of the list of transitions that might be needed has now been completed.

The above enables us to convince ourselves that each delay will be of finite duration. To that purpose we associate with a delayed machine the string of (atternating) links and machines to its right, up to and including the machine that holds or the link that carries the token. For that string we define k by

k = the number of elements in the string t the number of white machines in the string.
To begin with we observe that k>0 and that none of the transitions increase k. We now convince ourselves that k decreases within a finite period of time because the states s, t, and c are of finite duration:

from (7) and (4) we conclude that the delayed machine occurs in a Q;

(i) for a Q in H, the string contains an s, and within a finite time 5.0, 5.1, 5.2, or 5.3 will decrease k

(ii) for the Q in Q+H, t.0, t.1, or t.2 will decrease is within a finite time.

(iii) for the Q in Q u Bc u, c.1 will decrease k within a finite time.

and from (7) we conclude that this case analysis has been exhaustive.

And this concludes (the compact presentation of) our example.

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A number of retrospective remarks are in order.

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In the above, the machines themselves have remained anonymous. We could have numbered them from 0 through N-1, but invite the reader to try to visualize how our invariant (7) would have looked like, had we used quantifications over machine subscripts! It would have been totally unmanageable. (Not only did we leave the individual machines anonymous, but even their number is not mentioned in the analysis: for a ring of N machines, only the strings of length 2.N that belong to the grammar (7) are applicable. A fringe benefit is that very small values of N do not require a special analysis.)

After the decision to try to use regular expressions, it took me several iterations before I had reached the above treatment. My first efforts contained errors, due to my lack of experience in using the "regularity calculus" for deriving a transitive closure under rewrite rules.

The lack of experience was the more severe since the same language can be characterized by

many different regular expressions: for instance, (a[b)\*, (a]b[ab)\*, (a]ba\*)\* are all equivalent. In the beginning I experienced this great freedom as a nuisance, but now I think this was naive, since precisely these languagepreserving transformations enable us to massage a regular expression in a form suitable for our next manipulation. Equivalences lie at the heart of any practical calculus.

Finally, it took me quite some time before I discovered the proper abbreviations to introduce. (The H and the Q, easy to defend in hindsight, could have been chosen much earlier, had we had more familiarity with the regularity calculus.)

I mentioned that, due to the calculational approach to program design, each specific problem may pose a new conceptual and notational challenge. The above example has been included to give the reader some feeling for the forms that challenge may take. I called the consequences of this recent development still unfathomed, the reason being that the machines executing our programs are truly worthy of the name "generalpurpose equipment" and that, consequently, the area that calls for the effective application of formal techniques seems to have lost its boundaries.

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