CS429: Computer Organization and Architecture Storage Technologies

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Random-Access Memory (RAM)

- Key Features
 - RAM is packaged as a chip
 - The basic storage unit is a cell (one bit per cell)
 - Multiple RAM chips form a memory.
- Static RAM (SRAM)
 - Each cell stores a bit with a 6-transistor circuit.
 - Retains value indefinitely, as long as kept powered.
 - Relatively insensitive to disturbances such as electrical noise.
 - Faster but more expensive than DRAM.
- Dynamic RAM (DRAM)
 - Each cell stores a bit with a capacitor and transistor.
 - Value must be refreshed every 10-100 ms.
 - Sensitive to disturbances, slower and cheaper than SRAM

Random-Access Memory (RAM) (2)

• Flash RAM (what's in your ipod and cell phone)

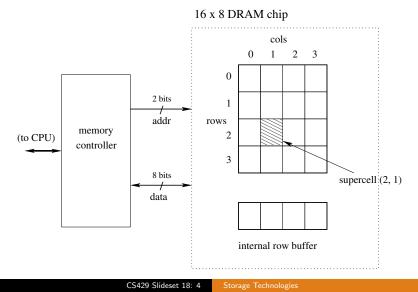
- Each cell stores 1 or more bits on a "floating-gate" capacitor
- Keeps state even when power is off
- As cheap as DRAM, but much slower

RAM Summary

Туре	Trans.	Access	Persist?	Sensitive	Cost	Applications
	per bit	time				
SRAM	6	1X	No	No	100X	cache memory
DRAM	1	10X	No	Yes	1X	main memory
Flash	1/2-1	10000X	Yes	No	1X	disk substitute

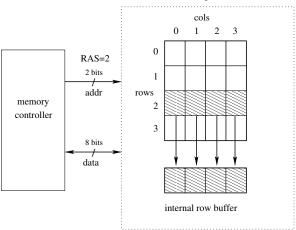
Conventional DRAM Organization

DRAM is typically organized as a $d \times w$ array of d supercells of size w bits.



Reading DRAM Supercell (2, 1)

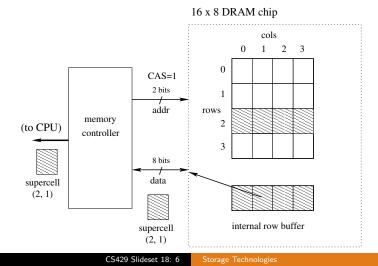
- Step 1(a): Row access strobe (RAS) selects row 2.
- Step 1(b): Row copied from DRAM array to row buffer.



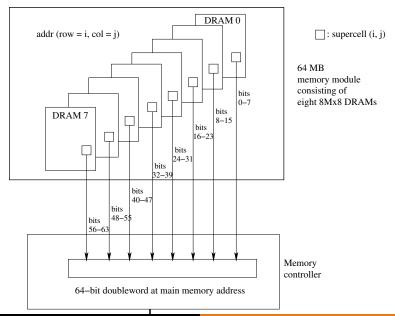
16 x 8 DRAM chip

Reading DRAM Supercell (2, 1)

- Step 2(a): Column access strobe (CAS) selects col 1.
- Step 2(b): Supercell (2, 1) copied from buffer to data lines, and eventually back to the CPU.



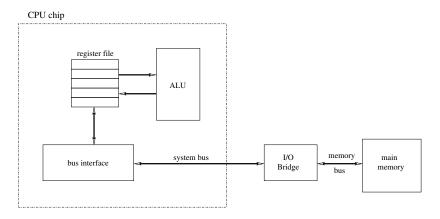
Memory Modules



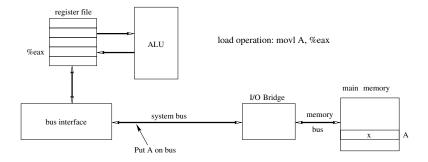
- DRAM and SRAM are volatile memories; they lose information if powered off.
- Nonvolatile memories retain their value even if powered off.
 - The generic name is read-only memory (ROM).
 - This is misleading because some ROMs can be read and modified.
- Types of ROMs
 - Programmable ROM (PROM)
 - Eraseable programmable ROM (EPROM)
 - Electrically eraseable PROM (EEPROM)
 - Flash memory
- Firmware: Program stored in a ROM
 - Boot time code, BIOS (basic input/output system)
 - Graphics cards, disk controllers

Connecting CPU and Memory

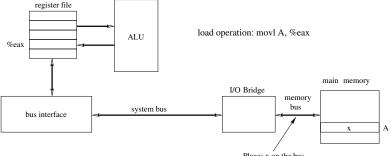
- A *bus* is a collection of parallel wires that carry address, data, and control signals.
- Buses are typically shared by multiple devices.



CPU places address A on the memory bus.

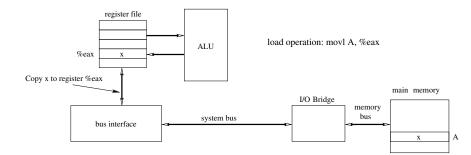


Main memory reads A from the memory bus, retrieves word x, and places it on the bus.

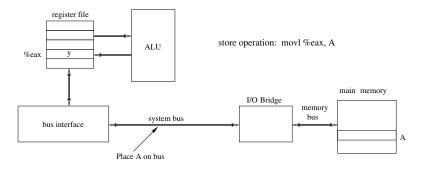


Places x on the bus.

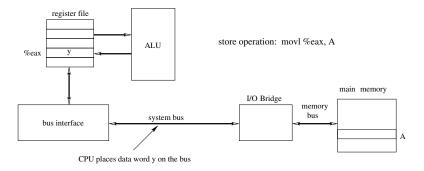
CPU reads word x from the bus and copies it into register %eax.



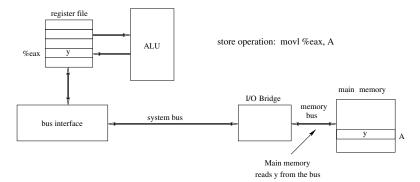
CPU places address A on bus. Main memory reads it and waits for the corresponding data word to arrive.



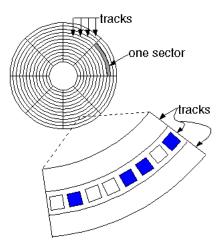
CPU places data word y on the bus.



Main memory reads data word y from the bus and stores it at address A.

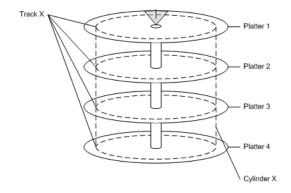


- Disks consist of platters, each with two *surfaces*.
- Each surface consists of concentric rings called *tracks*.
- Each track consists of sectors separated by gaps.



Disk Geometry (Multiple-Platter View)

Aligned tracks form a cylinder. Read/write heads move in unison so are all on the same cylinder at any one time.



Disk Capacity

- **Capacity:** maximum number of bits that can be stored. Vendors express this in terms of gigabytes (GB), where $1GB = 10^9$ bytes.
- Capacity is determined by these technology factors:
 - **Recording density** (bits/in): number of bits that can be squeezed into a 1 inch segment of a track.
 - **Track density** (tracks/in): number of tracks that can be squeezed into a 1 inch radial segment.
 - Areal density (bits/in²): product of recording and track density.
- Modern disks partition tracks into disjoint subsets called **recording zones**.
 - Each track in a zone has the same number of sectors, determined by the circumference of the innermost track.
 - Each zone has a different number of sectors/track.

 $\begin{aligned} \mathsf{Capacity} = (\ \mathsf{bytes/sector}) \times (\mathsf{avg. sectors/track}) \times \\ & (\mathsf{tracks/surface}) \times \mathsf{surfaces/platter}) \times \mathsf{platters/disk}) \end{aligned}$

Example:

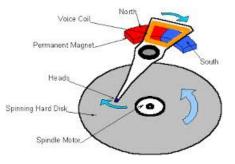
- 512 bytes/sector
- 300 sectors/track (on average)
- 20,000 tracks/surface
- 2 surfaces/platter
- 5 platters/disk

Capacity = $512 \times 300 \times 20000 \times 2 \times 5 = 30,720,000,000 = 30.72$ GB

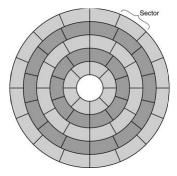
The disk surface spins at a fixed rotational rage.

The read/write head is attached to the end of the arm and flies over the disk surface on a a very thin cushion of air (around 0.1 microns).

By moving radially, the arm can position the read/write head over any track.



Reading a Sector



To read a sector on a disk requires:

- Seek: the read head is moved to the proper track.
- Rotational latency: the desired sector must rotate to the read head.
- Data transfer: the sector is read as it rotates under the read head.

Writing is the same.

Disk Access Time

The average time to access a target sector is approximately:

$$T_{access} = T_{seek} + T_{rotation} + T_{transfer}$$

- Seek time (T_{seek})
 - Time to position heads over cylinder containing the target sector.
 - Average T_{seek} = 9ms
- Rotational latency (*T_{rotation}*)
 - Time waiting for first bit of target sector to pass under read/write head.
 - Average $T_{rotation} = 1/2 \times 1/\text{RPMs} \times 60\text{sec}/1\text{min}$
- Transfer time (*T*_{transfer})
 - Time to read the bits in the target sector.
 - Average

 $T_{\textit{transfer}} = 1/\text{RPM} \times 1/((\text{average sectors/track}) \times 60 \text{sec}/1 \text{min}$

Disk Access Time Example

Given:

- Rotational rate: 7,200 RPM
- Average seek time: 9 ms
- Average sectors/track: 400

Derived:

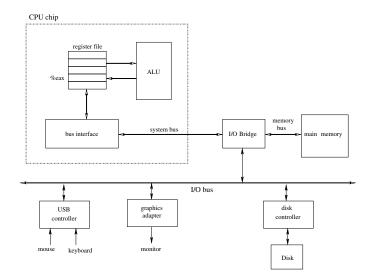
- Average T_{seek} : $1/2 \times (60 \text{sec}/7200 \text{RPM} \times 1000 \text{ms/sec} = 4 \text{ms}$
- Average $T_{transfer}$: 60/7200RPM × 1/(400 sectors/track) × 1000ms/sec = 0.02ms
- *T_{access}*: 9 ms + 4 ms + 0.02 ms

Important points:

- Access time is dominated by seek time and rotational latency.
- The first bit in a sector is the most expensive; the rest are free.
- SRAM access time is about 4ns / doubleword; DRAM about 60ns.
- Disk is about 40,000 times slower than SRAM, and 2,500 times slower than DRAM.

- Modern disks present a simpler abstract view of the complex sector geometry.
 - The set of available sectors is modeled as a sequence of b-sized **logical blocks** (0, 1, 2, ...).
- Mapping between logical blocks and actual (physical) sectors:
 - Is maintained by a hardware/firmware device called a disk controller.
 - Converts requests for logical blocks into (surface, track, sector) triples.
- Allows the controller to set aside spare cylinders for each zone.
 - This accounts for the difference between "formatted capacity" and "maximum capacity."

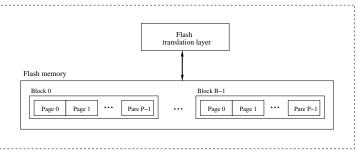
I/O Bus



- The CPU initiates a disk read by writing a command, logical block number, and destination memory address to a *port* (address) associated with the disk controller.
- On the disk controller reads the associated sector and performs a direct memory access (DMA) transfer into main memory.
- When the DMA transfer completes, the disk controller notifies the CPU with an *interrupt* (i.e., asserts a special "interrupt" pin on the CPU).

Solid State Disks (SSDs)





- Requests to read and write logical disk blocks come across the I/O bus to the Flash translation layer.
- Pages are 512KB to 4KB; blocks are 32 to 128 pages.
- Data is read/written in units of pages.
- A page can only be written after its block has been erased.
- A block wears out after around 100,000 repeated writes.

Sequential read tput	250 MB/s	Sequential write tput	170 MB/s
Random read tput	140 MB/s	Random write tput	14 MB/s
Random read access	30 μ s	Random write access	300 μ s

Why are random writes so slow?

- Erasing a block is slow (around 1 ms).
- Write to a page triggers a copy of all useful pages in the block.
- Must find a used block (new block) and erase it.
- Write the page into the new block.
- Copy other pages from the old block to the new block.

Advantages:

• No moving parts; faster, less power, more rugged.

Disadvantages:

- Have the potential to wear out. This is mitigated by "wear leveling logic" in the flash translation layer.
- E.g., Intel X25 guarantees 1 petabyte (10^{15} bytes) of random writes before they wear out.
- In 2010, they were about 100X more expensive. But by November, 2013 this has fallen to 10X.

Applications:

- MP3 players, smart phones, laptops.
- They are beginning to appear in desktops and servers.

Year:	1980	1985	1990	1995	2000	2005	2010	1980:2010	
SRAM									
\$/MB	19.2K	2.9K	320	256	100	75	60	320	
access (ns)	300	150	35	15	3	2	1.5	200	
	DRAM								
\$/MB	8K	880	100	30	1	0.1	0.06	130K	
access (ns)	375	200	100	70	60	50	40	9	
typical size	0.064	0.256	4	16	64	2K	8K	125K	
Disk									
\$/MB	500	100	8	0.30	0.001	0.005	0.0003	1.6M	
access (ns)	87	75	28	10	8	4	3	29	
typical size	1	10	160	1K	20K	160K	1.5M	1.5M	

Year:	1980	1985	1990	1995	2000	2005	2010	1980:2010
CPU	8080	386	Pentium	P-III	P-4	Core 2	Core i7	
Clock MHz	1	20	150	600	3300	2000	2500	2500
Cycle (ns)	1000	50	6	1.6	0.3	0.5	0.4	2500
Cores	1		1	1	1	12	4	4
Effective	1000	50	6	1.6	0.3	0.25	0.1	10K
Cycle time								

Around 2003, was the inflection point in computer history when designers hit the "Power Wall." Cores increased, but the clock rate actually decreased.

CPU-Memory Gap

CPU speed increases *faster* than memory speed, meaning that:

- memory is more and more a limiting factor on performance;
- increased importance for caching and similar techniques.

