

# CS429: Computer Organization and Architecture

## Optimization II

Warren Hunt, Jr. and Bill Young  
Department of Computer Sciences  
University of Texas at Austin

Last updated: August 26, 2014 at 08:54

## Miss Rate

- Fraction of memory references not found in cache (misses / references)
- Typical numbers: 3-10% for L1; can be quite small (e.g., < 1%) for L2, depending on size, etc.

## Hit Time

- Time to deliver a line in the cache to the processor (including time to determine whether the line is in the cache).
- Typical numbers: 1-3 clock cycles for L1; 5-12 clock cycles for L2.

## Miss Penalty

- Additional time required because of a miss.
- Typically 100-300 cycles for main memory.

# Writing Cache Friendly Code

- Repeated references to variables are good (temporal locality).
- Stride-1 reference patterns are good (spatial locality).

## Examples:

Assume cold cache, 4-byte words, 4 word cache blocks.

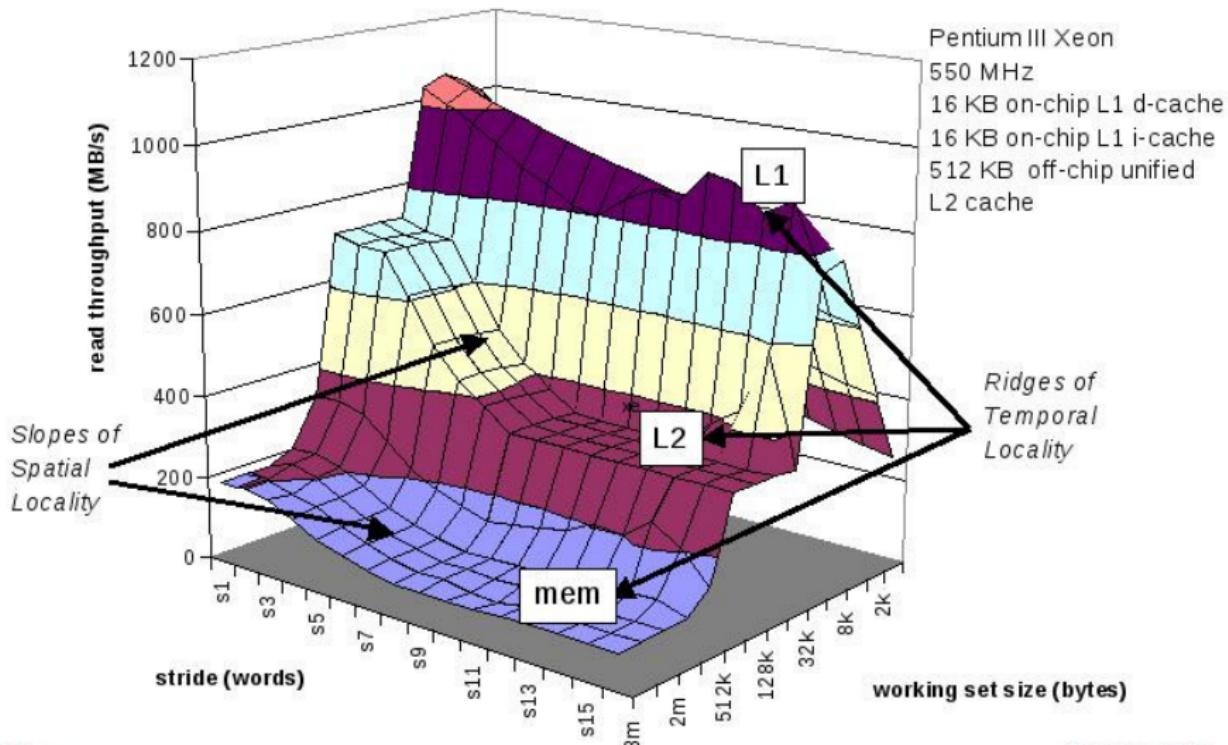
```
int sumarrayrows( int a[M][N]
)
{
    int i, j, sum = 0;
    for( i = 0; i < M; i++ )
        for( j = 0; j < N; j++ )
            sum += a[i][j];
    return sum;
}
```

```
int sumarraycols( int a[M][N]
)
{
    int i, j, sum = 0;
    for( j = 0; j < N; j++ )
        for( i = 0; i < M; i++ )
            sum += a[i][j];
    return sum;
}
```

Miss rate =  $1/4 = 25\%$

Miss rate =  $100\%$

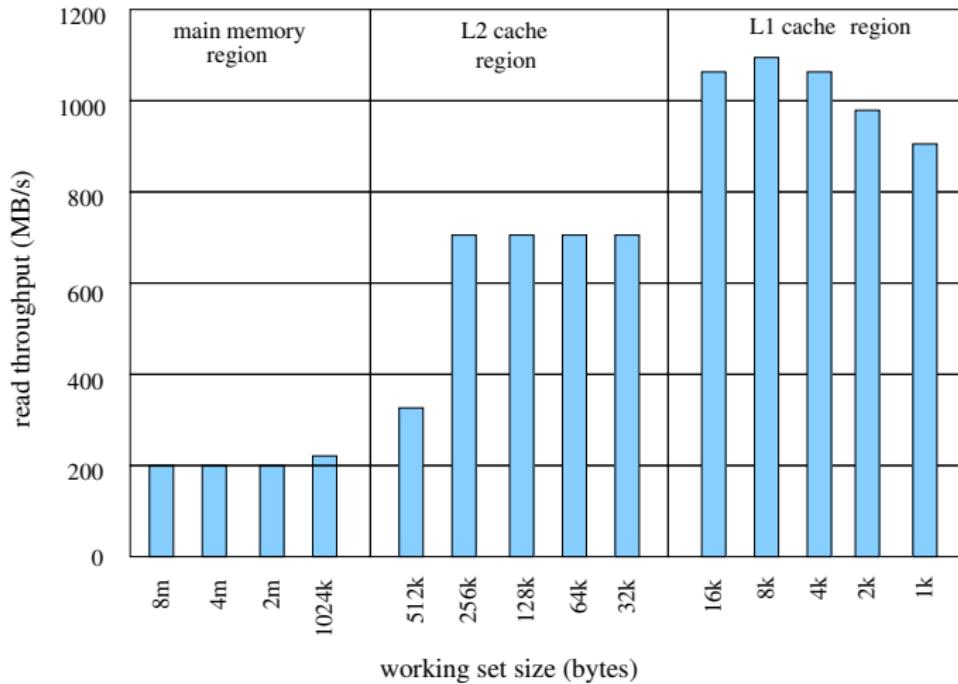
# The Memory Mountain



# Ridges of Temporal Locality

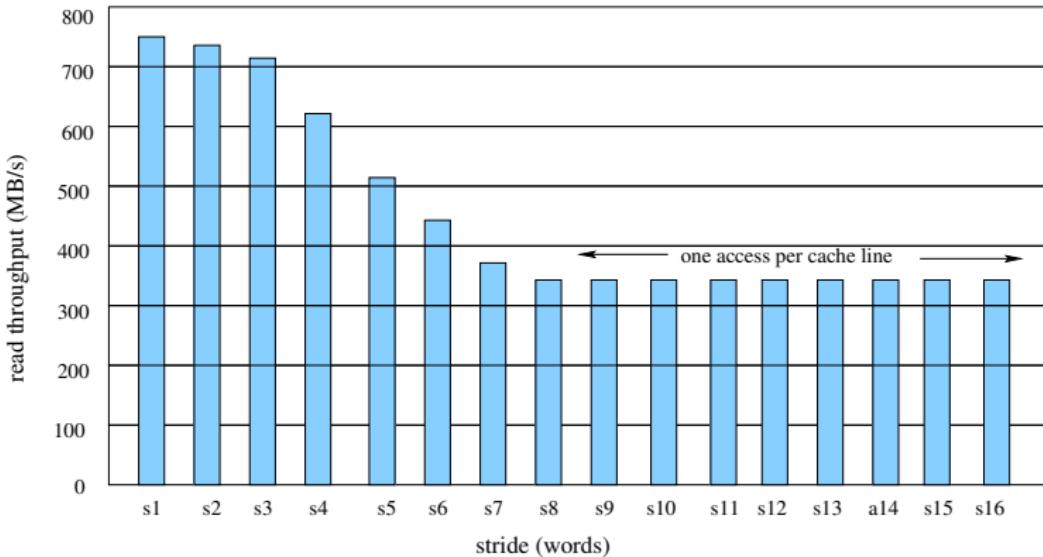
**Slice through the memory mountain with stride = 1.**

This illustrates read throughput with different caches and memory.



# A Slope of Spatial Locality

**Slice through memory mountain with size = 256KB.**  
This shows cache block size.



# Matrix Multiplication Example

## Major Cache Effects to Consider.

- Total cache size: Exploit temporal locality and keep the working set small (e.g., by using blocking).
- Block size: Exploit spatial locality.

## Description

- Multiply  $N \times N$  matrices.
- $O(N^3)$  total operations.
- Accesses:
  - $N$  reads per source element
  - $N$  values summed per destination (but may be held in register).

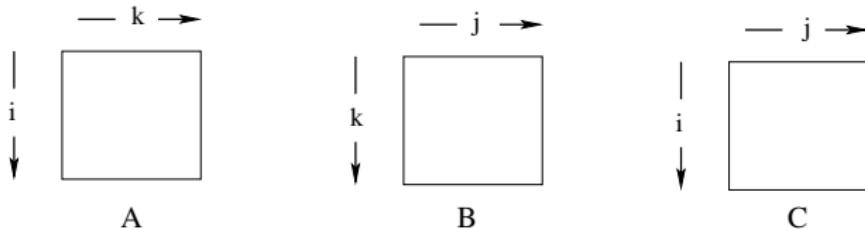
```
/* ijk */
for (i=0; i<n; i++) {
    for (j=0; j<n; j++) {
        sum = 0.0; // in reg
        for (k=0; k<n; k++)
            sum += a[i][k] * b[k][j];
        c[i][j] = sum;
    }
}
```

# Miss Rate for Matrix Multiply

## Assume:

- Line size =  $32B$  (big enough for 4 64-bit words)
- Matrix dimension  $N$  is very large.
- We can approximate  $1/N$  as 0.0.
- Cache is not even big enough to hold multiple rows.

**Analysis Method:** Look at access pattern of the inner loop.



# Layout of C Arrays in Memory (review)

## C arrays are allocated in row-major order.

- Each row is allocated in contiguous memory locations.

### Stepping through columns in one row:

```
for (i = 0; i < N; i++)
    sum += a[j][i];
```

- This accesses successive elements.
- If block size  $B > 4$  bytes, exploits spatial locality.
- Compulsory miss rate = 4 bytes / B.

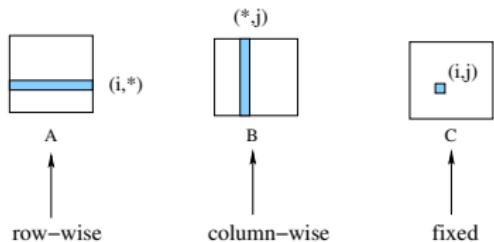
### Stepping through rows in one column:

```
for (i = 0; i < N; i++)
    sum += a[i][i];
```

- Accesses distant elements.
- No spatial locality!
- Compulsory miss rate = 1 (i.e., 100%).

# Matrix Multiplication (ijk)

```
/* ijk */
for (i=0; i<n; i++) {
    for (j=0; j<n; j++) {
        sum = 0.0; // in reg
        for (k=0; k<n; k++)
            sum += a[i][k] * b[k][j];
        c[i][j] = sum;
    }
}
```

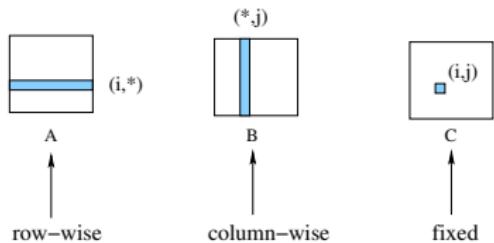


Misses per Inner Loop Iteration:

A	B	C
0.25	1.0	0.0

# Matrix Multiplication (jik)

```
/* ijk */
for (j=0; j<n; j++) {
    for (i=0; i<n; i++) {
        sum = 0.0; // in reg
        for (k=0; k<n; k++)
            sum += a[i][k] * b[k][j];
        c[i][j] = sum;
    }
}
```

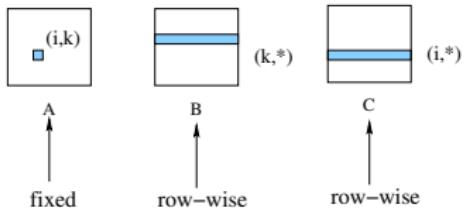


Misses per Inner Loop Iteration:

A	B	C
0.25	1.0	0.0

# Matrix Multiplication (kij)

```
/* kij */
for (k=0; k<n; k++) {
    for (i=0; i<n; i++) {
        r = a[i][k];
        for (j=0; j<n; j++)
            c[i][j] += r * b[k][j];
    }
}
```

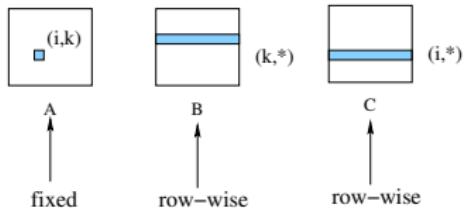


Misses per Inner Loop Iteration:

A	B	C
0.0	0.25	0.25

# Matrix Multiplication (ikj)

```
/* ikj */
for (i=0; i<n; i++) {
    for (k=0; k<n; k++) {
        r = a[i][k];
        for (j=0; j<n; j++)
            c[i][j] += r * b[k][j];
    }
}
```

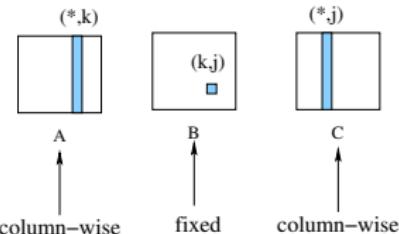


Misses per Inner Loop Iteration:

A	B	C
0.0	0.25	0.25

# Matrix Multiplication (jki)

```
/* jki */
for (j=0; j<n; j++) {
    for (k=0; k<n; k++) {
        r = b[k][j];
        for (i=0; i<n; i++)
            c[i][j] += a[i][k] * r;
    }
}
```

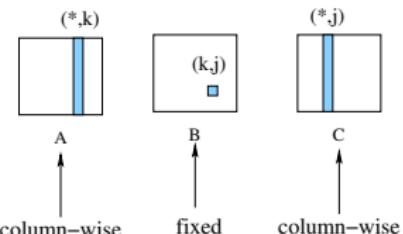


Misses per Inner Loop Iteration:

A	B	C
1.0	0.0	1.0

# Matrix Multiplication (kji)

```
/* kji */
for (k=0; k<n; k++) {
    for (j=0; j<n; j++) {
        r = b[k][j];
        for (i=0; i<n; i++)
            c[i][j] += a[i][k] * r;
    }
}
```



Misses per Inner Loop Iteration:

A	B	C
1.0	0.0	1.0

# Summary of Matrix Multiplication

## ijk (& jik):

- 2 loads, 0 stores
- misses / iteration = 1.25

## kij (& ikj):

- 2 loads, 1 store
- misses / iteration = 0.5

## jki (& kji):

- 2 loads, 1 store
- misses / iteration = 2.0

*Miss rates are important, but not perfect predictors of performance.. Code scheduling matters, also.*

# Improving Temporal Locality by Blocking

## Example: Blocked matrix multiplication

- “Block” (in this context) does not mean “cache block.”
- It means a sub-block within the structure (matrix).
- Example:  $N = 8$ ; sub-block size = 4.

$$\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \times \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix}$$

**Key idea:** Sub-blocks (e.g.,  $A_{xy}$ ) can be treated just like scalars.

$$C_{11} = A_{11}B_{11} + A_{12}B_{21} \quad C_{12} = A_{11}B_{12} + A_{12}B_{22}$$

$$C_{21} = A_{21}B_{11} + A_{22}B_{21} \quad C_{22} = A_{21}B_{12} + A_{22}B_{22}$$

# Blocked Matrix Multiply (bijk)

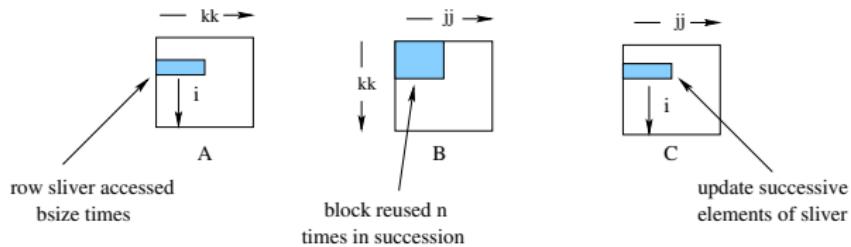
```
for (jj=0; jj<n; jj+=bsize) {
    for (i=0; i<n; i++)
        for (j=jj; j < min(jj+bsize, n); j++)
            c[i][j] = 0.0;
    for (kk=0; kk<n; kk+=bsize) {
        for (i=0; i<n; i++) {
            for (j=jj; j < min(jj+bsize, n); j++) {
                sum = 0.0;
                for (k=kk; k < min(kk+bsize, n); k++) {
                    sum += a[i][k] * b[k][j];
                }
                c[i][j] += sum;
            }
        }
    }
}
```

# Blocked Matrix Multiply Analysis

```
for ( i=0; i<n; i++ ) {
    for ( j=jj; j < min( jj+bsize ,n ); j++ ) {
        sum = 0.0;
        for ( k=kk; k < min( kk+bsize ,n ); k++ ) {
            sum += a[ i ][ k ] * b[ k ][ j ];
        }
        c[ i ][ j ] += sum;
    }
}
```

Innermost loop pair multiplies a  $1 \times bsize$  sliver of A by a  $bsize \times bsize$  block of B and accumulates into a  $1 \times bsize$  sliver of C.

Loop over i steps  
through n row slivers of  
A and C, using same B.



# Blocked Matrix Multiply Performance

On a Pentium, blocking ( $bijk$  and  $bikj$ ) improves performance by a factor of two over the unblocked versions ( $ijk$  and  $jik$ ).

The result is relatively insensitive to array size.

## **The programmer can optimize for cache performance.**

- How data structures are organized.
- How data are accessed (e.g., nested loop structure).
- Blocking is a general technique.

## **All systems favor “cache friendly code.”**

- Getting absolute optimum performance is very platform specific.
- Involves cache sizes, line sizes, associativities, etc.
- Can get most advantage with generic code.
- Keep working set reasonably small (temporal locality).
- Use small strides (spatial locality).