

CS429: Computer Organization and Architecture

Instruction Set Architecture V

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Integral

- Stored and operated on in general registers.
- Signed vs. unsigned depends on instructions used.

Intel	GAS	Bytes	C
byte	b	1	[unsigned] char
word	w	2	[unsigned] short
double word	l	4	[unsigned] int
quad word	q	8	[unsigned] long int

Floating Point

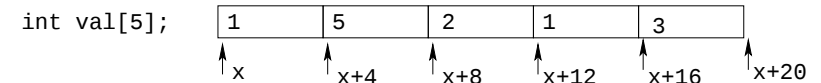
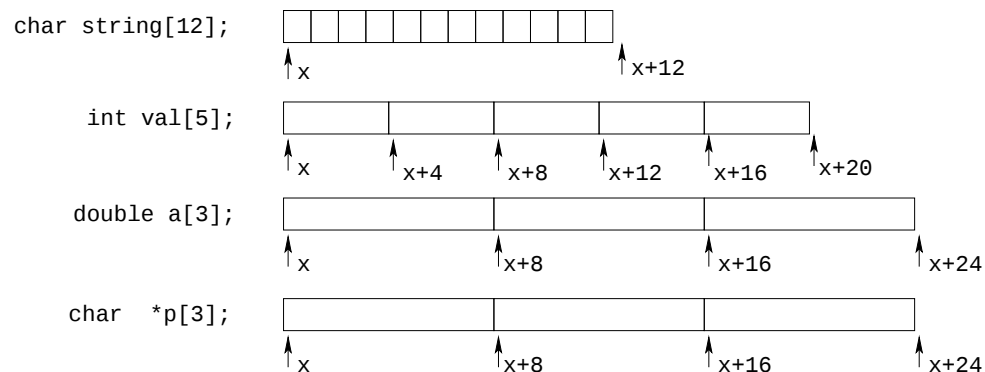
Stored and operated on in floating point registers.

Intel	GAS	Bytes	C
Single	s	4	float
Double	l	8	double
Extended	t	10/12	long double

Array Allocation

Basic Principle: T A[L]

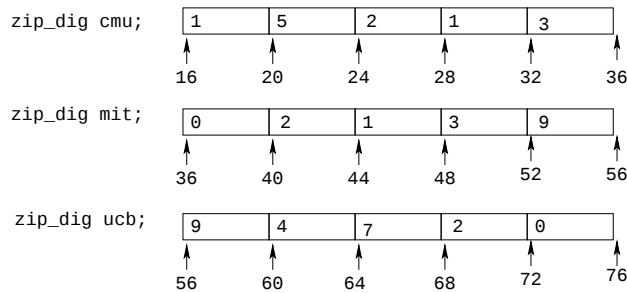
- Array (named A) of data type T and length L.
- Contiguously allocated region of $L * \text{sizeof}(T)$ bytes.



Reference	Type	Value
val[4]	int	3
val	int *	x
val+1	int *	$x + 4$
&val[2]	int *	$x + 8$
val[5]	int	??
*(val+1)	int	5
val+j	int *	$x + 4j$

Note the use of pointer arithmetic.

Array Example



```
#define ZLEN 5
typedef int zip_dig[ZLEN];

zip_dig cmu = { 1, 5, 2, 1, 3 };
zip_dig mit = { 0, 2, 1, 3, 9 };
zip_dig ucb = { 9, 4, 7, 2, 0 };
```

Declaration `zip_dig cmu` is equivalent to `int cmu[5]`.

Example arrays were allocated in successive 20 byte block.

That's not guaranteed to happen in general.

Array Accessing Example

```
int get_digit
( zip_dig z, int dig )
{
    return z[dig];
}
```

Memory Reference Code

```
# %rdi = z
# %rsi = dig
movl (%rdi,%rsi,4),%eax # z[dig]
```

Computation

- Register `%rdi` contains the starting address of the array.
- Register `%rsi` contains the array index.
- The desired digit is at $\%rdi + (4 * \%rsi)$.
- User memory reference $(\%rdi, \%rsi, 4)$.

Array Loop Example

```
void zincr( zip_dig z ) {
    size_t i;
    for (i = 0; i < ZLEN; i++)
        z[i]++;
}
```

```
# %rdi = z
movl $0, %eax          # i = 0
jmp .L3                # goto middle
.L4:                   # loop:
    addl $1, (%rdi, %rax, 4) # z[i]++
    addq $1, %rax          # i++
.L3:                   # middle:
    cmpq $4, %rax         # i:4
    jbe .L4              # if <=, goto loop
ret                    # return
```

Multidimensional (Nested) Arrays

Declaration: `T A[R][C];`

- 2D array of data type `T`
- `R` rows, `C` columns
- Type `T` element requires `K` bytes

$$\begin{bmatrix} A[0][0] & \dots & A[0][C-1] \\ \vdots & & \vdots \\ A[R-1][0] & \dots & A[R-1][C-1] \end{bmatrix}$$

Array Size: $R * C * K$ bytes

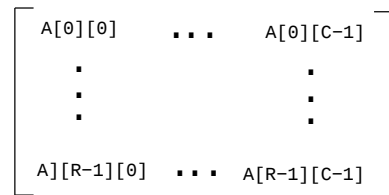
Arrangement: Row-Major ordering (guaranteed)

Row major order means the elements are stored in the following order:

$$[A_{0,0}, \dots, A_{0,C-1}, A_{1,0}, \dots, A_{1,C-1}, \dots, A_{R-1,0}, \dots, A_{R-1,C-1}].$$

Declaration: `T A[R][C];`

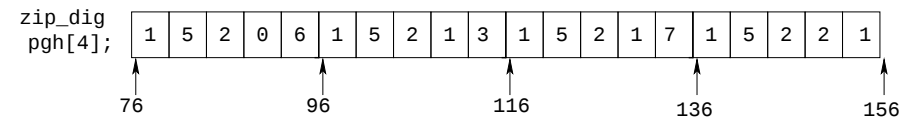
- 2D array of data type T
- R rows, C columns
- Type T element requires K bytes



To access element $A[i][j]$, perform the following computation:

$$A + i * C * K + j * K$$

```
#define PCOUNT 4
zip_dig pgh[PCOUNT] =
    {{1, 5, 2, 0, 6},
     {1, 5, 2, 1, 3},
     {1, 5, 2, 1, 7},
     {1, 5, 2, 2, 1}};
```

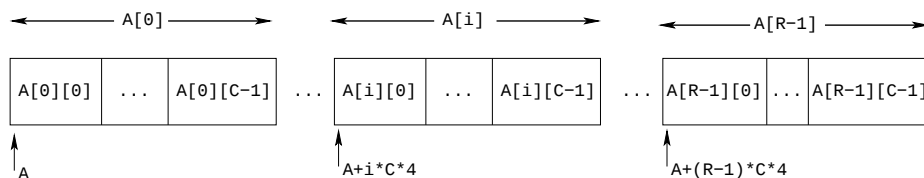


- Declaration “`zip_dig pgh[4]`” is equivalent to “`int pgh[4][5]`.”
- Variable `pgh` denotes an array of 4 elements allocated contiguously.
- Each element is an array of 5 ints, which are allocated contiguously.
- This is “row-major” ordering of all elements, guaranteed.

Row Vectors:

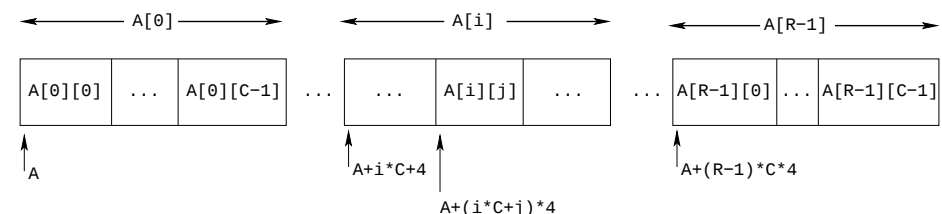
Given a nested array declaration `T A[R][C]`, you can think of this as an array of arrays.

- $A[i]$ is an array of C elements.
- Each element of $A[i]$ has type T, and requires K bytes.
- The starting address of $A[i]$ is $A + i * C * K$.



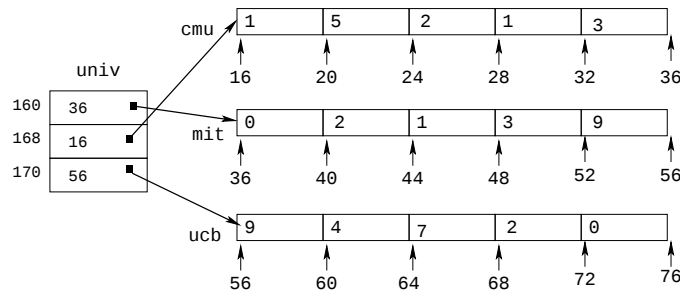
Array Elements

- $A[i][j]$ is an element of type T, which requires K bytes.
- The address is $A + (i * C + j) * K$.



```
zip_dig cmu = { 1, 5, 2, 1, 3 };
zip_dig mit = { 0, 2, 1, 3, 9 };
zip_dig ucb = { 9, 4, 7, 2, 0 };
```

```
#define UCOUNT 3
int *univ[UCOUNT]
    = {mit, cmu, ucb};
```



- Variable `univ` denotes an array of 3 elements.
- Each element is a pointer (8 bytes).
- Each pointer points to an array of ints (may vary in length; i.e., ragged array is possible).

Computation

- Element access
Mem[Mem[univ+8*index] + 4*dig]
- Must do two memory reads:
 - First get pointer to row array.
 - Then access element within the row.

```
int get_univ_digit
(size_t index, size_t dig)
{
    return univ[index][dig];
}
```

```
salq    $2, %rsi          # 4*dig
addq    univ(,%rdi,8),%rsi # p = univ[index] + 4*dig
movl    (%rsi), %eax       # return *p
ret
```

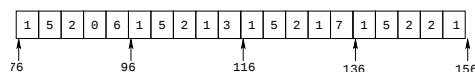
Array Element Accesses

N x N Matrix Code

Nested Array

```
int get_pgh_digit
(size_t index,
 size_t dig)
{
    return pgh[index][dig];
}
```

Element at
Mem[pgh+20*index+4*dig]

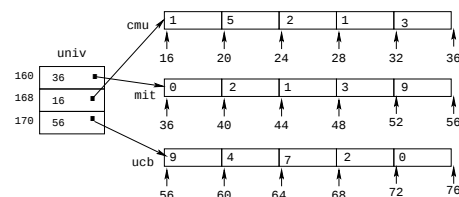


Similar C references, but different address computations.

Multi-Level Array

```
int get_univ_digit
(size_t index,
 size_t dig)
{
    return univ[index][dig];
}
```

Element at
Mem[Mem[univ+8*index]+4*dig]



Fixed dimensions:
Know value of N at compile time.

Variable dimensions, explicit indexing:
Traditional way to implement dynamic arrays

Variable dimensions, implicit indexing:
Now supported by gcc

```
#define N 16
typedef int fix_matrix[N][N];
/* Get element a[i][j] */
int fix_ele( fix_matrix a,
             size_t i, size_t j ) {
    return a[i][j];
}
```

```
#define IDX(n, i, j) ((i) * (n) + (j))
/* Get element a[i][j] */
int vec_ele( size_t n, int *a,
             size_t i, size_t j ) {
    return a[IDX(n, i, j)];
}
```

```
/* Get element a[i][j] */
int var_ele( size_t n, int a[n][n],
             size_t i, size_t j ) {
    return a[i][j];
}
```

Array Elements

- Address $A + i * (C * K) + j * K$
- $C = 16, K = 4$

```
/* Get element a[i][j] */
int fix_ele( fix_matrix a, size_t i, size_t j ) {
    return a[i][j];
}
```

```
# a in %rdi, i in %rsi, j in %rdx
salq    $6, %rsi          # 64*i
addq    %rsi, %rdi         # a + 64*i
movl    (%rdi, %rdx, 4), %eax # M[a + 64*i + 4*j]
```

Array Elements

- Address $A + i * (C * K) + j * K$
- $C = n, K = 4$
- Must perform integer multiplication

```
/* Get element a[i][j] */
int var_ele( size_t n, int a[n][n], size_t i, size_t j )
{
    return a[i][j];
}
```

```
# n in %rdi, a in %rsi, i in %rdx, j in %rcx
imulq   %rdx, %rdi         # n*i
leaq    (%rsi, %rdi, 4), %rax # a + 4*n*i
movl    (%rax, %rcx, 4), %eax # a + 4*n*i + 4*j
ret
```

Structure Representation

```
struct rec {
    int a[4];
    size_t i;
    struct rec *next;
};
```



Structure represented as block of memory

- Big enough to hold all the fields

Fields ordered according to declaration

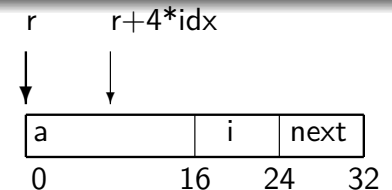
- Even if another ordering could yield a more compact representation

Compiler determines overall size and position of fields

- Machine-level program has no understanding of the structures in the source code.

Generating Pointer to Structure Member

```
struct rec {
    int a[4];
    size_t i;
    struct rec *next;
};
```



Generating Pointer to Array Element

- Offset of each structure member determined at compile time
- Compute as $r + 4 * idx$

```
int *get_ap
(struct rec *r, size_t idx)
{
    return &r->a[idx];
}
```

```
# r in %rdi, idx in %rsi
leaq   (%rdi, %rsi, 4), %rax
ret
```

BTW: why does $r \rightarrow i$ need 8 bytes? Alignment. (Next slide set)



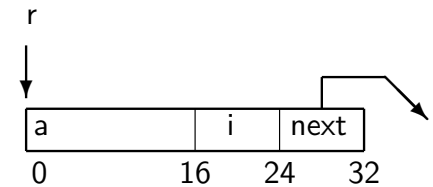
If you have a *pointer* `r` to a structure, use `r->x` to access component `x`.

If you have the structure `s` itself, use `s.x`.

`r->x` is just syntactic sugar for `(*r).x`

```
void set_val
(struct rec *r, int val)
{
    while (r) {
        int i = r->i;
        r->a[i] = val;
        r = r->next;
    }
}
```

```
struct rec {
    int a[4];
    size_t i;
    struct rec *next;
};
```



```
.L11:                                # loop:
    testq    %rdi, %rdi              # Test r
    je       .L12                    # if = 0, goto done
    movq     16(%rdi), %rax           # i = M[r+16]
    movl     %esi, (%rdi, %rax, 4)    # M[r+4*i] = val
    movq     24(%rdi), %rdi          # r = M[r+24]
    jmp      .L11                    # goto loop
.L12:                                # done:
```