**Why Y86?**

The Y86 is a “toy” machine that is similar to the x86 but *much simpler*. It is a gentler introduction to assembly level programming than the x86.

- just a few instructions as opposed to hundreds for the x86;  
- fewer addressing modes;  
- simpler system state;  
- absolute addressing.

*Everything you learn about the Y86 will apply to the x86 with very little modification.* But the main reason we’re bothering with the Y86 is because we’ll be explaining pipelining in that context.

---

**Assembly Language View**

- Processor state: registers, memory, etc.  
- Instructions and how instructions are encoded

**Layer of Abstraction**

- Above: how to program machine, processor executes instructions sequentially  
- Below: What needs to be built  
  - Use variety of tricks to make it run faster  
  - E.g., execute multiple instructions simultaneously
There are various means of giving a semantics or meaning to a programming system.

Probably the most sensible for an assembly (or machine) language is an operational semantics, also known as an interpreter semantics.

That is, we explain the semantics of each possible operation in the language by explaining the effect that execution of the operation has on the machine state.

The most fundamental abstraction for the machine semantics for the x86/Y86 or similar machines is the fetch-decode-execute cycle. This is also called the von Neumann architecture.

The machine repeats the following steps forever:
- fetch the next instruction from memory (the PC tells you which is next);
- decode the instruction (in the control unit);
- execute the instruction, updating the state appropriately;
- go to step 1.

We’re actually describing two languages: the assembly language and the machine language. There is nearly a 1-1 correspondence between them.

**Machine Language Instructions**
- 1-10 bytes of information read from memory
  - Can determine instruction length from first byte
  - Not as many instruction types and simpler encoding than x86-64
- Each instruction accesses and modifies some part(s) of the program state.
### Y86 Instruction Set

<table>
<thead>
<tr>
<th>Byte</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
<th>9</th>
</tr>
</thead>
<tbody>
<tr>
<td>halt</td>
<td>0</td>
<td>0</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>nop</td>
<td>1</td>
<td>0</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>cmovXX rA,rB</td>
<td>2</td>
<td>fn</td>
<td>rA</td>
<td>rB</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>irmovq V,rB</td>
<td>3</td>
<td>0</td>
<td>F</td>
<td>rB</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>rmovq rA,D(rB)</td>
<td>4</td>
<td>0</td>
<td>rA</td>
<td>rB</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>rmovq D(rB),rA</td>
<td>5</td>
<td>0</td>
<td>rA</td>
<td>rB</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>OPq rA,rB</td>
<td>6</td>
<td>fn</td>
<td>rA</td>
<td>rB</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>jXX Dest</td>
<td>7</td>
<td>fn</td>
<td></td>
<td>Dest</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>call Dest</td>
<td>8</td>
<td>0</td>
<td></td>
<td>Dest</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>ret</td>
<td>9</td>
<td>0</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>pushq rA</td>
<td>A</td>
<td>0</td>
<td>rA</td>
<td>F</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>popq rA</td>
<td>B</td>
<td>0</td>
<td>rA</td>
<td>F</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Example from C to Assembly

Suppose we have the following simple C program in file `code.c`.

```c
int sumInts(long int n)
{
    /* Add the integers from 1..n. */
    long int i;
    long int sum = 0;
    for (i = 1; i <= n; i++) {
        sum += i;
    }
    return sum;
}
```

(We used `long int` to force usage of the 64-bit registers.) You can compile it using the following commands:

```bash
> gcc -O -S code.c
```

### x86 Assembly Example

```assembly
.file   "code.c"
.text
.globl sumInts
.type   sumInts, @function
sumInts:
    .LFB0:
        .cfi_startproc
        testq   %rdi, %rdi
        jle .L4
        movq    $0, %rax
        movq    $1, %rdx
        .L3:
            addq   %rdx, %rax
            addq   $1, %rdx
            cmpq   %rdx, %rdi
            jge .L3
        ret
        .L4:
            movq    $0, %rax
            ret
        .cfi_endproc
    .LFE0:
.size   sumInts, .-sumInts
.ident "GCC: (Ubuntu 4.8.4-2ubuntu1~14.04) 4.8.4"
```

### Y86 Assembly Example

This is a hand translation into Y86 assembler:

```assembly
sumInts:
    andq   %rdi, %rdi
    jle .L4  # test %rdi = n
    irmovq $1, %rcx   # if <= 0, done
    irmovq $0, %rax
    irmovq $1, %rdx   # sum = 0
    .L3:
        rmovq %rdi, %rsi
        addq   %rdx, %rax
        addq   $1, %rdx   # i += 1
        subq   %rdx, %rsi
        jge .L3  # temp = n
        ret
        .L4:
            irmovq $0, %rax  # done
            ret
```

How does it get the argument? How does it return the value?
Encoding Registers

Each register has an associated 4-bit id:

<table>
<thead>
<tr>
<th>Register</th>
<th>ID</th>
</tr>
</thead>
<tbody>
<tr>
<td>%rax</td>
<td>0</td>
</tr>
<tr>
<td>%rcx</td>
<td>1</td>
</tr>
<tr>
<td>%rdx</td>
<td>2</td>
</tr>
<tr>
<td>%rax</td>
<td>3</td>
</tr>
<tr>
<td>%r8</td>
<td>4</td>
</tr>
<tr>
<td>%r9</td>
<td>5</td>
</tr>
<tr>
<td>%r10</td>
<td>6</td>
</tr>
<tr>
<td>%r14</td>
<td>7</td>
</tr>
<tr>
<td>%rcx</td>
<td>8</td>
</tr>
<tr>
<td>%rdx</td>
<td>9</td>
</tr>
<tr>
<td>%rax</td>
<td>A</td>
</tr>
<tr>
<td>%r9</td>
<td>B</td>
</tr>
<tr>
<td>%r11</td>
<td>C</td>
</tr>
<tr>
<td>%r12</td>
<td>D</td>
</tr>
<tr>
<td>%r13</td>
<td>E</td>
</tr>
<tr>
<td>%r14</td>
<td>F</td>
</tr>
</tbody>
</table>

Almost the same encoding as in x86-64.

Most of these registers are general purpose; %rsp has special functionality.

Y86 Instruction Set (2)

Y86 Instruction Set (3)

Y86 Instruction Set (4)

Encompasses:

encompasses:

unconditional jump

jump if less or equal

jump if less

jump if equal

jump if not equal

jump if greater or equal

jump if greater
Simple Addressing Modes

- **Immediate**: value
  - irmovq $0xab, %rbx

- **Register**: Reg[R]
  - rrmovq %rcx, %rbx

- **Normal (R)**: Mem[Reg[R]]
  - Register R specifies memory address.
  - This is often called *indirect* addressing.
  - mrmovq (%rcx), %rax

- **Displacement D(R)**: Mem[Reg[R]+D]
  - Register R specifies start of memory region.
  - Constant displacement D specifies offset
  - mrmovq 8(%rcx), %rdx

Conventions

It’s important to understand how individual operations update the system state. *But that’s not enough!*

Much of the way the Y86/x86 operates is based on a set of *programming conventions*. Without them, you won’t understand how programs work, what the compiler generates, or how your code can interact with code written by others.

Sample Program

Let’s write a fragment of Y86 assembly code. Our program swaps the 8-byte values starting in memory locations 0x0100 (value A) and 0x0200 (value B).

```assembly
start:
  xorq %rax, %rax
  mrmovq 0x100(%rax), %rbx
  mrmovq 0x200(%rax), %rcx
  rrmovq %rcx, 0x100(%rax)
  rrmovq %rbx, 0x200(%rax)
  halt
```

<table>
<thead>
<tr>
<th>Reg.</th>
<th>Use</th>
</tr>
</thead>
<tbody>
<tr>
<td>%rax</td>
<td>0</td>
</tr>
<tr>
<td>%rbx</td>
<td>A</td>
</tr>
<tr>
<td>%rcx</td>
<td>B</td>
</tr>
</tbody>
</table>

It’s usually a good idea to have a table like this to keep track of the use of registers.
Now, we generate the machine code for our sample program. Assume that it is stored in memory starting at location 0x030. *I did this by hand, so check for errors!*

<table>
<thead>
<tr>
<th>Location</th>
<th>Machine Code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x030:</td>
<td>6300</td>
</tr>
<tr>
<td>0x032:</td>
<td>50300000100000000000000000000000</td>
</tr>
<tr>
<td>0x03c:</td>
<td>50100002000000000000000000000000</td>
</tr>
<tr>
<td>0x046:</td>
<td>40100001000000000000000000000000</td>
</tr>
<tr>
<td>0x050:</td>
<td>40300002000000000000000000000000</td>
</tr>
<tr>
<td>0x05a:</td>
<td>00</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Reg.</th>
<th>Use</th>
</tr>
</thead>
<tbody>
<tr>
<td>%rax</td>
<td>0</td>
</tr>
<tr>
<td>%rbx</td>
<td>A</td>
</tr>
<tr>
<td>%rcx</td>
<td>B</td>
</tr>
</tbody>
</table>

**A Peak Ahead: Argument Passing**

By convention, the first 6 parameters to any procedure are passed in order in 6 specific registers. Others are passed on the stack in reverse order.

**Registers: First 6 arguments**

```
%rdi  %rsi  %rdx  %rcx  %r8  %r9
```

Mnemonic to remember the order: “*Diane’s silk dress cost $89.*”

**Return value**

```
%rax
```

**Addition Instruction**

Generic form: `addq rA, rB`

Encoded representation: `

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>6</td>
<td>0</td>
<td>rA rB</td>
</tr>
</tbody>
</table>

- Add value in register rA to that in register rB.
  - Store result in register rB
  - Note that Y86 only allows addition to be applied to register data.
- E.g., `addq %rax, %rsi` is encoded as: 60 06. *Why?*
- Set condition codes based on the result.
- Two byte encoding:
  - First indicates instruction type.
  - Second gives source and destination registers.

**Effects on the State**

You completely characterize an operation by saying how it changes the state.

What effects does `addq %rsi, %rdi` have on the state?
Effects on the State

You completely characterize an operation by saying how it changes the state.

What effects does `addq %rsi, %rdi` have on the state?

- Set contents of `%rdi` to the sum of the current contents of `%rsi` and `%rdi`.
- Set condition codes based on the result of the sum.
  - OF: set (i.e., is 1) iff the result causes an overflow
  - ZF: set iff the result is zero
  - SF: set iff the result is negative
- Increment the program counter by 2. Why 2?

There are no effect on the memory or status flag.

Arithmetic and Logical Operations

Add

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Encoding</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>addq rA, rB</code></td>
<td>6 0  rA rB</td>
<td>Refer to generically as “OPq”</td>
</tr>
</tbody>
</table>

Subtract (rA from rB)

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Encoding</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>subq rA, rB</code></td>
<td>6 1  rA rB</td>
<td>Encodings differ only by “function code”: lower-order 4-bits in first instruction byte.</td>
</tr>
</tbody>
</table>

And

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Encoding</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>andq rA, rB</code></td>
<td>6 2  rA rB</td>
<td>Set condition codes as side effect.</td>
</tr>
</tbody>
</table>

Exclusive Or

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Encoding</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>xorq rA, rB</code></td>
<td>6 3  rA rB</td>
<td></td>
</tr>
</tbody>
</table>

Move Operations

Register to Register

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Encoding</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>rrmovq rA, rB</code></td>
<td>2 0  rA rB</td>
<td></td>
</tr>
</tbody>
</table>

Immediate to Register

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Encoding</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>irmovq V, rB</code></td>
<td>3 0  F  rB V</td>
<td></td>
</tr>
</tbody>
</table>

Register to Memory

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Encoding</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>rmmovq rA, D(rB)</code></td>
<td>4 0  rA rB D</td>
<td>Similar to the x86-64 movq instruction.</td>
</tr>
</tbody>
</table>

Memory to Register

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Encoding</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>rmrmovq D(rB), rA</code></td>
<td>5 0  rA rB D</td>
<td>Similar format for memory addresses.</td>
</tr>
</tbody>
</table>

Move Instruction Examples

<table>
<thead>
<tr>
<th>x86-64</th>
<th>Y86</th>
<th>Y86 Encoding</th>
</tr>
</thead>
<tbody>
<tr>
<td>movq $0xabcd, %rdx</td>
<td>irmovq $0xabcd, %rdx</td>
<td>30 F2 cd ab 00 00 00 00 00 00</td>
</tr>
<tr>
<td>movq %rsi, %rbx</td>
<td>rrmovq %rsi, %rbx</td>
<td>20 43</td>
</tr>
<tr>
<td>movq -12(%rbp), %rcx</td>
<td>rrmovq -12(%rbp), %rcx</td>
<td>50 15 f4 ff ff ff ff ff ff</td>
</tr>
<tr>
<td>movq %rsi, 0x41c(%rsp)</td>
<td>rrmovq %rsi, 0x41c(%rsp)</td>
<td>40 64 1c 04 00 00 00 00 00 00</td>
</tr>
<tr>
<td>movq %rax, %rdx</td>
<td>none</td>
<td></td>
</tr>
<tr>
<td>movq %rdx, %rax</td>
<td>none</td>
<td></td>
</tr>
</tbody>
</table>

The Y86 adds special move instructions to compensate for the lack of certain addressing modes.
Conditional Move Instructions

Move (conditionally)

<table>
<thead>
<tr>
<th>cmovXX rA, rB</th>
<th>2</th>
<th>fn</th>
<th>rA</th>
<th>rB</th>
</tr>
</thead>
</table>

- Refer to generically as "cmovXX"
- Encodings differ only by function code fn
- rrmovq instruction is a special case
- Based on values of condition codes
- Conditionally copy value from source to destination register

Note that rrmovq is a special case of cmovXX.

Example of CMOV

Suppose you want to compile the following C code:

```c
long min (long x, long y) {
    if (x <= y)
        return x;
    else
        return y;
}
```

The following is one potential implementation of this. Notice that there are no jumps.

```
min:
    rrmovq %rdi, %rax  # ans ← x
    rrmovq %rdi, %r8   # temp ← x
    subq %rsi, %r8    # if (temp − y) > 0
    cmovge %rsi, %rax # ans ← y
    ret
```

Jump Instructions

Jump (conditionally)

| jXX Dest | 7 | fn | Dest |

- Refer to generically as "jXX"
- Encodings differ only by function code fn
- Based on values of condition codes
- Same as x86-64 counterparts
- Encode full destination address (unlike PC-relative addressing in x86-64)
### Jump Instructions

<table>
<thead>
<tr>
<th>Jump Unconditionally</th>
<th>jmp Dest</th>
<th>7</th>
<th>0</th>
<th>Dest</th>
</tr>
</thead>
<tbody>
<tr>
<td>Jump when less or equal</td>
<td>jle Dest</td>
<td>7</td>
<td>1</td>
<td>Dest</td>
</tr>
<tr>
<td>Jump when less</td>
<td>jl Dest</td>
<td>7</td>
<td>2</td>
<td>Dest</td>
</tr>
<tr>
<td>Jump when equal</td>
<td>je Dest</td>
<td>7</td>
<td>3</td>
<td>Dest</td>
</tr>
<tr>
<td>Jump when not equal</td>
<td>jne Dest</td>
<td>7</td>
<td>4</td>
<td>Dest</td>
</tr>
<tr>
<td>Jump when greater or equal</td>
<td>jge Dest</td>
<td>7</td>
<td>5</td>
<td>Dest</td>
</tr>
<tr>
<td>Jump when greater</td>
<td>jg Dest</td>
<td>7</td>
<td>6</td>
<td>Dest</td>
</tr>
</tbody>
</table>

### Jump Example

Suppose you want to count the number of elements in a null terminated list A with starting address in %rdi.

```c
len:
  irmovq $0, %rax # result = 0
  mrmovq (%rdi), %rdx # val = *A
  andq %rdx, %rdx # Test val
  je Done # If 0, goto Done
Loop:
  ...
Done:
  ret
```

### Y86 Program Stack

- Region of memory holding program data.
- Used in Y86 (and x86-64) for supporting procedure calls.
- Stack top is indicated by %rsp, address of top stack element.
- Stack grows toward lower addresses.
  - Top element is at lowest address in the stack.
  - When pushing, must first decrement stack pointer.
  - When popping, increment stack pointer.

### Stack Operations

**Push**

```c
pushq rA | a 0 rA F
```

- Decrement %rsp by 8.
- Store quad word from rA to memory at %rsp.
- Similar to x86-64 pushq operation.

**Pop**

```c
popq rA | b 0 rA F
```

- Read quad word from memory at %rsp.
- Save in rA.
- Increment %rsp by 8.
- Similar to x86-64 popq operation.
Subroutine Call and Return

Subroutine call

```
call Dest
```

- Push address of next instruction onto stack.
- Start executing instructions at Dest.
- Similar to x86-64 call instruction.

Subroutine return

```
ret
```

- Pop value from stack.
- Use as address for next instruction.
- Similar to x86-64 ret instruction.

*Note that call and ret don’t implement parameter/return passing.*
You have to do that in your code.

Miscellaneous Instructions

No operation

```
nop
```

- Don’t do anything but advance PC.

Halt execution

```
halt
```

- Stop executing instructions; set status to HLT.
- x86-64 has a comparable instruction, but you can’t execute it in user mode.
- We will use it to stop the simulator.
- Encoding ensures that program hitting memory initialized to zero will halt.

Status Conditions

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Code</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>AOK</td>
<td>1</td>
<td>Normal operation</td>
</tr>
<tr>
<td>HLT</td>
<td>2</td>
<td>Halt inst. encountered</td>
</tr>
<tr>
<td>ADR</td>
<td>3</td>
<td>Bad address (instr. or data)</td>
</tr>
<tr>
<td>INS</td>
<td>4</td>
<td>Invalid instruction</td>
</tr>
</tbody>
</table>

*Desired behavior:*

- If AOK, keep executing
- Otherwise, stop program execution

Writing Y86 Code

Try to use the C compiler as much as possible.

- Write code in C.
- Compile for x86-64 with `gcc -Og -S`.
- Transliterate into Y86 code.
- Modern compilers make this more difficult, because they optimize by default.

To understand Y86 (or x86) code, you have to know the meaning of the statement, but also certain *programming conventions*, especially the *stack discipline*.

- How do you pass arguments to a procedure?
- Where are local variables created?
- How does a procedure return a value?
- How do procedures save and restore the state of the caller?
**Coding example:** Find number of elements in a null-terminated list.

```c
long len1(long a[]);
```

The answer in this case should be 3.

**Problem:** Hard to do array indexing on Y86, since we don’t have scaled addressing modes.

**x86 Code:**

```assembly
L3:
addq $1, %rax
cmpq $0, (%rdi, %rax, 8)
jne L3
```

Compile with gcc -Og -S

**Result:**

- Compiler generates exact same code as before!
- Compiler converts both versions into the same intermediate form.
**Y86 Sample Program Structure**

```
init:     # Initialization
  ...
call Main
halt
.align 8 # Program data
Array:
  ...
Main:     # Main function
  ...
call len
len:      # Length function
  ...
pos 0x100 # Place stack
Stack:
```

- Program starts at address 0
- Must set up stack
  - Where located
  - Pointer values
  - Mustn't overwrite data
- Must initialize data

**Y86 Program Structure (2)**

```
init:     # Set up stack pointer
  irmovq Stack, %rsp
# Execute main program
  call Main
# Terminate
  halt

# Array of 4 elements + final 0
.align 8
Array:
  .quad 0x000d000d000d000d
  .quad 0x00c000c000c000c0
  .quad 0xb000b000b000b00
  .quad 0xa000a000a000a00
  .quad 0
```

- Program starts at address 0
- Must set up stack
- Must initialize data
- Can use symbolic names

**Y86 Program Structure (3)**

```
Main:
  irmovq Array, %rdi
# call len(Array)
call len
ret
```

Set up call to len:
- Follow x86-64 procedure conventions
- Pass array address as argument

**Y86 Assembler**

A program that translates Y86 code into machine language.
- 1-1 mapping of instructions to encodings.
- Resolves symbolic names.
- Translation is linear.
- Assembler directives give additional control.

Some common directives:
- .pos x: subsequent lines of code start at address x.
- .align x: align the next line to an x-byte boundary (e.g., long ints should be at a quadword address, divisible by 8).
- .quad x: put an 8-byte value x at the current address; a way to initialize a value.
Assembling Y86 Program

unix> yas len.ys

- Generates “object code” file len.yo
- Actually looks like disassembler output

| len : | 0x054 : | 30f80100000000000000000 |
|       | 0x055 : | 30f90800000000000000000 |
|       | 0x056 : | 30f00000000000000000000 |
|       | 0x057 : | 502700000000000000000000 |
|       | 0x05c : | 30f90800000000000000000 |
|       | 0x05f : | 30f00000000000000000000 |
|       | 0x06a : | 502700000000000000000000 |
|       | 0x06b : | 30f90800000000000000000 |
|       | 0x06c : | 30f00000000000000000000 |
|       | 0x06f : | 502700000000000000000000 |
|       | 0x070 : | 30f90800000000000000000 |
|       | 0x071 : | 30f00000000000000000000 |
|       | 0x072 : | 502700000000000000000000 |
|       | 0x073 : | 30f90800000000000000000 |
|       | 0x074 : | 30f00000000000000000000 |
|       | 0x075 : | 502700000000000000000000 |

Simulating Y86 Programs

unix> yis len.yo

- Instruction set simulator
- Computes effect of each instruction on process state
- Prints changes in state from original

Stopped in 33 steps at PC = 0x13, Status 'HLT', CC Z=1
S=0 O=0

Changes to registers:
%rax: 0x0000000000000000 0x0000000000000004
%rsp: 0x0000000000000000 0x0000000000000100
%rdi: 0x0000000000000000 0x0000000000000038
%rbx: 0x0000000000000000 0x0000000000000001
%rcx: 0x0000000000000000 0x0000000000000000
%rdx: 0x0000000000000000 0x0000000000000000
%rsi: 0x0000000000000000 0x0000000000000000
%rdi: 0x0000000000000000 0x0000000000000000
%rsi: 0x0000000000000000 0x0000000000000000
%r9: 0x0000000000000000 0x0000000000000000
%r10: 0x0000000000000000 0x0000000000000000
%r11: 0x0000000000000000 0x0000000000000000
%r12: 0x0000000000000000 0x0000000000000000
%r13: 0x0000000000000000 0x0000000000000000
%r14: 0x0000000000000000 0x0000000000000000
%r15: 0x0000000000000000 0x0000000000000000

Changes to memory:
0x00f0: 0x0000000000000000 0x0000000000000000
0x00f1: 0x0000000000000000 0x0000000000000000
0x00f2: 0x0000000000000000 0x0000000000000000
0x00f3: 0x0000000000000000 0x0000000000000000
0x00f4: 0x0000000000000000 0x0000000000000000
0x00f5: 0x0000000000000000 0x0000000000000000
0x00f6: 0x0000000000000000 0x0000000000000000
0x00f7: 0x0000000000000000 0x0000000000000000
0x00f8: 0x0000000000000000 0x0000000000000000
0x00f9: 0x0000000000000000 0x0000000000000000
0x00fa: 0x0000000000000000 0x0000000000000000
0x00fb: 0x0000000000000000 0x0000000000000000
0x00fc: 0x0000000000000000 0x0000000000000000
0x00fd: 0x0000000000000000 0x0000000000000000
0x00fe: 0x0000000000000000 0x0000000000000000
0x00ff: 0x0000000000000000 0x0000000000000000

RISC Instruction Sets

Reduced Instruction Set Computer

- Originated in IBM Research; popularized in Berkeley and Stanford projects.
- Few, simple instructions.
  - Takes more instructions to execute a task, but faster and simpler implementation
  - Fixed length instructions for simpler decoding
- Register-oriented ISA
  - More registers (32 typically)
  - Stack is back-up for registers
- Only load and store instructions can access memory (mrmovq and rmmovq in Y86).
- Explicit test instructions set condition values in register.
- Philosophy: KISS

Complex Instruction Set Computer

- Dominant ISA style through the 80s.
- Lots of instructions:
  - Variable length
  - Stack as mechanism for supporting functions
  - Explicit push and pop instructions.
- ALU instructions can access memory.
  - E.g., addq %rax, 12(%rbx, %rcx, 8)
  - Requires memory read and write in one instruction execution.
  - Some ISAs had much more complex address calculations.
- Set condition codes as a side effect of other instructions.
- Basic philosophy:
  - Memory is expensive;
  - Instructions to support high-level language constructs.
### Original Debate
- Strong opinions!
- CISC proponents—easy for compiler, fewer code bytes
- RISC proponents—better for optimizing compilers, can make run fast with simple chip design

### Current Status
- For desktop processors, choice of ISA not a technical issue
  - With enough hardware, can make anything run fast
  - Code compatibility more important
- x86-64 adopted many RISC features
  - More registers; use them for argument passing
- For embedded processors, RISC makes sense
  - Smaller, cheaper, less power
  - Most cell phones use ARM processor

### Y86-64 Instruction Set Architecture
- Similar state and instructions to x86-64
- Simpler encodings
- Somewhere between CISC and RISC

### How Important is ISA Design?
- Less now than before: with enough hardware, can make almost anything run fast!