

Lecture 14: Iterative Hard Thresholding

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NOTE: THESE NOTES HAVE NOT BEEN EDITED OR CHECKED FOR CORRECTNESS**Theorem 0.0.1.** *If A satisfies $(O(k), \epsilon (= 0.001))$ -RIP, then we can perform compressed sensing:**Given $y = Ax + e$ and $\|x\|_0 \leq k$, recover \hat{x} such that*

$$\|\hat{x} - x\|_2 \leq O(\|e\|_2)$$

therefore, we can get an upper bound if x is not k -sparse by

$$\begin{aligned} x &= x_k + (x - x_k) \\ Ax &= Ax_k + \underbrace{A(x - x_k)}_e \end{aligned}$$

1 Iterative Hard Thresholding (IHT)

1.1 The idea

Given a matrix A satisfies the RIP, then for all $O(k)$ -sparse x , we have

$$\begin{aligned} \Leftrightarrow \|Ax\|_2^2 &= (1 \pm \epsilon) \|x\|_2^2 \\ \Leftrightarrow x^T A^T Ax &= (1 \pm \epsilon) x^T x \\ \Leftrightarrow |x^T (A^T A - I)x| &\leq \epsilon x^T x \\ \Leftrightarrow \|(A^T A - I)_{S \times S}\|_2 &\leq \epsilon, \quad \forall S \subseteq [n] : |S| \leq O(k) \end{aligned}$$

Given y where $y = Ax + e$, we want to estimate x .

Idea: let

$$z = A^T y = \underbrace{A^T A}_{\approx I \text{ on sparse sets}} x + \underbrace{A^T e}_{\text{small if } e \text{ is small}}$$

Then

$$z - x = (A^T A - I)x + A^T e$$

Let $S \subseteq [n]$ such that $|S| \leq O(k)$ and $S \supseteq \text{supp}(x)$. Then

$$\|(z - x)_S\|_2 \leq \|(A^T A - I)x\|_2 + \|A^T e\|_2$$

Now we need to bound the two terms on the right-hand side.

$$\begin{aligned}\|[(A^T A - I)x]_S\|_2 &= \|(A^T A - I)_{S \times S} x_S\|_2 \quad \text{since } \text{supp}(x) \subseteq S \\ &\leq \|(A^T A - I)_{S \times S}\|_2 \cdot \|x_S\|_2 \\ &\leq \epsilon \|x\|_2\end{aligned}$$

and

$$\begin{aligned}\|(A^T e)_S\|_2 &\leq \|(A^T)_S\|_2 \cdot \|e\|_2 \\ &\leq \sqrt{\|(A^T A)_{S \times S}\|_2} \cdot \|e\|_2 \\ &\leq \sqrt{1 + \epsilon} \|e\|_2 \\ &\leq 2 \|e\|_2\end{aligned}$$

Thus,

$$\|(z - x)_S\|_2 \leq \epsilon \|x\|_2 + 2 \|e\|_2$$

We want error: $\|\hat{x} - x\| \leq O(\|e\|_2)$.

Idea: In order to reduce the error, we can apply the same method to the vector $r = x - z$. We now know

$$y^{(2)} = A(x - z) + e = y - Az$$

We set

$$z^{(2)} = A^T y^{(2)}$$

and let

$$\hat{r} = z^{(2)} - z$$

Then \hat{r} is an estimate of r and

$$\begin{aligned}\|(z^{(2)} - x)_S\|_2 &= \|(z + \hat{r} - x)_S\|_2 \\ &= \|(\hat{r} - (x - z))_S\|_2 \\ &\leq \epsilon \|x - z\|_2 + 2 \|e\|_2\end{aligned}$$

However, there are two problems with the idea:

1. The vector $r = x - z$ is no longer k -sparse so the equality in our first argument $\|[(A^T A - I)x]_S\|_2 = \|(A^T A - I)_{S \times S} x_S\|_2$ no longer holds.
2. From the first argument we got a bound on $\|(z - x)_S\|_2$ but our idea bounds $\|(z^{(2)} - x)_S\|_2$ using $\|x - z\|_2$.

Algorithm 1 Iterative Hard Thresholding (IHT)

1: **for** $r = 0, 1, \dots, R - 1$ **do**
2: $x^{(r+1)} = H_k(x^{(r)} + A^T(y - Ax^{(r)}))$
3: **end for**
4: **return** $x^{(R)}$

1.2 The algorithm

It turns out there is a simple fix to our idea: at the end of each update, we restrict the vector to the largest k values. See Algorithm 1.

Lemma 1.2.1.

$$\|x^{(r+1)} - x\|_2 \leq O(\epsilon) \|x^{(r)} - x\|_2 + O(\|e\|_2)$$

Proof. Set $S = \text{supp}(x) \cup \text{supp}(x^{(r)}) \cup \text{supp}(x^{(r+1)})$ and thus $|S| \leq 3k$. As before,

$$\| [A^T(A(x - x^{(r)}) + e) - (x - x^{(r)})]_S \|_2 \leq \epsilon \|x - x^{(r)}\|_2 + 2\|e\|_2$$

Note that in our algorithm:

$$A^T(y - Ax^{(r)}) = A^T A(x - x^{(r)}) + e$$

and if we let

$$z = x^{(r)} + A^T(y - Ax^{(r)})$$

then our algorithm becomes

$$x^{(r+1)} = H_k(z)$$

and the inequality becomes

$$\|(z - x)_S\|_2 \leq \|x - x^{(r)}\|_2 + 2\|e\|_2$$

We need the following lemma to proceed.

Lemma 1.2.2. *If $x, z \in \mathbb{R}^n$ and x is k -sparse with $S = \text{supp}(x)$, and $T \subseteq [n]$ contains the indices of k largest values in z , then*

$$\|x - z_T\|_2^2 \leq O(1) \|(x - z)_{S \cup T}\|_2^2$$

This implies

$$\begin{aligned} \|x - x^{(r+1)}\|_2 &\leq O(1) \|(x - z)_{\text{supp}(x) \cup \text{supp}(x^{(r+1)})}\|_2 \\ &\leq O(\epsilon) \|x - x^{(r)}\|_2 + O(\|e\|_2) \end{aligned}$$

Proof of Lemma 1.2.2. Consider the following three sets: $S \cap T$, $S \setminus T$, $T \setminus S$.

$$\begin{aligned} \|x - z_T\|_2^2 &= \underbrace{\|(x - z)_{S \cap T}\|_2^2}_{\leq \|(x - z)_{S \cup T}\|_2^2} + \|x_{S \setminus T}\|_2^2 + \underbrace{\|z_{T \setminus S}\|_2^2}_{= \|(x - z)_{T \setminus S}\|_2^2} \\ &\leq \|(x - z)_{S \cup T}\|_2^2 + \|(x - z)_{T \setminus S}\|_2^2 \\ &\leq \|(x - z)_{S \cup T}\|_2^2 \end{aligned}$$

Now we analyze $\|x_{S \setminus T}\|_2^2$. The trick is to notice that since $|S| = |T|$, then $|S \setminus T| = |T \setminus S|$. Therefore, for all $i \in S \setminus T$ we can pair with a $j \in T \setminus S$ such that $|z_i| \leq |z_j|$ (or we use the fact that $\|z_{S \setminus T}\|_2^2 \leq \|z_{T \setminus S}\|_2^2$). Thus,

$$\begin{aligned} x_i^2 &= (x_i - z_i + z_i)^2 \\ &\leq (|z_i| + |z_i - x_i|)^2 \\ &\leq (|z_j| + |z_i - x_i|)^2 \\ &\leq 2|z_j|^2 + 2|z_i - x_i|^2 \end{aligned}$$

and

$$\begin{aligned} \|x_{S \setminus T}\|_2^2 &\leq 2\|z_{T \setminus S}\|_2^2 + 2\|(z - x)_{S \setminus T}\|_2^2 \\ &\leq 2\|(x - z)_{S \cup T}\|_2^2 \end{aligned}$$

□

Thus, for small ϵ , we have

$$\begin{aligned} \|x^{(r+1)} - x\|_2 &\leq \frac{1}{4} \|x^{(r)} - x\|_2 + O(\|e\|_2) \\ &\leq \frac{1}{2} \|x^{(r)} - x\|_2 \quad \text{unless } \|x^{(r)} - x\|_2 \leq O(\|e\|) \end{aligned}$$

and we can converge geometrically to $O(\|e\|_2)$ if we pick

$$R = \log_2 \frac{\|x\|_2}{\|e\|_2}$$

□

2 A Brief Introduction to Model-based Compressed Sensing

Suppose x is k -sparse and $\text{supp}(x) \in \mathcal{F}$ where \mathcal{F} is a subset of the family of all $\binom{n}{k}$ subsets of size k .

- Block sparsity. If the non-zeros in the vector are concentrated in blocks with block size $B > \log n$, then

$$|\mathcal{F}| \leq \binom{n/B}{k/B} \lesssim 2^{\frac{k}{B} \log \frac{n}{k}} \lesssim 2^k$$

- Tree sparsity (often appears in wavelet). In tree sparsity, each large coordinate correspondingly has 3 children. We want to find a subset of tree that is connected with k nonzeros. Consider the Eulerian tour on the large coordinates. At each step we can choose to go downleft, downright and up. We make at most $2k$ choices. We have $|\mathcal{F}| \leq 3^{2k} \leq 2^{O(k)}$.

Model-based RIP for \mathcal{F} : if $\forall x$ with $\text{supp}(x) \in \mathcal{F} \oplus \mathcal{F} = \{S \cup T : S, T \in \mathcal{F}\}$,

$$\|Ax\|_2^2 = (1 \pm \epsilon) \|x\|_2^2$$

[For Gaussian matrices: we need $O(k)$ measurements since $N(\epsilon, T_{\mathcal{F}}, \|\cdot\|_2) \leq (1/\epsilon)^k 2^{O(k)}$].

If we run model-IHT, we need to change H_k to $H_{\mathcal{F}}$. However, $H_{\mathcal{F}}$ could be slow. ($O(nk)$ for tree by DP and $O(n \log n)$ for $O(1)$ -approximation).