CS378: Natural Language Processing

Lecture 14: Neural Network (Sequence)



Slides from Greg Durrett, Yoav Artzi, Yejin Choi.



Neural Network

- Recurrent Neural Network (RNN)
 - Input is a variable length sequence, but output is not.
- Encoder-Decoder model
 - Both input / output is a variable length sequence
 - Attention mechanism
- Alternative approaches to model sequence
 - Convolutional Neural Network
 - Transformer

Readings

- Recurrent Neural Network (RNN)
 - ► J&M 9
- Encoder-Decoder model
 - ► J&M 10

- Thursday: Alternative approaches to model sequence
 - Convolutional Neural Network [Voita]
 - Transformer [Vaswani et al, 2017], JM 11.2-5



Logistics

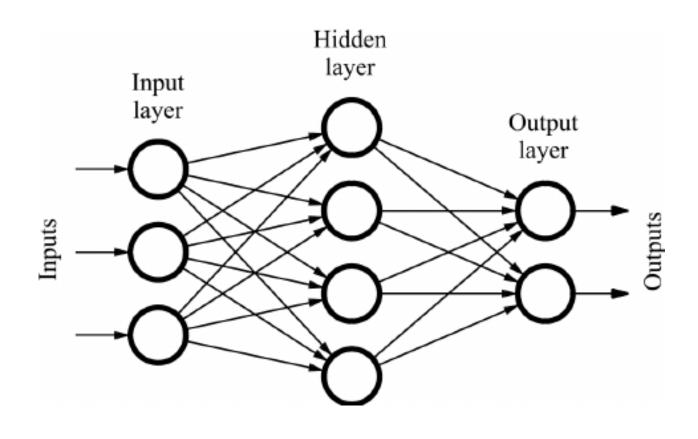
Independent study proposal — I'll return it sometime this week!

HW3 intermediate deadline today

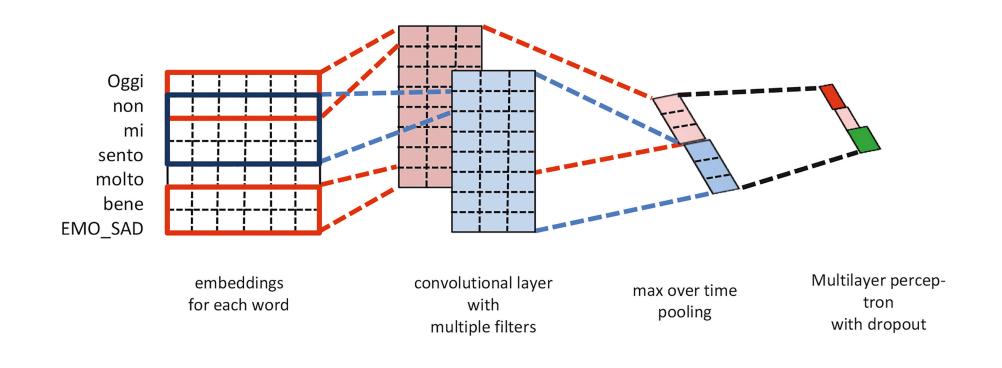


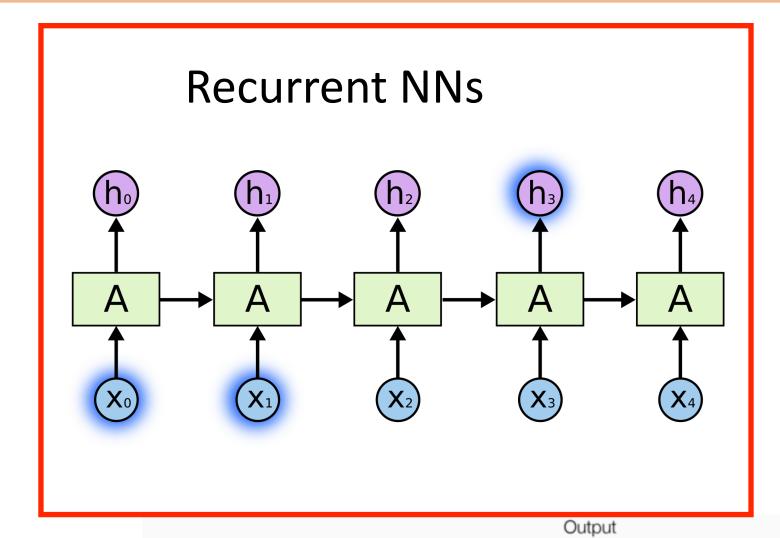
Neural Networks in NLP

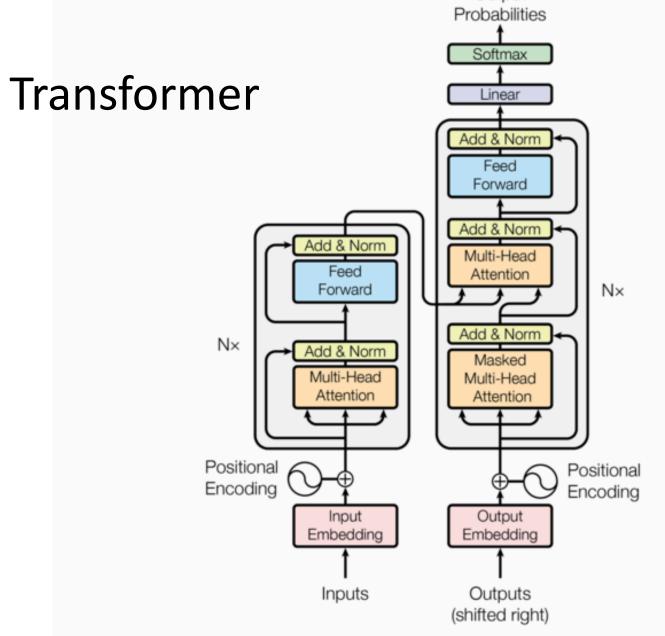
Feed-forward NNs



Convolutional NNs







Credits: Princeton NLP course



Recap: RNNs

- Maps from dense input sequence to dense hidden state representation sequence $x_1, ..., x_n \rightarrow h_1, ..., h_n$
- $S = \mathbb{R}^{d_{hid}}$ hidden state space $(h_1, h_2 \dots)$
- $\Sigma = \mathbb{R}^{d_{in}}$ input state space $(x_1, x_2 \dots)$
- $\mathbf{s}_0 \in S$ initial state vector (h_0)
- $R: \mathbb{R}^{d_{in}} imes \mathbb{R}^{d_{hid}} o \mathbb{R}^{d_{hid}}$ transition function

- For all $i \in \{1, ..., n\}$,
 - $h_i = R(h_{i-1}, \mathbf{x}_i)$
 - Simple definition of R: $R(h_{i-1}, x_i) = \tanh(Wx_i + Vh_{i-1} + b)$
 - R is parameterized, where the parameters are shared across all steps.

$$h_4 = R(h_3, \mathbf{x}_4) = \dots = R(R(R(R(h_0, \mathbf{x}_1), \mathbf{x}_2), \mathbf{x}_3), \mathbf{x}_4)$$



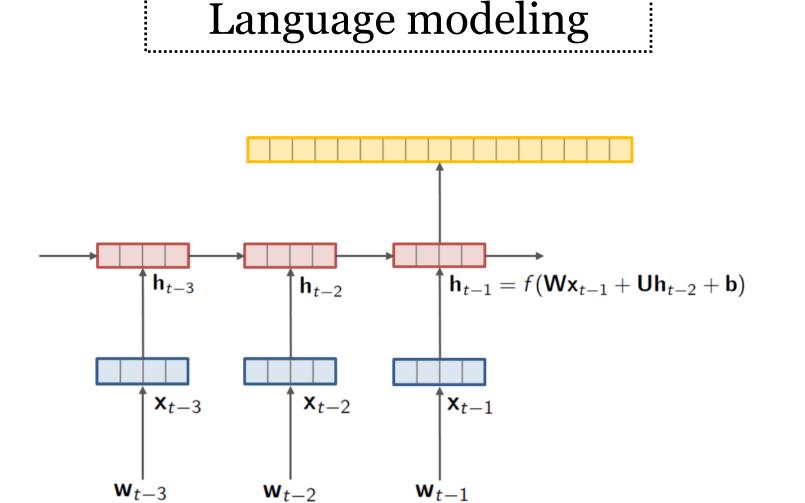
Recap: RNNs

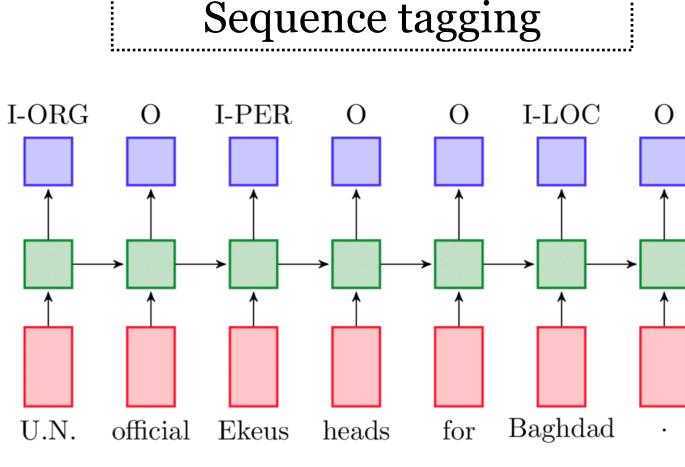
- lacksquare Hidden states h_i can be used in different ways
- Output function maps hidden state vectors to symbols:

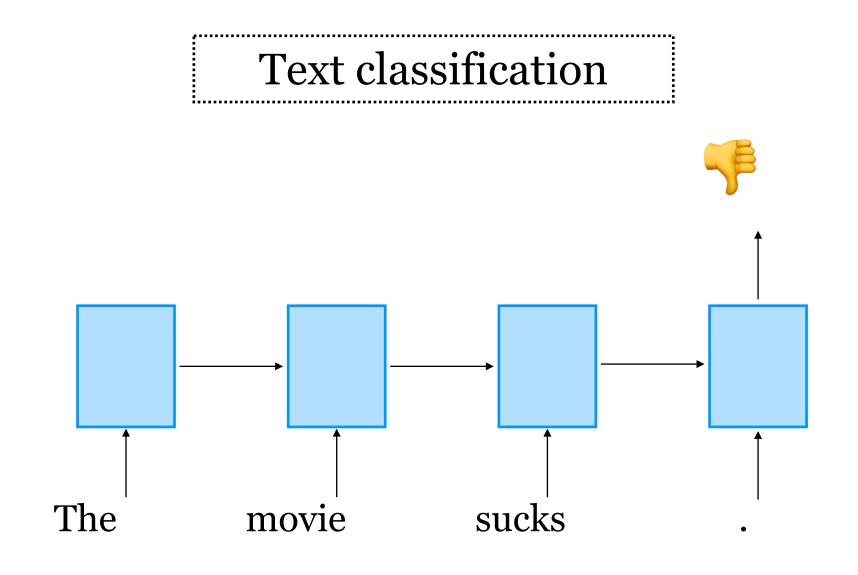
$$O: \mathbb{R}^{d_{hid}}
ightarrow \mathbb{R}^{d_{out}}$$

For example: single layer + softmax

$$O(h_i) = \operatorname{softmax}(h_i W + b)$$



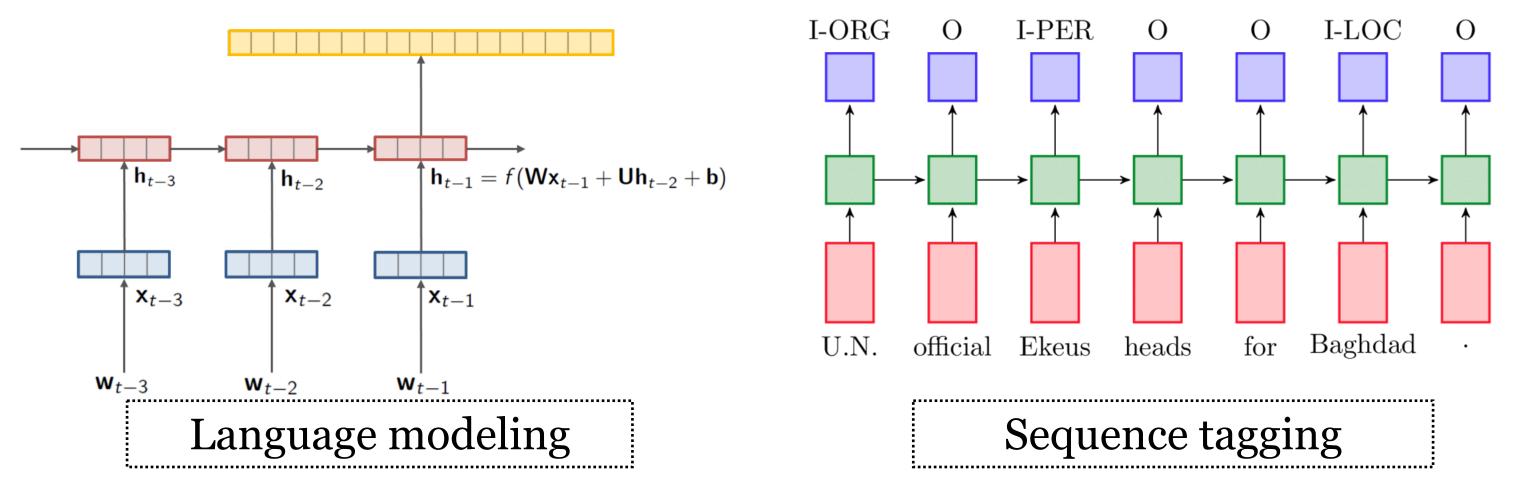




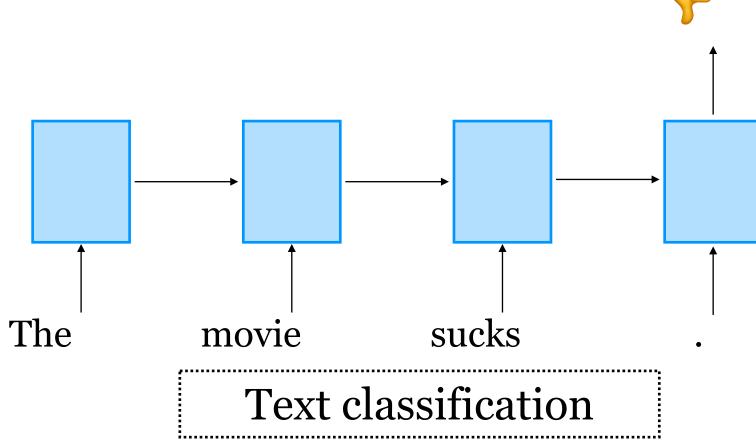


Output functions can be

Transducer: make some prediction for each element in a sequence



 Acceptor/encoder: encode a sequence into a fixed-sized vector and use that for some purpose

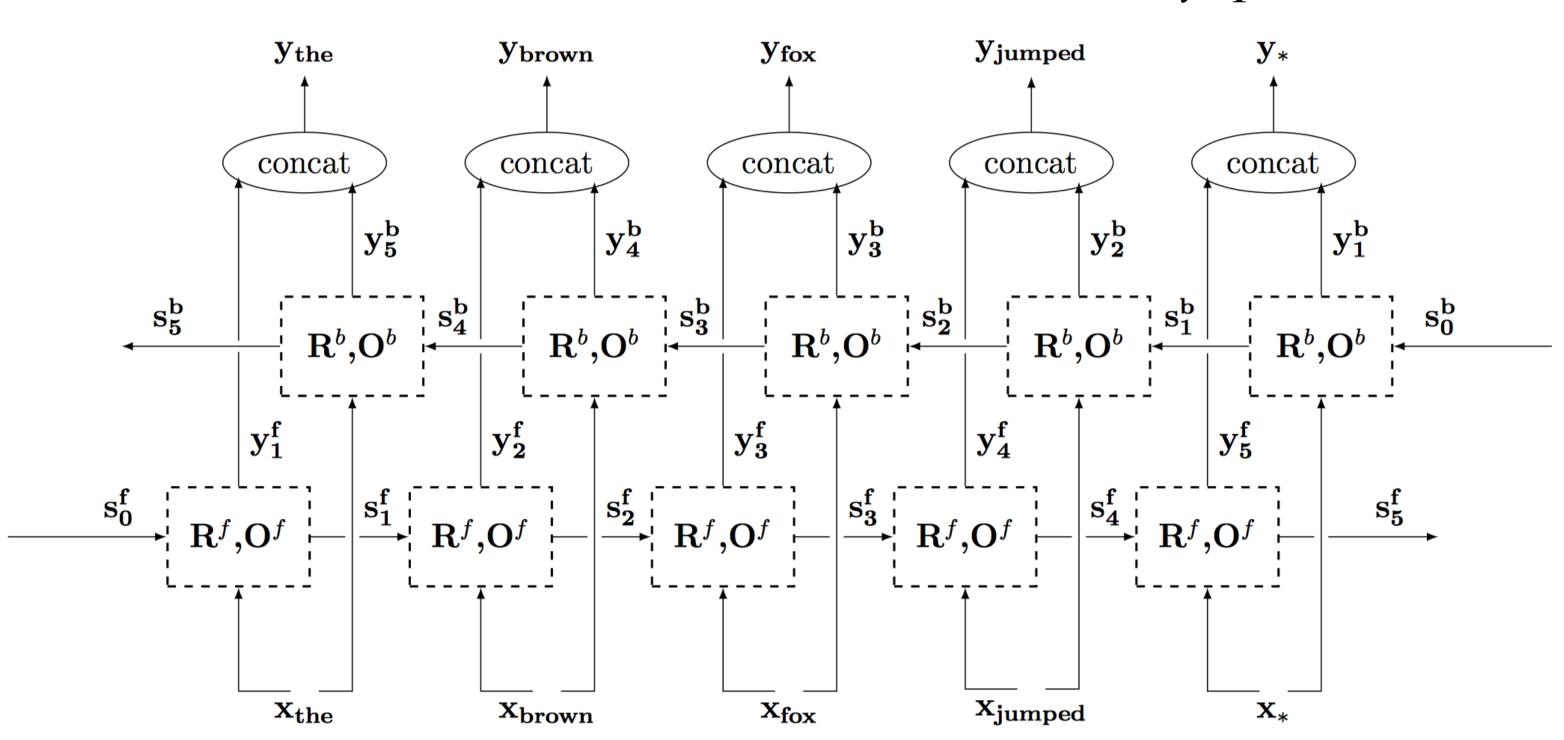




Bi-directional RNNs

- RNN decisions are based on historical (past) data only.
- How can we account for future input?
- Is it realistic?

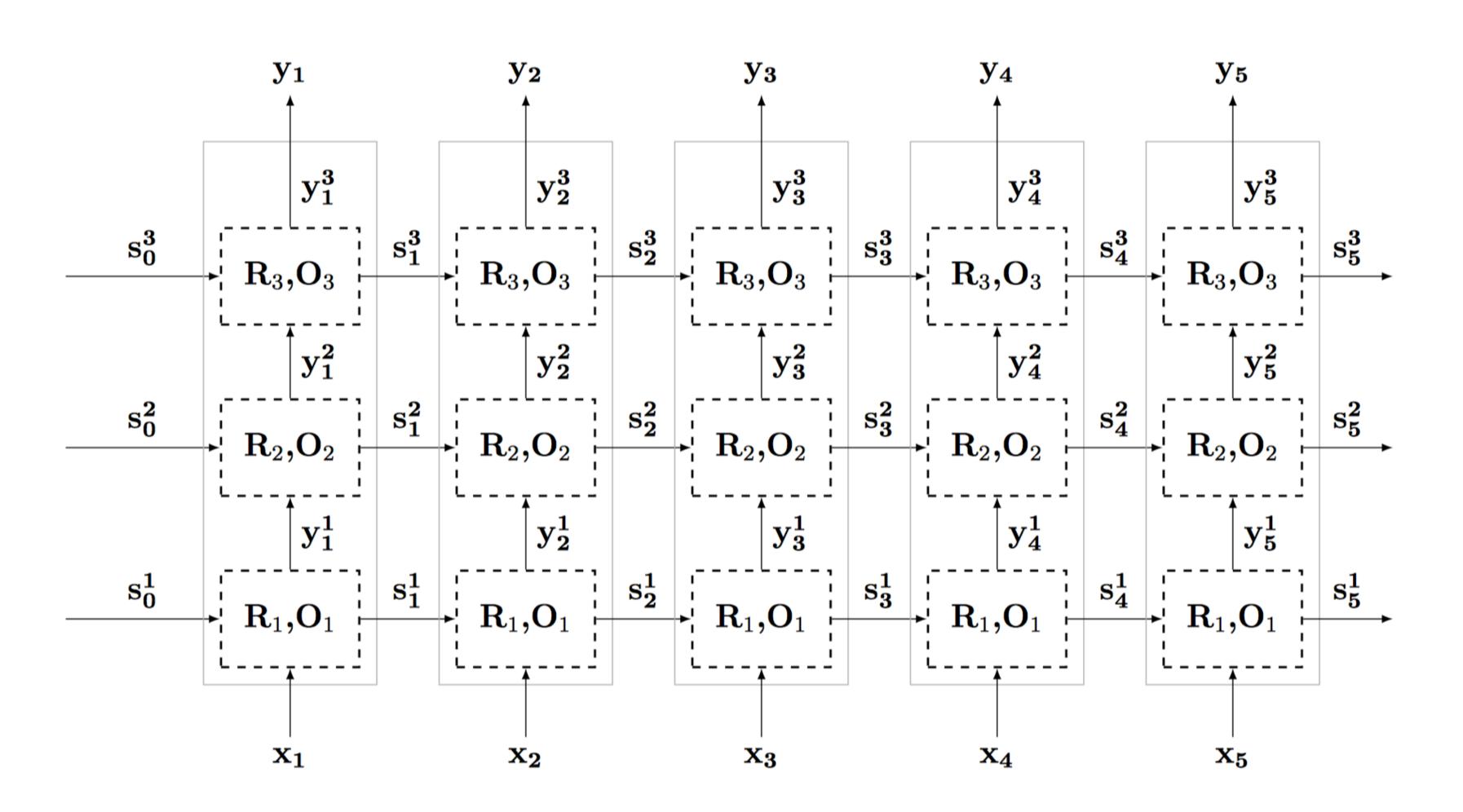
$$p(X) = \prod_{i=1}^{n} p(x_i \mid x_1, ..., x_{i-1}, x_{i+1}, ..., x_n)$$





Deep RNNs

We can make RNNs deeper (vertically) by stacking them.





Recurrent Neural Language Model

$$P(x_1, x_2, ..., x_n) = P(x_1) \times P(x_2 \mid x_1) \times P(w_3 \mid x_1, x_2) \times ... \times P(x_n \mid x_1, x_2, ..., x_{n-1})$$

$$= P(x_1 \mid \mathbf{h}_0) \times P(x_2 \mid \mathbf{h}_1) \times P(x_3 \mid \mathbf{h}_2) \times ... \times P(x_n \mid \mathbf{h}_{n-1})$$

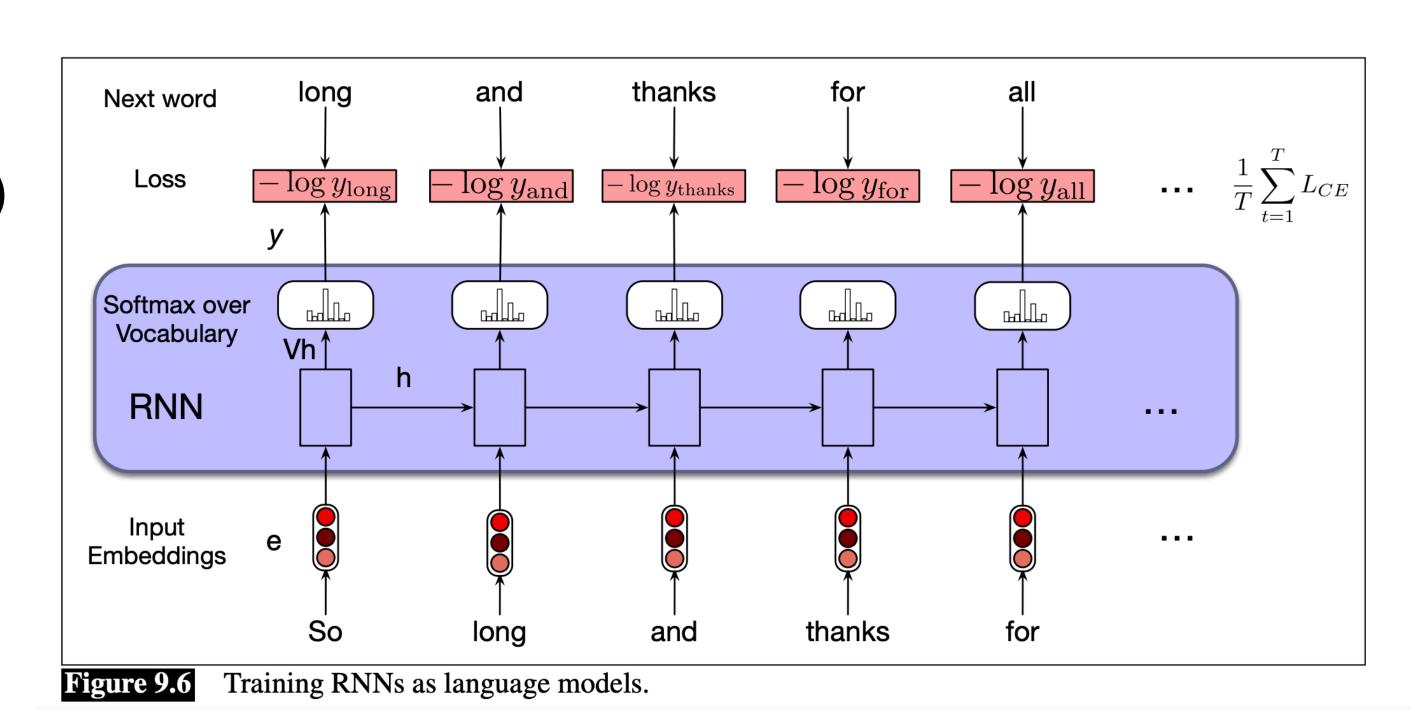
$$x_t = E(w_t)$$

$$R(h_{i-1}, x_i) = \tanh(Wx_i + Vh_{i-1} + b)$$

$$O(h_i) = \operatorname{softmax}(h_i W_o)$$

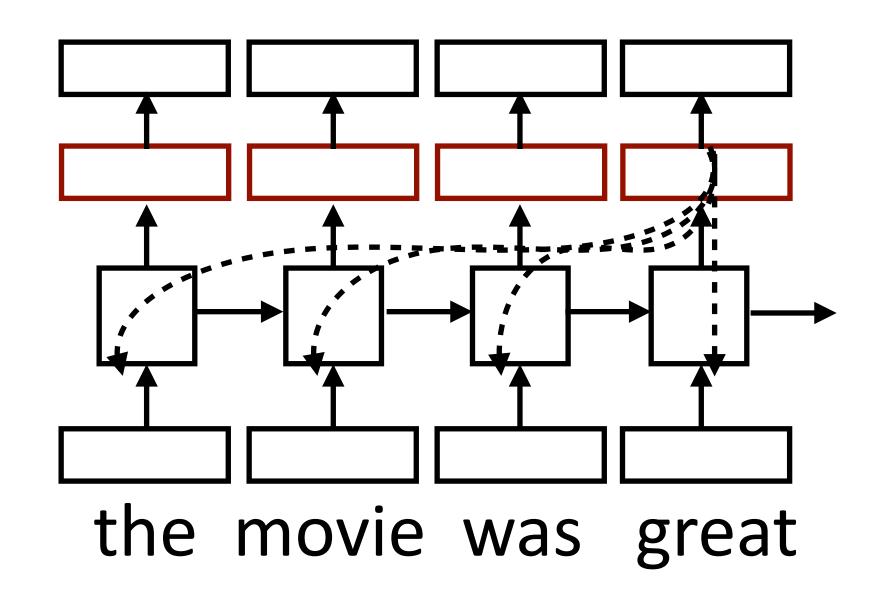
$$L(\theta) = -\frac{1}{n} \sum_{t=1}^{n} \log O(h_{t-1})(x_t)$$

$$\theta = \{\mathbf{W}, \mathbf{V}, \mathbf{b}, \mathbf{W}_o, \mathbf{E}\}$$





Training RNNs



- Loss = negative log likelihood of probability of gold prediction tag
- Training uses stochastic gradient descent and back propagation
- Backpropagation through time (BPTT)
 - Run forward propagation
 - Run backward propagation

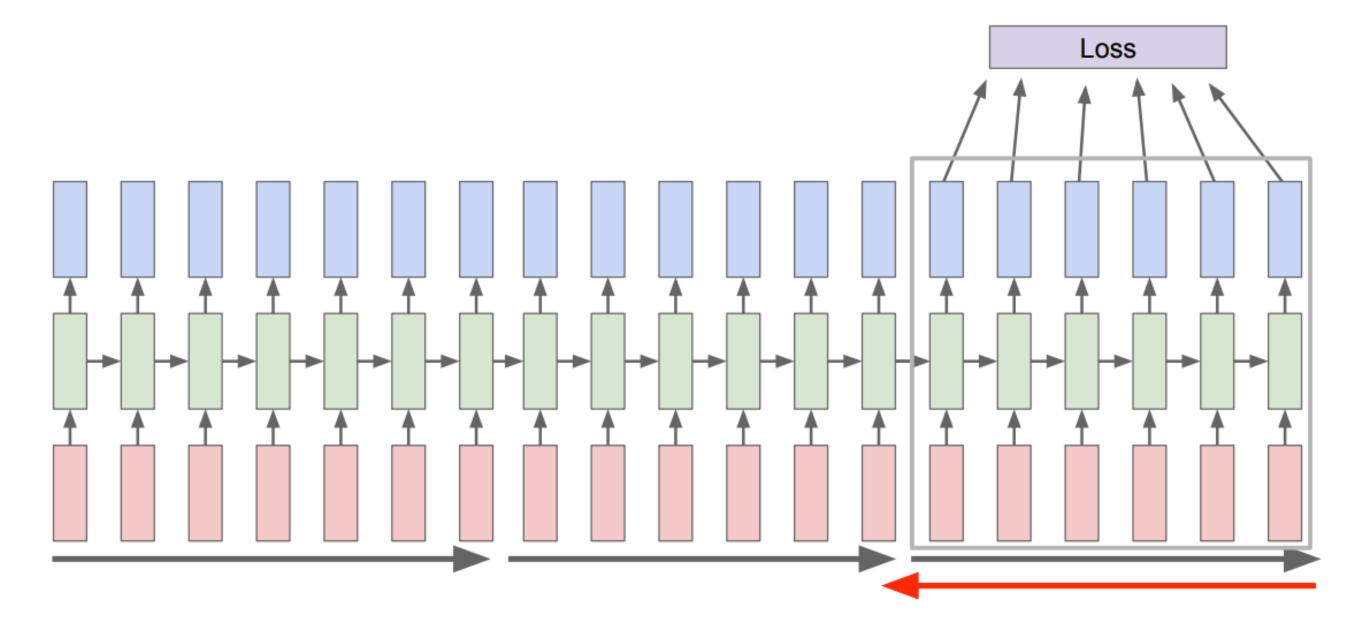
The derivative
$$\frac{\partial L_t}{\partial \mathbf{V}} = \frac{\partial L_t}{\partial \mathbf{h_{t-1}}} \frac{\partial \mathbf{h_{t-1}}}{\partial V}$$

Affected by
$$\frac{\partial \mathbf{h}_{t-2}}{\partial V}$$



[Truncated] Backpropagation through time

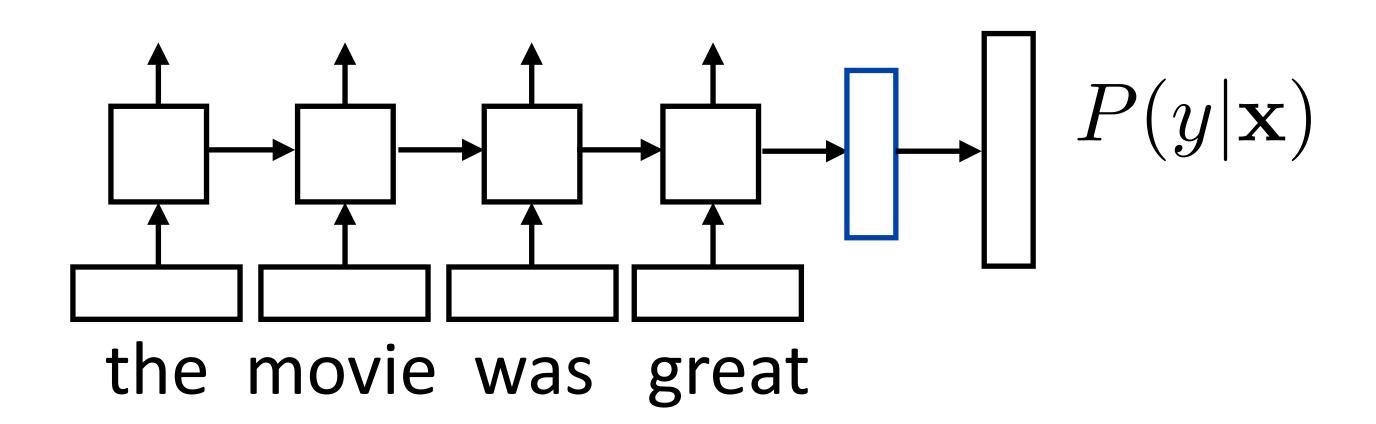
Backpropagation is very expensive if you handle long sequences



- Run forward and backward through chunks of the sequence instead of whole sequence
- Carry hidden states forward in time forever, but only backpropagate for some smaller number of steps



Training RNNs



RNN potentially needs to learn how to "remember" information for a long time!

it was my favorite movie of 2016, though it wasn't without problems -> +



Long-term depedencies with RNN

 If the gradients becomes vanishingly small (or explodingly large) over long distances, models cannot easily capture long-term dependencies

it was my favorite movie of 2016, though it wasn't without problems -> +

- Key signal is from earlier hidden state, but gradient larger at later hidden states
- Repeated multiplication by V causes problems

$$\mathbf{h}_t = \tanh(W\mathbf{x}_t + V\mathbf{h}_{t-1} + \mathbf{b}_h)$$

- How to fix vanishing gradient problem?
 - LSTMs: Long short term memory networks



Gated Connections

Designed to fix "vanishing gradient" problem using gates

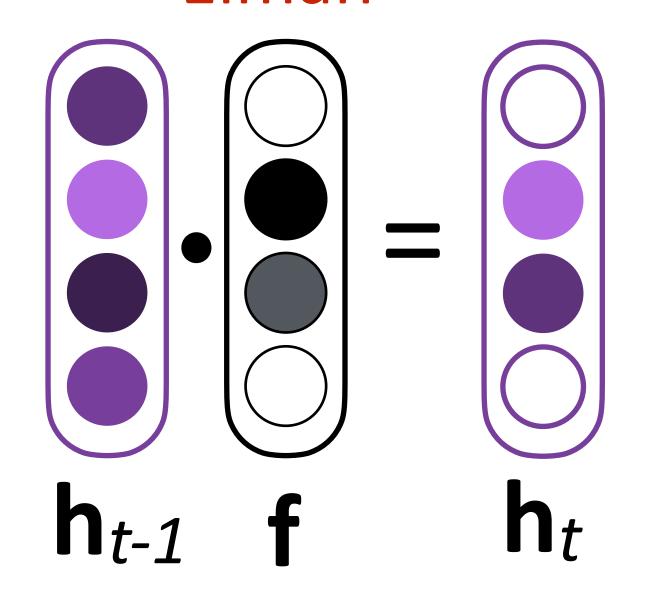
$$\mathbf{h}_t = \mathbf{h}_{t-1} \odot \mathbf{f} + \mathrm{func}(\mathbf{x}_t)$$
 Gated

 $\mathbf{h}_t = \tanh(W\mathbf{x}_t + V\mathbf{h}_{t-1} + \mathbf{b}_h)$ Elman

 Vector-valued "forget gate" f computed based on input and previous hidden state

$$\mathbf{f} = \sigma(W^{xf}\mathbf{x}_t + W^{hf}\mathbf{h}_{t-1})$$

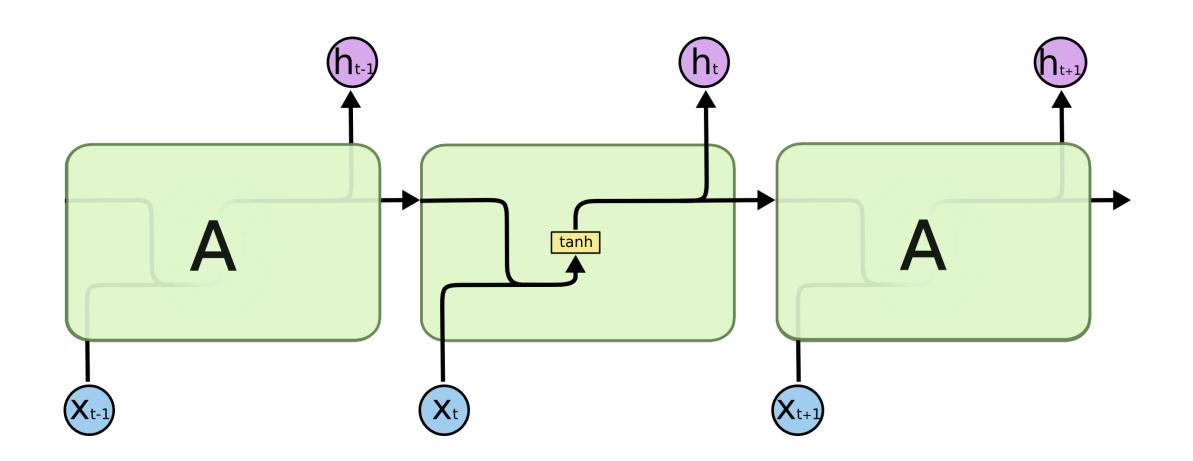
► Sigmoid: elements of **f** are in (0, 1)

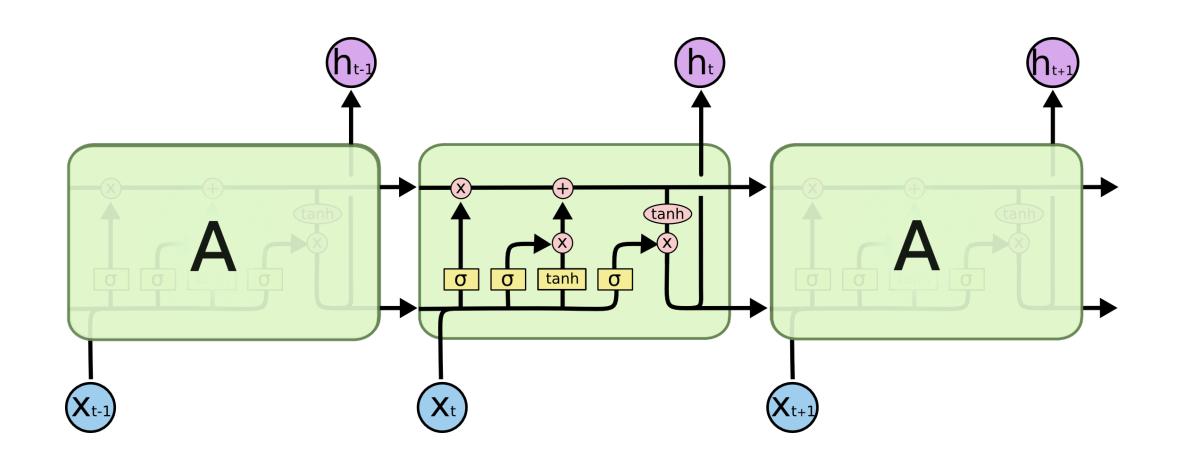


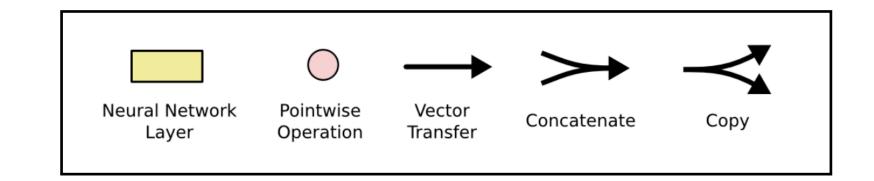
If $\mathbf{f} \approx \mathbf{1}$, we simply sum up a function of all inputs — gradient doesn't vanish! More stable without matrix multiply (V) as well



Elman RNN vs LSTMs





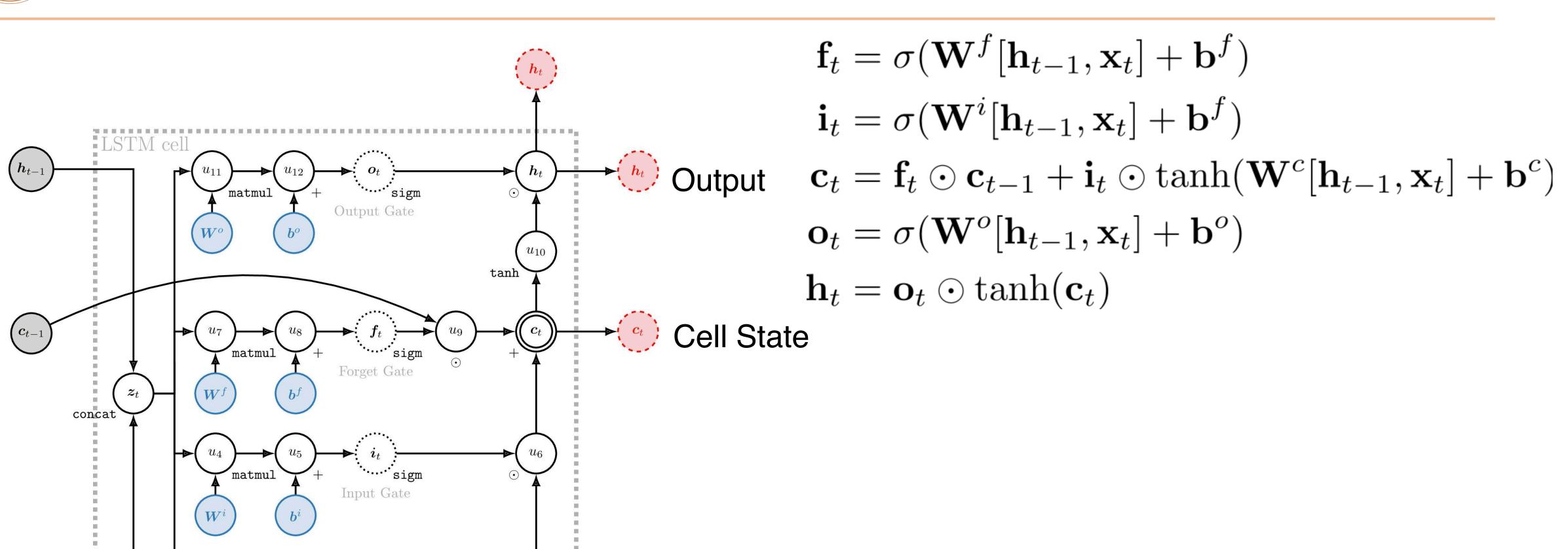


LSTMs

- "Long short-term memory": hidden state is a "short-term" memory
- "Cell" c in addition to hidden state h cell state —> stores long-term information
 - We write / erase cell c_i after each step
 - We read hidden state h_i from c_i
 - ▶ Basic communication flow: **x** -> **c** -> **h** -> output



LSTMs

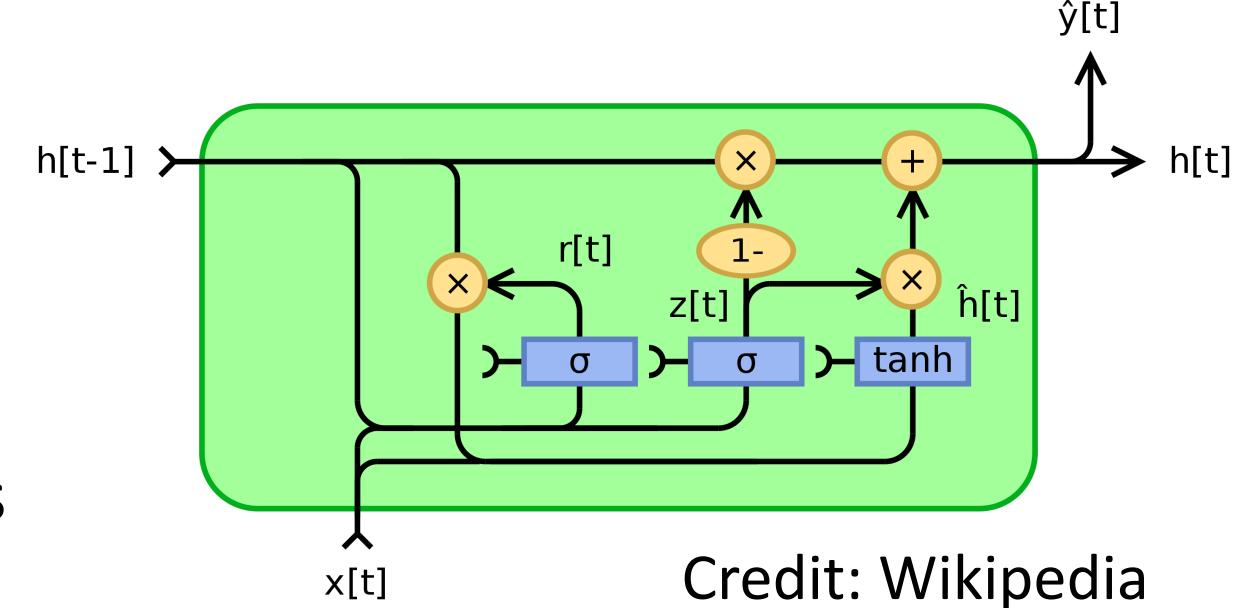


Input



Gated Recurrent Unit (GRU)

- z is update, r is reset
- The single hidden state and simpler update gate gives simpler mixing semantics than in LSTMs
- Faster to train and sometimes works better than LSTMs, often a tossup

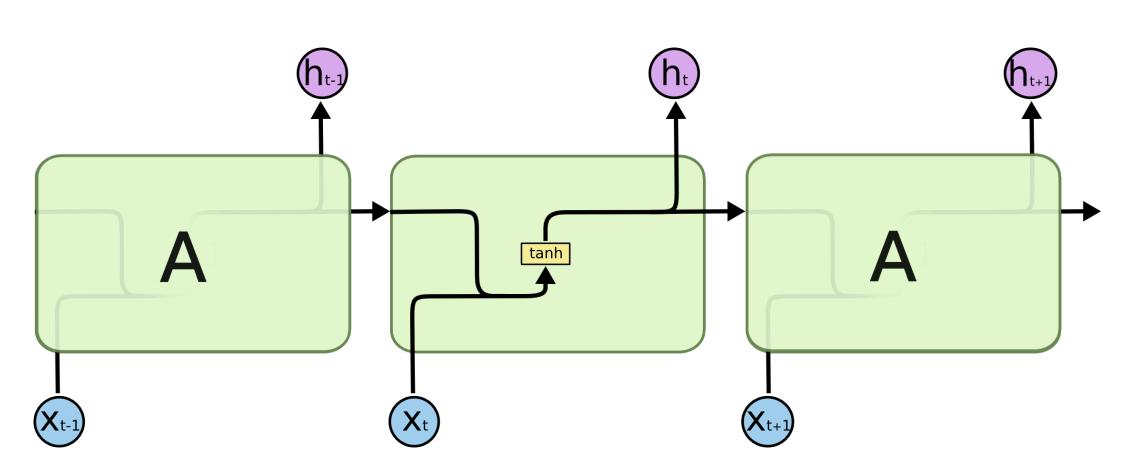


$$egin{aligned} z_t &= \sigma_g(W_z x_t + U_z h_{t-1} + b_z) \ r_t &= \sigma_g(W_r x_t + U_r h_{t-1} + b_r) \ h_t &= (1-z_t) \circ h_{t-1} + z_t \circ \sigma_h(W_h x_t + U_h(r_t \circ h_{t-1}) + b_h) \end{aligned}$$

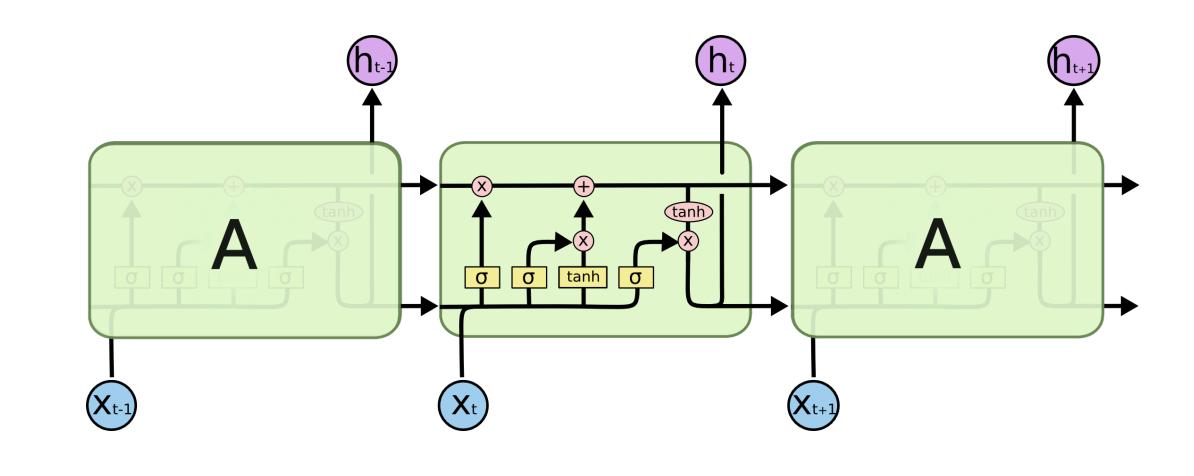


Recap

- Recurrent Neural Network
 - An architecture to handle variable length input
 - Preserves the states from previous tokens

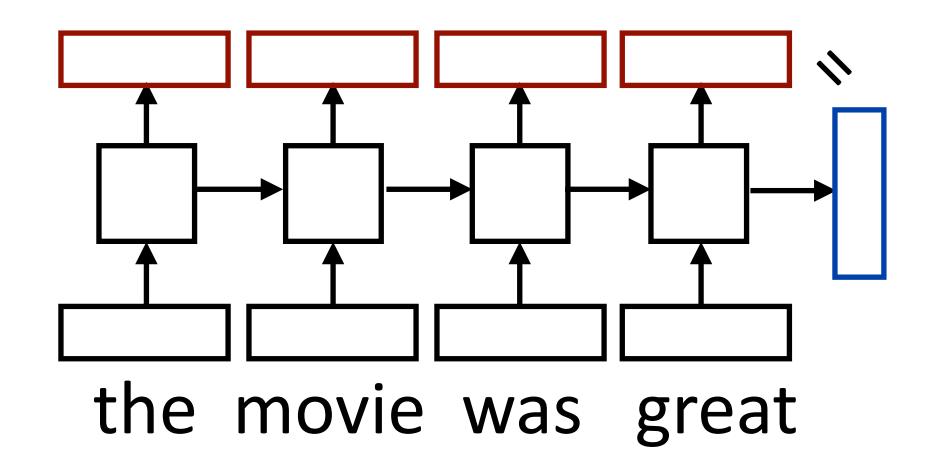


- LSTM
 - Gating mechanism to control information flow, to maintain longer term history





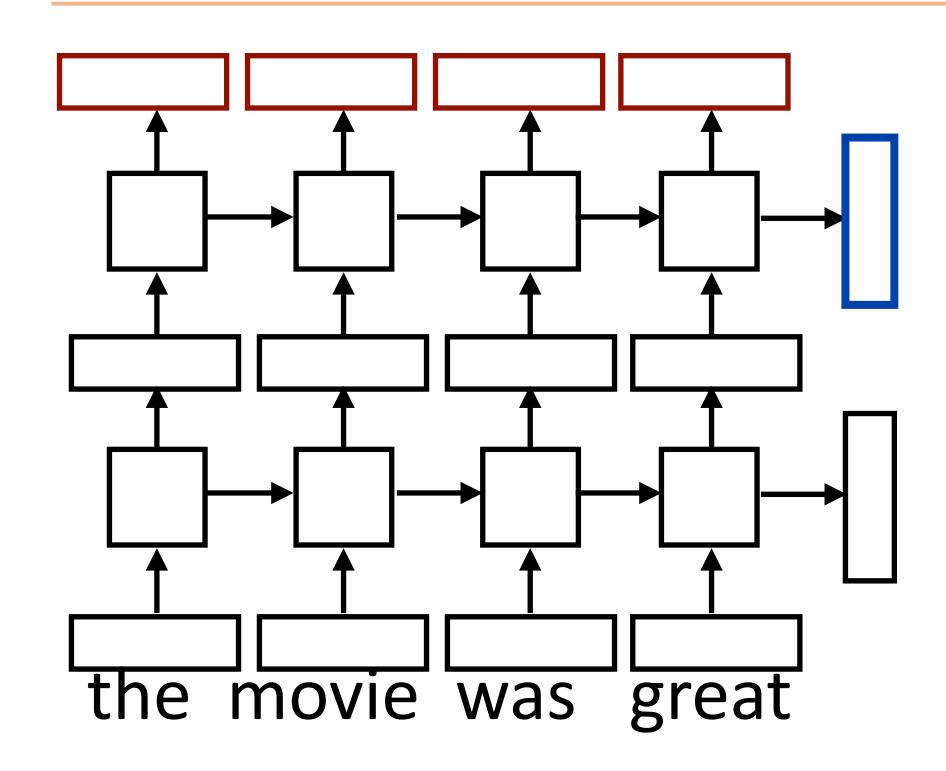
What do RNNs produce?



- Encoding of the sentence can pass this a decoder or make a classification decision about the sentence
- Encoding of each word can pass this to another layer to make a prediction (can also pool these to get a different sentence encoding)
- RNN can be viewed as a transformation of a sequence of vectors into a sequence of context-dependent vectors

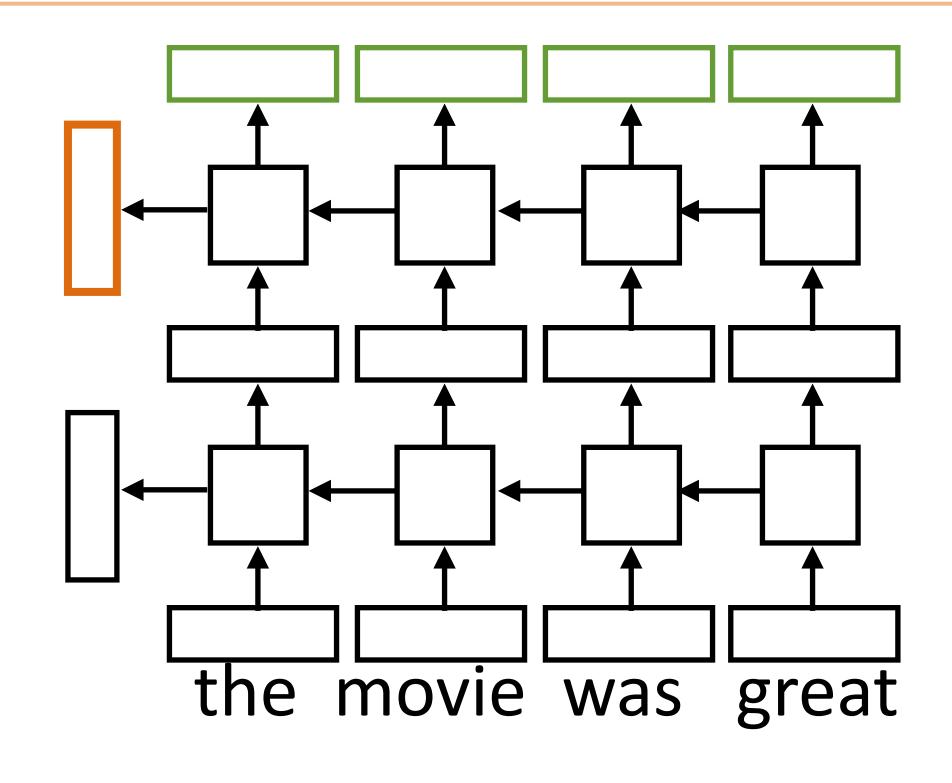


Multilayer Bidirectional RNN



 Sentence classification based on concatenation of both final outputs





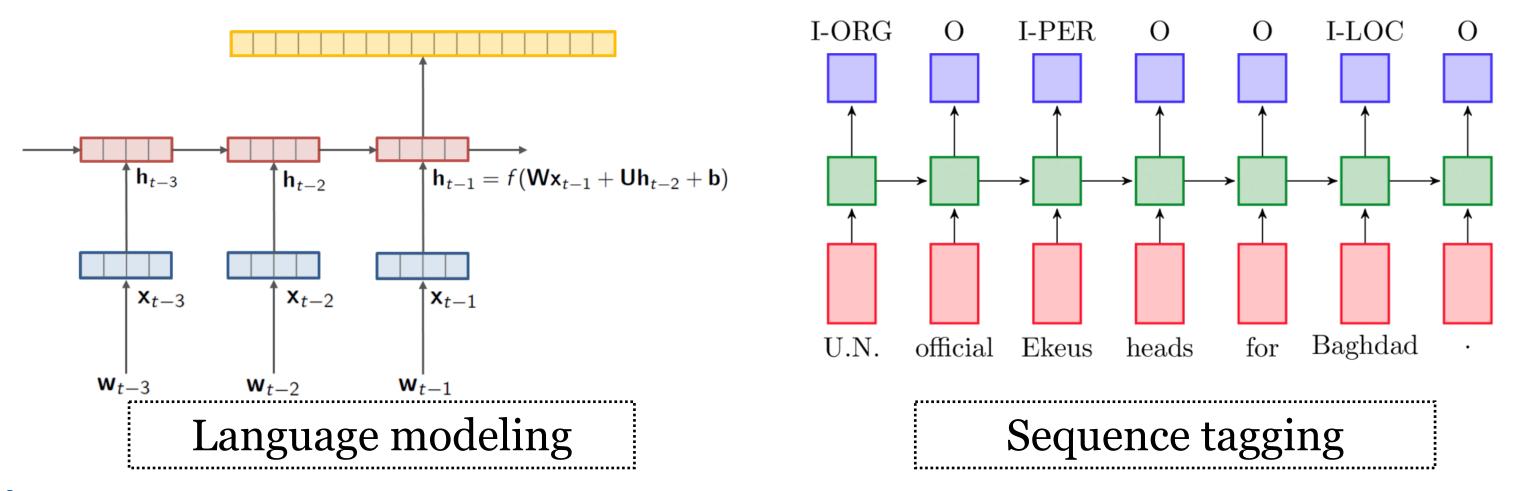
 Token classification based on concatenation of both directions' token representations





Recap: RNN can be used for...

Transducer: make some prediction for each element in a sequence



Acceptor/encoder: encode a sequence into a fixed-sized vector and use

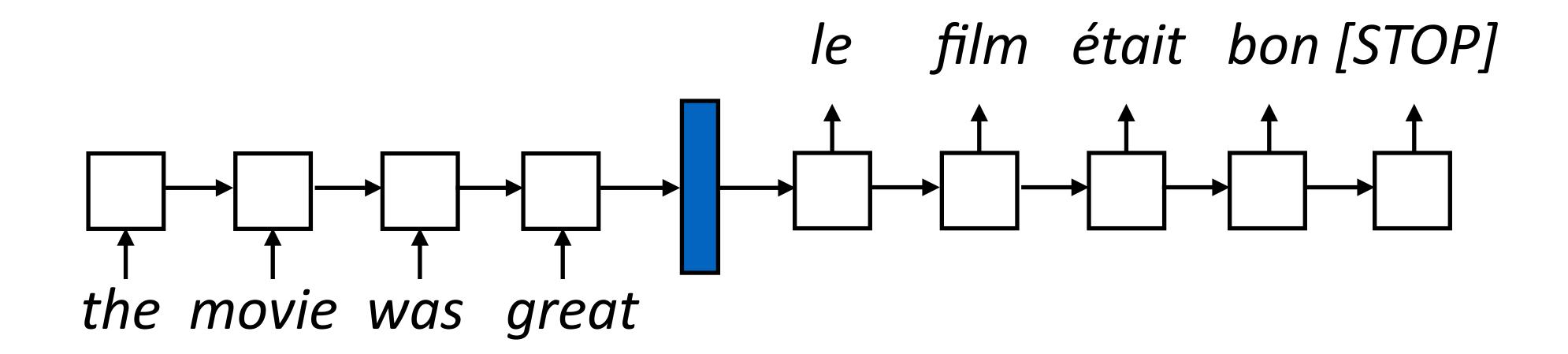


How can we use this for machine translation? summarization?



Seq2Seq Model

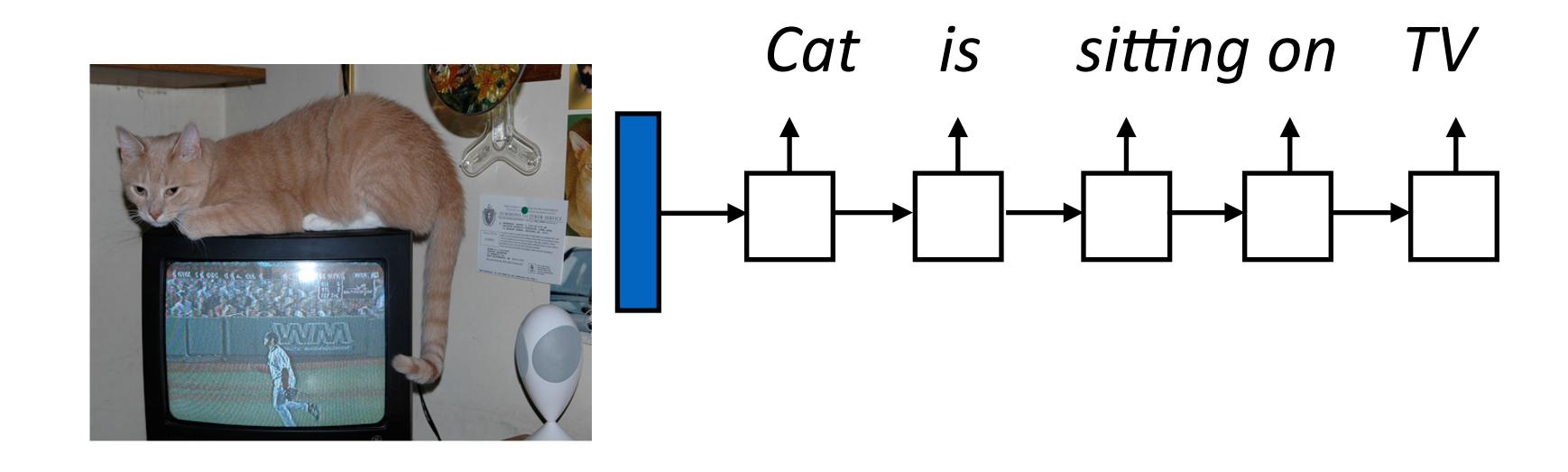
- Input: a sequence of tokens
- Output: a sequence of tokens (of arbitrary length)





One2Seq

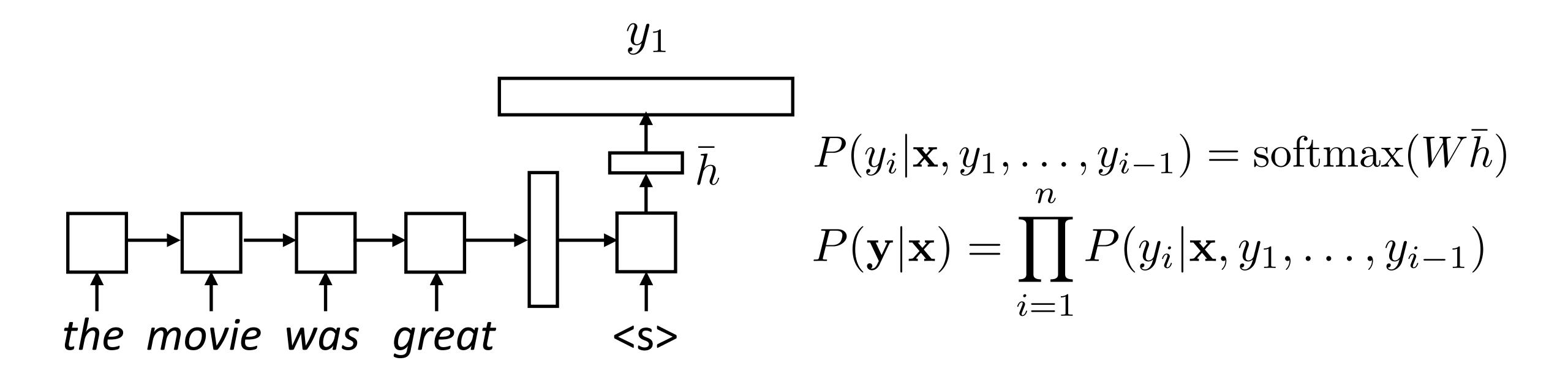
- Input: one item
- Output: a sequence of tokens (of arbitrary length)





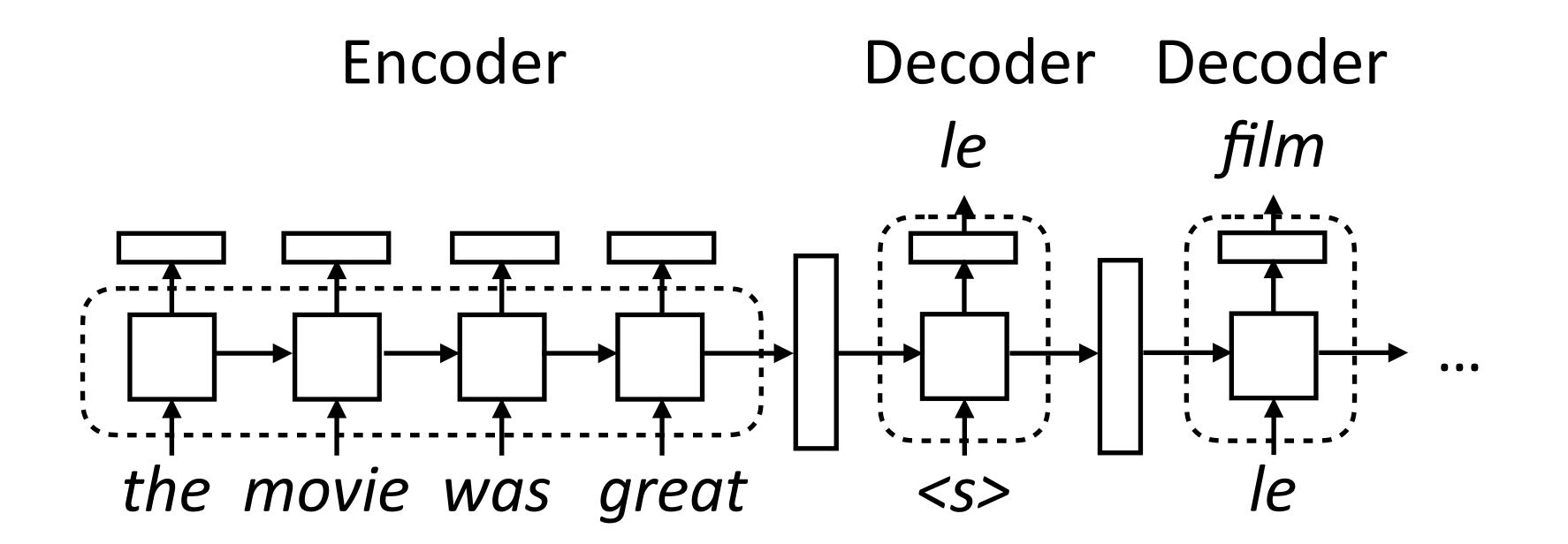
Model

Generate next word conditioned on previous word as well as hidden state





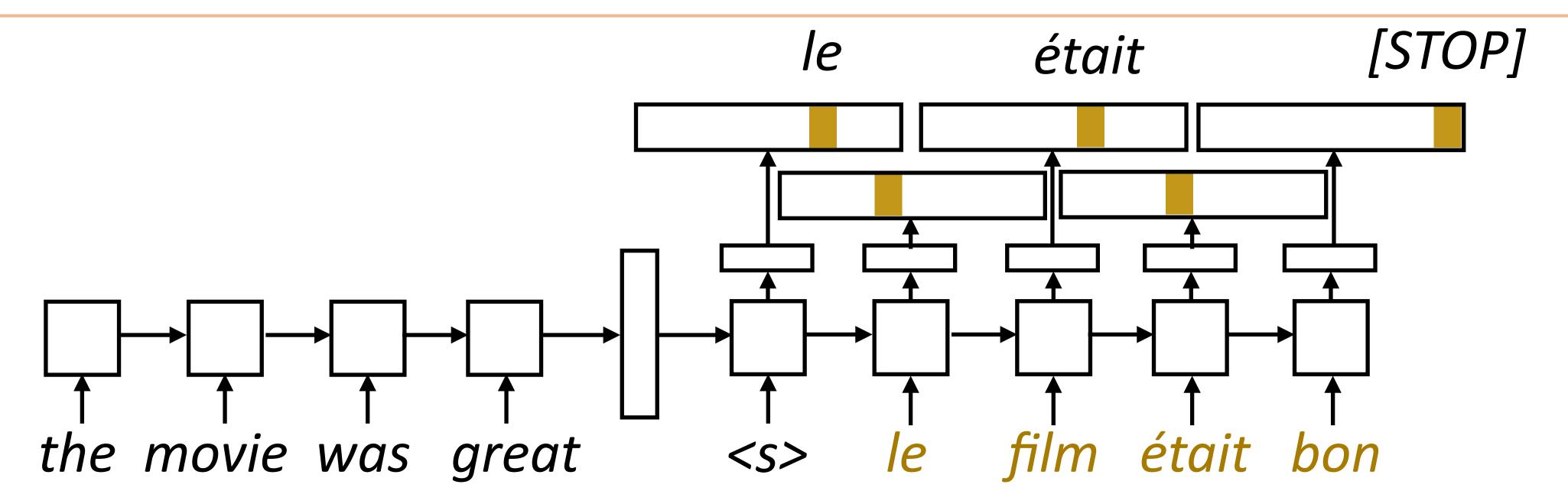
Implementing seq2seq Models



- Encoder: consumes sequence of tokens, produces a vector. Analogous to encoders for classification/tagging tasks
- Decoder: separate module, single cell.
 - Takes two inputs: hidden state and previous token.
 - Outputs token and a new hidden state.



Training



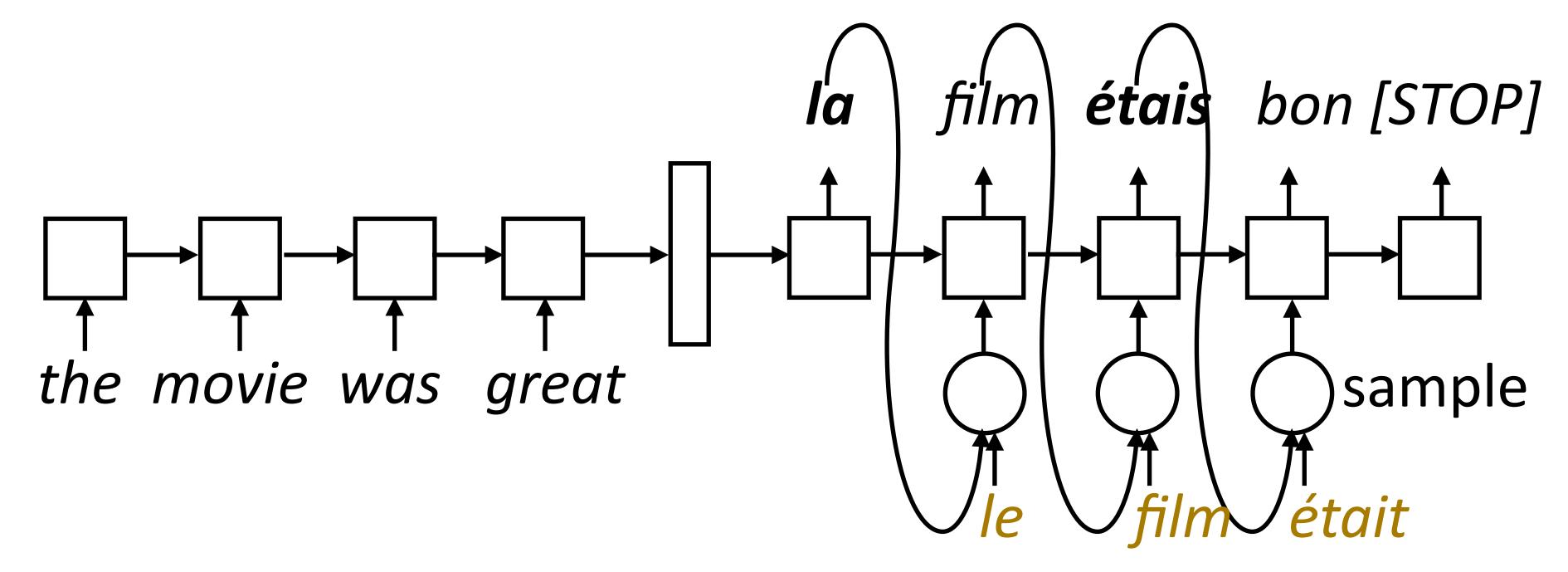
• Objective: maximize $\sum_{(\mathbf{x},\mathbf{y})} \sum_{i=1}^{n} \log P(y_i^*|\mathbf{x},y_1^*,\ldots,y_{i-1}^*)$

 One loss term for each target-sentence word, feed the correct word regardless of model's prediction (called "teacher forcing")



Training: Scheduled Sampling

Model needs to do the right thing even with its own predictions



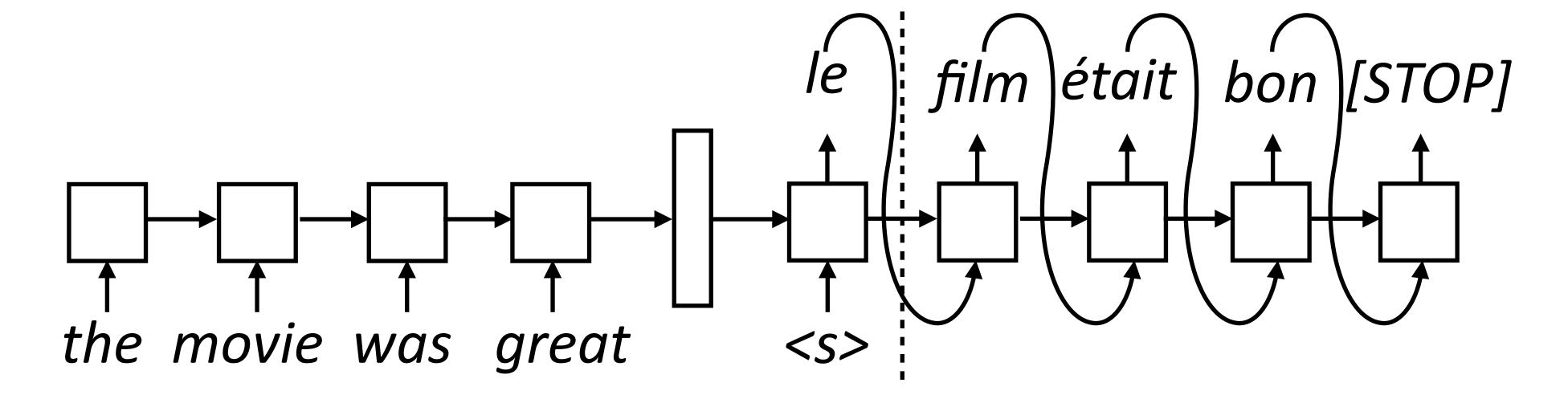
- Scheduled sampling: with probability p, take the gold as input, else take the model's prediction
- Starting with p = 1 (teacher forcing) and decaying it works best

Bengio et al. (2015)



Inference

Generate next word conditioned on previous word as well as hidden state



- Need to compute the argmax over the word predictions and then feed that to the next RNN state
- Need to actually evaluate computation graph up to this point to form input for the next state
- Decoder is advanced one state at a time until [STOP] is reached



Takeaways

- RNNs can transduce inputs (produce one output for each input) or compress the whole input into a vector
- Useful for a range of tasks with sequential input: sentiment analysis, language modeling, natural language inference, machine translation