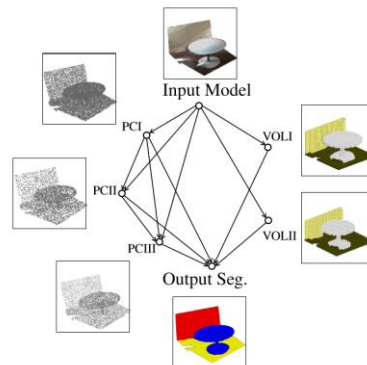
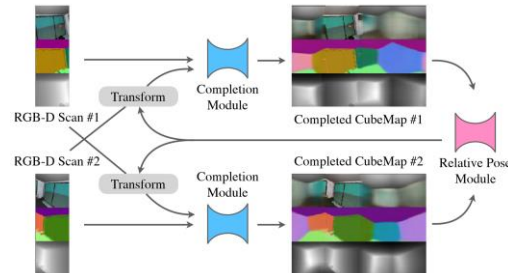
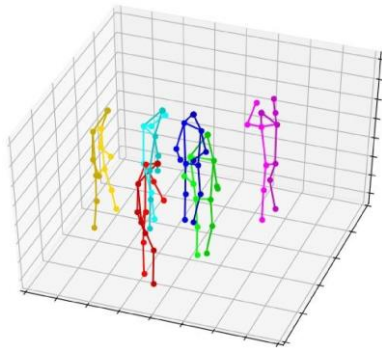
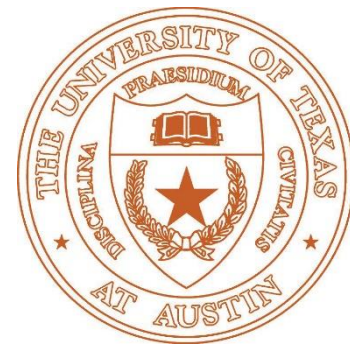


CS376 Computer Vision



Qixing Huang
January 23th 2019



Introductions

- Instructor
 - Prof. Qixing Huang
- TA:
 - Zhenpei Yang

Today

- Course overview
- Requirements, logistics

What is computer vision



Done?

Computer Vision

- Automatic understanding of images and video
 - 1. Computing properties of the 3D world from visual data (measurement)

1. Vision for measurement (Sensing)

Real-time stereo

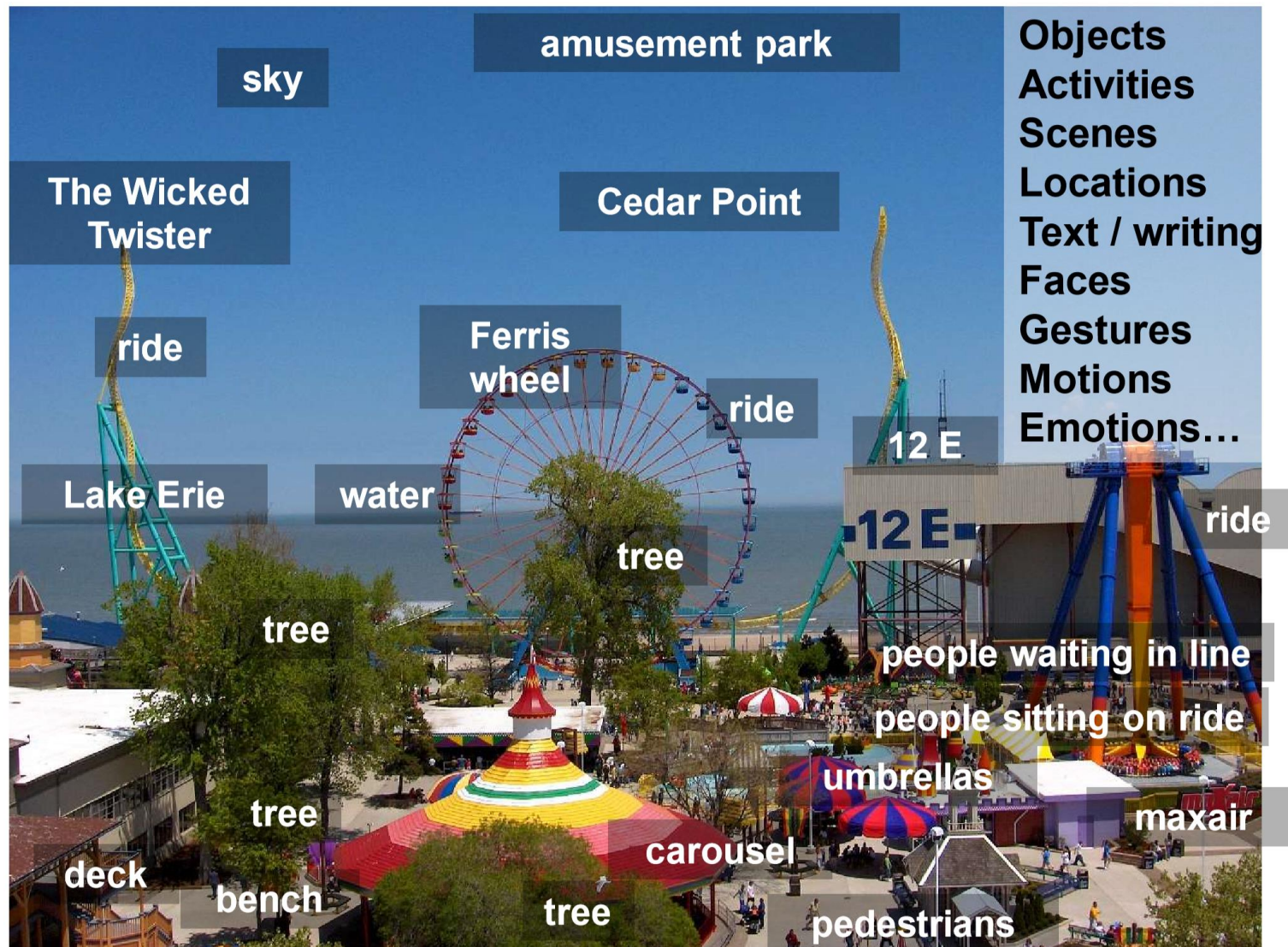


Wang et al.

Computer Vision

- Automatic understanding of images and video
 - 1. Computing properties of the 3D world from visual data (measurement)
 - 2. Data representations and algorithms to allow a machine to recognize objects, people, scenes, and activities. (perception and interpolation)

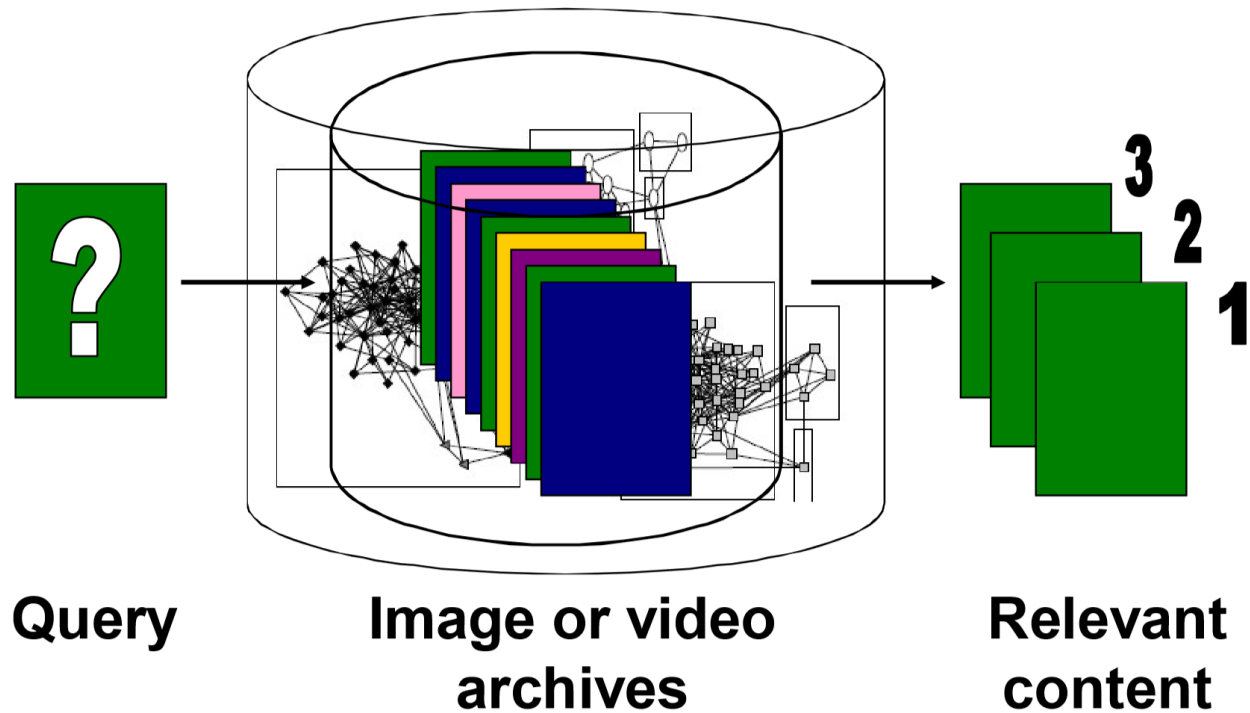
2. Vision for perception, interpretation



Computer Vision

- Automatic understanding of images and video
 - 1. Computing properties of the 3D world from visual data (measurement)
 - 2. Data representations and algorithms to allow a machine to recognize objects, people, scenes, and activities. (perception and interpolation)
 - 3. Data representations and algorithms to mine, search, and interact with visual data (search and organization)

3. Visual search, organization

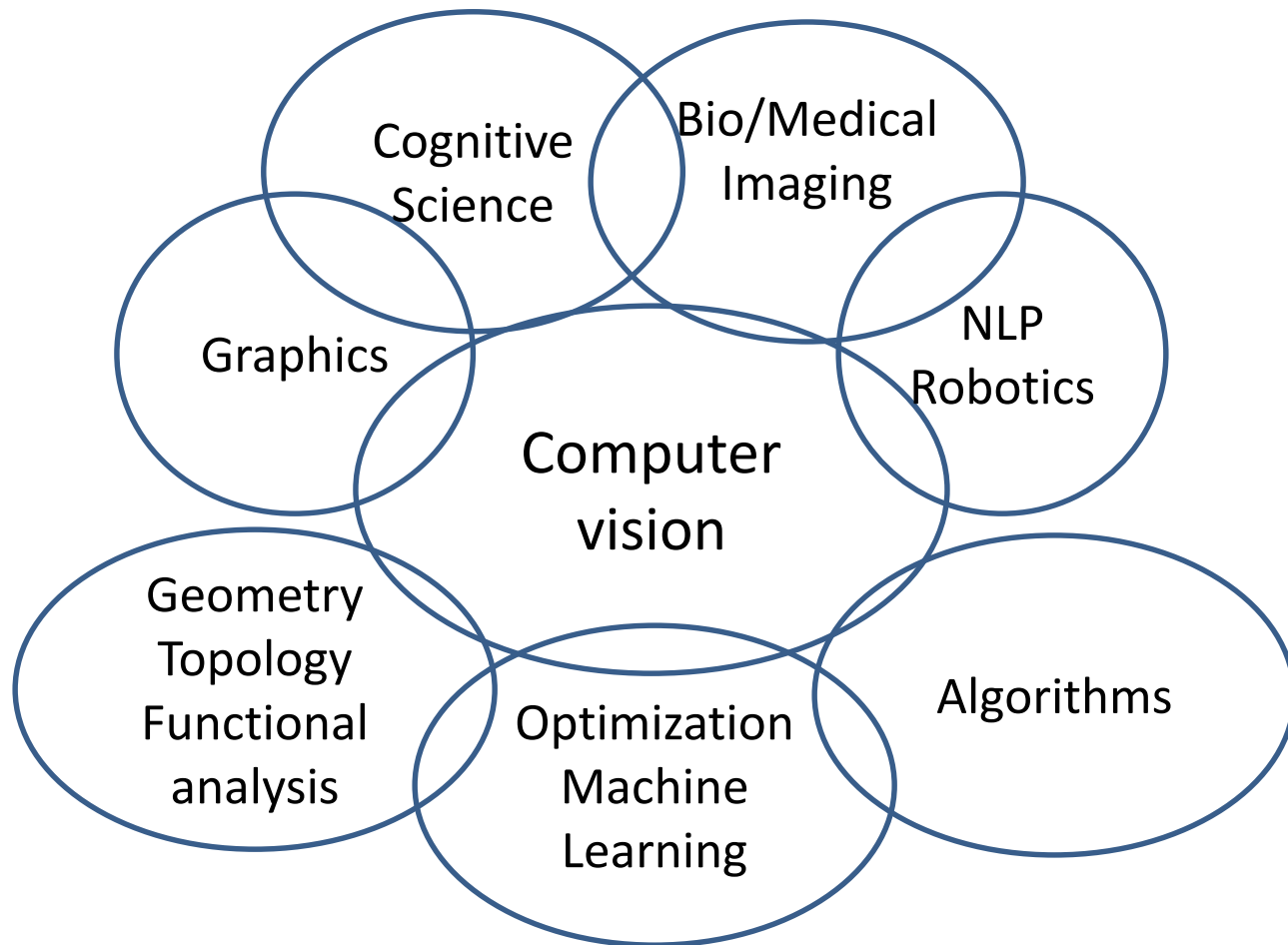


Different representations and algorithms involved

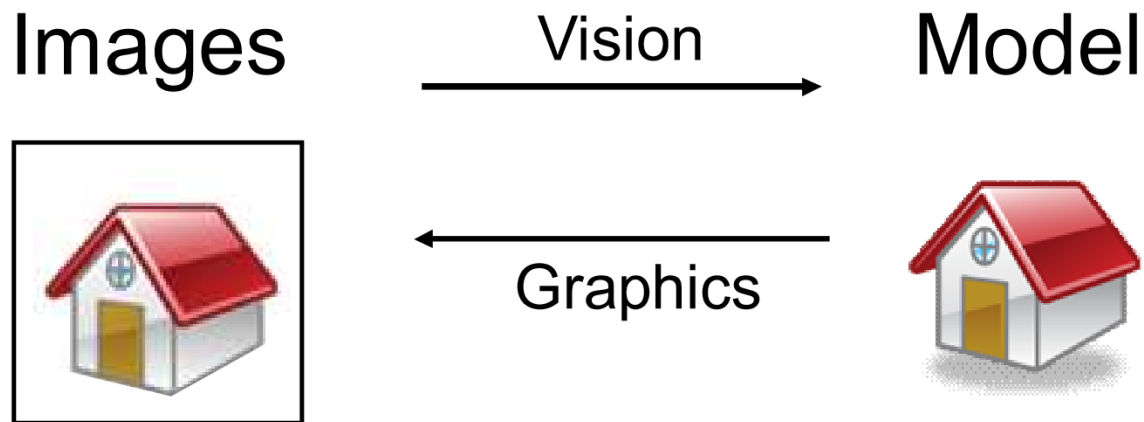
Computer Vision

- Automatic understanding of images and video
 - 1. Computing properties of the 3D world from visual data (measurement)
 - 2. Data representations and algorithms to allow a machine to recognize objects, people, scenes, and activities. (perception and interpolation)
 - 3. Data representations and algorithms to mine, search, and interact with visual data (search and organization)

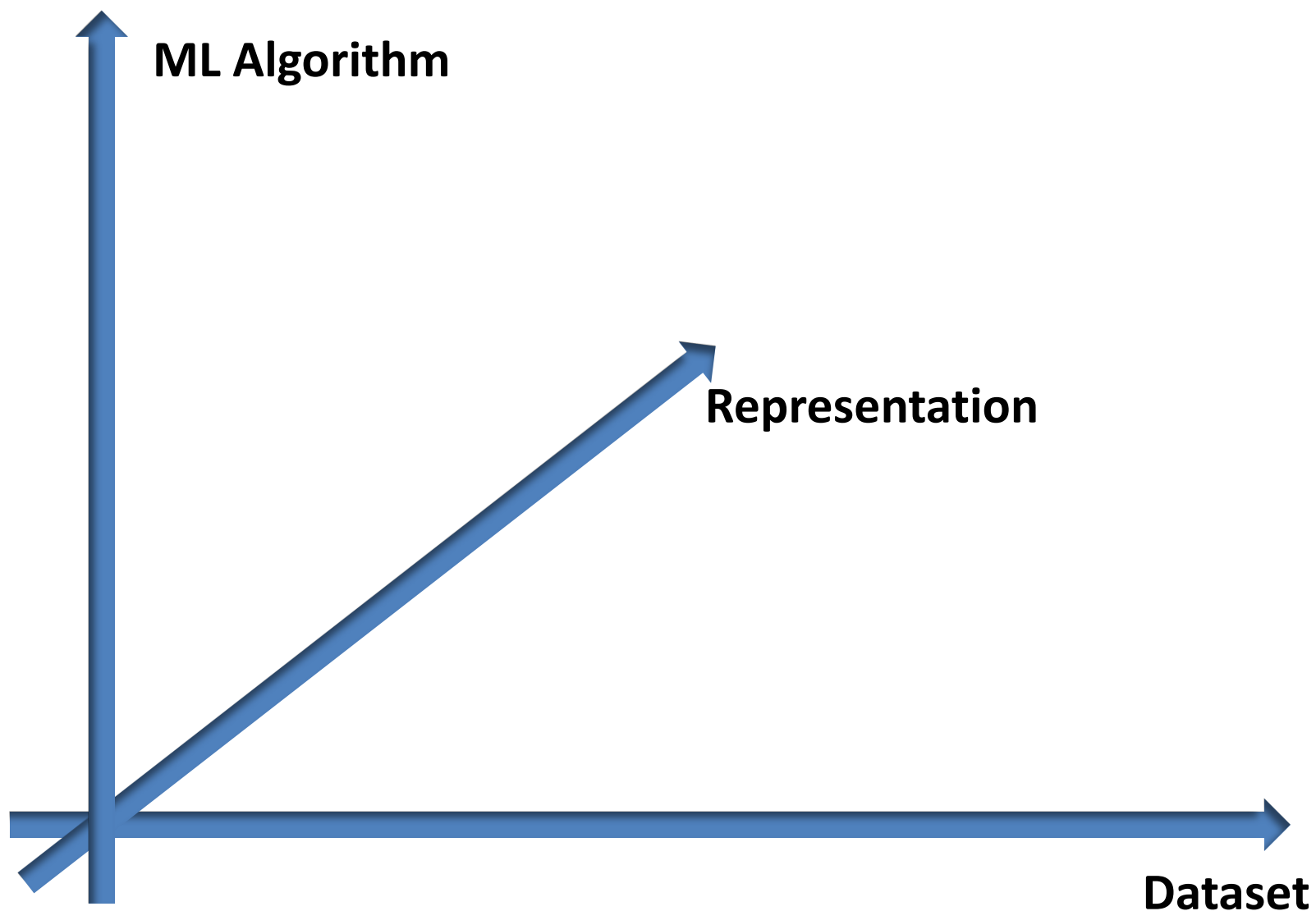
Related disciplines



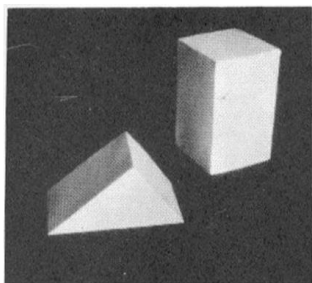
Vision and graphics



Inverse problems: analysis and synthesis



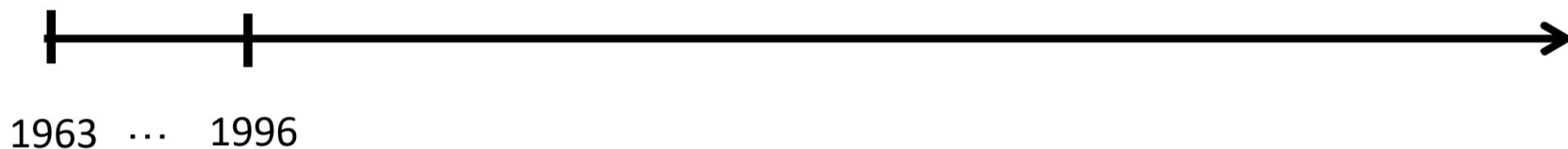
Progress charted by datasets



Roberts 1963



COIL



Progress charted by datasets



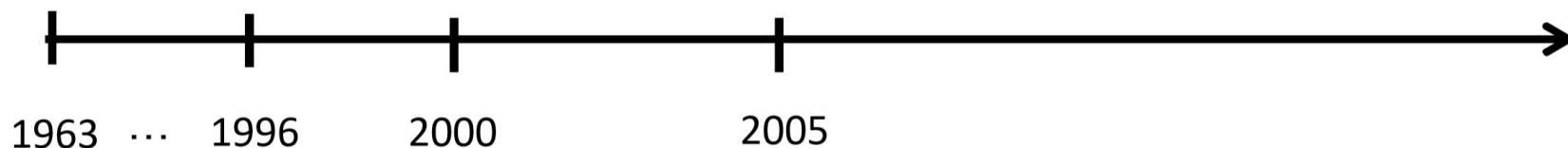
MSRC 21 Objects



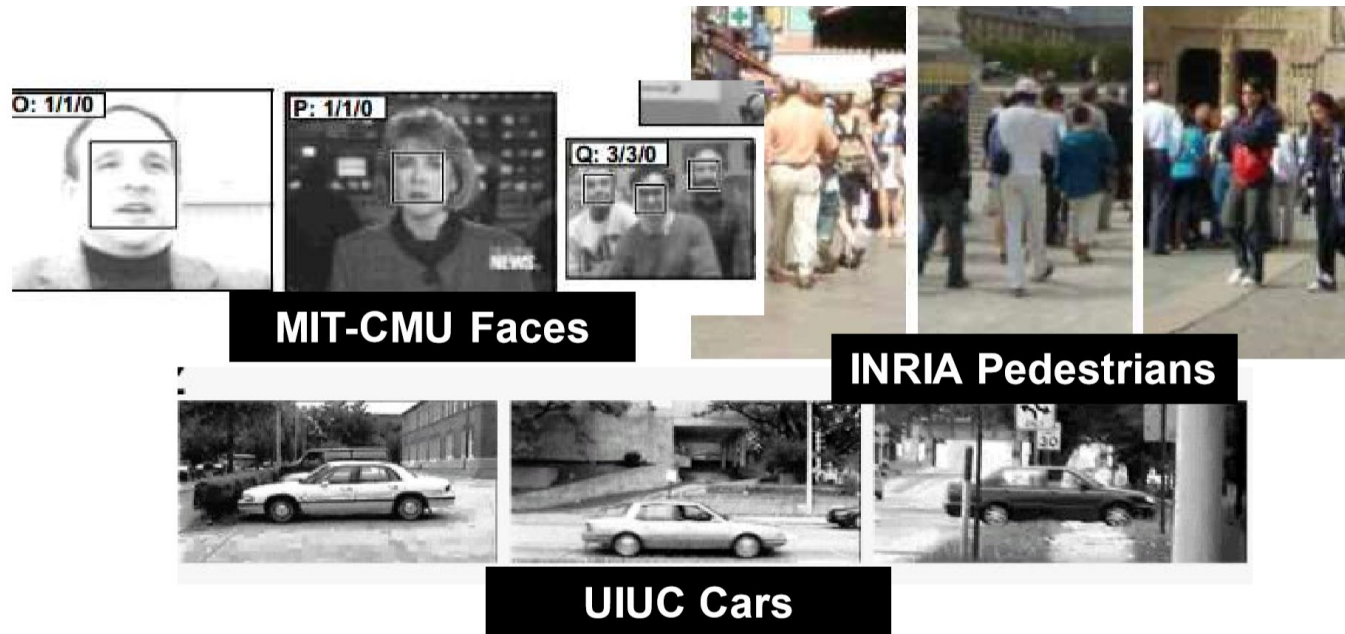
Caltech-101



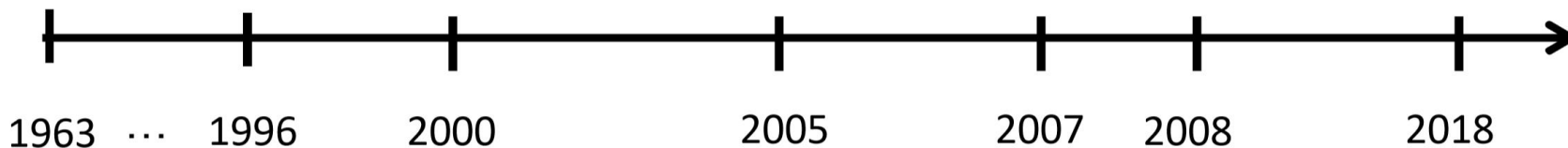
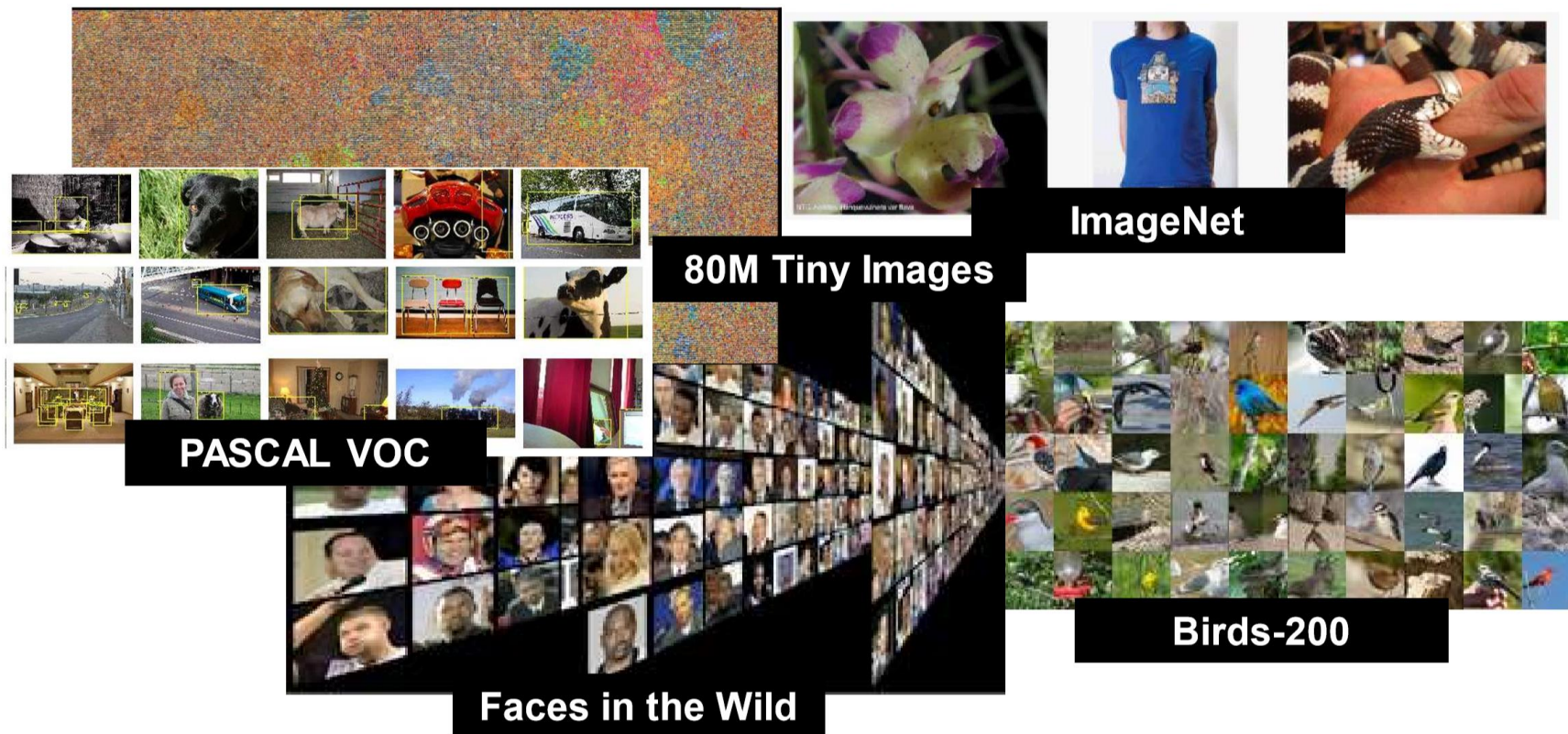
Caltech-256



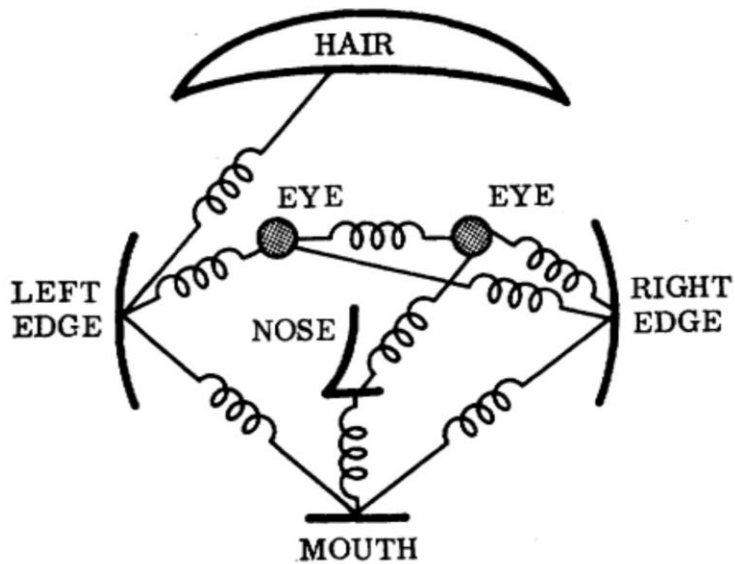
Progress charted by datasets



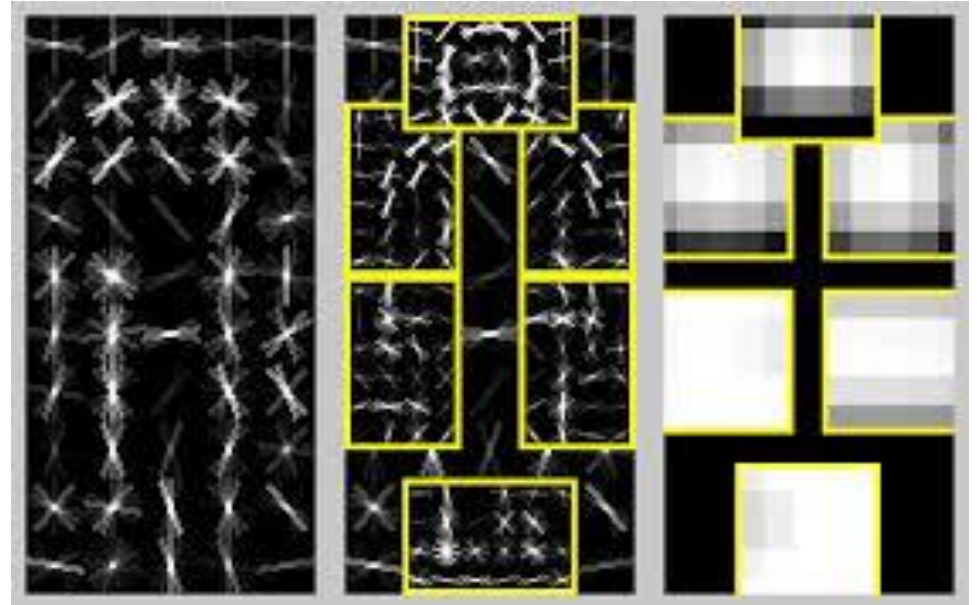
Progress charted by datasets



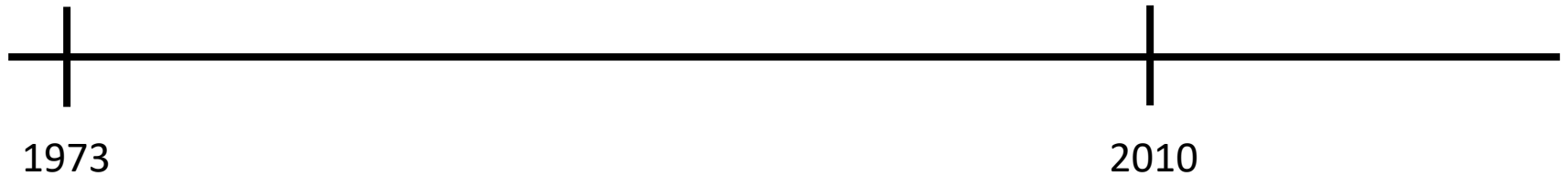
Data Representations

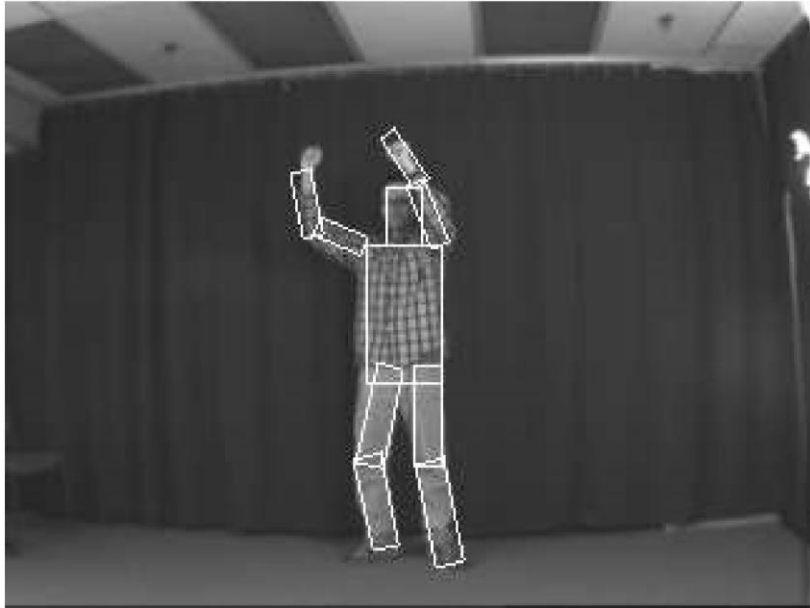


Pictorial Structures
(Fischler et al. 73)

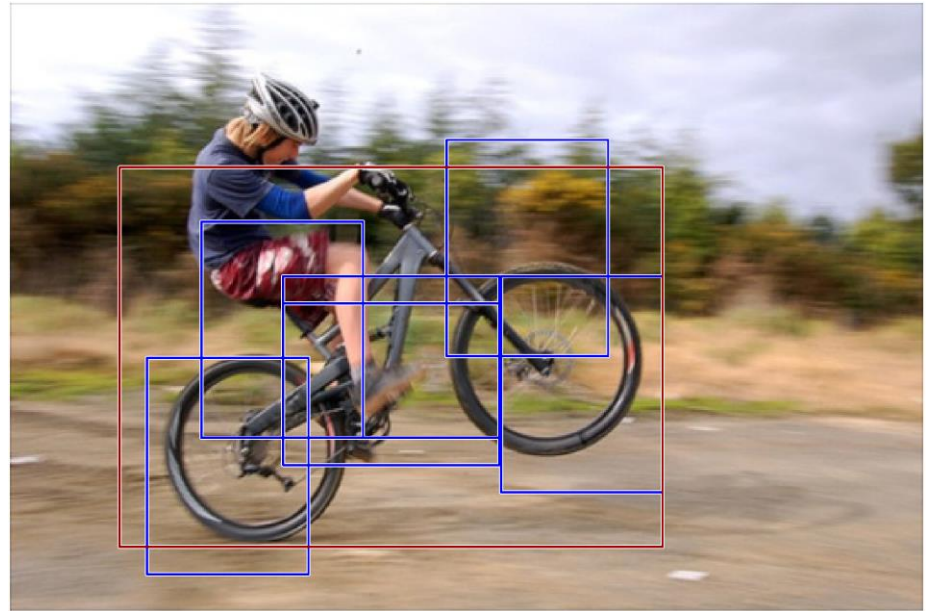


Deformable-Part-Model
(Felzenszwalb et al. 10)

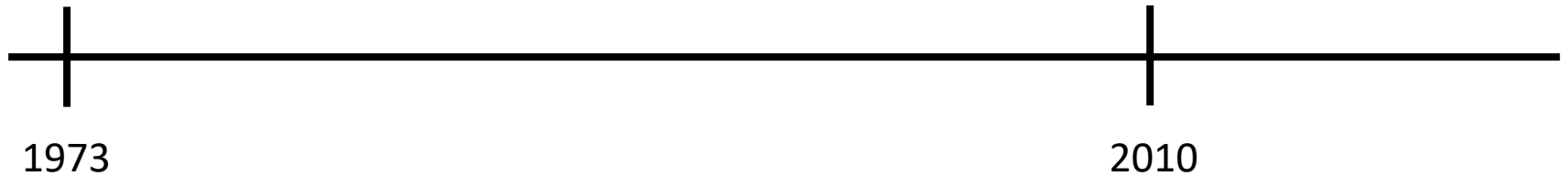


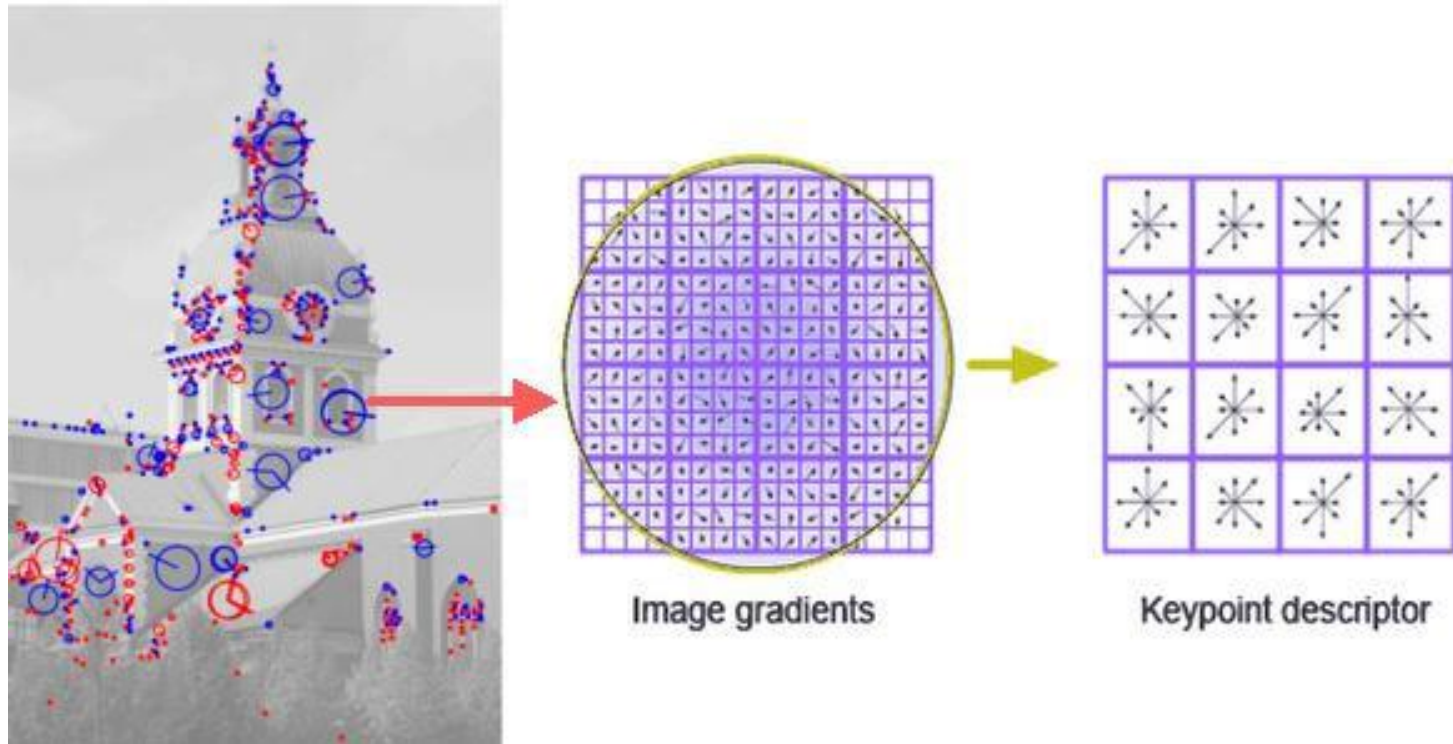


Pictorial Structures
(Fischler et al. 73)

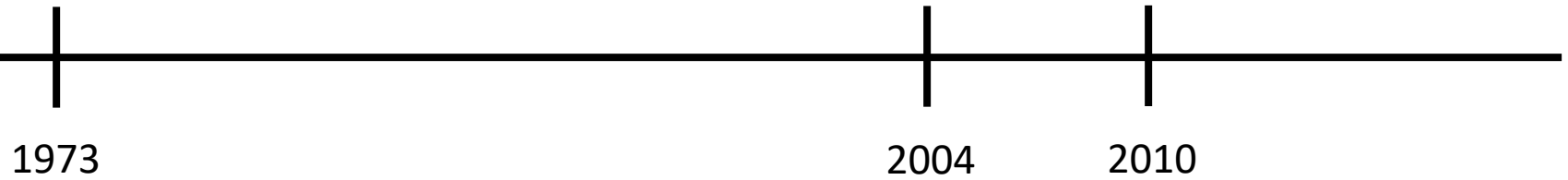


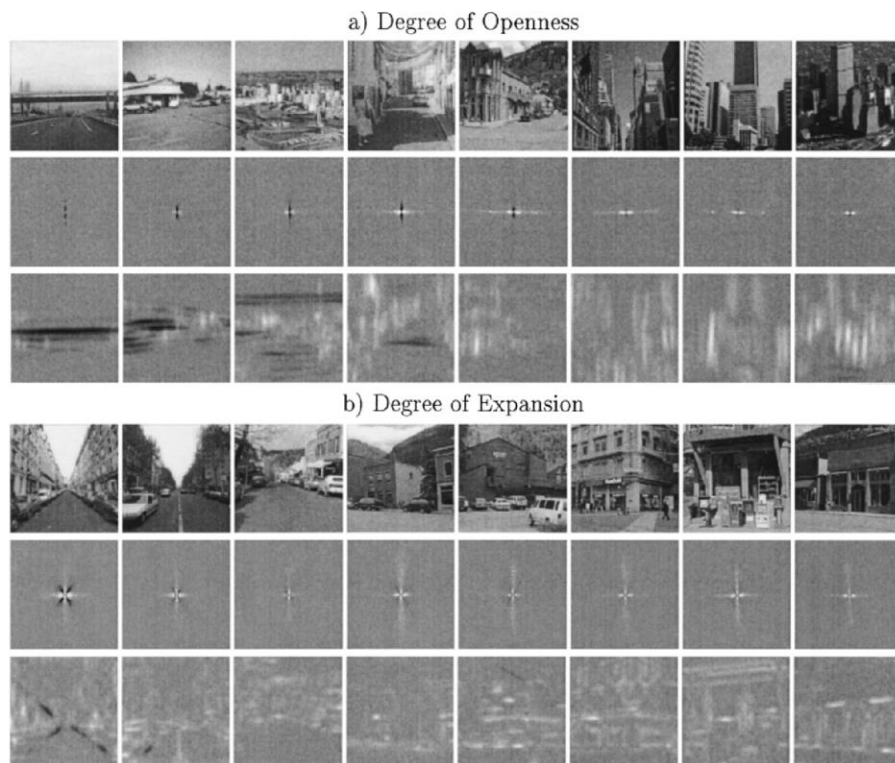
Deformable-Part-Model
(Felzenszwalb et al. 10)



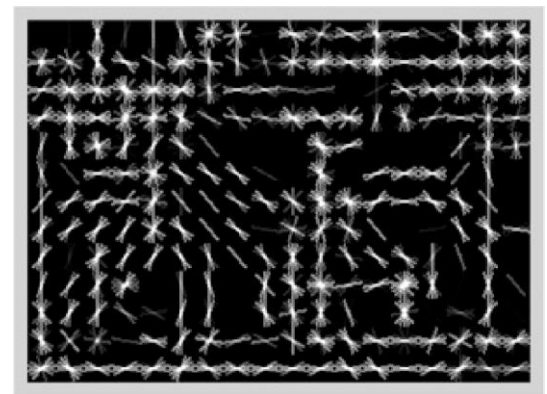


SIFT (Lowe 04)

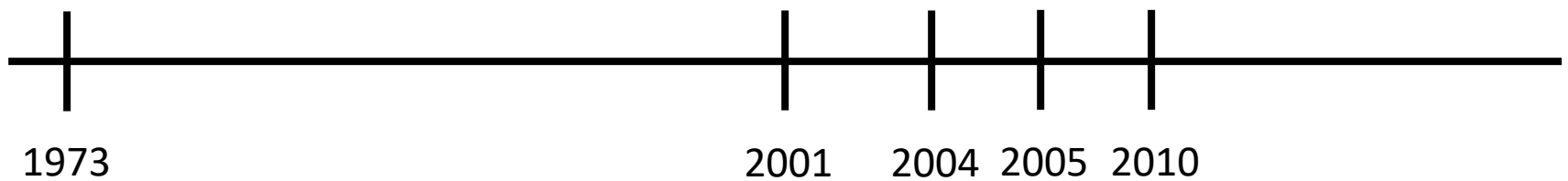


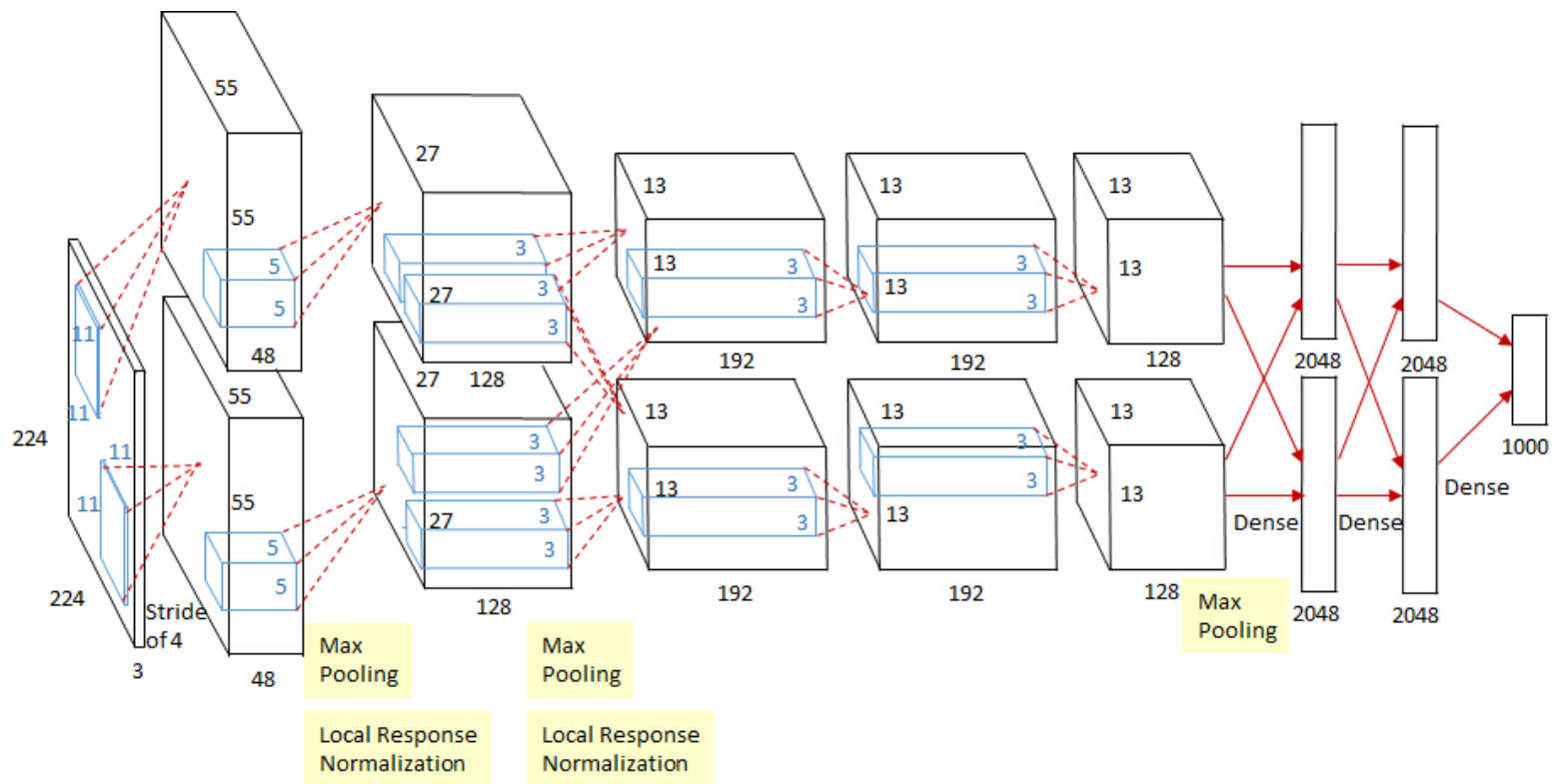


GIST (Oliva and Torralba 01)

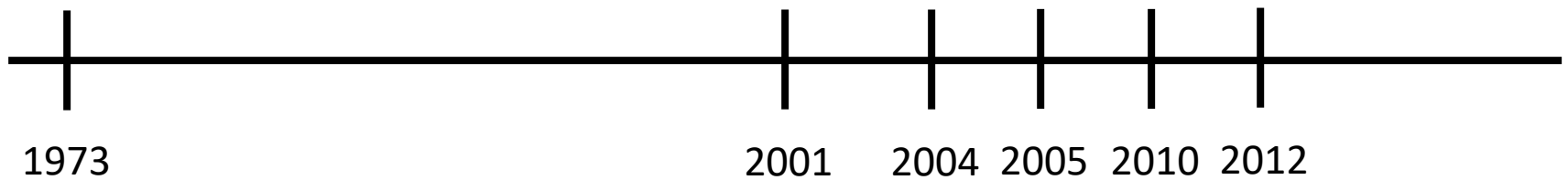


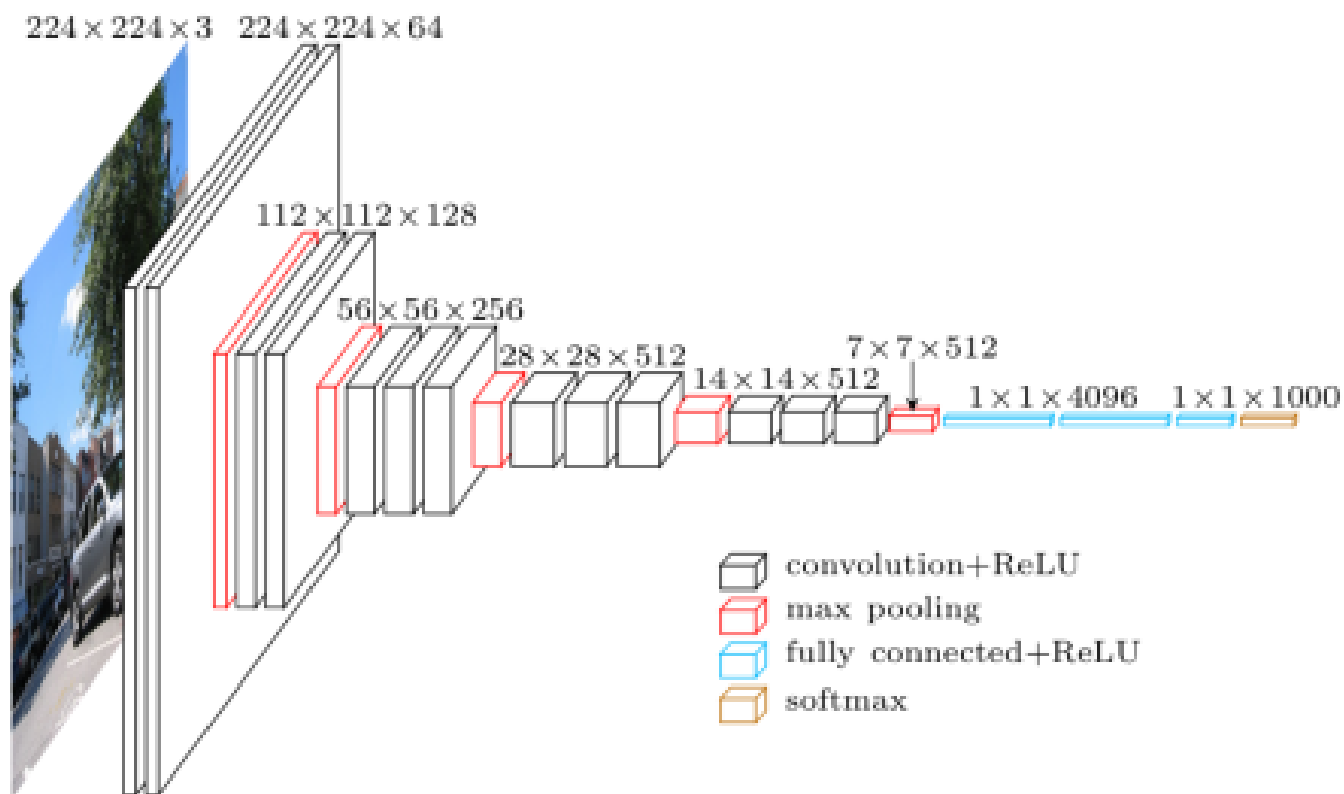
HOG (Dalal and Triggs 05)



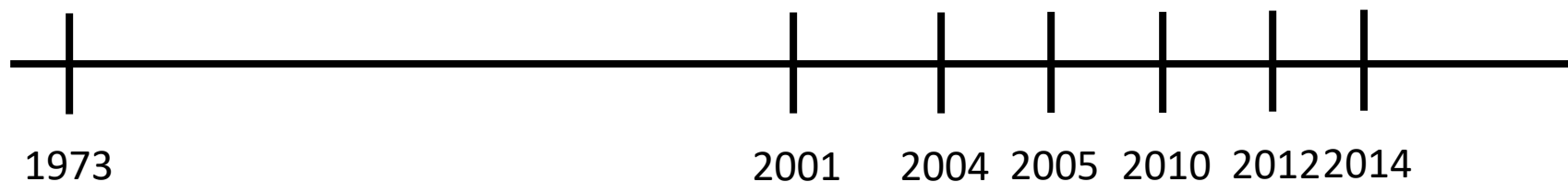


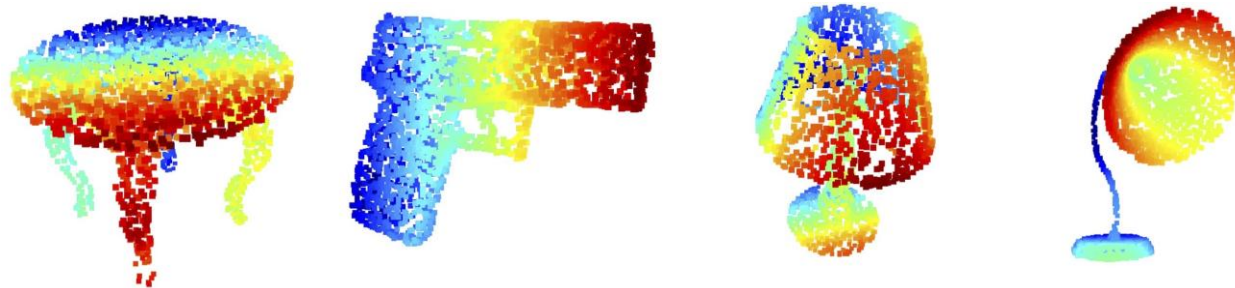
AlexNet (Krizhevsky et al. 12)



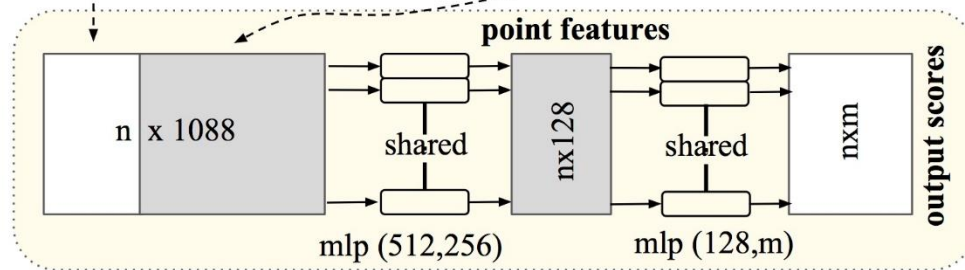
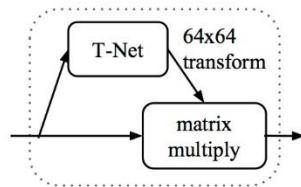
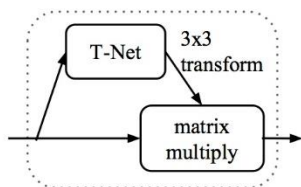
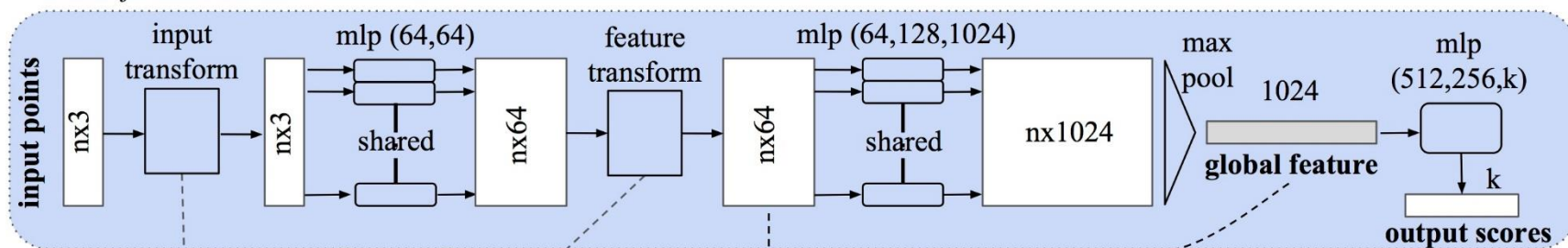


VGG19 (Simonyan and Zisserman 14)



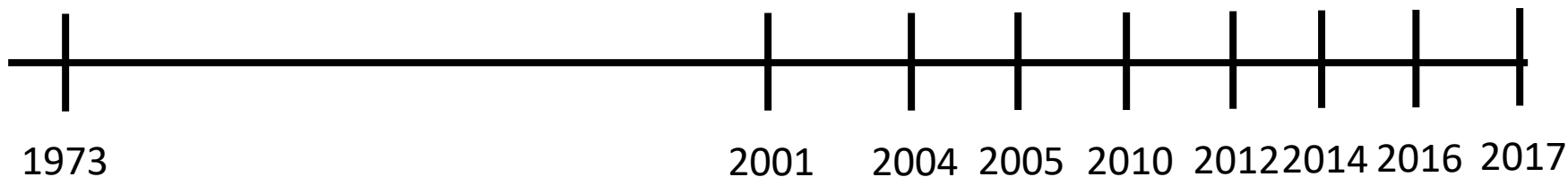


Classification Network

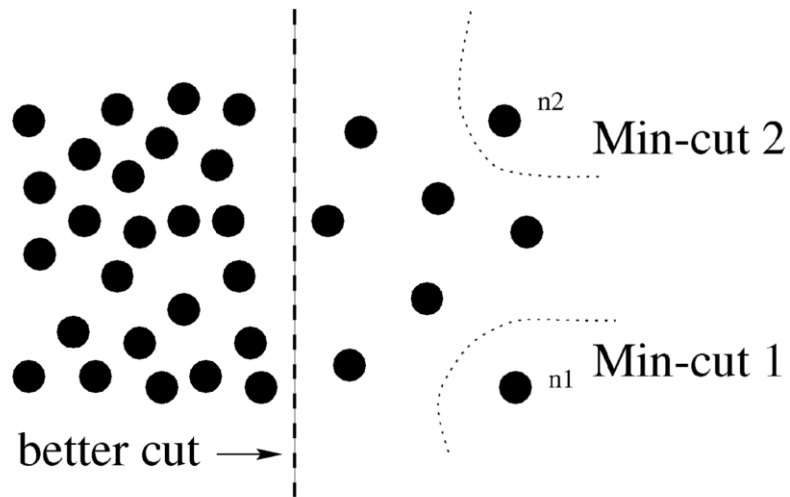


Segmentation Network

PointNet (R. Qi and Su et al. 17)



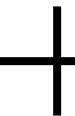
Machine Learning Algorithms

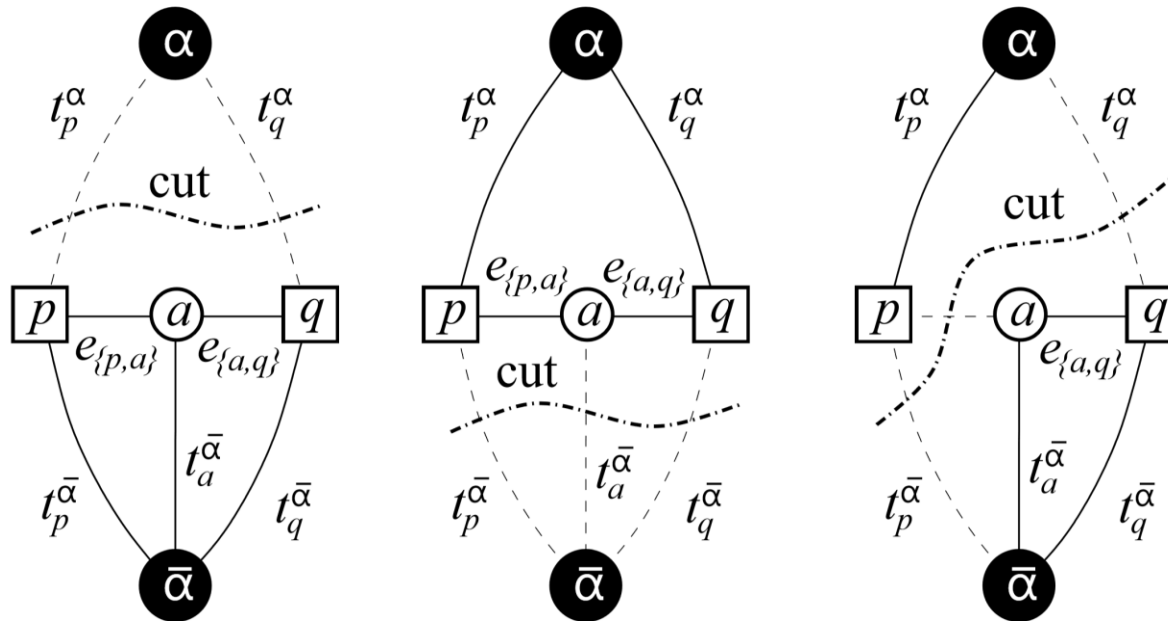


$$Ncut(A, B) = \frac{cut(A, B)}{assoc(A, V)} + \frac{cut(A, B)}{assoc(B, V)}$$

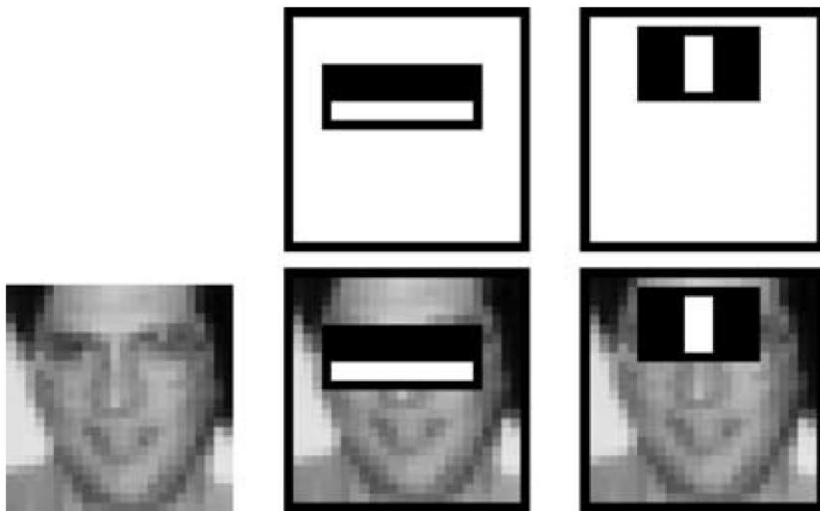


Normalized Cut (Shi and Malik 97)

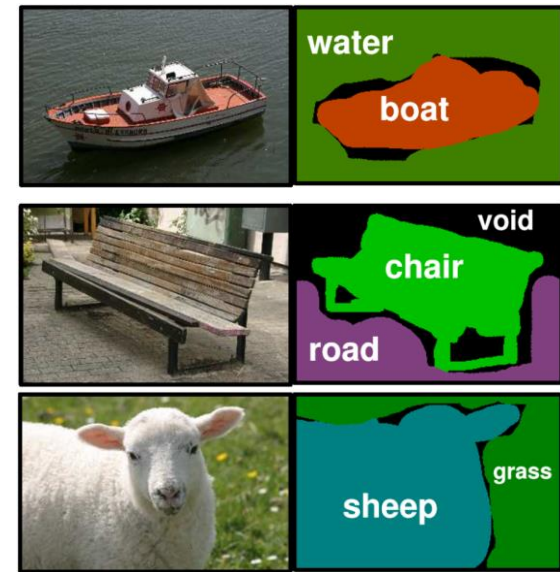




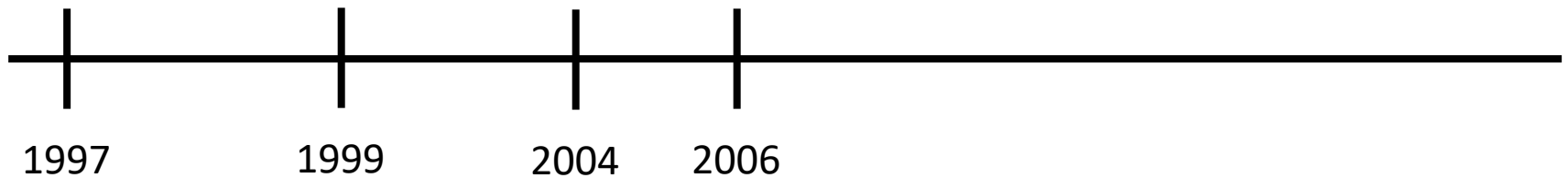
Graph Cut (Boykov et al. 99)

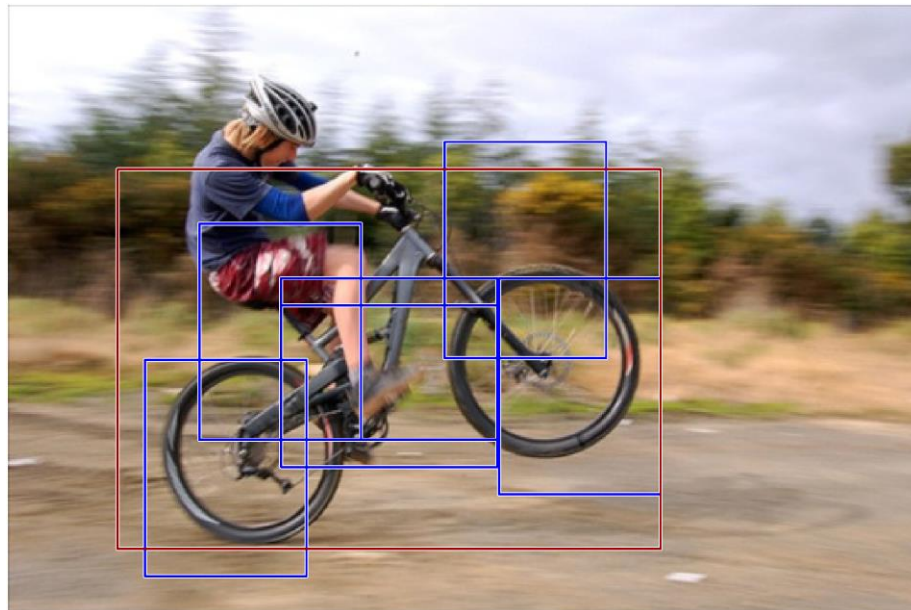
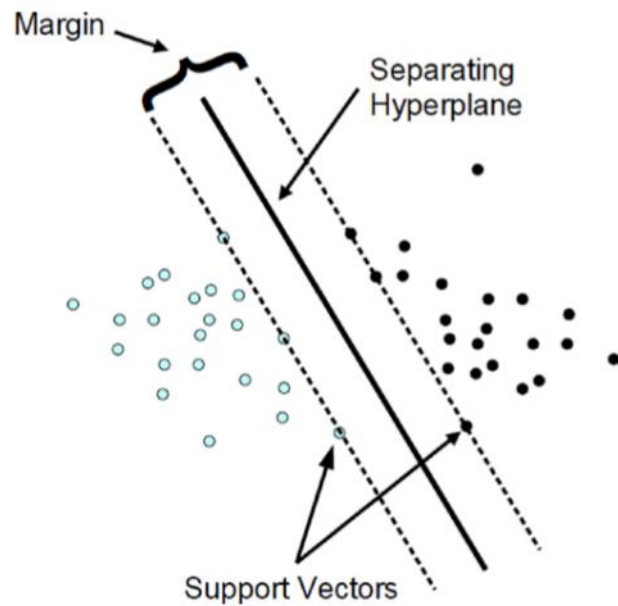


AdaBoosting for face detection
(Viola and Jones 04)

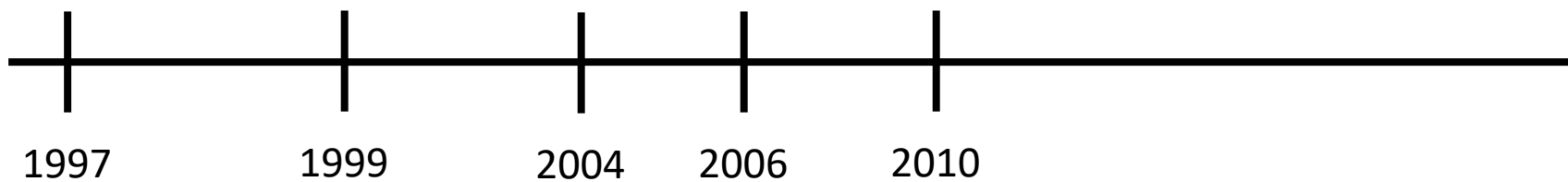


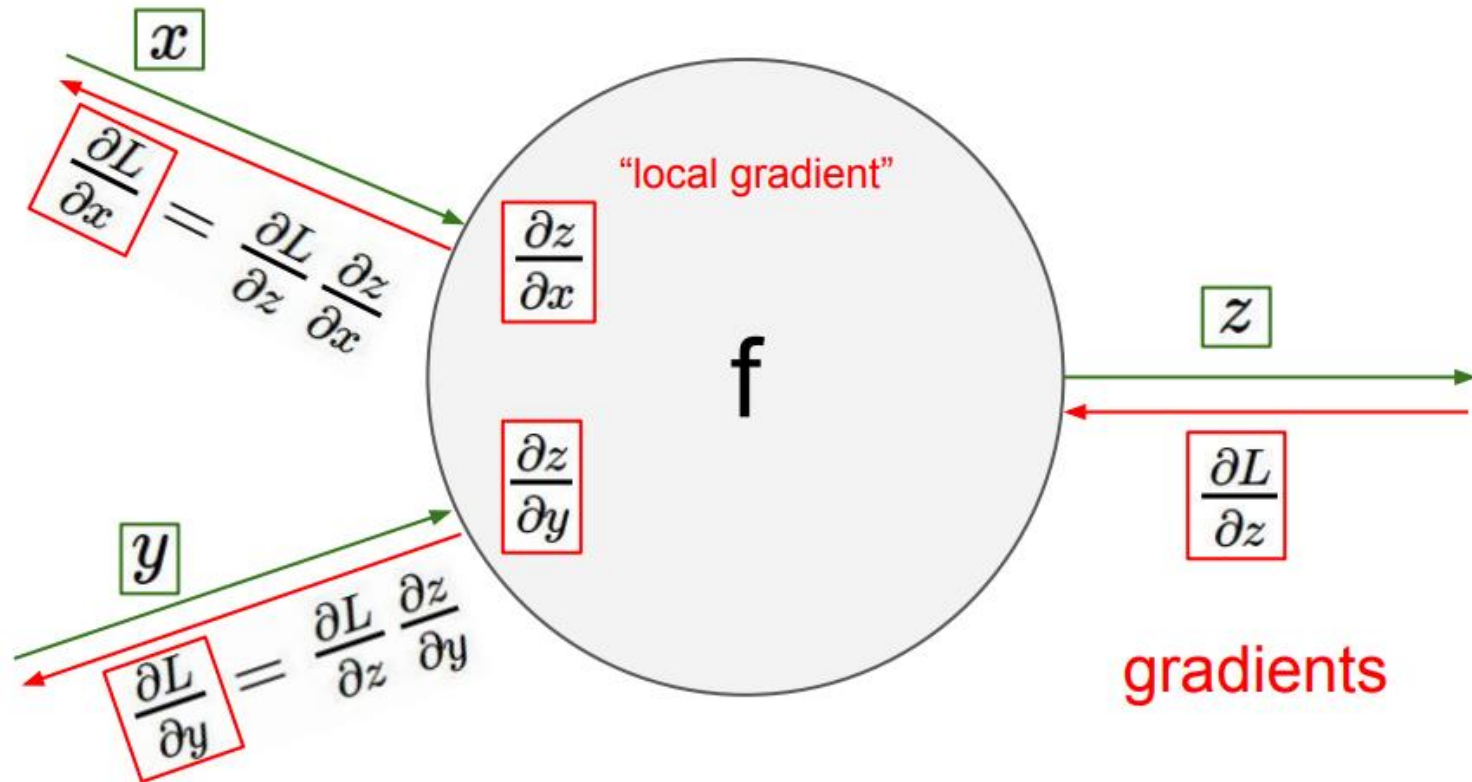
TextonBoost for segmentation
(Shotton et al. 06)



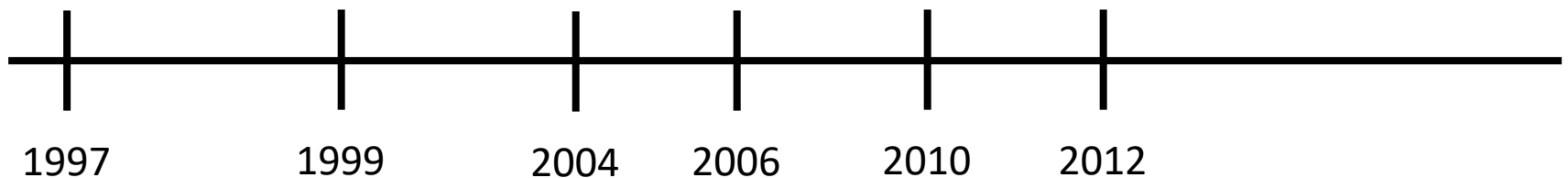


Support Vector Machine in Deformable Part Model
(Felzenszwalb et al. 10)

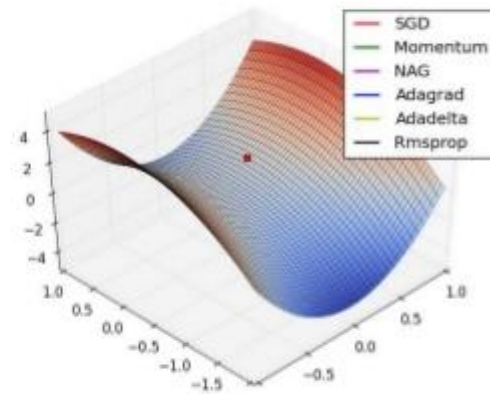
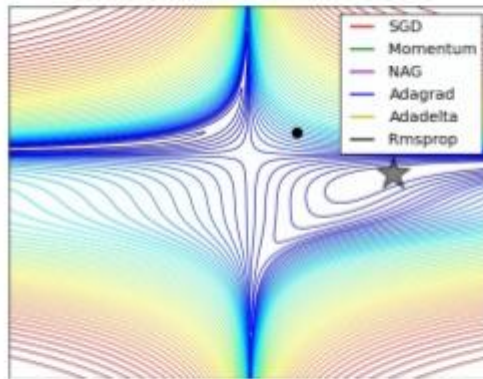




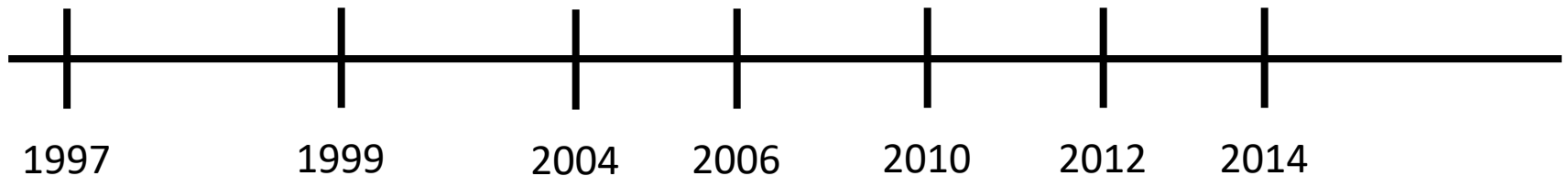
Back-propagation in neural network training/implementation
(Rumelhart et al. 86, LeCun et al. 98, Abadi et al. 16)



Optimization



Adam: A method for stochastic optimization
(Kingma and Ba 14)



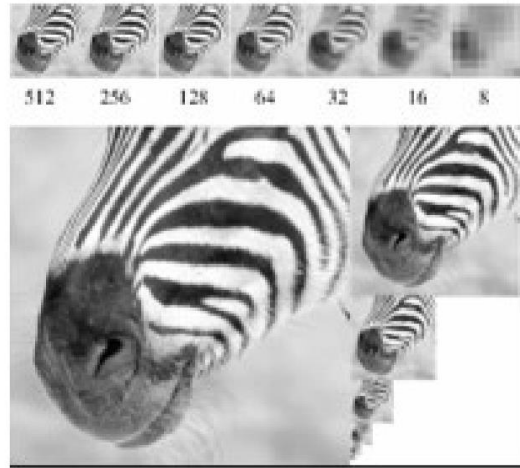
Goals of this course

- Upper division undergrad course
- Introduction to primary topics
 - Fundamentals of computer vision- image processing, grouping, multiple views
 - Recognition – emphasis on machine learning (the most active research area in computer vision)
- Hands-on experience with algorithms
- Basic knowledge of the research field of computer vision

Topics overview

- Features & filters
- Grouping & fitting
- Multiple views
- Recognition

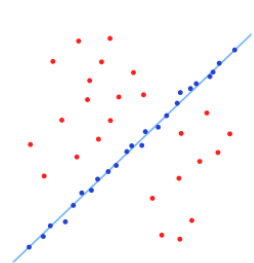
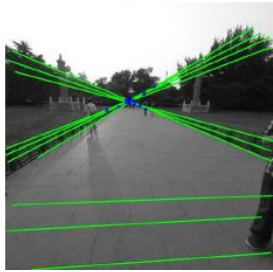
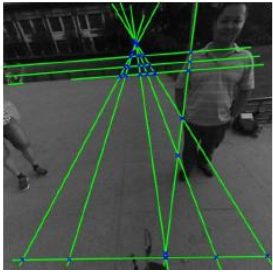
Features and filters



Transforming and
describing images;
Textures, colors, edges

Building blocks for
neural networks

Grouping & fitting

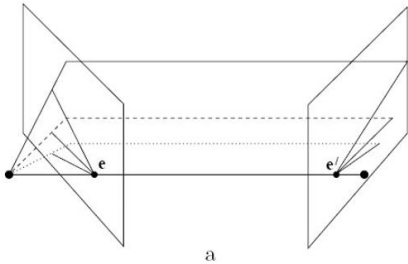


Shi et al.

Clustering, Segmentation, fitting; what parts belong together?

Multiple Views

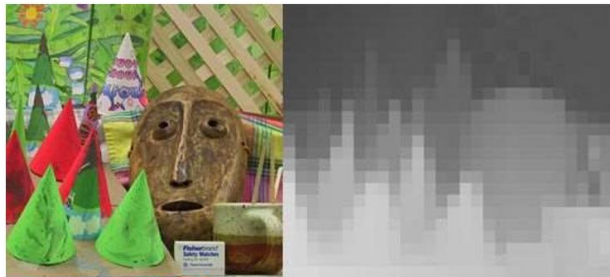
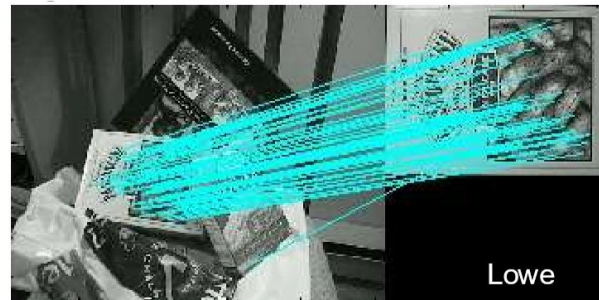
Invariant features, matching
Epipolar geometry
Structure-from-motion, stereo



a

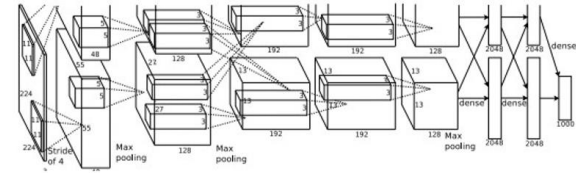
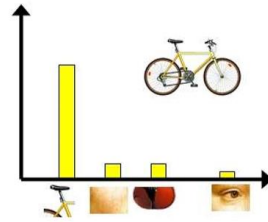


Hartley and Zisserman

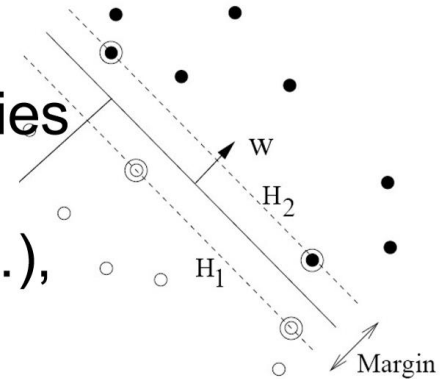


Fei-Fei Li

Recognition and learning



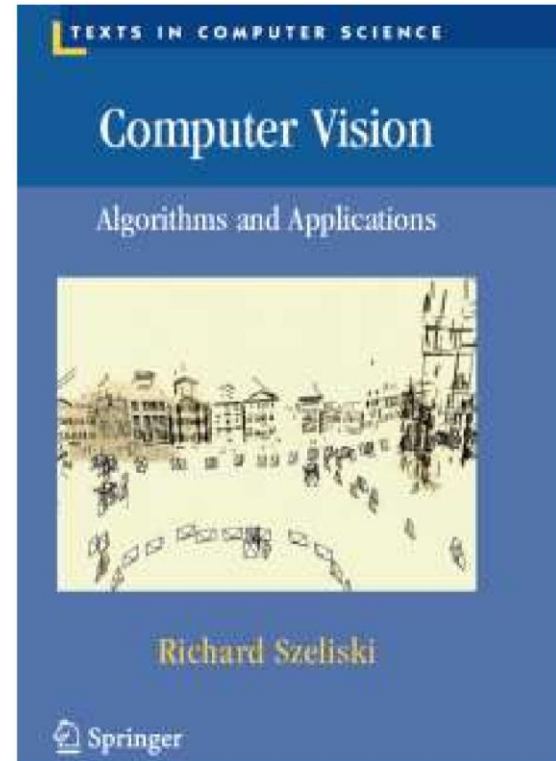
Recognizing categories
(objects, scenes,
activities, attributes...),
learning techniques



Data representation (vectorized) -> machine learning techniques

Textbooks

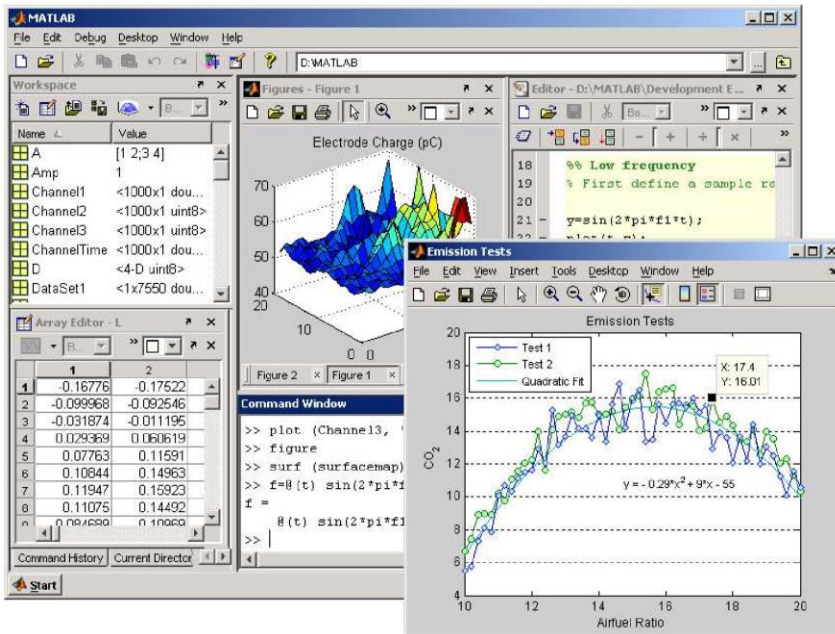
- Recommend book:
 - Computer Vision:
Algorithms and
Applications
 - By Rick Szeliski
 - <http://szeliski.org/Book>
 - Online



Assignments

- Majority - Programming problem
 - Implementation
 - Explanation, results
- Code in Matlab – available on CS Unix machines (see course page)
- Optional Latex templates
- Most of these assignments take significant time to do. We recommend starting early

Matlab

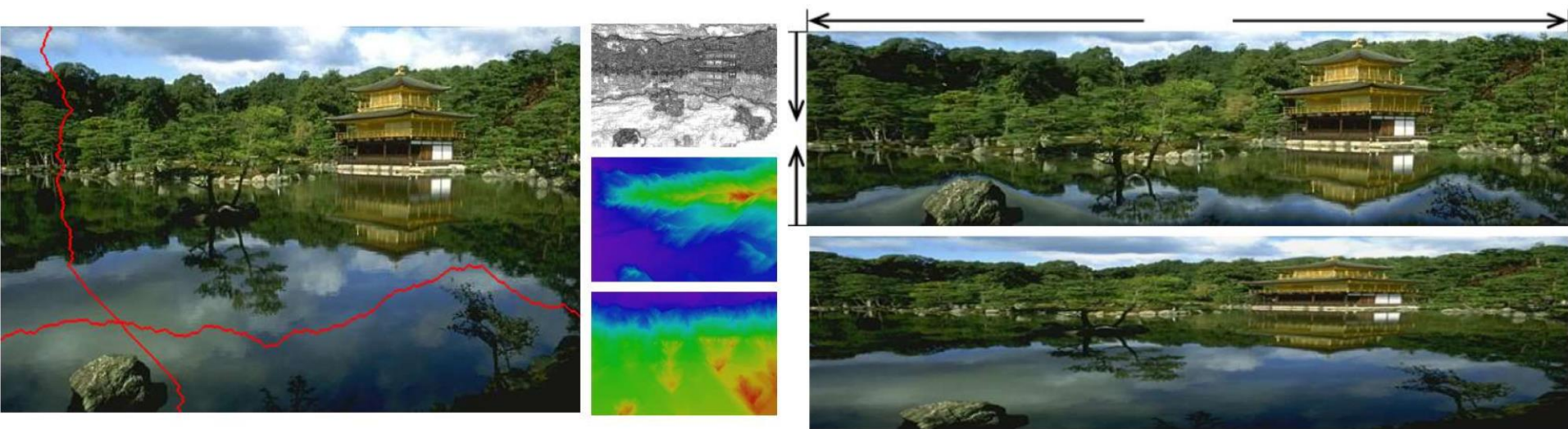


- Built-in toolboxes for low-level image processing, visualization
- Compact programs
- Intuitive interactive debugging
- Widely used in engineering
- I use it a lot!

Assignment 0

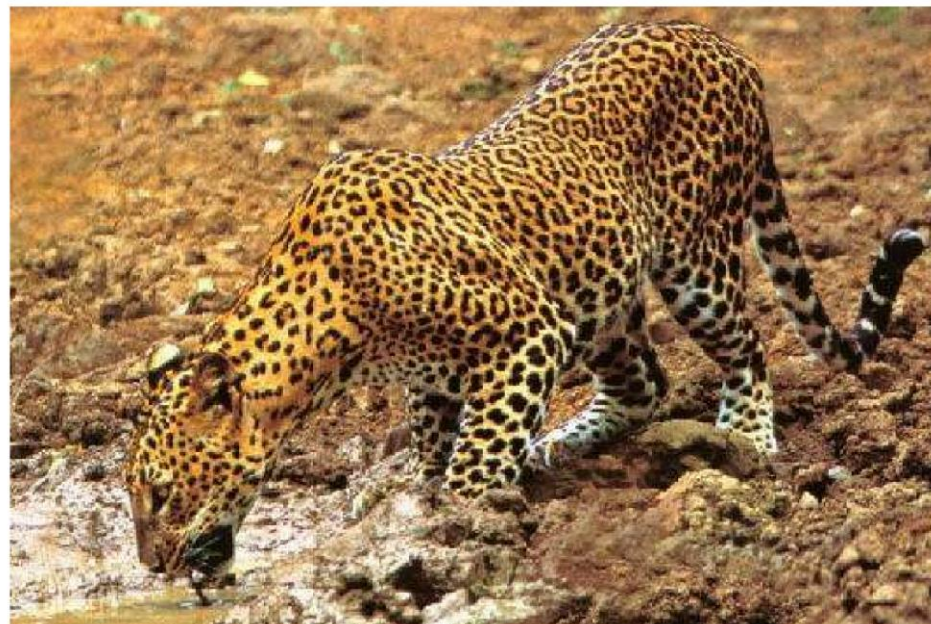
- A0: Matlab warmup + basic image manipulation
 - Out today, due Tues Jan 29
-
- Verify CS account and Matlab access
 - Look at the tutorial online

Preview of assignments



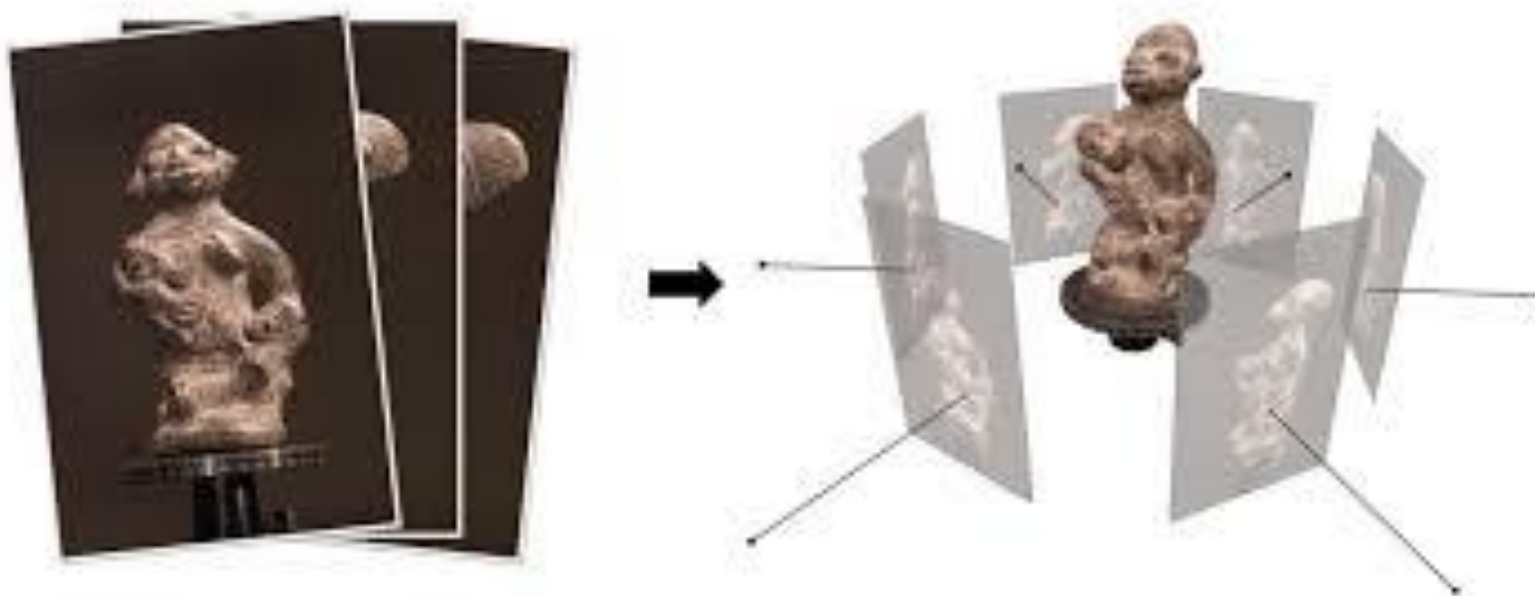
Seam carving

Preview of assignments



Grouping for segmentation

Preview of assignments



Structure-from-motion and stereo

Preview of assignments

airplane



automobile



bird



cat



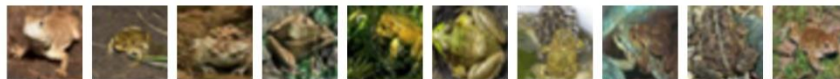
deer



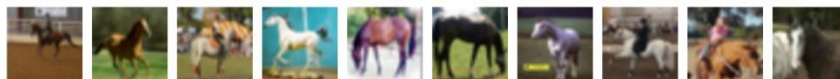
dog



frog



horse



ship

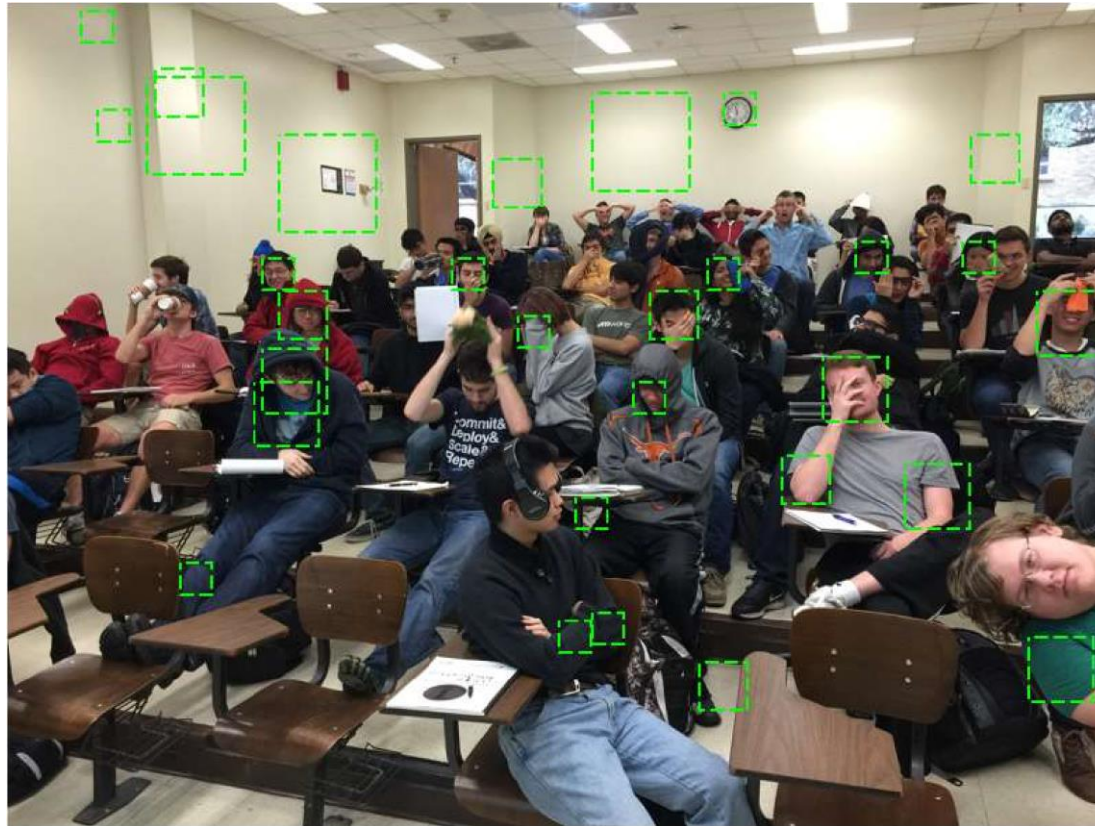


truck



Image classification

Preview of assignments



Object detection

Collaboration policy

- All responses and code must be written individually unless otherwise specified
- Students submitting answers or code found to be identical or substantially similar (due to inappropriate collaboration) risk failing the course.

Assignment deadlines

- Due about every two weeks
 - Tentative deadlines posted online but could slightly shift depending on lecture pace
- Assignments in by 11:59 pm on due date
 - Submit on Canvas, following submission instructions given in assignment
 - Deadlines are firm. We will use timestamp

Miscellaneous

- Slides, announcements via class website
- No laptops, phones, tablets, etc. open in class please
- Please use the front rows

Coming up

- Now: check out Matlab tutorial online
- A0 due Tuesday Jan. 29
- Textbook reading posted for next week