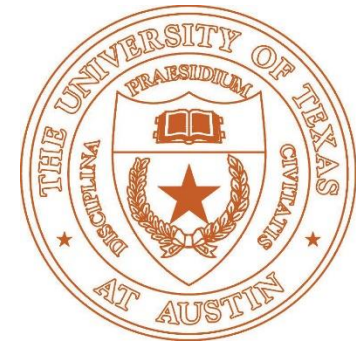
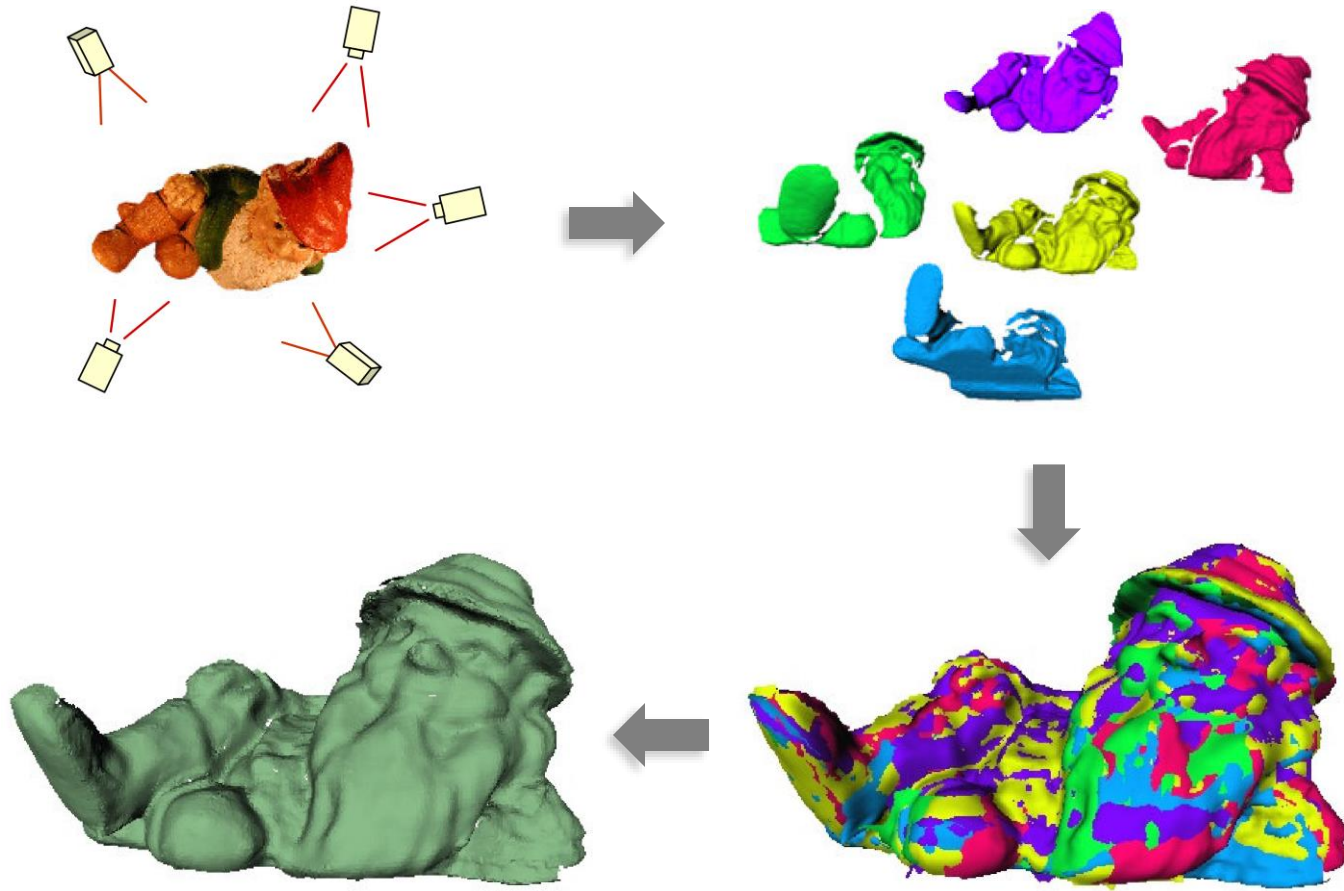


Multi-View Matching & Mesh Generation

Qixing Huang
Feb. 13th 2017



Geometry Reconstruction Pipeline

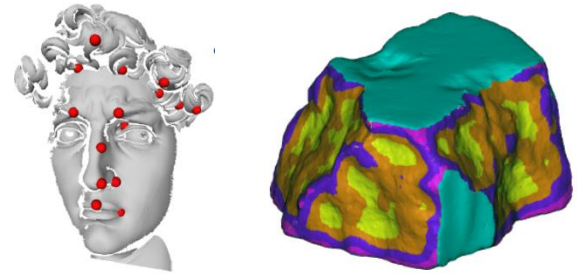


RANSAC --- facts

- Sampling

- Feature point detection

[Gelfand et al. 05, Huang et al. 06]



- Correspondences

- Use feature descriptors $m \ll O(n^2)$
- The candidate correspondences
- Denote the success rate $p \approx \frac{n}{m}$

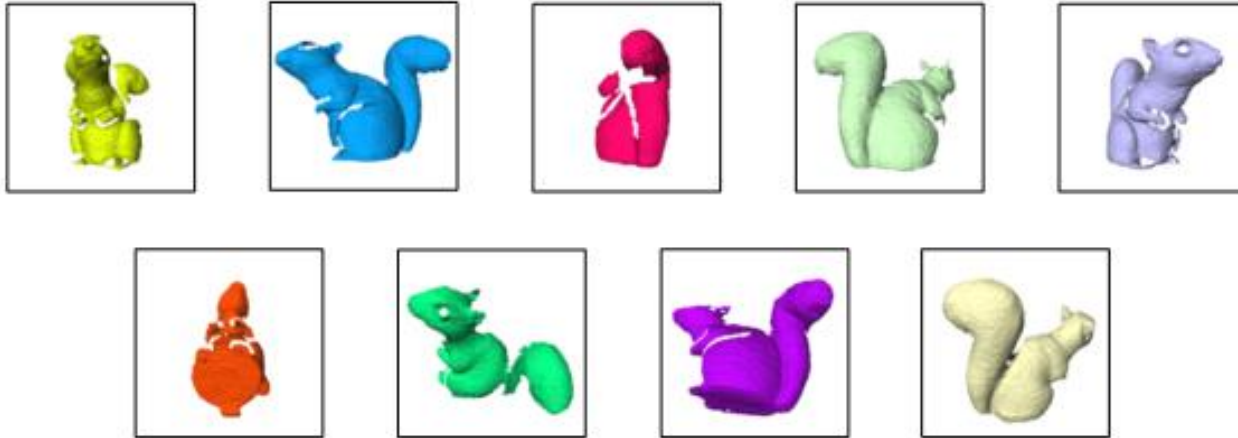
- *Basic* analysis

- The probability of having a valid triplet p^3
- The probability of having a valid triplet in N trials is $1 - (1 - p^3)^N$

Multiple Matching

Spanning tree based

From this...

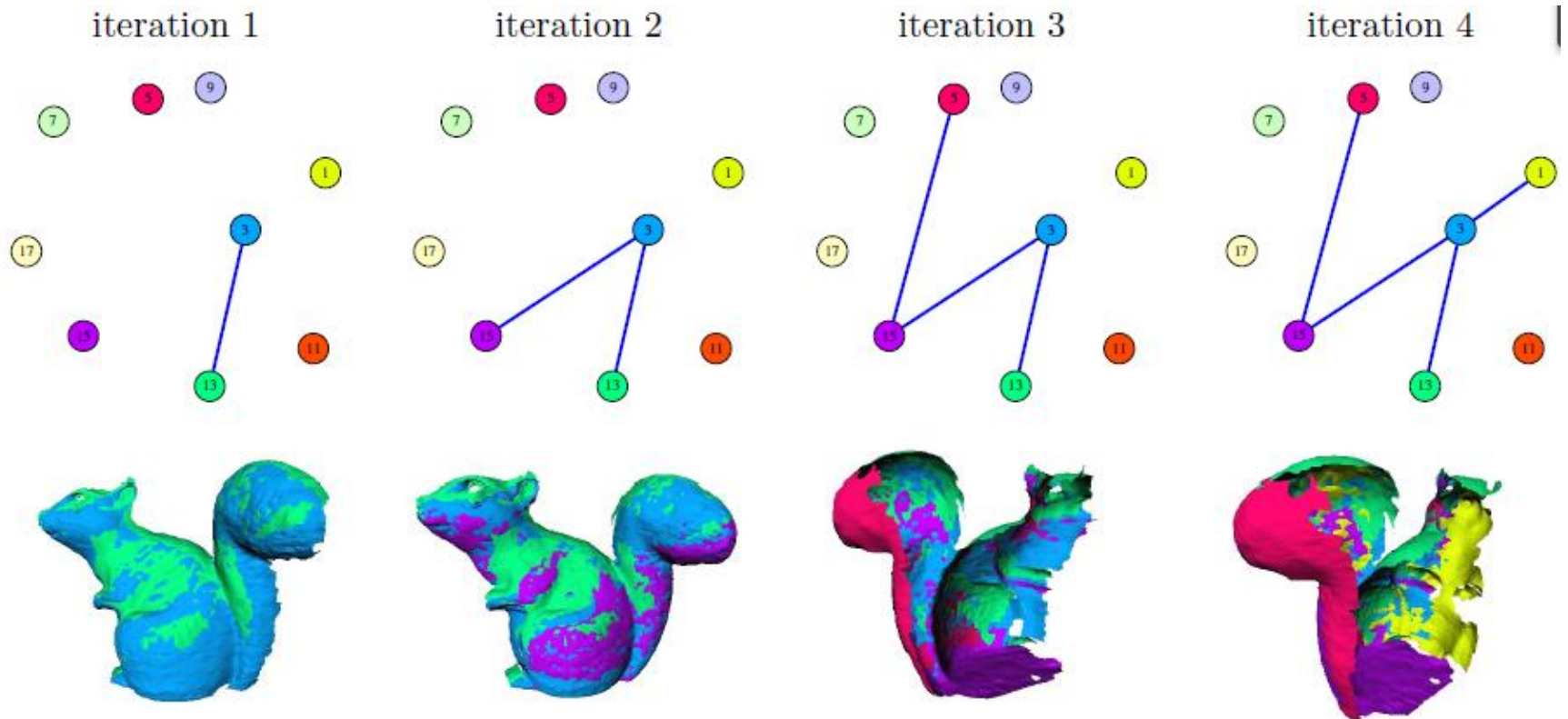


to this...

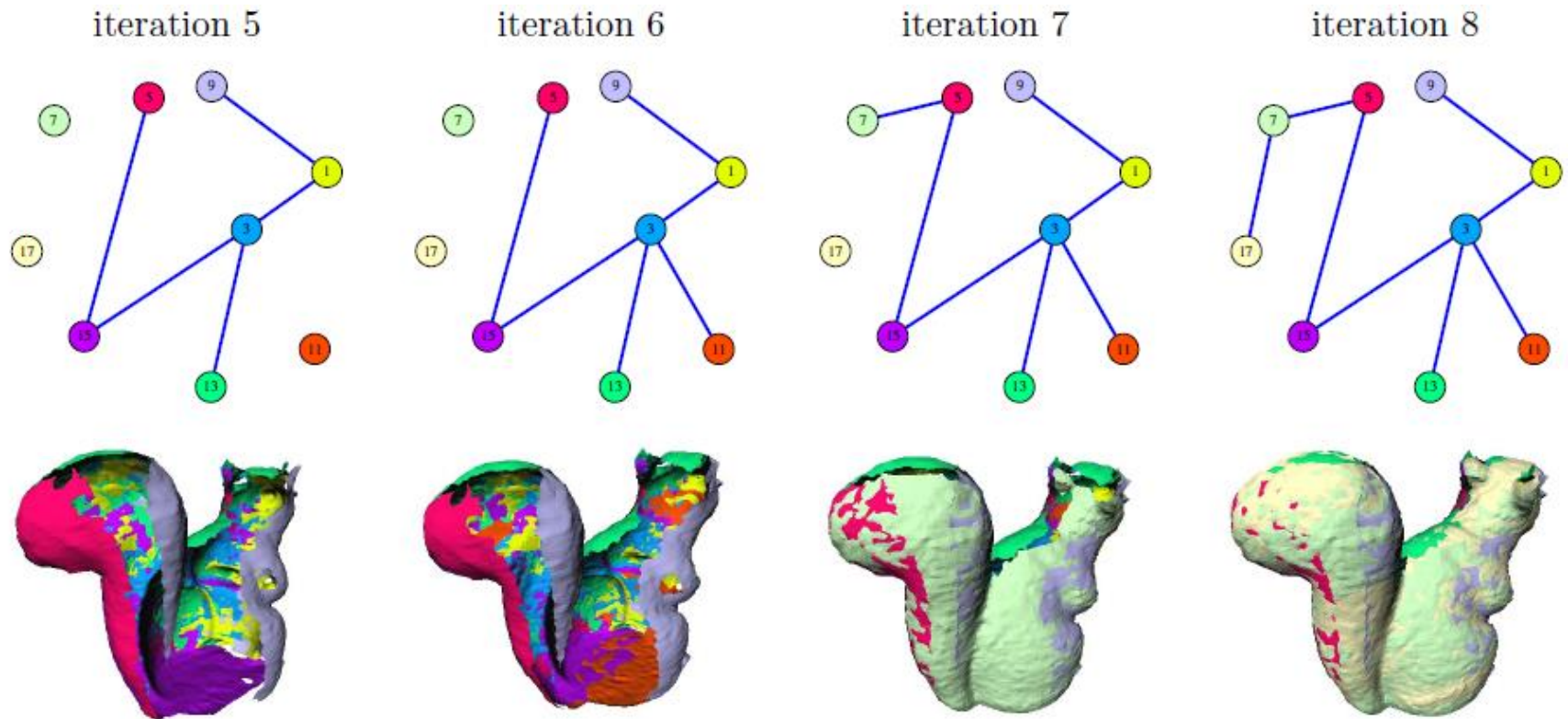


...automatically

Spanning tree based



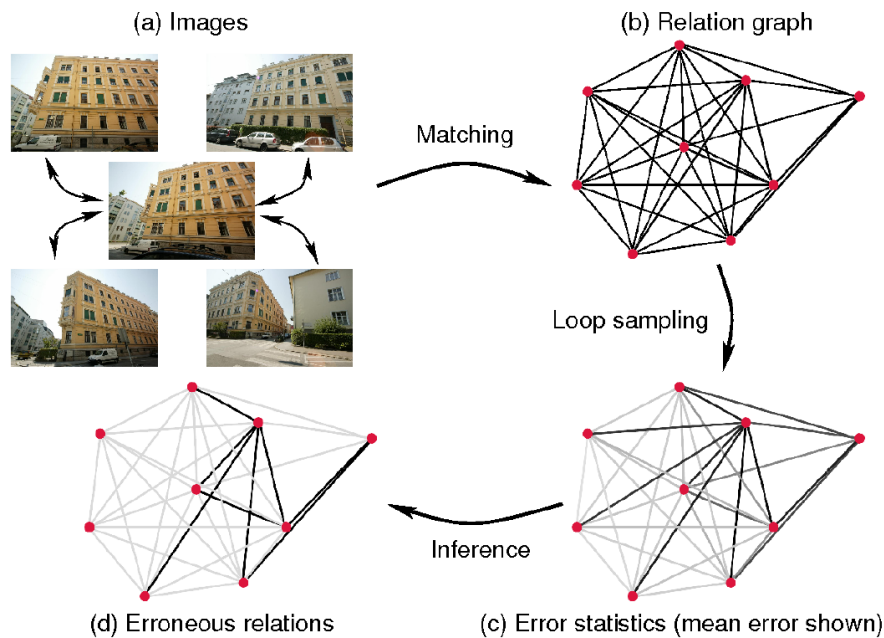
Spanning tree based



Issue: A single incorrect match can destroy everything

Detecting inconsistent cycles

large for inconsistent cycles



maximize

$$\sum_L \rho_L x_L$$

subject to

$$x_L \geq x_e \quad \forall e \in L,$$

$$x_L \leq \sum_{e \in L} x_e,$$

$$x_L \in [0, 1],$$

$$x_e \in [0, 1].$$

Rotation

[Wang and Singer'13]

$$\mathbf{R} = \begin{bmatrix} I_3 & \cdots & \mathbf{R}_{1n} \\ \vdots & \ddots & \vdots \\ \mathbf{R}_{1n}^T & \cdots & I_3 \end{bmatrix}$$

$$\text{minimize} \quad \sum_{(i,j) \in \mathcal{G}} \|\mathbf{R}_{ij} - \mathbf{R}_{ij}^{init}\|_{\mathcal{F}}$$

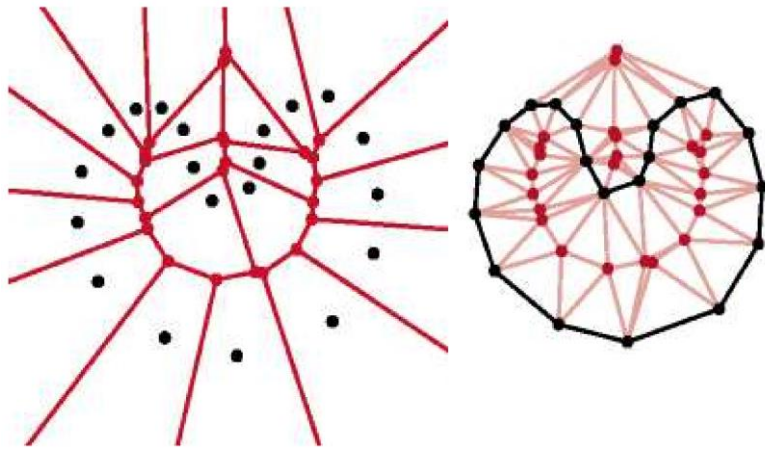
$$\text{subject to} \quad \mathbf{R} \succeq 0$$

$$\mathbf{R}_{ii} = I_3, \quad 1 \leq i \leq n$$

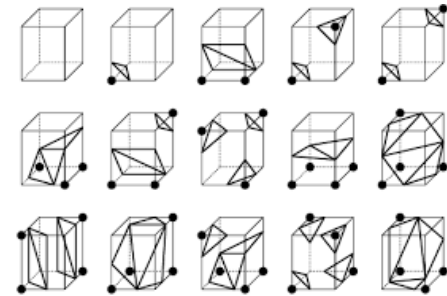
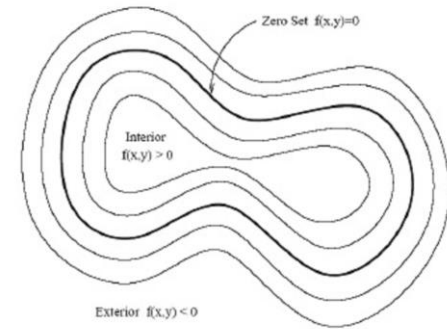
$$\mathbf{R}_{ij} \in \text{convex-hull}(SO(3)), \quad 1 \leq i < j \leq n$$

Meshing

Two Approaches

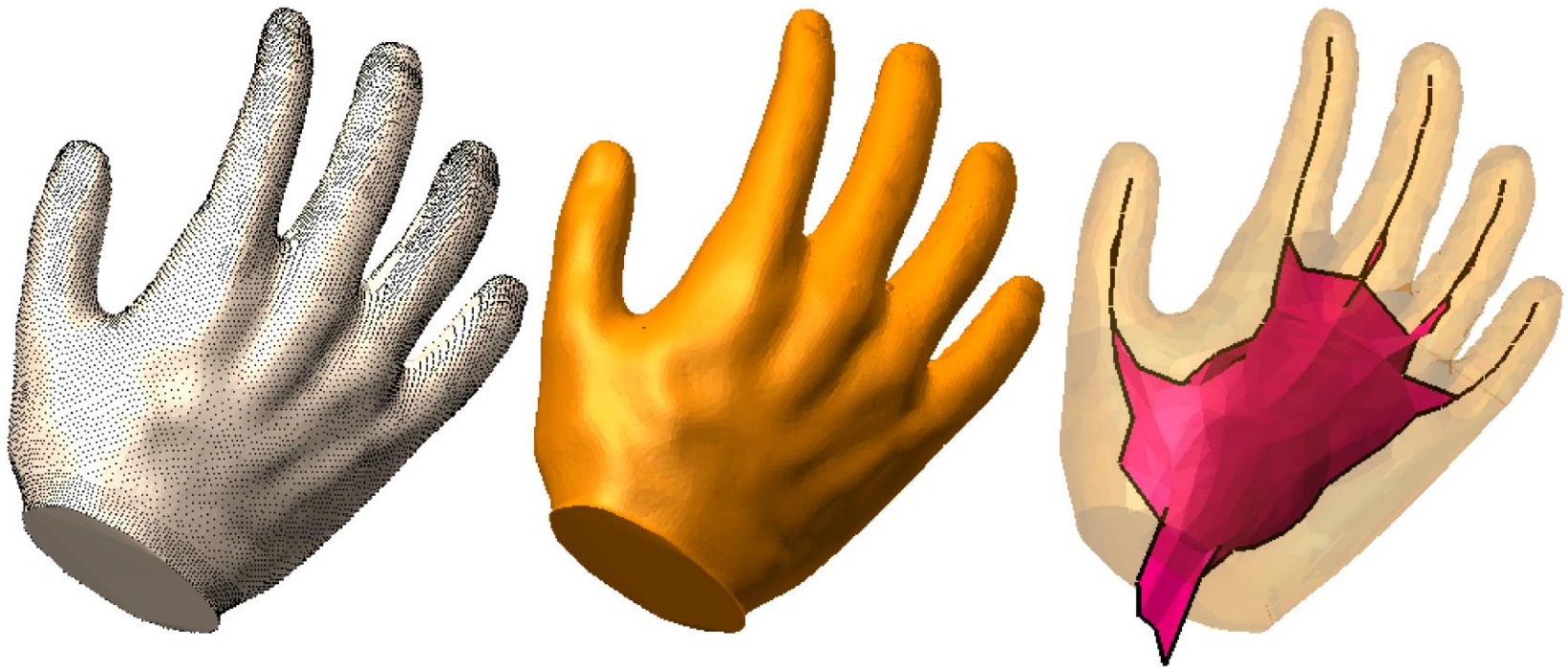


Computational Geometry
Based

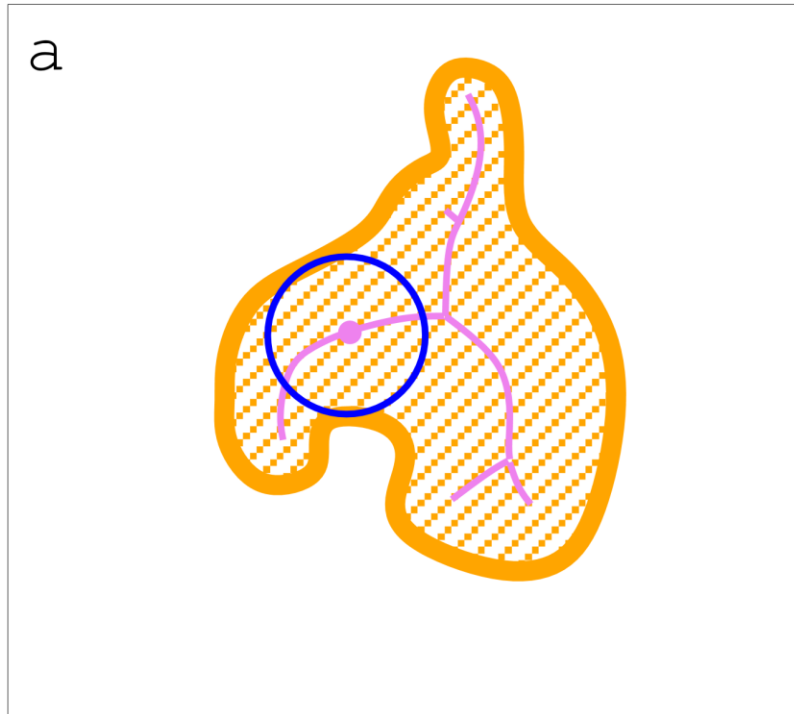


Implicit Surface -> Contouring

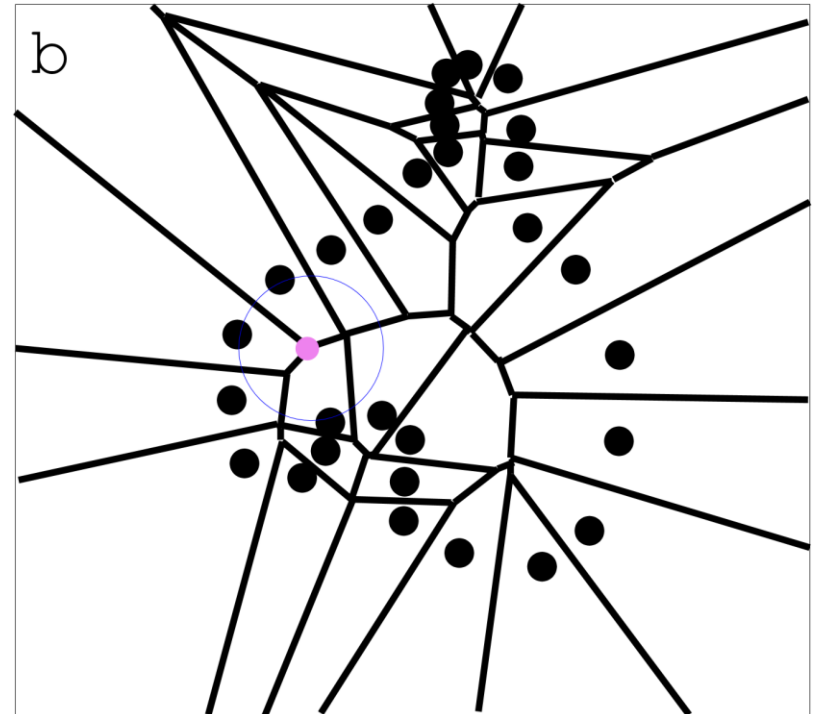
Power Crust [Amenta et al. 02]



Power Crust [Amenta et al. 02]

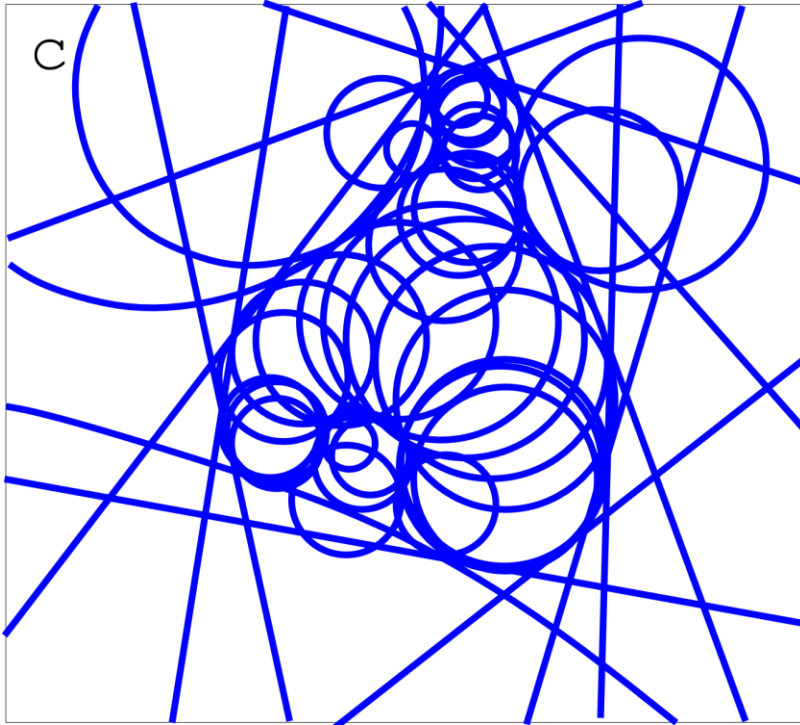


(a) An object with its medial axis; one maximal interior ball is shown.

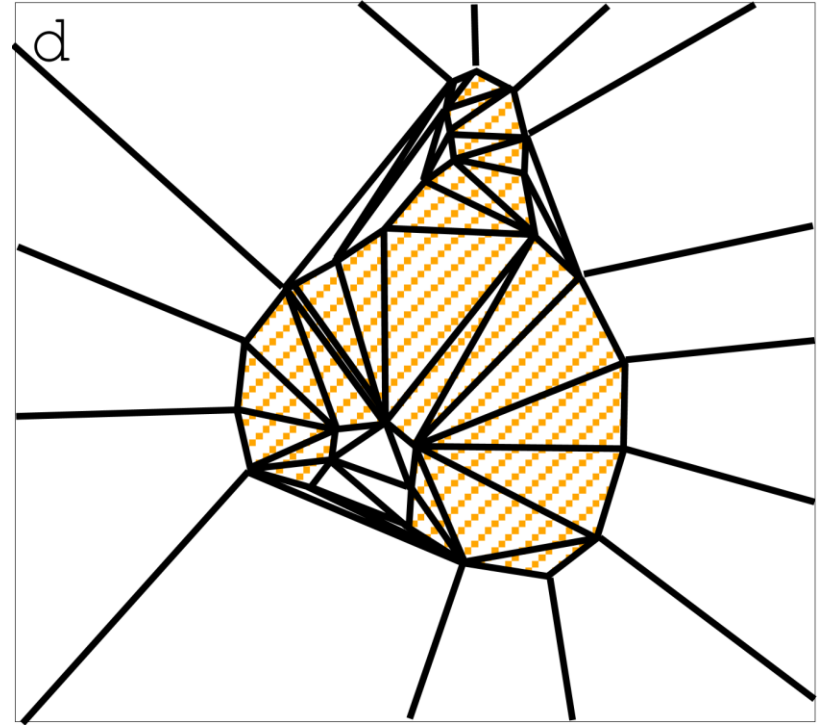


b) The Voronoi diagram of S , with the Voronoi ball surrounding one pole shown. In 2D, we can select all Voronoi vertices as poles, but not in 3D

Power Crust [Amenta et al. 02]

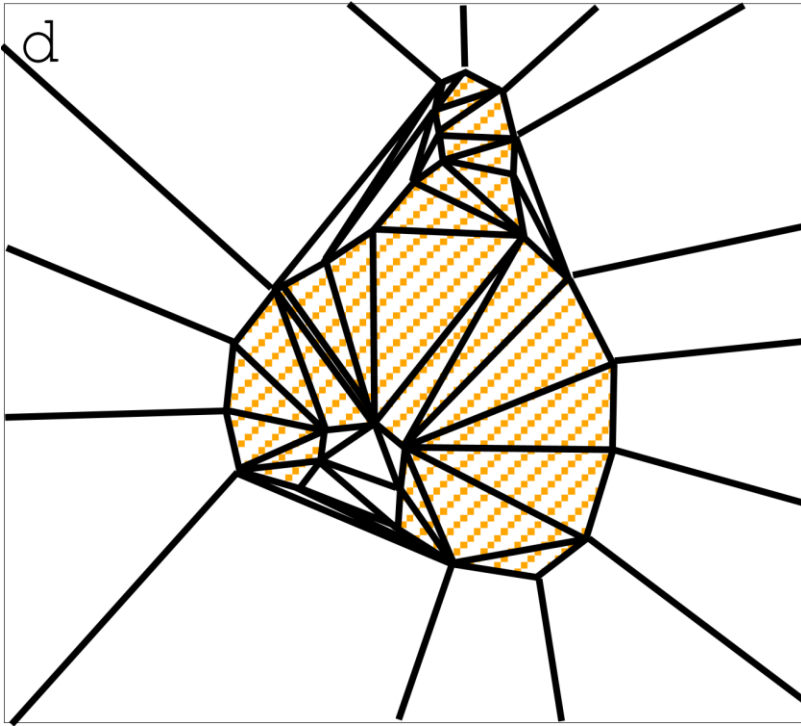


c) The inner and outer polar balls. Outer polar balls with centers at infinity degenerate to halfspaces on the convex hull.

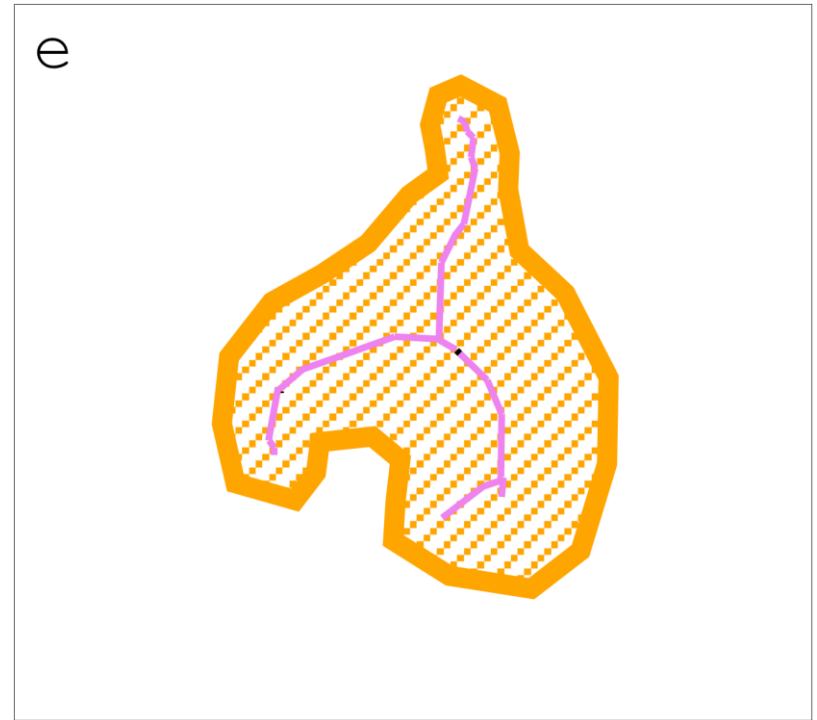


d) The power diagram cells of the poles, labeled inner and outer.

Power Crust [Amenta et al. 02]

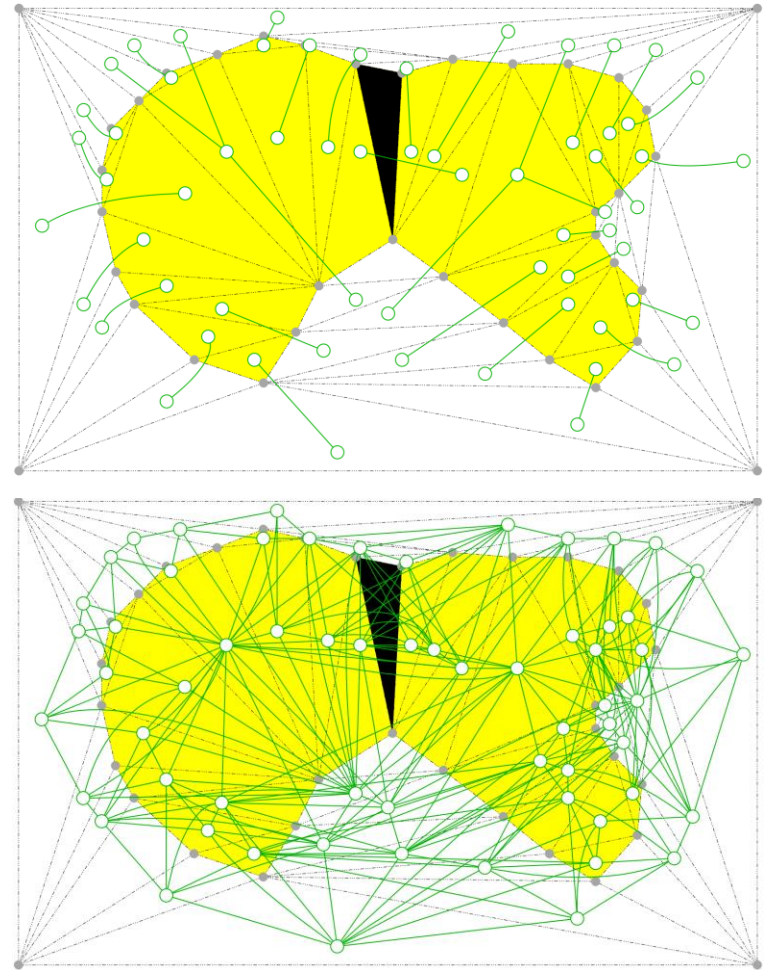
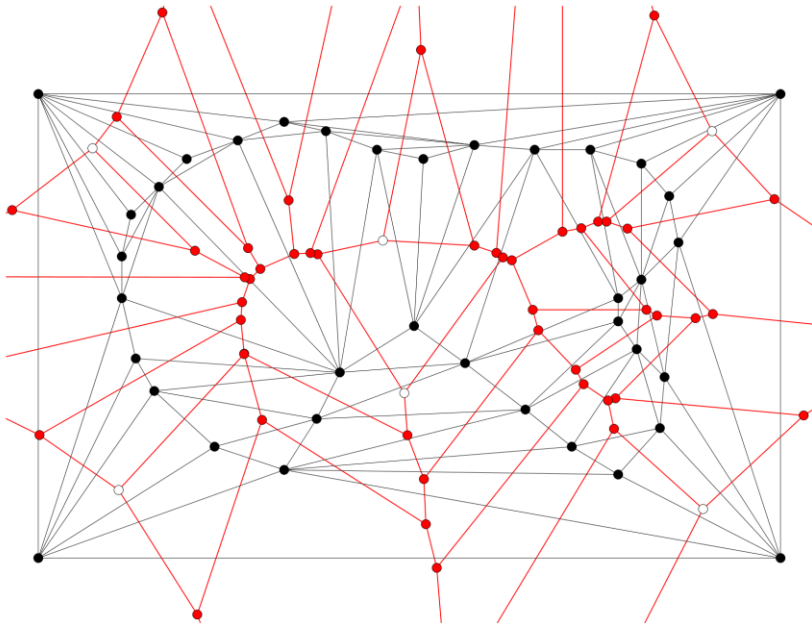


d) The power diagram cells of the poles, labeled inner and outer.



e) The power crust and the power shape of its interior solid.

Eigen Crust [Kolluri et al. 04]



Eigen Crust [Kolluri et al. 04]

200 outliers



1,200 outliers



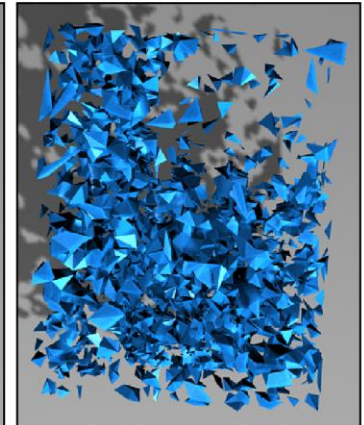
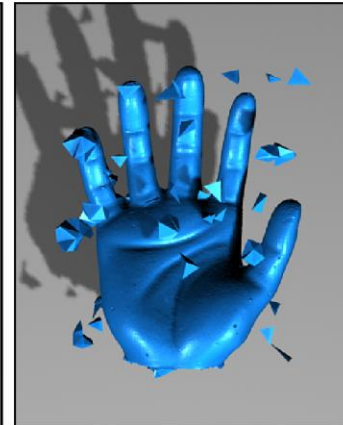
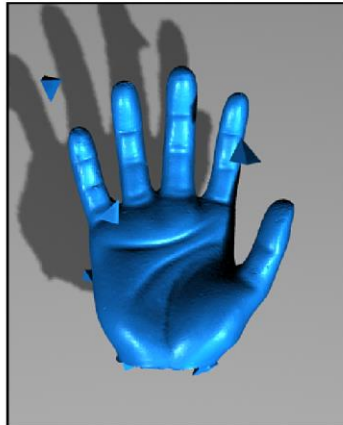
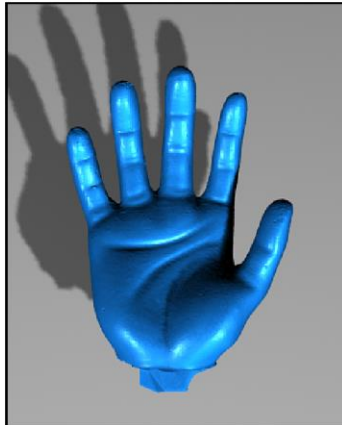
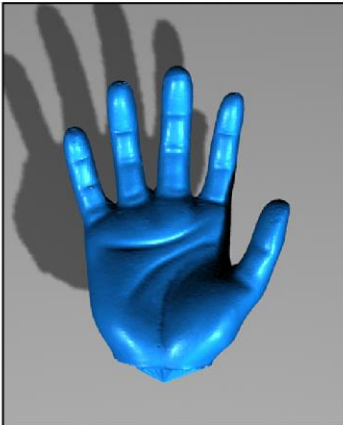
1,800 outliers



6,000 outliers

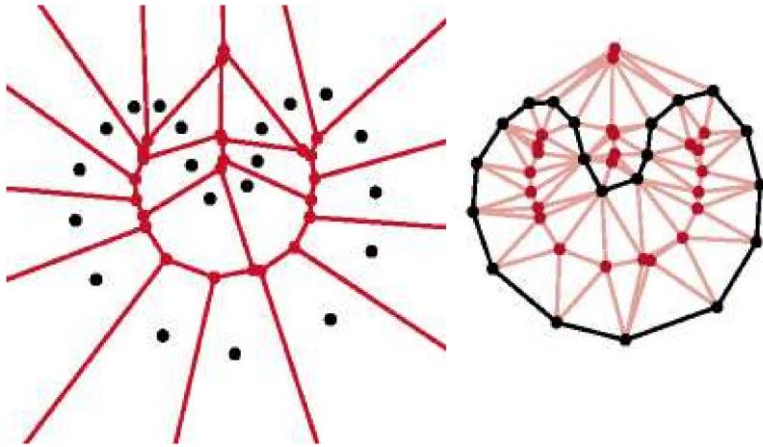


10,000 outliers

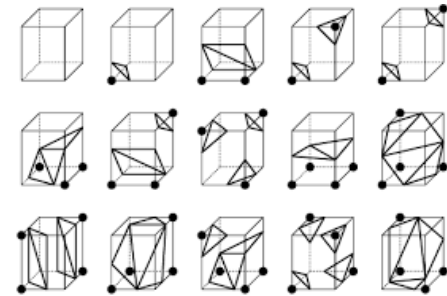
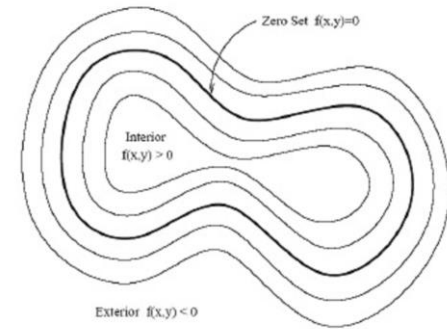


EigenCrust

Two Approaches

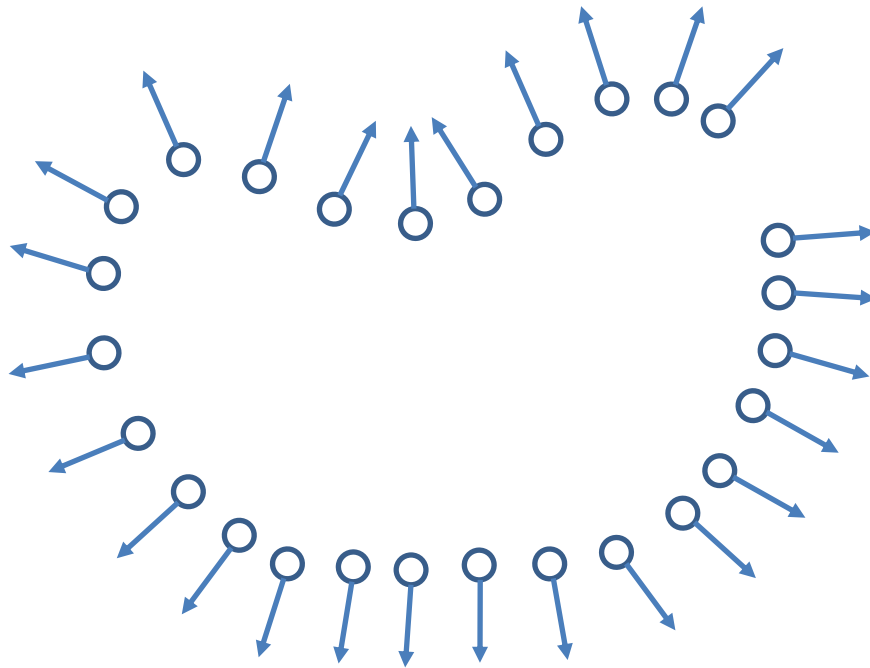


Computational Geometry
Based



Implicit Surface -> Contouring

Point Cloud -> Implicit Surface?



Challenges:

Irregular Samples

Holes

Noise

$$\sum_{i=1}^N w_i(\mathbf{x})(\mathbf{x} - \mathbf{p}_i)^T \mathbf{n}_i = 0$$

$$w_i(\mathbf{x}) = \frac{\exp(-\frac{\|\mathbf{x} - \mathbf{p}_i\|^2}{2\sigma^2})}{\sum_{i=1}^n \exp(-\frac{\|\mathbf{x} - \mathbf{p}_i\|^2}{2\sigma^2})}$$

Defining point-set surfaces [Amenta et al. 05]

Defining Point-Set Surfaces

Nina Amenta

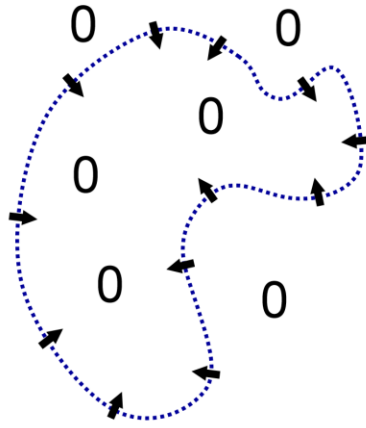
Yong J. Kil

Center for Image Processing and Integrated Computing, U C Davis

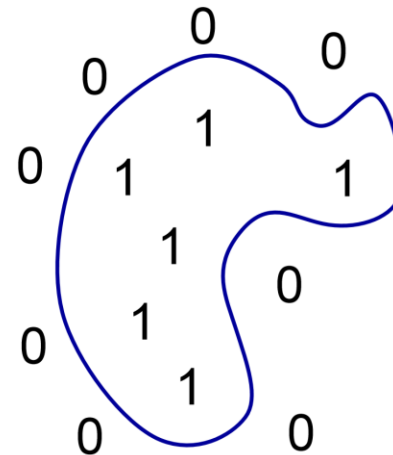
Poisson surface reconstruction [Kazhdan et al. 06]



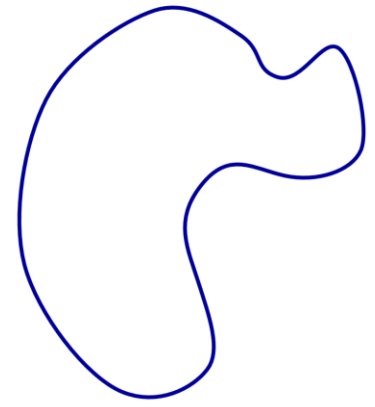
Oriented points
 $\vec{V}$



Indicator gradient
 $\nabla \chi_M$



Indicator function
 χ_M



Surface
 ∂M

Poisson surface reconstruction [Kazhdan et al. 06]

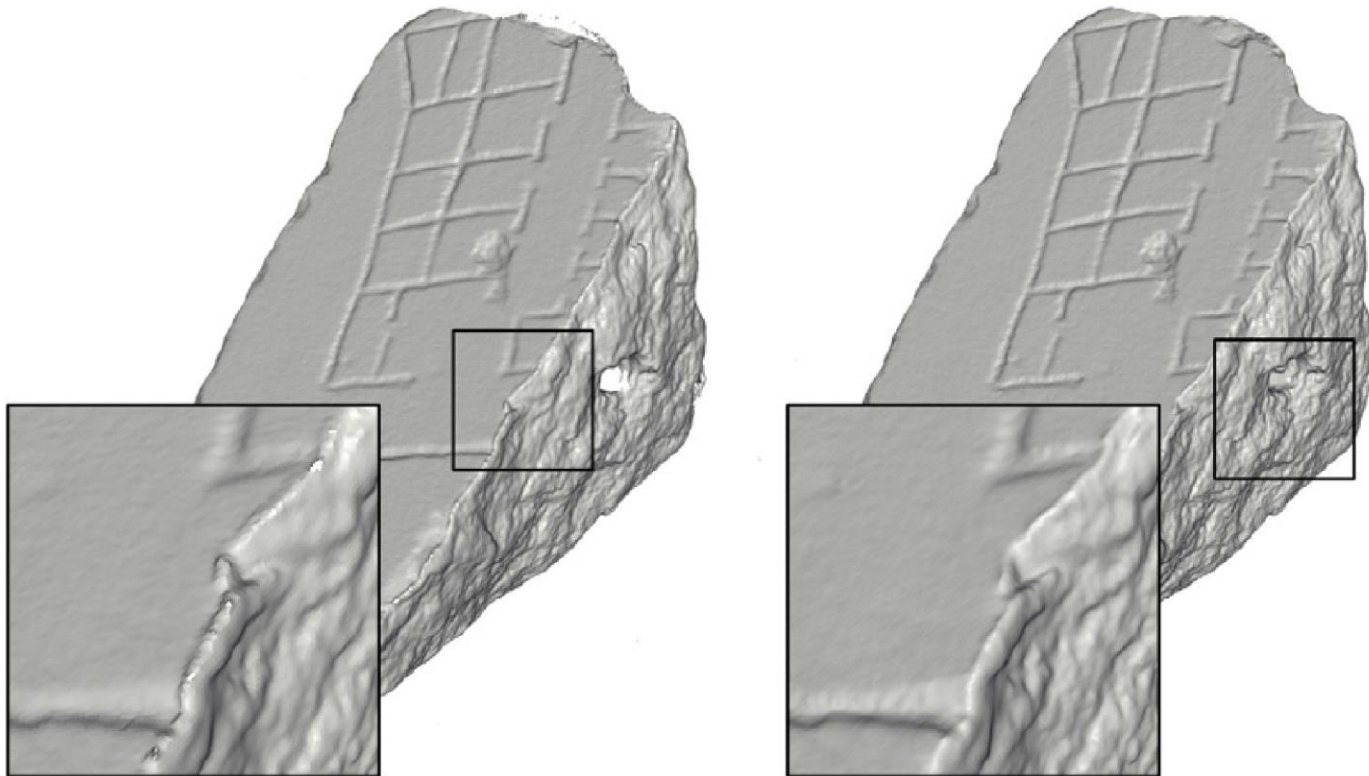
Define the vector field:

$$\begin{aligned}\nabla(\chi_M * \tilde{F})(q) &= \sum_{s \in S} \int_{\mathcal{P}_s} \tilde{F}_p(q) \vec{N}_{\partial M}(p) dp \\ &\approx \sum_{s \in S} |\mathcal{P}_s| \tilde{F}_{s.p}(q) s.\vec{N} \equiv \vec{V}(q)\end{aligned}$$

Solve the Poisson equation:

$$\Delta \tilde{\chi} = \nabla \cdot \vec{V}.$$

Poisson surface reconstruction [Kazhdan et al. 06]



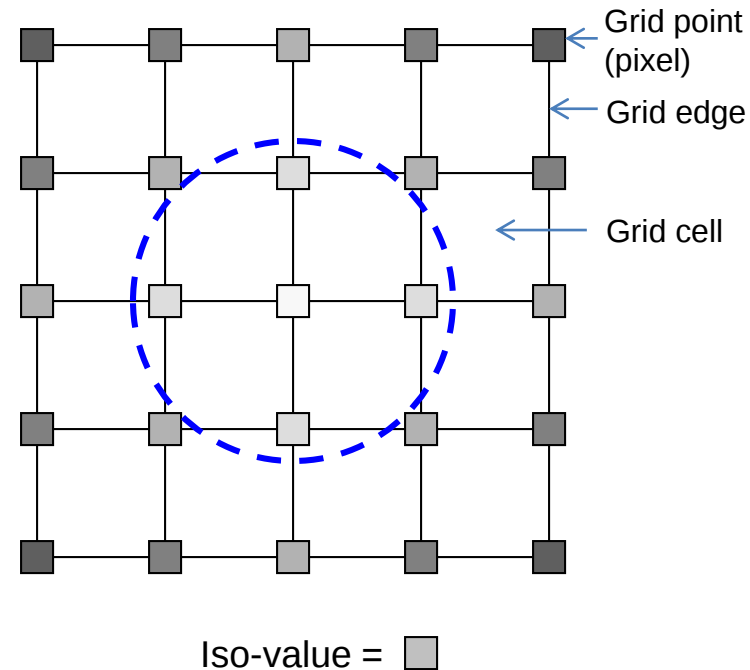
VRIP

Poisson Surface
Reconstruction

Contouring

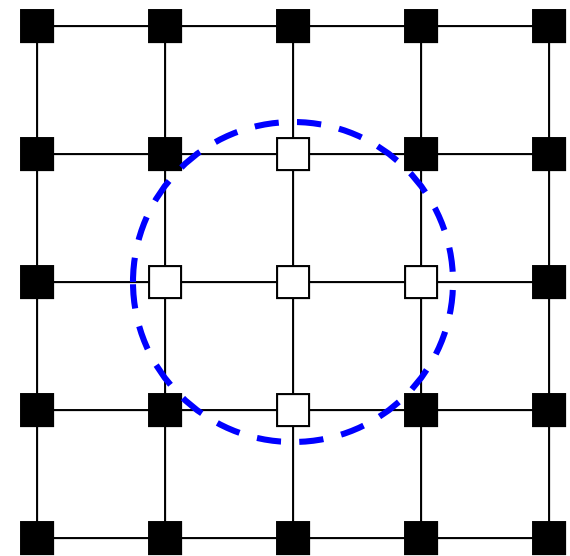
Contouring (On A Grid)

- Input
 - A grid where each grid point (pixel or voxel) has a value (color)
 - An iso-value (threshold)
- Output
 - A closed, manifold, non-intersecting polyline (2D) or mesh (3D) that separates grid points **above** the iso-value from those that are **below** the iso-value.



Contouring (On A Grid)

- Input
 - A grid where each grid point (pixel or voxel) has a value (color)
 - An iso-value (threshold)
- Output
 - Equivalently, we extract the zero-contour (separating **negative** from **positive**) after **subtracting the iso-value from the grid points**



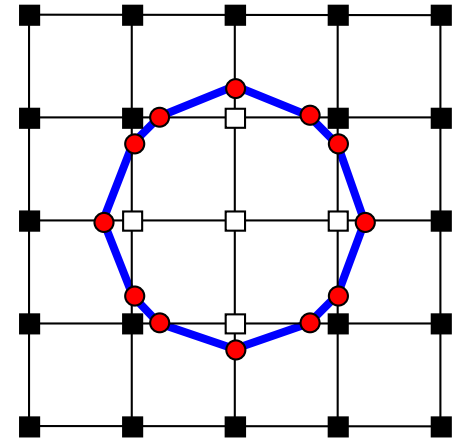
Iso-value = 0

■ negative

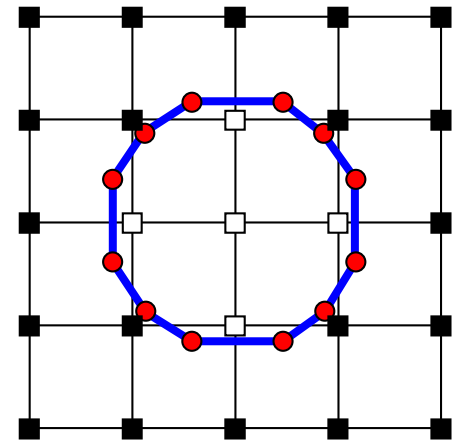
□ positive

Algorithms

- Primal methods
 - Marching Squares (2D),
Marching Cubes (3D)
 - Placing vertices on **grid edges**

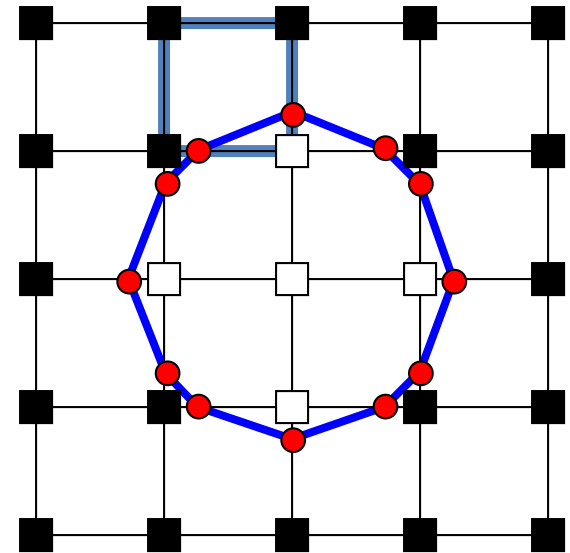


- Dual methods
 - Dual Contouring (2D,3D)
 - Placing vertices in **grid cells**



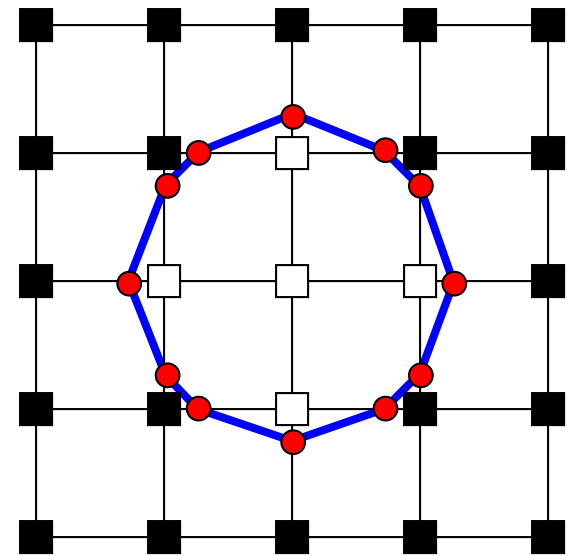
Marching Squares (2D)

- For each grid cell with a sign change
 - Create one vertex on each grid edge with a sign change
 - Connect vertices by lines



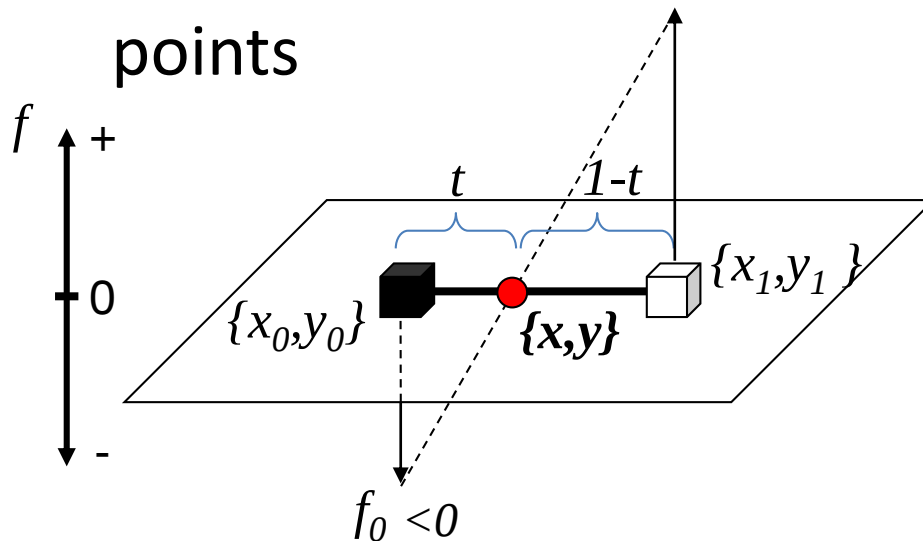
Marching Squares (2D)

- For each grid **cell** with a sign change
 - Create one vertex on each grid edge with a sign change
 - Connect vertices by lines



Marching Squares (2D)

- Creating vertices: linear interpolation
 - Assuming the underlying, continuous function is linear on the grid edge
 - Linearly interpolate the positions of the two grid points



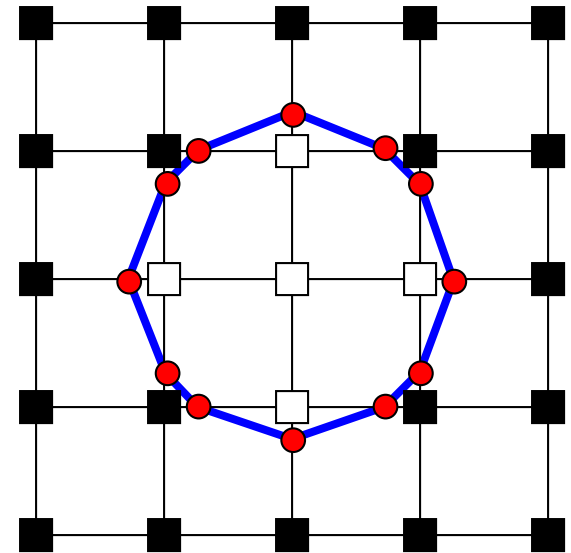
$$t = \frac{f_0}{f_0 - f_1}$$

$$x = x_0 + t(x_1 - x_0)$$

$$y = y_0 + t(y_1 - y_0)$$

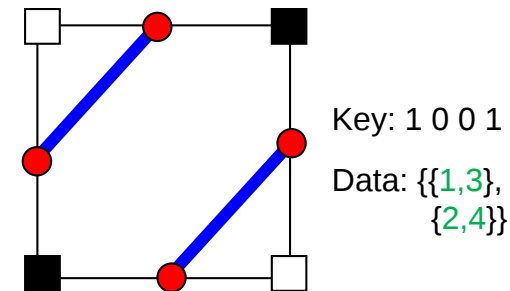
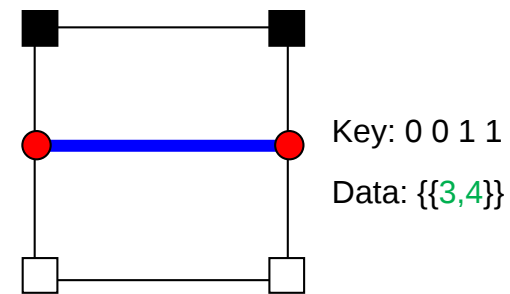
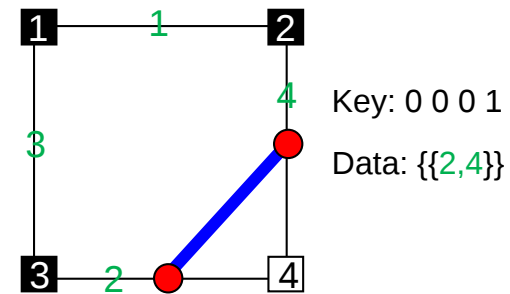
Marching Squares (2D)

- For each grid cell with a sign change
 - Create one vertex on each grid edge with a sign change
 - Connect vertices by lines



Marching Squares (2D)

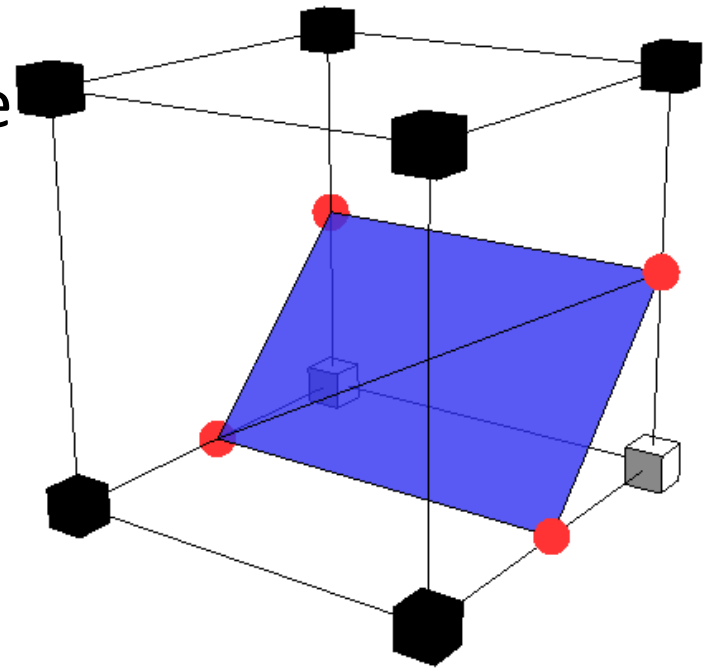
- Connecting vertices by lines
 - Lines shouldn't intersect
 - Each vertex is used once
 - So that it will be used exactly twice by the two cells incident on the edge
- Two approaches
 - Do a walk around the grid cell
 - Connect consecutive pair of vertices
 - Or, using a pre-computed look-up table
 - $2^4=16$ sign configurations
 - For each sign configuration, it stores the indices of the grid edges whose vertices make up the lines.



Slide Credit: Tao Ju

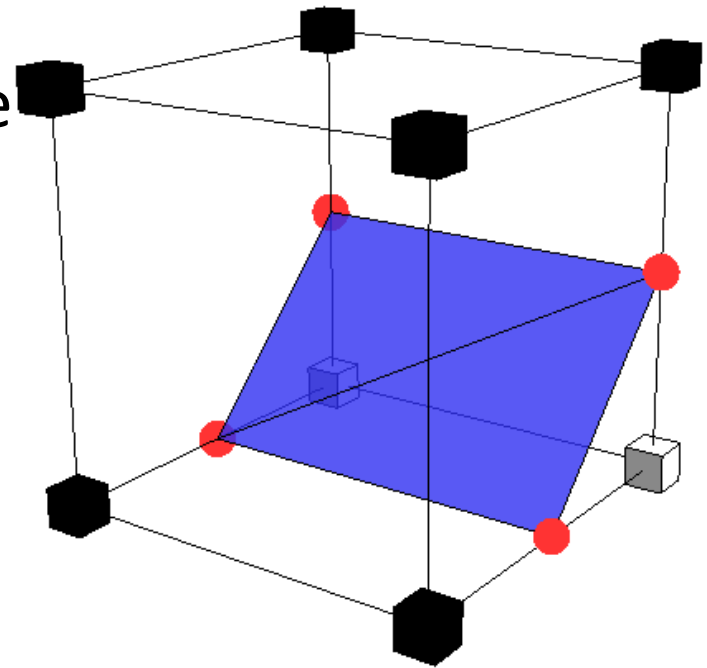
Marching Cubes (3D)

- For each grid **cell** with a sign change
 - Create one vertex on each grid edge with a sign change (using linear interpolation)
 - Connect vertices into **triangles**



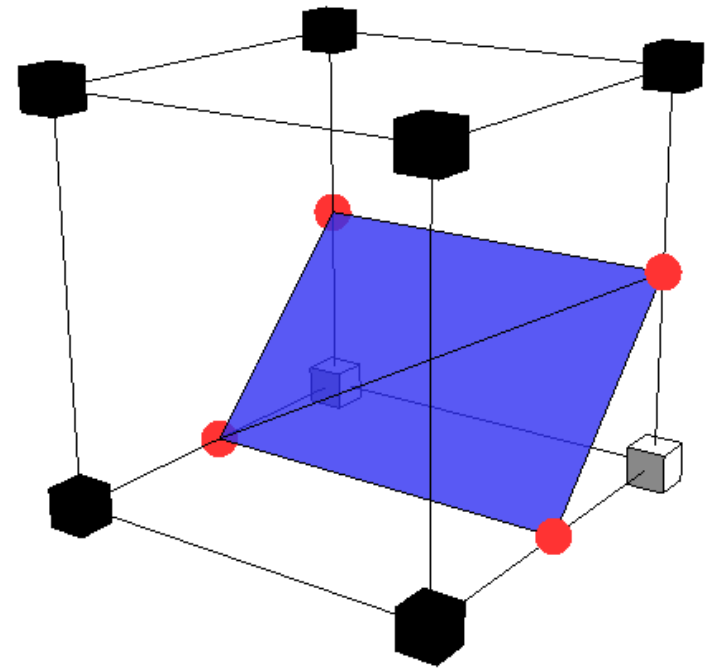
Marching Cubes (3D)

- For each grid **cell** with a sign change
 - Create one vertex on each grid edge with a sign change (using linear interpolation)
 -
 - Connect vertices into **triangles**



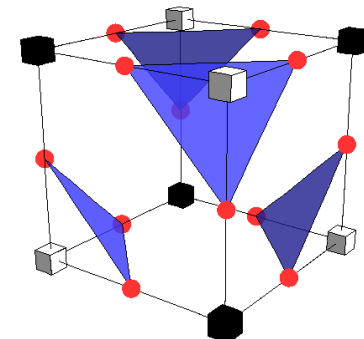
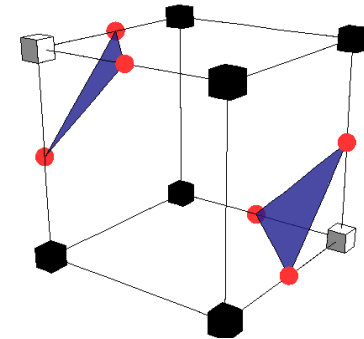
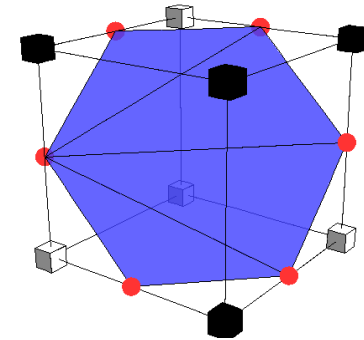
Marching Cubes (3D)

- Connecting vertices by triangles
 - Triangles shouldn't intersect
 - To be a closed manifold:
 - Each vertex used by a triangle “fan”
 - Each mesh edge used by 2 triangles (if inside grid cell) or 1 triangle (if on a grid face)



Marching Cubes (3D)

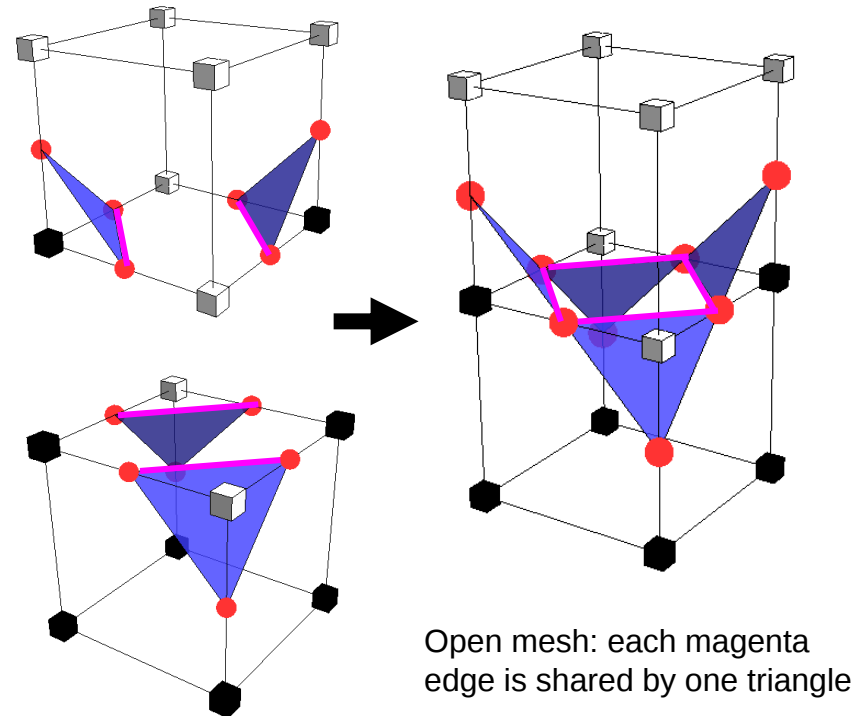
- Connecting vertices by triangles
 - Triangles shouldn't intersect
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Slide Credit: Tao Ju

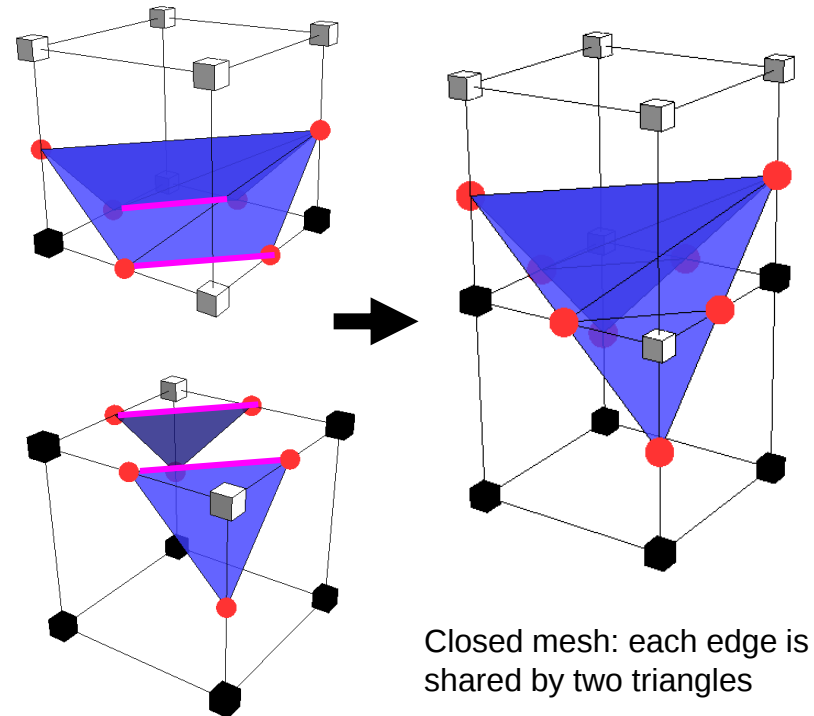
Marching Cubes (3D)

- Connecting vertices by triangles
 - Triangles shouldn't intersect
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 - Each vertex used by a triangle "fan"
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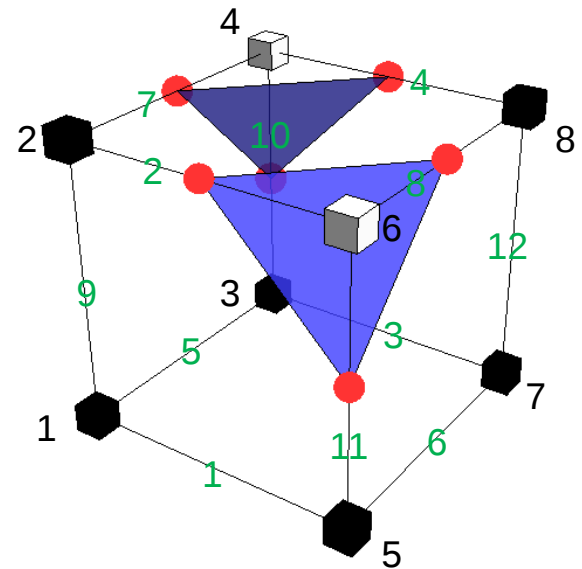
Marching Cubes (3D)

- Connecting vertices by triangles
 - Triangles shouldn't intersect
 - To be a closed manifold:
 - Each vertex used by a triangle "fan"
 - Each mesh edge used by 2 triangles (if inside grid cell) or 1 triangle (if on a grid face)
 - Each mesh edge on the grid face is **shared** between adjacent cells



Marching Cubes (3D)

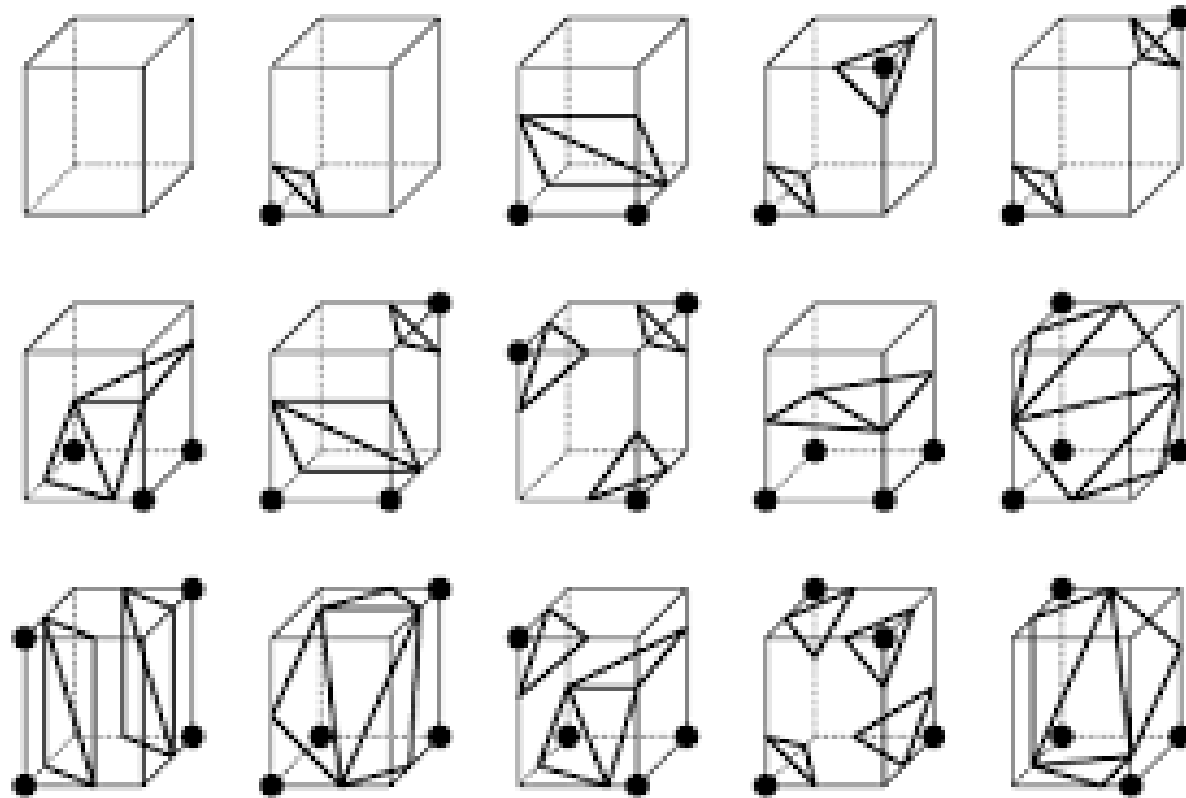
- Connecting vertices by triangles
 - Triangles shouldn't intersect
 - To be a closed manifold:
 - Each vertex used by a triangle "fan"
 - Each mesh edge used by 2 triangles (if inside grid cell) or 1 triangle (if on a grid face)
 - Each mesh edge on the grid face is **shared** between adjacent cells
- Look-up table
 - $2^8=256$ sign configurations
 - For each sign configuration, it stores indices of the grid edges whose vertices make up the triangles



Sign: "0 0 0 1 0 1 0 0"

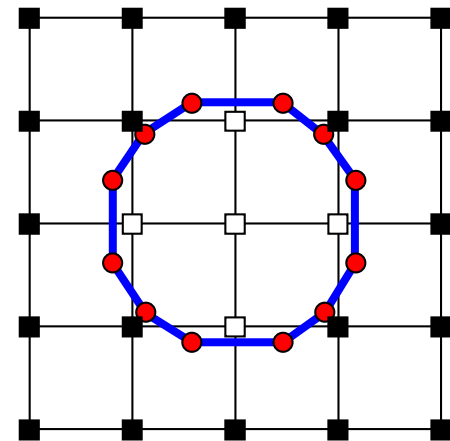
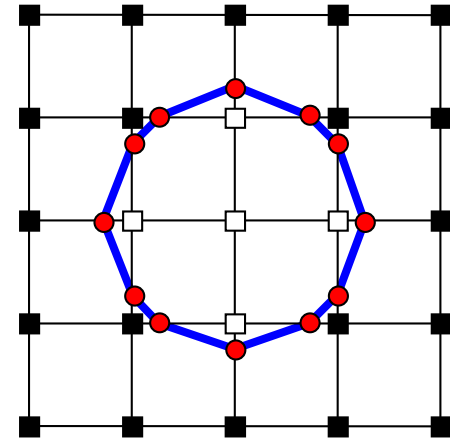
Triangles: {{2,8,11},{4,7,10}}

Lookup Table



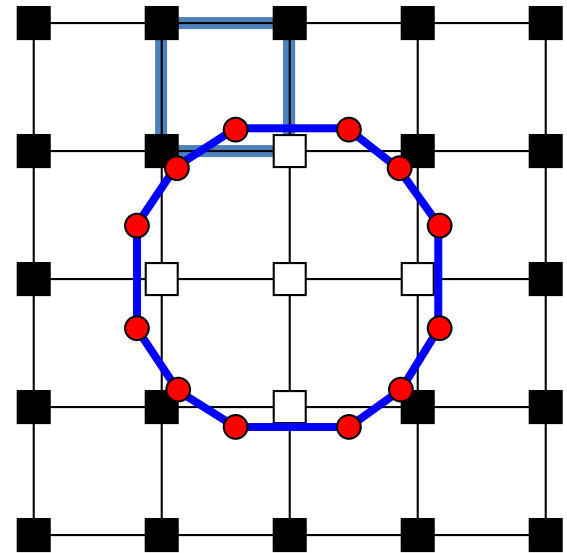
Algorithms

- Primal methods
 - Marching Squares (2D),
Marching Cubes (3D)
 - Placing vertices on **grid edges**
- Dual methods
 - Dual Contouring (2D,3D)
 - Placing vertices in **grid cells**



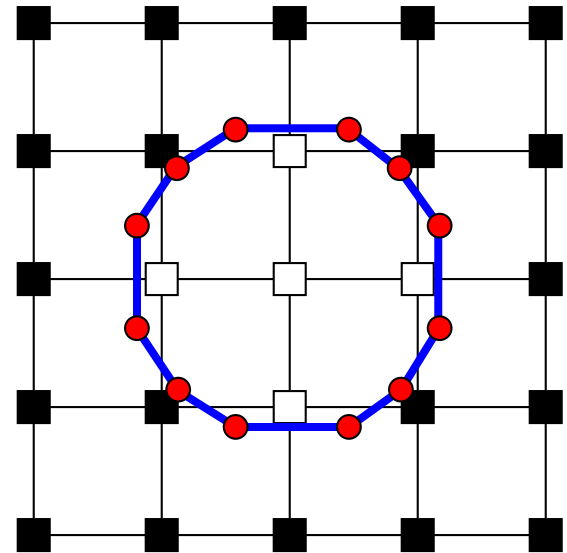
Dual Contouring (2D)

- For each grid **cell** with a sign change
 - Create one vertex
- For each grid **edge** with a sign change
 - Connect the two vertices in the adjacent cells with a line segment



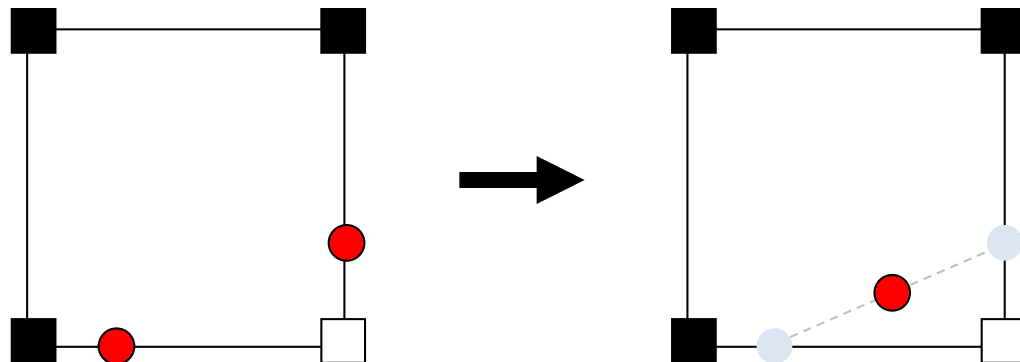
Dual Contouring (2D)

- For each grid **cell** with a sign change
 - – Create one vertex
- For each grid **edge** with a sign change
 - Connect the two vertices in the adjacent cells with a line segment



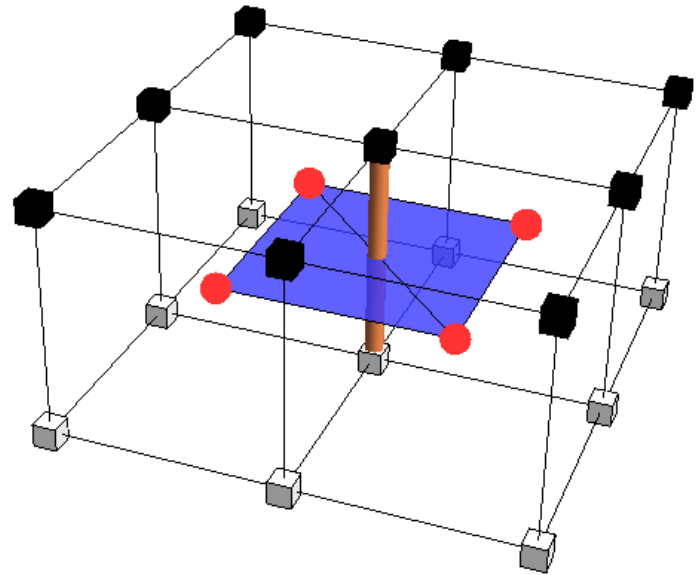
Dual Contouring (2D)

- Creating the vertex within a cell
 - Compute one point on each grid edge with a sign change (by linear interpolation)
 - There could be more than two sign-changing edges, so >2 points possible
 - Take the centroid of these points



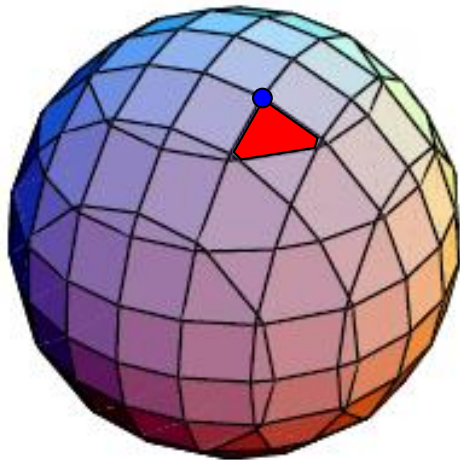
Dual Contouring (3D)

- For each grid **cell** with a sign change
 - Create one vertex (same way as 2D)
- For each grid **edge** with a sign change
 - Create a quad (or two triangles) connecting the four vertices in the adjacent grid cubes
 - No look-up table is needed!

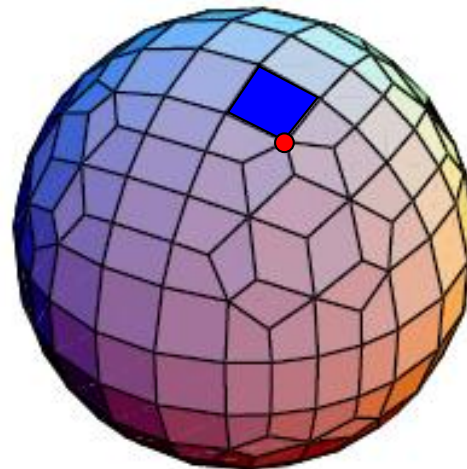


Duality

- The two outputs have a dual structure
 - Vertices and quads of Dual Contouring correspond (roughly) to un-triangulated polygons and vertices produced by Marching Cubes



Marching Cubes



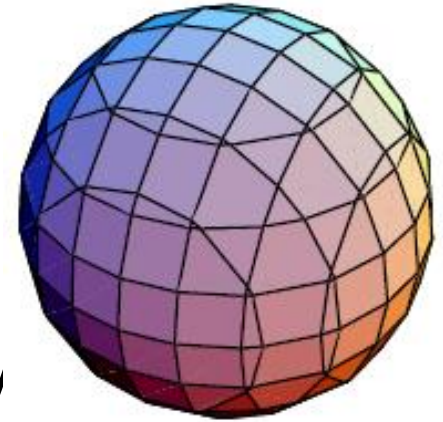
Dual Contouring

Slide Credit: Tao Ju

Primal vs. Dual

- Marching Cubes

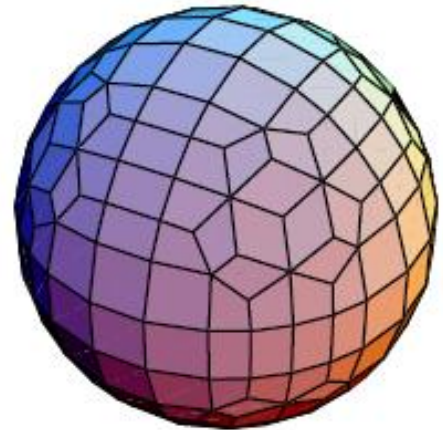
- ✓ Always manifold
- ✗ Requires look-up table in 3D
- ✗ Often generates thin and tiny poly



Marching Cubes

- Dual Contouring

- ✗ Can be non-manifold
- ✓ No look-up table needed
- ✓ Generates better-shaped polygon



Dual Contouring

Primal vs. Dual

- Marching Cubes
 - ✓ Always manifold
 - ✗ Requires look-up table in 3D
 - ✗ Often generates thin and tiny polygons
 - ✗ Restricted to uniform grids
- Dual Contouring
 - ✗ Can be non-manifold
 - ✓ No look-up table needed
 - ✓ Generates better-shaped polygon
 - ✓ Can be applied to any type of grid

