

GLOBAL OPTIMIZATION FOR COMPOSITIONAL SYSTEMS

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Co-design

Metropolis
Motivation

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SE example
Constraints

Cases

Fabric
Vision

1 CO-DESIGN OF EMBEDDED SYSTEMS

- The Metropolis framework
- Motivation for co-optimization

2 Co-optimization using symbolic execution

- Symbolic execution by example
- Constraint detection and propagation

3 Case Studies

- Switch fabric
- Vision system

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- Composition of hardware and software IP modules
 - Communicate with dedicated hardware devices
- Heterogeneous by nature
 - Application specific integrated circuits (ASICs)
 - Field programmable gate arrays (FPGAs)
 - Embedded software running on one or more processors
- Applications: communications, image processing, and automotive electronics

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- Techniques exist to optimize each IP module and the underlying network (Ch+-DAC-95,HwSwCoDesign-02)
- Integrating computing components introduce new opportunities for optimizations
- Need for co-optimization techniques
 - Work across components
 - Work across hardware and software boundaries

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IMPORTANT QUESTIONS

- Can software be developed before hardware is committed?

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IMPORTANT QUESTIONS

- Can software be developed before hardware is committed?
- What if new versions of software used hardware that was optimized away?

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- Express embedded systems in Metropolis Meta Model (MMM) netlists
 - MMM extends a subset of the Java programming language
- Separate computation and communication
 - Processes: computing elements
 - Media: communication elements
- Independent of the model of computation (MoC)
 - Similar to the tagged signal model (Ed+-IEEE-97)

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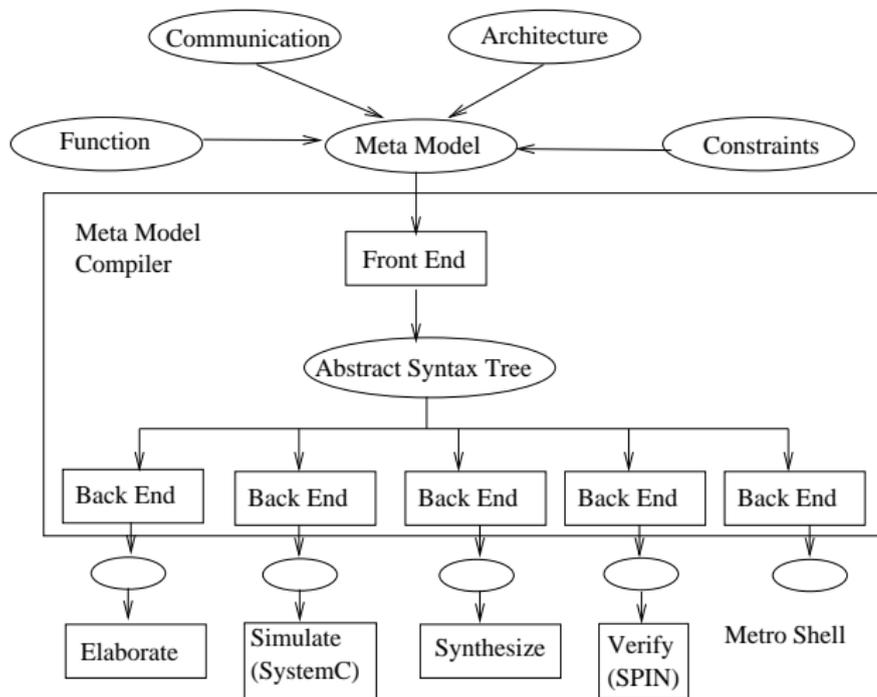
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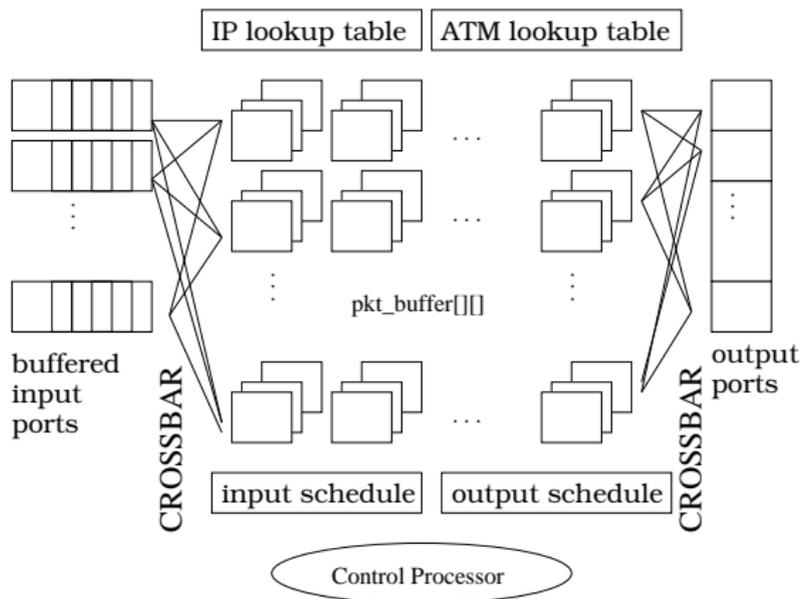
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- Optimization opportunities: IP traffic only, dedicated ports
- Need for co-optimization techniques

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int x, y;
```

```
if (x > y) {
```

```
    x = x + y;
```

```
    y = x - y;
```

```
    x = x - y;
```

```
if (x - y > 0)
```

```
    assert(false)
```

```
}
```

$x = A, y = B$

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$x = A, y = B$

$A > ? B$

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```
    assert(false)
```

```
}
```

```
x = A, y = B
```

```
A >? B
```

```
 $\langle A \leq B \rangle$  end
```

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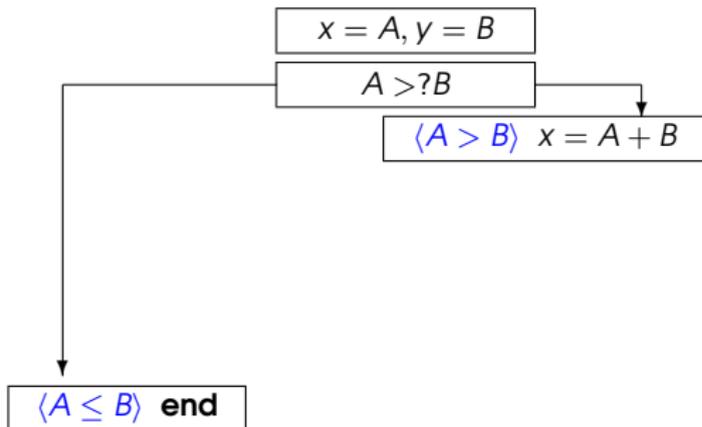
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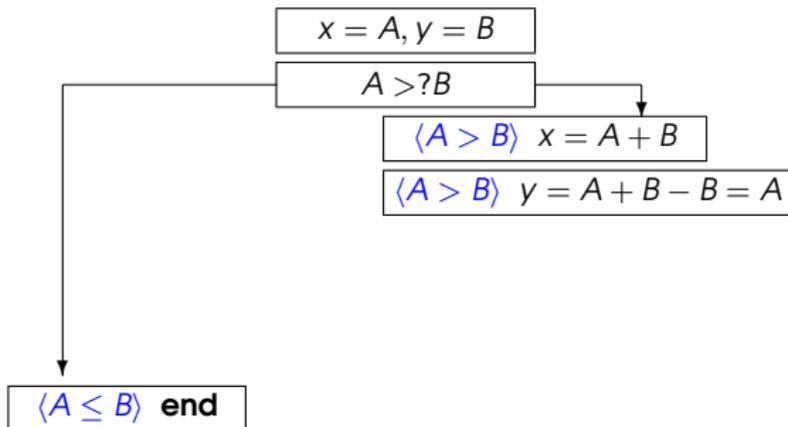
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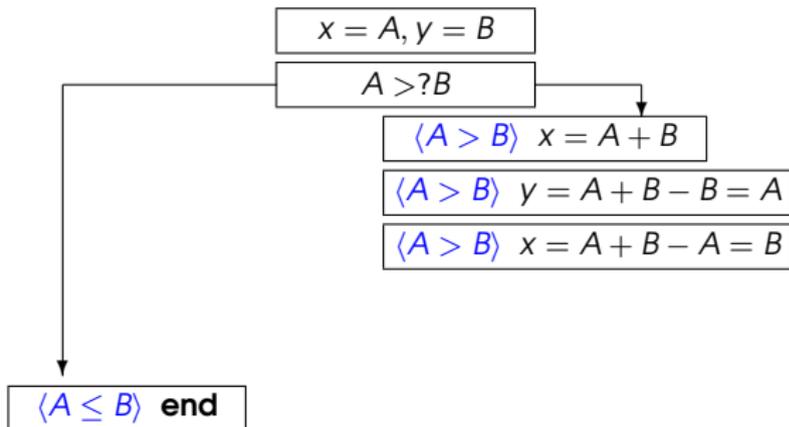
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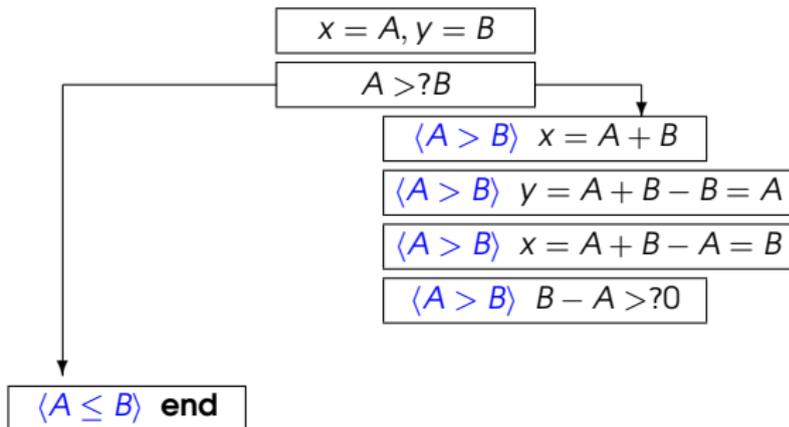
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  x = x - y;
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```



SYMBOLIC EXECUTION BY EXAMPLE

JUZI/CVC-LITE [KH+-TACAS-03]

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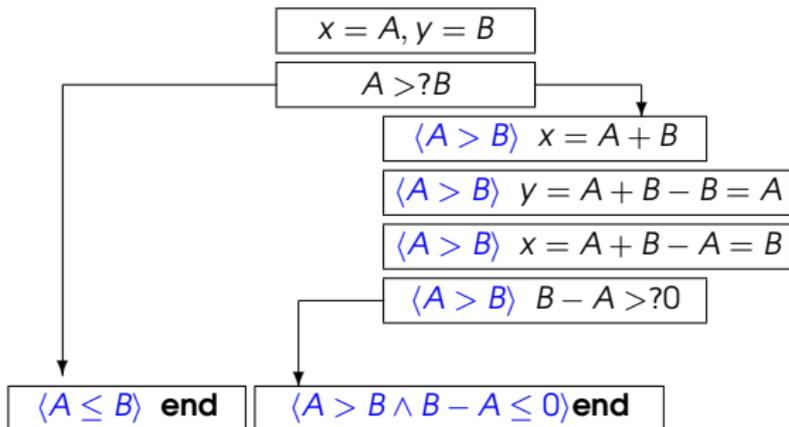
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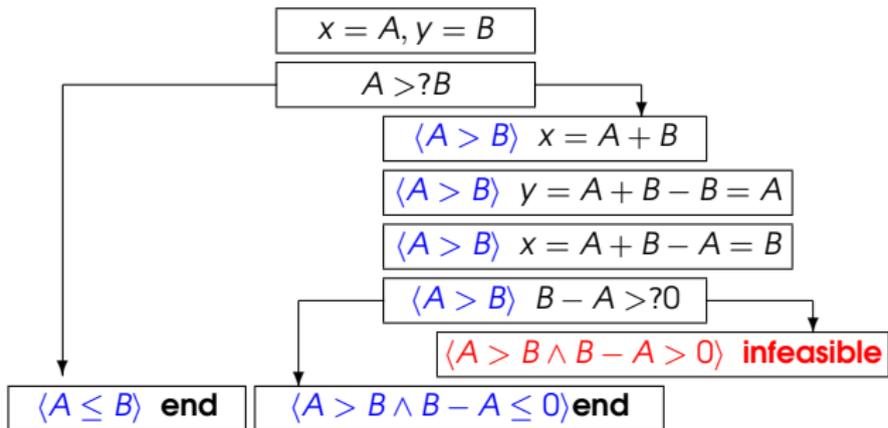
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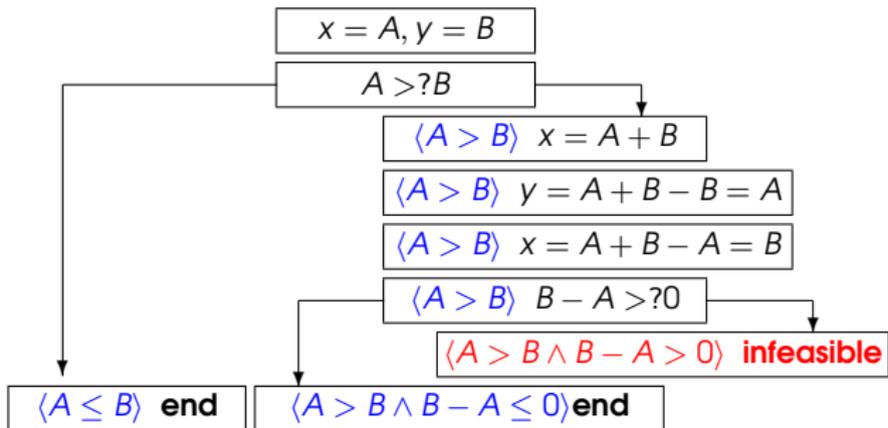
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- COSE instruments MMM code to perform symbolic execution

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- Use symbolic execution on component level
 - Detect local invariants—constraints
 - Accumulate path conditions
- Annotate ports with detected constraints
- Quality of detected invariants
 - Designer may not know them
 - Designer may not recognize them as useful to optimize other components

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- Build dependency map between components
- Propagate constraints to other components
 - Start with detected constraints as initial path conditions
 - Use symbolic execution to propagate constraints

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- Translate MMM into inlined Java
 - MMM is an extension of a Java subset
 - Process, medium, and netlist: class
- Juzi instruments Java code
- CVC-Lite solves and simplifies path conditions

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Qualitatively different than those detected by local compiler optimizations

- Eliminate dead code — infeasible path conditions
- Detect range restrictions and re-encode variables
- Detect mutually exclusive executions
 - Target resources sharing and multiplexing
- Annotate MMM with constraints and pass to synthesis tools
 - Apply constant propagation, redundancy removal, and observability don't care reductions

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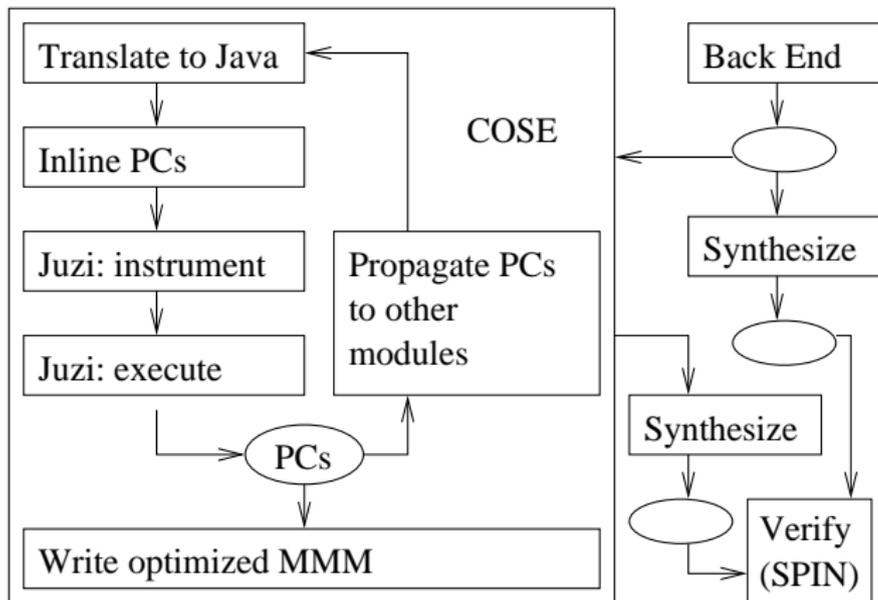
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MMM FOR SWITCH FABRIC EXAMPLE

OPPORTUNITIES: IP TRAFFIC ONLY, DEDICATED PORTS

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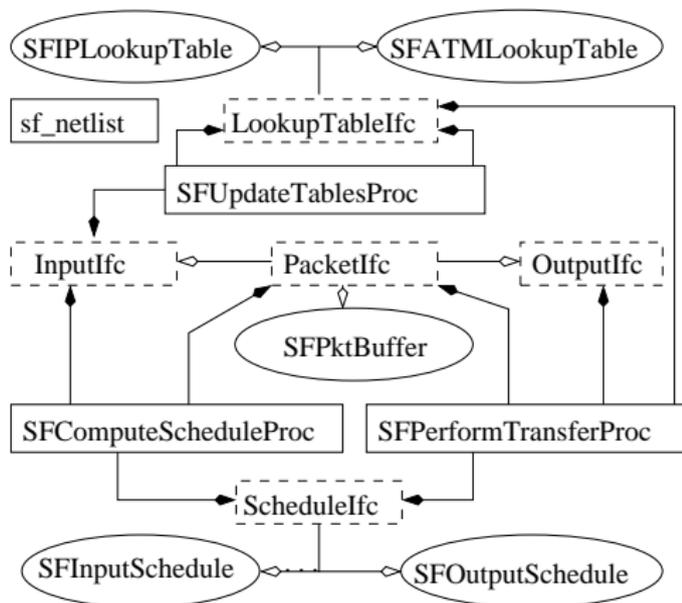
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Processes: compute schedule, perform transfer, update

CASE STUDY: SWITCH FABRIC

MIXED TRAFFIC, MULTIPOINT, 755 LINES OF MMM CODE

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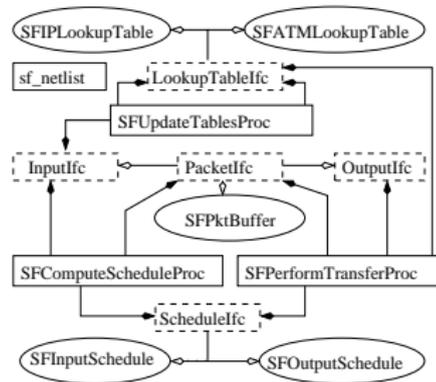
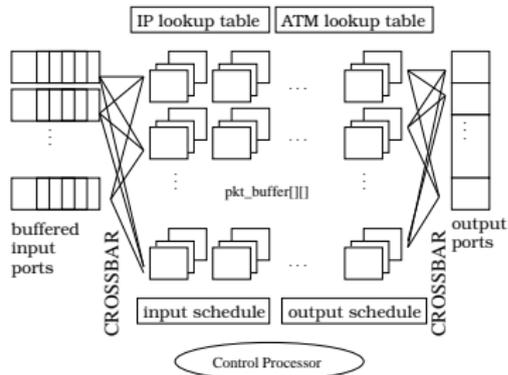
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IP traffic only

- 4 input ports, 4 output ports, and 8×16 packet buffers
- 192 minutes and 37K symbolic variables

CASE STUDY: SWITCH FABRIC

MIXED TRAFFIC, MULTIPOINT, 755 LINES OF MMM CODE

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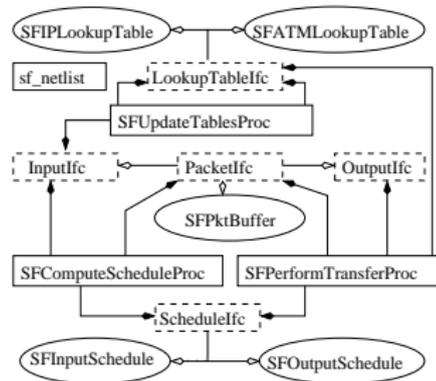
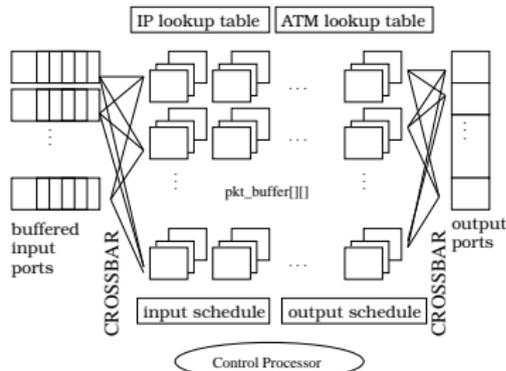
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Limited output ports

- 4 input ports, 8 output ports, and 8×16 packet buffers
- Enabled dropping 4 output ports
- 247 minutes and 61K symbolic variables

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CASE STUDY: OBJECTID VISION SYSTEM

FLOW DIAGRAM, 4K LINES OF C/RTL CODE

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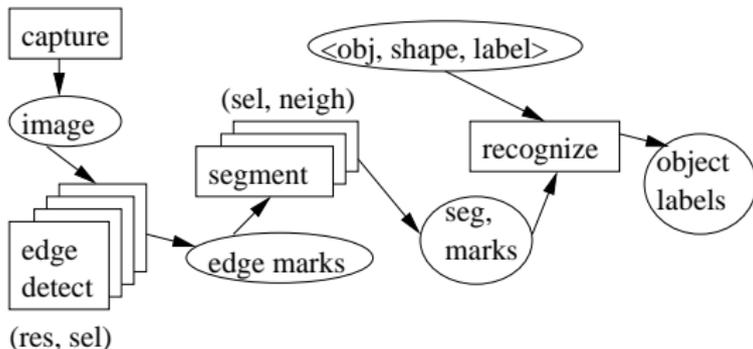
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- Labels objects in image with identified names
- Developed for military and medical purposes
 - Deployed for home surveillance applications

CASE STUDY: OBJECTID VISION SYSTEM

CLASS DIAGRAM, 1255 LINES OF MMM

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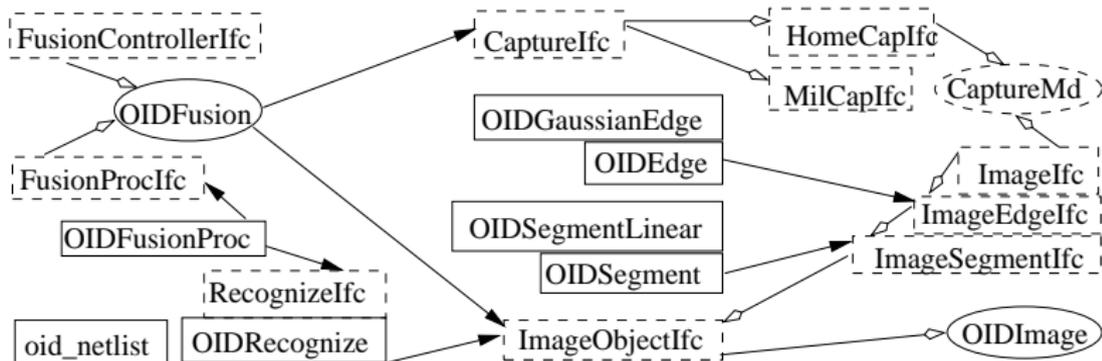
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- 4 process classes, 3 media classes, and 10 Interfaces

CASE STUDY: OBJECTID VISION SYSTEM

RESULTS: LOW RESOLUTION CAPTURE

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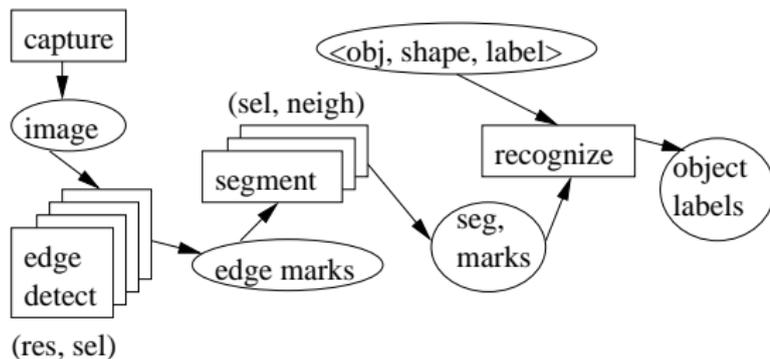
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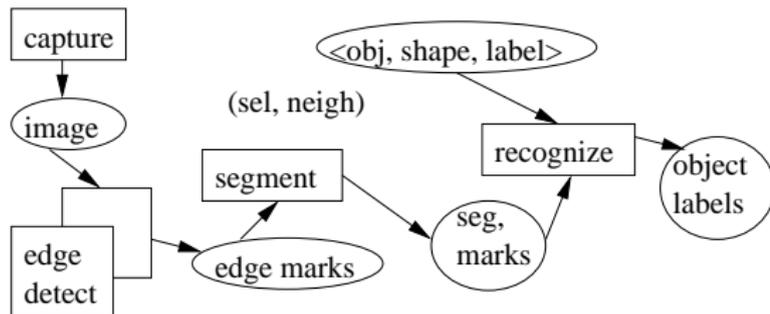
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- Dropped 2 edge detectors in the first iteration
- Dropped a segmentation process in the second iteration
- 15 minutes and 13K symbolic variables

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- Use a difference equation solver instead of CVC-Lite
- Use symbolic execution to optimize linking compilable software modules

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- Questions?
 - Can software be developed before hardware is committed?
 - What if new versions of software used hardware that was optimized away?
 - ...

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Answers

4 ANSWERS

Can software be developed before hardware is committed?

- Metropolis supports different design abstraction and implementation refinement levels
 - At each refinement level discard COSE optimizations and compute again

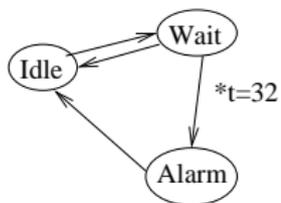
What if new versions of software used hardware that was optimized away?

- COSE produces the path conditions it used to optimize the design
 - Can be used as a guide to avoid adding optimized hardware
 - Can be used to undo the optimizations

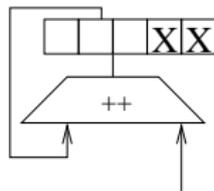
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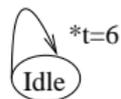
Answers



(a) seat belt controller



(b) counter



(c) force key off