

# CS389L: Automated Logical Reasoning

## Lecture 3: Practical SAT solving

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## Overview

- ▶ Today: How state-of-the-art SAT solvers work
- ▶ Many competitive solvers based on DPLL, but extend it in three important ways:
  1. Non-chronological backtracking
  2. Learning from past “mistakes”
  3. Heuristics for choosing variables and assignments

## Non-Chronological Backtracking

- ▶ Recall basic DPLL: First try assigning  $p$  to  $\top$ ; if doesn't work, backtrack to **most recent** decision level and try  $p = \perp$
- ▶ Called chronological backtracking but often sub-optimal
- ▶ Suppose made assignments  $p_1, p_2, \dots, p_{100}$  but discovered  $p_4$  was a bad choice
- ▶ Backtracking to decision level associated with  $p_{100}$  is stupid...
- ▶ In **non-chronological backtracking**, can go back to earlier decision levels

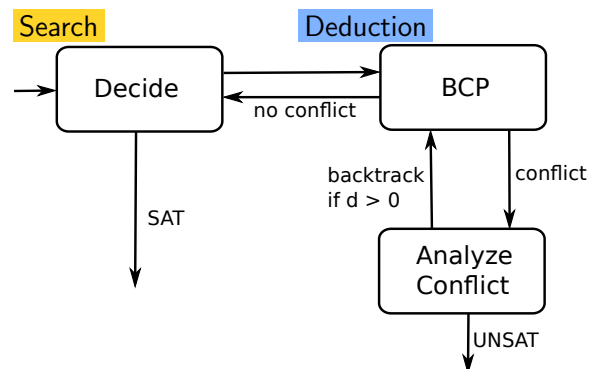
## Learning

- ▶ Learning = acquisition of new clauses to prevent similar bad assignments
- ▶ For instance, suppose we discover  $p_5 = \top, p_{32} = \perp, p_{100} = \top$  is inconsistent, i.e.,
$$\phi \Rightarrow \neg(p_5 \wedge \neg p_{32} \wedge p_{100})$$
- ▶ Can add this clause without changing satisfiability (why?)
- ▶ Such clauses called **conflict clauses**  $\Rightarrow$  SAT solver has database of conflict clauses

## Decision Heuristics

- ▶ Basic DPLL chooses variables in random order
- ▶ But making assignment to certain variables can make formula much easier to solve!
- ▶ Modern solvers use more sophisticated heuristics
- ▶ This is something of a black art, but one of the most important elements in SAT solving ...

## Architecture of DPLL-Based SAT Solvers



## The Plan

- ▶ We will talk about BCP and AnalyzeConflict first (related)
- ▶ Then: common decision heuristics used in the Decide step
- ▶ Finally: Implementation tricks to make all this fast

## BCP in SAT Solvers

- ▶ Recall: BCP is all possible applications of unit resolution
- ▶ SAT solvers remember deductions performed in the BCP process  $\Rightarrow$  recorded as **implication graph**
- ▶ First some terminology ...

## Some Terminology and Conventions

- ▶ **Decision variable**: variable assigned in the Decide step
- ▶ The **decision level** of a decision variable is the level (order) in which it was assigned
- ▶ The decision level of a variable assigned due to BCP is the decision level of the last assigned decision variable
- ▶ **Important note**: Think of assignments as literals: Assignment  $p = \top$  is literal  $p$ ; assignment  $p = \perp$  as literal  $\neg p$
- ▶ **Also**: An assignment corresponds to a new unit clause added to our set of clauses

## Decision Level Example

$$(\neg x_1 \vee x_2) \wedge (\neg x_3 \vee \neg x_4)$$

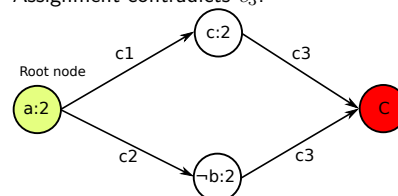
- ▶ Decide assigns  $x_1 = \top \Rightarrow x_1$  decision var at level 1
- ▶ BCP yields:
- ▶ Decision level of  $x_2$ ?
- ▶ Decide next assigns  $x_4 = \top$ . BCP deduces:
- ▶  $x_4$  decision variable with decision level:
- ▶  $x_3$ 's decision level:

## Implication Graph

- ▶ An **implication graph** is a labeled directed acyclic graph
- ▶ **Nodes**: literals in the current partial assignment
- ▶ **Node labels**: Indicate assignment and decision level.
- ▶ Example: Node labeled  $\neg x : 3$  means variable  $x$  was assigned to  $\perp$  at decision level 3
- ▶ **Edges from  $l_1, \dots, l_k$  to  $l$  labeled with  $c$** : Assignments  $l_1, \dots, l_k$  caused assignment  $l$  due to clause  $c$  during BCP
- ▶ A special node  $C$  is called the **conflict node**.
- ▶ Edge to conflict node labeled with  $c$ : current partial assignment contradicts clause  $c$ .

## Implication Graph Example

- ▶ Consider the following set of clauses:  
 $c_1 : (\neg a \vee c) \quad c_2 : (\neg a \vee \neg b) \quad c_3 : (\neg c \vee b)$
- ▶ Assume *Decide* assigned  $a = \top$  at decision level 2
- ▶ BCP yields:
- ▶ Assignment contradicts  $c_3$ !



## Another Example

- ▶ Consider the following clauses:  
 $c_1 : (\neg a \vee c)$   $c_2 : (\neg c \vee \neg a \vee b)$   $c_3 : (\neg c \vee d)$   $c_4 : (\neg d \vee \neg b)$
- ▶ Suppose *Decide* assigned  $a = \top$  at decision level 1
- ▶ Using clause  $c_1$ , BCP yields:
- ▶ Using clause  $c_2$ , BCP yields:
- ▶ Using clause  $c_3$ , BCP yields:
- ▶ Assignment  $b = \top, d = \top$  contradicts:

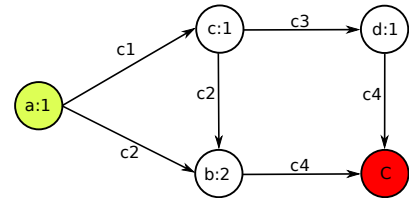
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## Example cont.

- ▶ Consider the following clauses:  
 $c_1 : (\neg a \vee c)$   $c_2 : (\neg c \vee \neg a \vee b)$   $c_3 : (\neg c \vee d)$   $c_4 : (\neg d \vee \neg b)$
- ▶ Suppose *Decide* assigned  $a = \top$  at decision level 1
- ▶ Resulting implication graph:

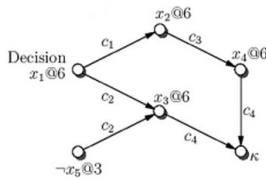


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## Example 3



- ▶ Based on this implication graph, what is  $c_4$ ?
- ▶ What is  $c_3$ ?
- ▶ What is  $c_1$ ?
- ▶ What is  $c_2$ ?

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## Implication Graph Properties

- ▶ Root nodes in the implication graph correspond to what kind of variables?
- ▶ Edges and internal nodes arise due to BCP
- ▶ If literal  $l$  has incoming edge labeled  $c$ , what do we know about  $c$ ?
- ▶ If literal  $l$  has outgoing edge labeled  $c$ , what do we know about  $c$ ?

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## Analyzing Conflicts

- ▶ Point of implication graph: **analyze conflict**
- ▶ AnalyzeConflict has two goals:
  1. Learn new conflict clauses
  2. Figure out what level to backtrack to

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## Conflict Clauses

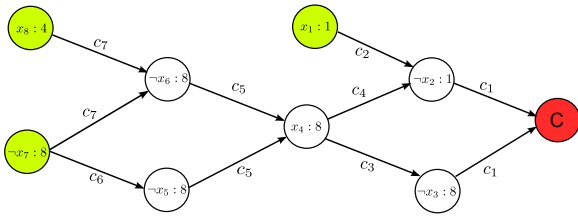
- ▶ A **conflict clause** is a clause implied by the original formula
- ▶ **Point of conflict clause**: Prevent bad partial assignments by deriving contradiction as quickly as possible
- ▶ **Question**: To achieve this goal, are small or large conflict clauses better?
- ▶ **Answer**: Small ones because the smaller the clause, the quicker BCP forces variable assignments, and the quicker we derive contradictions!
- ▶ The implication graph is very useful for deriving small clauses implied by the original formula!

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## Using Implication Graph to Analyze Conflicts

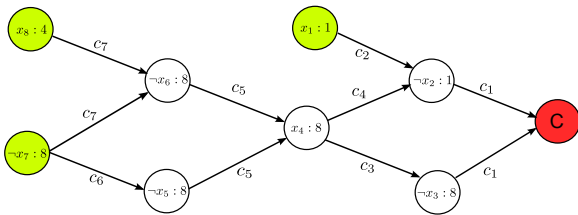


- ▶ What can we say about source of conflict based on this (partial) implication graph?
- ▶
- ▶ Are other decision variables relevant to conflict?

## Simple Strategies to Derive Conflict Clause

- ▶ **One way to derive conflict clause:** The negation of current partial assignment
- ▶ **Another way:** Conjoin all literals associated with root nodes **reaching conflict node**, use negation as conflict clause
- ▶ **Question:** Which one is better?

## Using Implication Graph to Analyze Conflicts



- ▶ In this example, this would yield:
- ▶  $c'$  prevents the same partial assignment in the next step

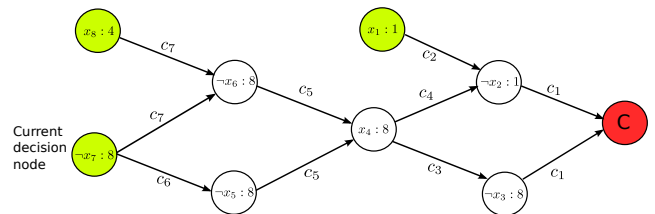
## Analyzing Conflicts

- ▶ This strategy is one of the earliest strategies proposed for inferring conflict clauses (e.g., the GRASP SAT solver)
- ▶ But people have improved upon this; possible to derive even better conflict clauses!
- ▶ A key concept is **unique implication points**

## Unique Implication Point

- ▶ A node  $N$  in the implication graph is a **unique implication point (UIP)** if all paths from current decision node to the conflict node must go through  $N$
- ▶ Is the current decision node a UIP?
- ▶ Can there be multiple unique implication points?
- ▶ **First unique implication point:** UIP closest to conflict node

## UIP Example

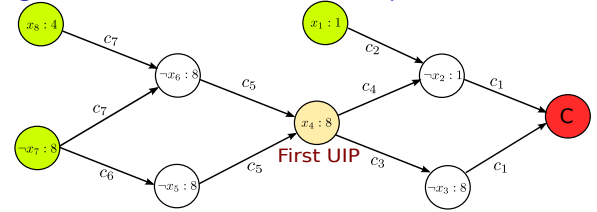


- ▶ Which nodes are UIP's?
- ▶ Which node is first UIP?

## Using UIP and Resolution for Deriving Conflict Clause

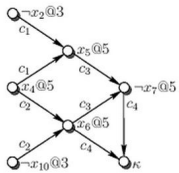
- ▶ **Common heuristic to infer conflict clauses:** Start with clause labeling incoming edge to conflict node, derive new clauses via resolution until we find literal in first UIP
- ▶ **Specifically:** In current clause  $c$ , find last assigned literal  $l$  in  $c$ .
- ▶ Pick any incoming edge to  $l$  labeled with clause  $c'$ .
- ▶ Resolve  $c$  and  $c'$ .
- ▶ Set current clause be resolvent of  $c$  and  $c'$ .
- ▶ Repeat until current clause contains negation of the first UIP literal (as the single literal at current decision level)

## Analyzing Conflict via Resolution Example



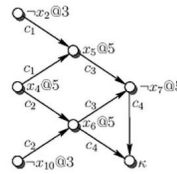
- ▶ What is  $c_1$ ?
- ▶ Last assigned literal in  $c_1$ :
- ▶ Clause  $c_3$  labeling incoming edge:
- ▶ Resolve  $c_1$  and  $c_3$ :
- ▶  $\neg x_4$  only literal from decision level 8  $\Rightarrow x_2 \vee \neg x_4$  conflict clause

## Another Example



- ▶ What is the first UIP?
- ▶ Start with clause  $c_4$ :
- ▶ Suppose we pick  $\neg x_7$
- ▶ Clause on incoming edge to  $\neg x_7$ :
- ▶ Resolve  $c_3, c_4$ :
- ▶ Suppose  $x_6$  assigned later, pick  $x_6$
- ▶ Clause on incoming edge:
- ▶ Resolve current clause with  $c_2$ :

## Another Example, cont.



- ▶ Current clause:
- ▶ Are we done?
- ▶ Pick last assigned literal:  $x_5$
- ▶ Incoming edge to  $x_5$ :
- ▶ Resolve with current clause:
- ▶ Are we done?
- ▶ New conflict clause:  $x_2 \vee \neg x_4 \vee x_{10}$

## Why is this correct?

- ▶ Why are the clauses obtained this way implied by formula?
- ▶
- ▶ Unclear if there is a deep reason why this works well, but seems effective in practice ...

## Backtracking

- ▶ **Recall:** AnalyzeConflict has two goals.
- ▶ **First goal:** Deriving conflict clauses ✓
- ▶ **Second goal:** Figure out what level to backtrack to
- ▶ **Backtrack to level  $d$**  means delete all variable assignments made after level  $d$  (but assignments at level  $d$  not deleted)

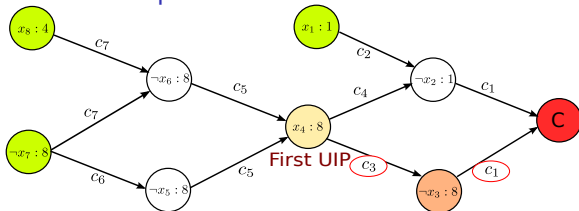
## Backtracking and Asserting Clauses

- ▶ **A good strategy:** We want to backtrack to a level that makes conflict clause  $c$  an **asserting clause** in the next step
- ▶ Asserting clause is a clause with exactly one unassigned literal
- ▶ Hence, if we make  $c$  an asserting clause, BCP will force at least one assignment

## Choosing Backtracking Level

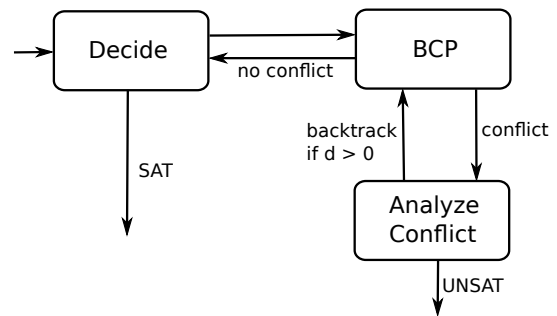
- ▶ **Question:** If we want to make conflict clause  $c$  an asserting clause in the next step, what level should we backtrack to?
- ▶ **Answer:**
- ▶ Since conflict clause contains only one literal, say  $l'$ , from the first highest decision level, backtracking to  $d$  will assert  $l'$ !

## Going Back to Example



- ▶ **Recall:** We obtained the conflict clause  $x_2 \vee \neg x_4$
- ▶ What level do we backtrack to?
- ▶ What do we delete in the graph?
- ▶ After we add  $x_2 \vee \neg x_4$  to clause database, BCP implies:
- ▶ Different assignment than before!

## Recall: SAT Solver Architecture



- ▶ Decision heuristics for choosing variable order and truth assignment

## Decision Heuristics

- ▶ Important part of SAT solvers, but something of a black art
- ▶ Can come up with hundreds of heuristics with varying tradeoffs
- ▶ We'll only talk about two:
  1. dynamic largest individual sum (DLIS)
  2. variable state independent decaying sum (VSIDS)

## Dynamic Largest Individual Sum (DLIS)

- ▶ This heuristic chooses the literal that satisfies the **largest number of currently unsatisfied clauses**.
- ▶ **Example:**  $(x_1 \vee \neg x_2) \wedge (\neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee \neg x_3)$
- ▶ What assignment would DLIS pick for this formula? (assuming no assignments so far)
- ▶ How is this heuristic is **dynamic**?
- ▶ Thus, overhead can be high and must be implemented carefully to minimize bookkeeping

## Variable State Independent Decaying Sum (VSIDS)

- ▶ Similar to DLIS, but tries to reduce overhead and favor literals involved in conflicts (i.e. **conflict-driven**)
- ▶ Count number of clauses in which the literal appears, but disregard if the clause it appears in is satisfied or not
- ▶ Specifically, initialize the score of each literal to the number of clauses in which literal appears
- ▶ Every time we add a conflict clause involving literal  $l$ , increase the score of that literal by 1
- ▶ Periodically divide scores of all literals by 2  
⇒ **decaying sum**

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## Variable State Independent Decaying Sum (VSIDS), cont.

- ▶ Favors literals involved in conflicts
- ▶ If a literal doesn't appear in recent conflict, its score will decay over time
- ▶ On the other hand, if literal appears in recent conflict, its score will be increased, so its score won't decay as much
- ▶ Much cheaper compared to DLIS because we don't need to scan all clauses to figure out which ones are satisfied
- ▶ Introduced in the CHAFF SAT solver from Princeton, written by undergrads!

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## Implementation Tricks

- ▶ To build competitive SAT solvers, it is important to minimize overhead of implementing Decide, BCP, and Analyze Conflict
- ▶ Very important because SAT solver might be searching through hundreds of thousands of assignments!
- ▶ We'll talk about two issues:
  1. number of conflict clauses
  2. trick to perform BCP fast: **watch literals**

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## Conflict Clauses

- ▶ **Recall:** After analyzing conflict, we add new conflict clause to our clause database
- ▶ **Pro:** Conflict clauses quickly block bad assignments and prevent future mistakes
- ▶ **Con:** More clauses = more overhead
- ⇒ Tradeoff between conflict prevention and minimizing overhead

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## Conflict Clauses, cont.

- ▶ For this reason, many SAT solvers do not keep all the conflict clauses they derive
- ▶ For example, they put a limit on the number of conflict clauses they derive
- ▶ Typically, keep most recent conflict clauses since they are most relevant to current part of search space

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## Implementing BCP

- ▶ Implementing BCP efficiently is very important because SAT solvers spend a lot of time doing BCP
- ▶ **Naive implementation of BCP:** Requires scanning all currently unsatisfied clauses
- ▶ But industrial SAT contain hundreds of thousands of clauses, so scanning all unsatisfied clauses too expensive!
- ▶ **A more intelligent implementation:** Keep mapping from each literal to all clauses in which each literal appears (because we perform unit resolution after each variable assignment)
- ▶ But this is still very expensive because typically each literals appears in **many** clauses

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## The Trick: Watch Literals

- ▶ Modern SAT solvers use a much more clever trick to perform BCP fast: **watch literals**
- ▶ **Observe:** Ultimate purpose of BCP is to figure out which variable assignments imply which others
- ▶ **Question:** If we are performing unit resolution between  $l$  and clause  $c = (\neg l \vee l_1, \dots \vee l_k)$ , under what condition will a new assignment be implied?
- ▶ **Answer:**
- ▶ **Idea:** Suffices to look at clauses that have **at most two unassigned literals!**

## Watch Literals

- ▶ Select two unassigned literals in each unsatisfied clause as **watch literals**
- ▶ If a watch literal is assigned and clause has other unassigned literals, choose any unassigned literal in clause to be new watch literal
- ▶ If a watch literal is assigned and there are no other unassigned non-watch literals left, BCP implies an assignment to the only remaining watch literal!

## Watch Literals, cont.

- ▶ **Upshot:** To determine if assignment  $l$  implies new assignment, only look at those clauses in which  $\neg l$  appears as a watch literal
  - ▶ If  $\neg l$  does not appear, we can't perform unit resolution
  - ▶ If  $\neg l$  appears but is not a watch literal, then clause has more than two unassigned literals  $\Rightarrow$  won't imply new assignment!
- ▶ Yielded huge improvement in SAT solver performance!

## Practical SAT Solving Summary

- ▶ Modern SAT solvers extend DPLL in three ways: non-chronological backtracking, conflict clause learning, decision heuristics, engineering tricks (watch literals)
- ▶ Referred to as **CDCL**: conflict-driven clause learning
- ▶ Many competitive SAT solvers based on CDCL