

CS 309: Autonomous Intelligent Robotics

Instructor: Jivko Sinapov

http://www.cs.utexas.edu/~jsinapov/teaching/cs309_spring2017/

Final Project Timeline

• Project Proposal due: Apr. 3rd

 Project Presentations / Demos: Finals Period assigned for this class

Final Report due: May 11th

Project Proposal Guidelines

• Work in groups of 2-3

 Preferably, team up with people with different skills than yours

Purpose of the proposal is to give you an outline / roadmap

Project Proposal Guidelines

- Each proposal should be about 3-4 pages
- Each proposal should include:
 - What is the application / task / problem?
 - Any previous experience you may have in that area
 - What do you expect to achieve by the end of the semester?
 - How do you plan to evaluate whether it works or not?
 - Related work in robotics
 - A timeline / schedule of progress and milestones

Project Proposal Guidelines

- Organization: your proposal should have sections and headings (don't just submit one long essay)
- For example:
 - Introduction / problem formulation
 - Related Work in Robotics
 - Proposed approach / software
 - Proposed evaluation
 - Summary of anticipated end result

Help the robot "see" something it currently cannot

Help the robot "hear" something (e.g., the elevator sound)

Help the robot "do" something (e.g., follow a person)

Final Project Timeline

The most important thing is to start early, and discuss your ideas with the TAs, mentors and myself. We'll point you to a starting point, describe functionality that already exists, and help refine your ideas.

What will be covered the rest of the semester...

Point Cloud Library (3D Vision)



http://pointclouds.org/

Auditory Perception and Speech Recognition



[https://www-i6.informatik.rwth-aachen.de/web/Research/Figures/SR_wavespec_02Nov01.jpeg]

LED Strip – implement and evaluate a behavior using the LED lights on the robot













PCL Viewer









Today

Sending navigation goals to the robot

 Breakout Session: discuss project with your group / find a group

Motion History computer vision example