

# CS 378: Autonomous Intelligent Robotics

#### Instructor: Jivko Sinapov

http://www.cs.utexas.edu/~jsinapov/teaching/cs378/

### **Overview of the Class**

• Quick Intro

Syllabus

Class Goals

Policies and Procedures

# **Class Web Page**

http://www.cs.utexas.edu/~jsinapov/teaching/cs378/

#### **Class Goals**

At the end of this class you will have an understanding of the current state of the art in autonomous robotics and will be able to contribute to original research conducted in our lab.

# Topics to be Covered

- Introduction to robotics
- Robot Operating System (ROS)
- Robot Control
- Autonomous Navigation and Localization
- 2D and 3D Computer Vision
- Computational Perception
- Human-Robot Interaction
- Developmental Robotics

# **Organization\***

This class will be taught as a seminar. The students will be expected to read the assigned papers for each lecture in advance and to actively participate in class discussions.

\* The instructor reserves the right to change any and all aspects of this class for whatever reason or no reason at all (a.k.a., academic freedom).

\*\* You agree that I have the unconditional right to exercise this discretion in a way that is most favorable or convenient to me.

### Prerequisites (2 out of 3)







#### (all episodes)



(all episodes)

#### Prerequisites

Programming skills will be required for the homework assignments and for the final project. The most important prerequisite of all, however, is your interest in the course, motivation, and commitment to learning.

#### Prerequisites

A strong interest in the question, ``What is intelligence and how can it be implemented in a physical robot?"

For best results take two lectures weekly. Common side effects may include sleepless nights, broken robots, nervousness, and banging head on keyboard. Frequent visits to the mentors and the TA have been shown to alleviate some of those symptoms. Talk to your instructor if this class is right for you.

# Students with Disabilities

The University of Texas at Austin provides upon request appropriate academic accommodations for qualified students with disabilities. To determine if you qualify, please contact the Dean of Students at 471-6529; 471-4641 TTY. If they certify your needs, I will work with you to make appropriate arrangements.

No retroactive accommodations will be provided in this class (within reason of course).

### Homework Assignments

There will be two types of assignments:

1) Weekly responses to readings on Canvas

 Programming Assignments (weekly or biweekly)

# **Reading Responses**

- 10 total posts, at least 5 must be original posts (not responses to others)

# **Final Project**

The final project must be a research or design project that is related to the topics covered in class. You may choose to work individually or in small groups (2-3 members each). Working in groups, however, is highly recommended.

You are encouraged to select a topic for your final project as soon as possible. A written project proposal (2-3 pages) will be due on March 21. The final project report (6-8 pages) will be due on May 11.

Each team will be required to present the results of their final project during the last week of the semester.

# Policy on Collaboration

You are encouraged to form study groups and discuss the reading materials assigned for this class. You are allowed to discuss the homework assignments with your colleagues. However, each student will be expected to write his own solutions/code. Sharing of code is not allowed.

#### IMPORTANT

 Cheating, plagiarism, and other academic misconducts will not be tolerated and will be handled according to UT's academic dishonesty procedures, which are posted here:

http://www.cs.utexas.edu/users/ear/CodeOfConduct.html#honesty

#### Attendance

You are expected to attend every class and actively participate in the discussions. If you miss a class, it is your responsibility to find out what we talked about, including any announcements.

# Grading

Your grade will be determined as follows:

- Class Participation: 10%
- Reading Responses: 10&
- Homework Assignments: 60%
- Final Project: 20%

#### How Difficult is this Class?

### **Programming Languages**

• C and/or C++

• Python

#### About the lab...

http://www.cs.utexas.edu/~larg/bwi\_web/

### Readings for this week

Irfan A. Essa (1999). ``Computers Seeing People'', Al Magazine 20(2): pp. 69-82.

Weng, *et al.* (2001), ``Autonomous Mental Development by Robots and Animals'', Science, v. 291, no. 5504, pp. 599-600.

Rosenthal, Stephanie, Joydeep Biswas, and Manuela Veloso. "An effective personal mobile robot agent through symbiotic human-robot interaction." Proceedings of the 9th International Conference on Autonomous Agents and Multiagent Systems, 2010.

#### Announcement

An ongoing robotics study needs participants. Contact Jesse Thomason at jesse@cs.utexas.edu

You'll get extra credit for helping the robot learn!

#### THE END