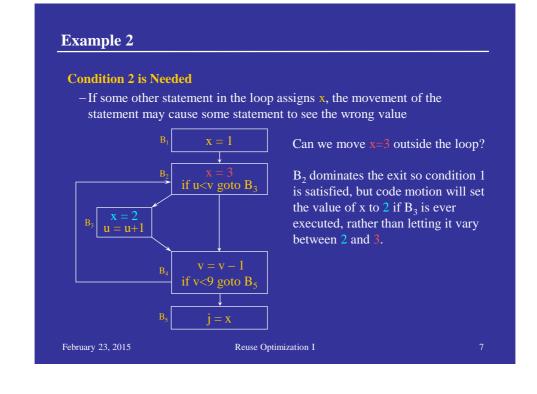
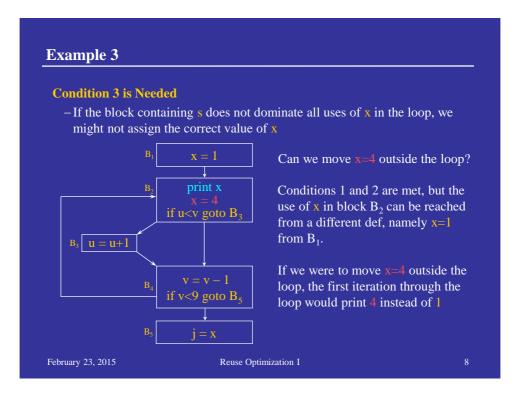
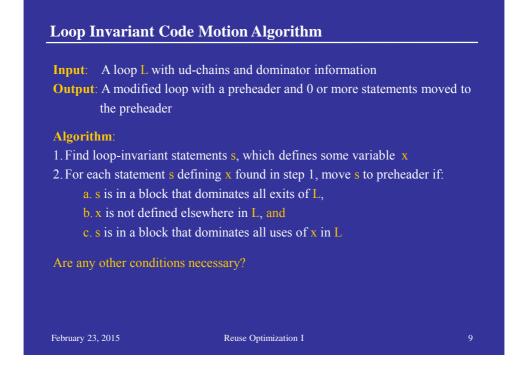


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# Loop Invariant Code Motion Algorithm (cont)

### **Profitability**

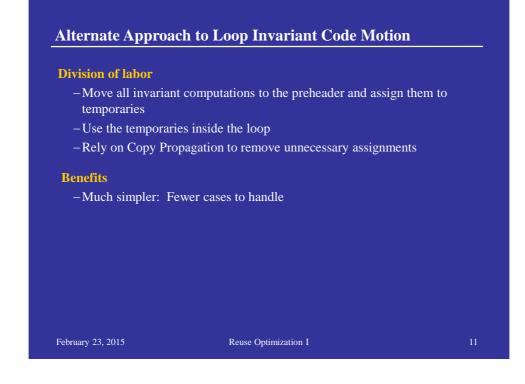
- -Can loop invariant code motion ever increase the running time of the program?
- -Can loop invariant code motion ever increase the number of instructions executed?
- -Before transformation, **s** is executed at least once (condition 2a)
- -After transformation, s is executed exactly once

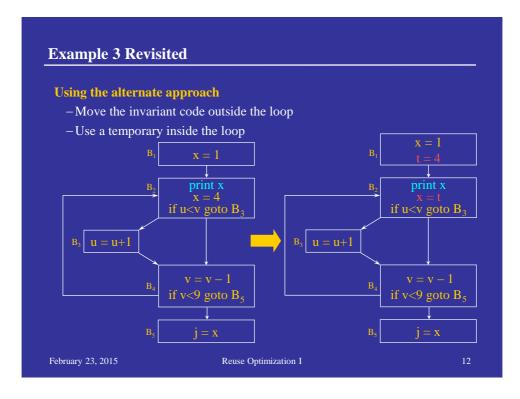
### **Relaxing Condition 1**

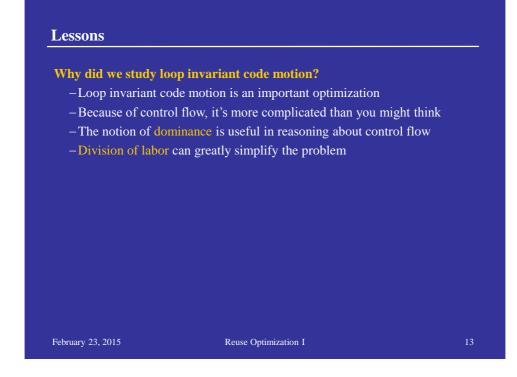
- -If we're willing to sometimes do more work: Change the condition to
  - a. The block containing **s** either dominates all loop exits, or **x** is dead after the loop

February 23, 2015

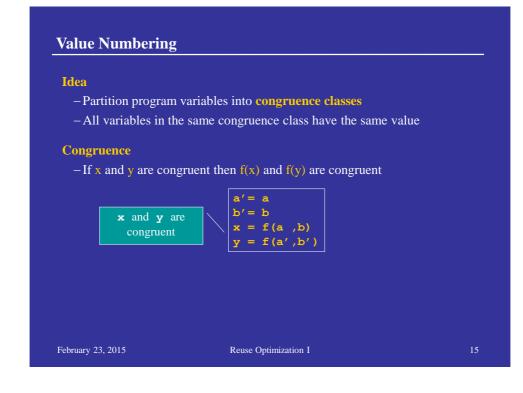
Reuse Optimization I

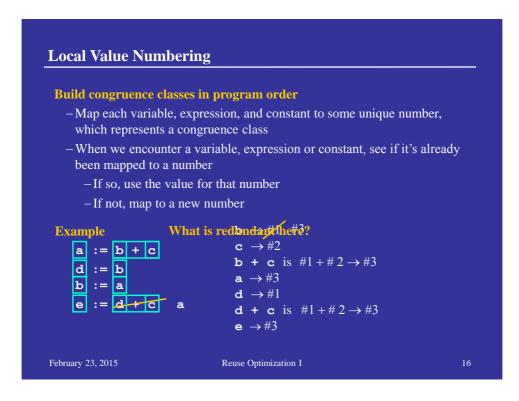




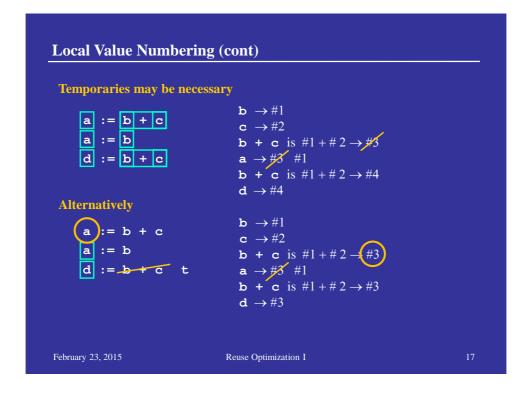


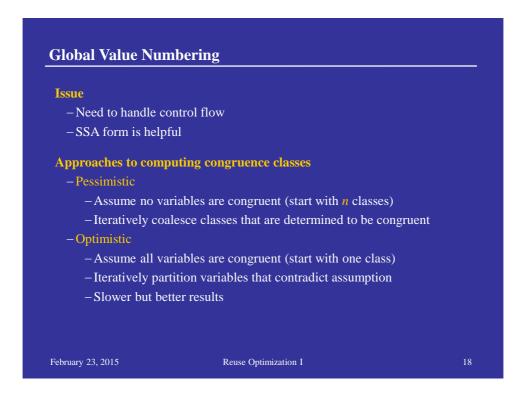
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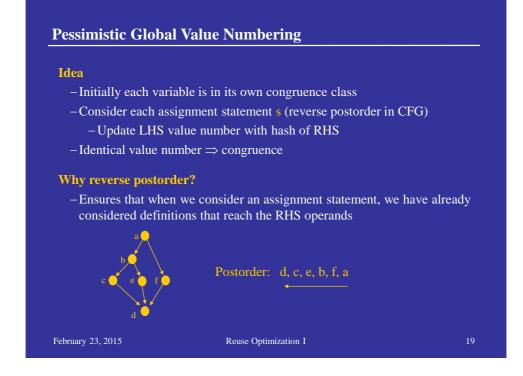


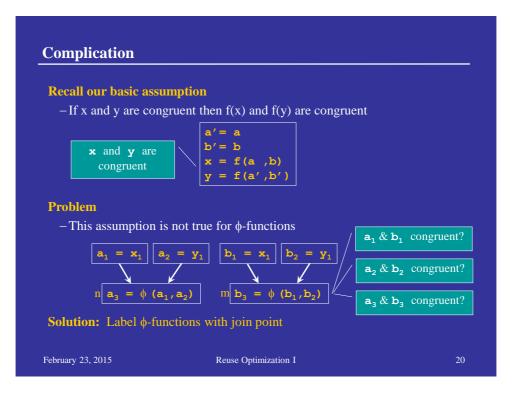


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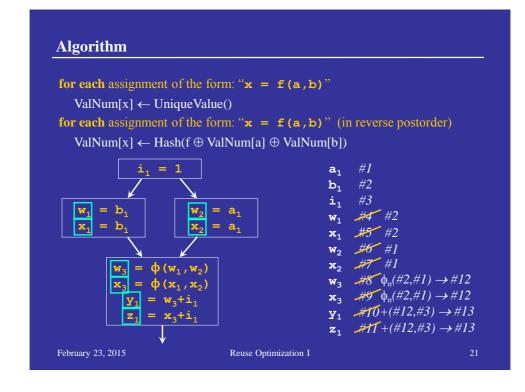




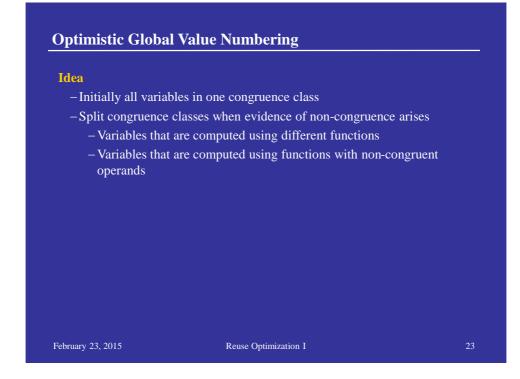


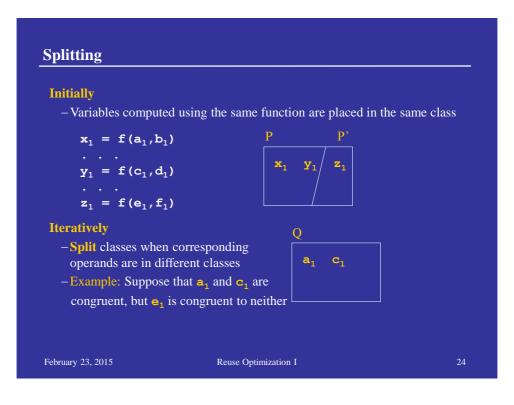


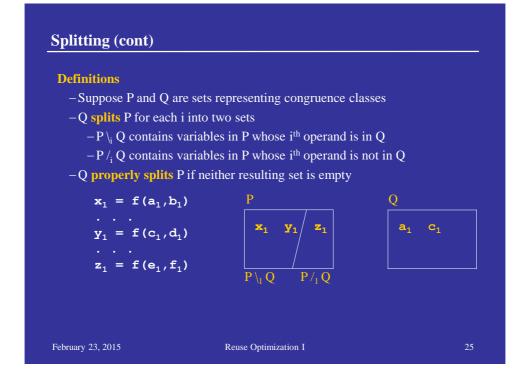
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Snag!		
Problem		
– Our algorithm ass depend upon it	sumes that we consider operands before	variables that
-Can't deal with co	ode containing loops!	
Solution		
– Ignore back edge	s	
	e (worst case) assumption for previousl me its in its own congruence class)	y unseen







worklist $\leftarrow \emptyset$		
for each function f		
$C_f \leftarrow \emptyset$		
for each assignm	ent of the form " $x = f(a,b)$ "	
$C_f \leftarrow C_f \cup \{$	x }	
worklist $\leftarrow$ workl	$list \cup \{C_{f}\}$	
$CC \leftarrow CC \cup \{C_f\}$	}	
while worklist $\neq \emptyset$		
Delete some D fro	om worklist	
for each class C	properly split by D (at operand i)	
$CC \leftarrow CC -$	С	
worklist $\leftarrow$ w	vorklist – C	
Create new c	ongruence classes $C_i \leftarrow \{C \setminus_i D\}$ and $C_k \leftarrow \{C /_i D\}$	
$CC \leftarrow CC \cup$		
worklist $\leftarrow$ w	vorklist $\cup C_i \cup C_k$	

SSA code	Congruence classes $S_{0} \{\mathbf{x}_{0}\}$ $S_{1} \{\mathbf{y}_{0}\}$ $S_{2} \{\mathbf{x}_{1}, \mathbf{y}_{1}, \mathbf{z}_{1}\}$ $S_{3} \{\mathbf{x}_{1}, \mathbf{z}_{1}\}$ $S_{4} \{\mathbf{y}_{1}\}$ $\mathbf{y}_{0}\}, S_{2} = \{\mathbf{x}_{1}, \mathbf{y}_{1}, \mathbf{z}_{1}\}, S_{4} = \{\mathbf{y}_{1}\}$	
$     \begin{aligned}             x_0 &= 1 \\             y_0 &= 2 \\             x_1 &= x_0 + 1 \\             y_1 &= y_0 + 1 \\             z_1 &= x_0 + 1         \end{aligned} $		
	$S_0 \text{ psplit } S_1^2, \mathbf{z}_1  S_3^2 = \{\mathbf{x}_1, \mathbf{y}_1, \mathbf{z}_1\} S_3^2 = \{\mathbf{x}_1, \mathbf{y}_1, \mathbf{y}_1, \mathbf{y}_2\} S_3^2 = \{\mathbf{x}_1, \mathbf{y}_2, \mathbf{y}_1, \mathbf{y}_2\} S_3^2 = \{\mathbf{x}_1, \mathbf{y}_2, \mathbf{y}_2\} S_3^2 = \{\mathbf{x}_1, $	
$S_2 \setminus_1 S_0 = \{\mathbf{x}_1, \mathbf{z}_1\} = S_3$ $S_2 /_1 S_0 = \{\mathbf{y}_1\} = S_4$		

