A Graphical Model Approach for Crowdsourcing

Qiang Liu (UC Irvine)

With Jian Peng, Prof. Alexander Ihler (MIT) (UC Irvine)

Presented in NIPS 2012

- Outsourcing tasks to crowds of of people
 - very powerful
 - human v.s. artificial intelligence
 - wisdom of crowds
 - cheap, fast, convenient











• Harvesting Human Intelligence / Judgments

Search Relevance Evaluation

Google bing Translation Cloud APT

Translation

Predication Market



Collecting Information Distributed in Crowds

Marie Curie Marie Skłodowska-Curie was a French-Polish physicist and chemist famous for her pioneering research on radioactivity. She was the first person Goo honored with two Nobel Prizes-in physics and nemistry. Born: November 7, 1867, Warsaw Died: July 4, 1934, Sancellemoz Images Maps Spouse: Pierre Curie (m. 1895-1906) Videos News Shopping Books More Mountain Vi Change loc. Any time Past hour Past 24 hour Past 24 ays Past week Past month Past year Children: Irène Joliot-Curie, Ève Curie Discovered: Radium, Polonium Education: École Supérieure de Physique et de Chimie Industrielles de la Ville de Paris, University of Paris from the AIP Center for History of I

Knowledge graph

Research datasets





Indoor maps



 Outsourcing tasks to crowds of people



- but be careful!
 - humans are unreliable and diverse
 - Need to ask different people and aggregate their opinions
- This talk:
 - Aggregation algorithms

Crowdsourcing for Labeling

- Goal: estimate true z_i from noisy labels $\{L_{ij}\}$.
 - minimize bit-wise error:

$$\min_{\hat{z}_i} \mathbb{E}[\sum_i 1(\hat{z}_i \neq z_i)]$$

- reliability:

$$q_j = \operatorname{prob}[L_{ij} = z_i]$$







• Majority Voting (MV):

$$\hat{z}_i = \operatorname{sign}[\sum_{j \in \partial_i} L_{ij}]$$

• Majority Voting (MV):

$$\hat{z}_i = \operatorname{sign}\left[\sum_{j \in \partial_i} L_{ij}\right]$$

• Iterative algorithm by Karger, Oh, Shah 2011 (KOS):

$$\hat{z}_i = \operatorname{sign}\left[\sum_{j \in \partial_i} L_{ij} y_{j \to i}\right]$$

Task-> workers:

$$x_{i \to j}^{t+1} = \sum_{j' \neq j} L_{ij'} y_{j' \to i}^t$$

Workers->Tasks:

$$y_{j \to i}^{t+1} = \sum_{i' \neq i} L_{i'j} x_{i' \to j}^{t+1},$$



• Majority Voting (MV):

$$\hat{z}_i = \operatorname{sign}\left[\sum_{j \in \partial_i} L_{ij}\right]$$

• Iterative algorithm by Karger, Oh, Shah 2011 (KOS):

$$\hat{z}_i = \operatorname{sign}\left[\sum_{j \in \partial_i} L_{ij} y_{j \to i}\right]$$

Task-> workers:

$$x_{i \to j}^{t+1} = \sum_{j' \neq j} L_{ij'} y_{j' \to i}^t$$

Workers->Tasks:
$$y_{j \to i}^{t+1} = \sum_{i' \neq i} L_{i'j} x_{i' \to j}^{t+1}$$
,





- This talk:
 - generalizes both MV and KOS
 - Better performance, principled derivation

- Expectation Maximization (Dawid & Skene 79, Smyth et al 95, Raykar et al 10, Whitehill et al 09, Welinder et al 10, etc)
 - Build generative probabilistic models
 - Maximizing likelihood by EM
 - Estimate \hat{z}_i with fixed parameters

- This talk:
 - Model complexity v.s. inference methods
 - Crowdsourcing as probabilistic graphical models

Probabilistic Graphical Models

• Factorized probability:

$$p(z) = \frac{1}{Z} \prod_{j \in [N]} \psi_j(z_{\partial_j})$$



- Example:
$$p(z) = \frac{1}{Z}\psi_1(x_1, x_2)\psi_2(x_1, x_2, x_3)\psi_3(x_2, x_3)$$

• Inference: calculating the marginal probabilities

$$p(z_i) = \sum_{z_{N \setminus i}} p(z)$$

- approximation: belief propagation, mean field, etc

Probabilistic Graphical Models

• Belief propagation: $p(z_i) \approx \prod_{j \in \partial_i} m_{j \to i}(z_i)$



Factors -> Variables:

$$m_{j \to i}(z_i) \propto \sum_{z_{\partial_j \setminus \{i\}}} \psi_j \prod_{i' \neq i} m_{i' \to j}(z_{i'})$$



- Mean field method:
 - approximate p(z) by fully independent models.

$$\min_{\{\tilde{p}_i\}} \mathrm{KL}\big[\prod_i \tilde{p}_i(z_i)||p(z)\big]$$

See Wainwright & Jordan 08, Koller & Friedman's book, Murphy's book.

Assumptions

- Workers' model: $p(L_{ij}|z_i, q_j) = \begin{cases} q_j, & \text{if } L_{ij} = z_i \text{ (correct)} \\ 1 q_j, & \text{if } L_{ij} \neq z_i \text{ (wrong)} \end{cases}$
- Prior of workers' reliability: $q_j \sim p(q_j)$
- Joint posterior distribution:

$$p(z,q|L) \propto \prod_{j} p(q_j) q_j^{c_j} (1-q_j)^{d_j-c_j}$$

 d_j : # of images by j in total c_j : # of correct images by j: $c_j = \sum_i 1[L_{ij} = z_i]$

• Estimator (Minimizes the bit-wise error):

$$\hat{z}_i = \underset{z_i}{\operatorname{arg\,max}} p(z_i|L)$$

Assumptions

- Workers' model: $p(L_{ij}|z_i, q_j) = \begin{cases} q_j, & \text{if } L_{ij} = z_i \text{ (correct)} \\ 1 q_j, & \text{if } L_{ij} \neq z_i \text{ (wrong)} \end{cases}$
- Prior of workers' reliability: $q_j \sim p(q_j)$
- Joint posterior distribution:

$$p(z,q|L) \propto \prod_{j} p(q_j) q_j^{c_j} (1-q_j)^{d_j-c_j}$$

 d_j : # of images by j in total c_j : # of correct images by j: $c_j = \sum_i 1[L_{ij} = z_i]$

• Estimator (Minimizes the bit-wise error):

$$\hat{z}_i = \arg\max_{z_i} \left\{ p(z_i|L) \equiv \sum_{z_{[N]\setminus i}} \int_q p(z,q|L) dq \right\}$$

Graph Model for Crowdsourcing

• Integrate out q_j analytically:

$$p(z|L) = \int_{q} p(z,q|L) dq = \prod_{j} \int_{0}^{1} p(q_{j}) q_{j}^{c_{j}} (1-q_{j})^{d_{j}-c_{j}} dq_{j}$$
$$\stackrel{def}{=} \prod_{j} \psi_{j}(c_{j})$$
where $\psi_{j}(c_{j}) = \int_{0}^{1} p(q_{j}) q_{j}^{c_{j}} (1-q_{j})^{d_{j}-c_{j}} dq_{j}$







Workers



Factors

$$\psi_j(c_j) = \int_0^1 q_j^{c_j} (1 - q_j)^{d_j - c_j} p(q_j) dq_j$$







$$\psi_j(c_j) = \int_0^1 q_j^{c_j} (1 - q_j)^{d_j - c_j} p(q_j) dq_j$$



Beta(1,1) Beta(3,1)



$$\psi_j(c_j) = \int_0^1 q_j^{c_j} (1 - q_j)^{d_j - c_j} p(q_j) dq_j$$





$$\psi_j(c_j) = \int_0^1 q_j^{c_j} (1 - q_j)^{d_j - c_j} p(q_j) dq_j$$





BP for Crowdsourcing

• Standard belief propagation on $p(z) = \prod \psi_{j:}(x_{\partial_j})$

JMarginal probability:
$$p(z_i) \approx \prod_{j \in \partial_i} m_{j \to i}(z_i)$$
Variables -> Factors: $m_{i \to j}(z_i) \propto \prod_{j' \neq j} m_{j' \to i}(z_i)$ Factors -> Variables: $m_{j \to i}(z_i) \propto \sum_{z_{\partial_j \setminus \{i\}}} \psi_j \prod_{i' \neq i} m_{i' \to j}(z_{i'})$ Decode solution: $\hat{z}_i = \arg \max_{z_i} p(z_i)$

i

• Log-odds transformation:

Marginals:
$$\hat{x}_i = \log \frac{p(z_i = +1)}{p(z_i = -1)}$$

Messages:
$$x_{i \to j} = \log \frac{m_{i \to j}(+1)}{m_{i \to j}(-1)}$$
 $y_{j \to i} = \log \frac{m_{j \to i}(+L_{ij})}{m_{j \to i}(-L_{ij})}$

Belief Propagation (log-odds form)

Estimate labels:

$$\hat{z}_i = \operatorname{sign}\left[\sum_{j \in \partial_i} L_{ij} y_{j \to i}\right]$$

Tasks → Workers:

$$x_{i \to j}^{t+1} = \sum_{j' \neq j} L_{ij'} y_{j' \to i}^t$$

Workers → Tasks:



 $y_{j \to i}^{t+1} = \sigma[\{L_{i'j} x_{i' \to j}^{t+1} : i' \neq i\}]$



 e_k are the elementary symmetric polynomials in $\{\exp(L_{i'j}x_{i'\to j})\},\$

Complexity: $O(d_j \log(d_j)^2)$

Special Priors

• Deterministic prior:



Our BP => majority voting

Includes no diversity;
 sensitive to adversaries

• Haldane prior:



Our BP => KOS

High diversity (variance);
 emphasizes adversaries



Frequentist Guarantees

• Density Evolution (e.g., Mezard & Montanari 09; Karger, Oh, Shah 11)

Frequentist Guarantees

• Density Evolution (e.g., Mezard & Montanari 09; Karger, Oh, Shah 11)

Assumption:

- 1. Random regular bipartite graphs
- 2. True reliability prior: $\mathbb{E}[q_j] > 1/2$
- 3. Our algorithm:
 - $\nabla^2 \log \psi(c_j) \ge 0, \quad \forall 0 \le c_j \le d_j$ $\nabla \log \psi(d_j) > 0$



Result:

$$\limsup_{N \to +\infty} \frac{1}{N} \sum_{i \in [N]} \operatorname{prob}[z_i \neq \hat{z}_i^t] \to 0, \quad \text{if } l \to +\infty$$

(*l* = # of workers per images)

Mean Field and EM

- Joint posterior distribution: p(z,q|L)
- Mean field approximation:

 $\min_{\tilde{p}} \operatorname{KL}[\tilde{p}(z,q)||p(z,q|L)] \quad \text{where } \tilde{p}(z,q) = \prod_{i} \mu_{i}(z_{i}) \prod_{j} \nu_{j}(q_{j})$

• Coordinate descent (when prior is $Beta(\alpha, \beta)$):

Updating μ_i : $\mu_i(z_i) \propto \prod_{j \in \mathcal{M}_i} a_j^{\delta_{ij}} b_j^{1-\delta_{ij}}$, where $\delta_{ij} = \mathbf{1}[z_i = L_{ij}]$ Updating ν_j : $\nu_j(q_j) \sim \text{Beta}(\sum_{i \in \mathcal{N}_j} \mu_i(L_{ij}) + \alpha, \sum_{i \in \mathcal{N}_j} \mu_i(-L_{ij}) + \beta)$,

where $a_j = \exp(\mathbb{E}_{\nu_j}[\ln q_j])$ and $b_j = \exp(\mathbb{E}_{\nu_j}[\ln(1-q_j)])$

• Taylor expansion:

 $a_j \approx \bar{q}_j$ and $b_j \approx 1 - \bar{q}_j$ where $\bar{q}_j = \mathbb{E}_{\nu_j}[q_j]$

Mean Field and EM

- Joint posterior distribution: p(z,q|L)
- Mean field approximation:

 $\min_{\tilde{p}} \operatorname{KL}[\tilde{p}(z,q)||p(z,q|L)] \quad \text{where } \tilde{p}(z,q) = \prod_{i} \mu_{i}(z_{i}) \prod_{j} \nu_{j}(q_{j})$

• Mean field (with first order approximation):

$$\mu_i(z_i) \propto \prod_j \bar{q}_j^{\mathbf{1}[L_{ij}=z_i]} (1-\bar{q}_j)^{\mathbf{1}[L_{ij}\neq z_i]} \qquad \bar{q}_j = \frac{\sum_i \mu_i(L_{ij}) + \alpha}{d_j + \alpha + \beta}$$

• EM:

$$\mu_i(z_i) \propto \prod_j \bar{q}_j^{\mathbf{1}[L_{ij}=z_i]} (1-\bar{q}_j)^{\mathbf{1}[L_{ij}\neq z_i]} \qquad \bar{q}_j = \frac{\sum_i \mu_i(L_{ij}) + \alpha - 1}{d_j + \alpha + \beta - 2}$$

- Different from EM only on replacing α -1 and β -1 with α and β .
- Add-one smoothing.

Mean Field and EM

• Approximation mean field (AMF):

$$\mu_i(z_i) \propto \prod_j \bar{q}_j^{\mathbf{1}[L_{ij}=z_i]} (1-\bar{q}_j)^{\mathbf{1}[L_{ij}\neq z_i]} \qquad \bar{q}_j = \frac{\sum_i \mu_i(L_{ij}) + \alpha}{d_j + \alpha + \beta}$$

• EM:

$$\mu_i(z_i) \propto \prod_j \bar{q}_j^{\mathbf{1}[L_{ij}=z_i]} (1-\bar{q}_j)^{\mathbf{1}[L_{ij}\neq z_i]} \qquad \bar{q}_j = \frac{\sum_i \mu_i(L_{ij}) + \alpha - 1}{d_j + \alpha + \beta - 2}$$
(E-step) (M-step)

- Different from EM only on replacing α -1 and β -1 with α and β .
- Add-one smoothing.

Extensions

• Sensitivity & Specificity models of workers:



Two-coin Model (Dawid & Skene 79): $s_j = \operatorname{prob}[L_{ij} = +1 | z_i = +1],$ (sensitivity) $t_j = \operatorname{prob}[L_{ij} = -1 | z_i = -1].$ (specificity)

• Model selection by marginal likelihood:

$$K = \frac{p(L|M_1)}{p(L|M_2)} = \frac{\sum_{z} \int_{q} p(z, q, L|M_1) dq}{\sum_{z} \int_{q} p(z, q, L|M_2) dq}$$

Incorporating item features, and expect labels

- 1000 tasks
- True data prior: spammer-hammer prior
- Varying # of workers per images (l), fixing # of images per worker (r)





- 1000 tasks
- True data prior: spammer-hammer prior
- Varying # of workers per images (l), fixing # of images per worker (r)





Algorithm Prior

- 1000 tasks
- True data prior: spammer-hammer prior
- Varying # of workers per images (l), fixing
 # of images per worker (r)



Algorithm Prior



- 1000 tasks
- True data prior: spammer-hammer prior
- Varying # of workers per images (l), fixing
 # of images per worker (r)



Algorithm Prior



- 1000 tasks
- True data prior: spammer-hammer prior
- Varying # of workers per images (l), fixing
 # of images per worker (r)





- 1000 tasks
- True data prior: spammer-hammer prior
- Varying # of images per worker (r), fixing # of workers per image (l)





- 1000 tasks
- Fixed degrees (*l*=9, *r*=9)
- Varying data prior: increasing percentage of adversaries

True Data Prior

 ${0.5 \atop q_{j}}$

0.5

0,



Bluebird dataset (Welinder et al 10)

- 108 tasks
- 39 workers
- Indigo Bunting v.s. Blue GrosBeak?







Thanks to P. Welinder and S. Belongie for providing the data and code.

Bluebird dataset (Welinder et al 10)

- 108 tasks
- 39 workers
- Indigo Bunting v.s. Blue GrosBeak?







Thanks to P. Welinder and S. Belongie for providing the data and code.

Natural language datasets

(snow et al 08)

- 800 tasks
- 164 workers

Temporal ordering (TEMP):

In the following, which event happens first: *fell* or *pushed*?

John fell. Sam pushed him.

Answer: Pushed



Conclusions & Future Work

- Crowdsourcing + graphical models
- Belief propagation (KOS, MV), mean field (EM)
- Choice of priors is critical
- Modeling choices
- Inference algorithms





Thanks 😳

Acknowledgements. Work supported in part by two Microsoft Research Fellowships and NSF IIS-1065618.

More results on Different priors



Belief Propagation

<i>Variables -> Factors:</i>	$m_{i \to j}(z_i) \propto \prod_{j' \neq j} m_{j' \to i}(z_i)$
Factors -> Variables:	$m_{j \to i}(z_i) \propto \sum_{z_{\partial_j \setminus \{i\}}} \psi_j \prod_{i' \neq i} m_{i' \to j}(z_{i'})$
Marginal probabilities:	$b_i(z_i) = \prod_{j \in \partial_i} m_{j \to i}(z_i)$
Decode solution: $z_i = \underset{z_i}{\operatorname{argmax}} b_i(z_i),$	

• Log-odds form:

$$\hat{x}_i = \log \frac{b_i(+1)}{b_i(-1)}, \qquad x_{i \to j} = \log \frac{m_{i \to j}(+1)}{m_{i \to j}(-1)}, \qquad y_{j \to i} = \log \frac{m_{j \to i}(+L_{ij})}{m_{j \to i}(-L_{ij})}$$

- 1000 tasks
- True data prior: spammer-hammer prior
- Varying both l and r, with l = r.





Natural language datasets (snow et al 08)

- 462 tasks
- 76 workers

Recognizing Textual Entailment:

Text: Many experts think that there is likely to be another terrorist attack on American soil within the next five years. **Hypothesis:** There will be another terrorist attack on American soil within the next five years. **Answer:** NO

