CS343 Artificial Intelligence

Prof: Peter Stone

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Good Afternoon, Colleagues



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Are there any questions?





• Questions about the syllabus?



- Questions about the syllabus?
- Class registration



- Questions about the syllabus?
- Class registration
- Problems with the assignment?



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- Class registration
- Problems with the assignment?
- Mailing list announcements yesterday



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 CC Daniel (urieli@cs), and me on everything



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- Assignments up through week 3



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• Autonomous robot



- Autonomous robot
- Information gathering agent
 - Find me the cheapest?



- Autonomous robot
- Information gathering agent
 - Find me the cheapest?
- E-commerce agents
 - Decides what to buy/sell and does it



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- Meeting scheduler
- Computer-game-playing agent



Not Intelligent Agents

- Thermostat
- Telephone
- Answering machine
- Pencil
- Java object



• Cooking agent (*6!),



Cooking agent (*6!), grocery shopper, jellybean sorter



- Cooking agent (*6!), grocery shopper, jellybean sorter
- piano tuner, music analyzer



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- Mario Bros. player, Mario Kart driver



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- autonomous toothbrush



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- piano tuner, music analyzer
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- survivor search helicopter, autonomous lawn mower, roomba, parallel parking car, GPS navigation device, automated car wash, Saluter robot



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- price setter for online merchant
- house alarm system, gentle alarm clock, treadmill, dog trainer,



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- RFID door lock, vaccine nanobot,



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- price setter for online merchant
- house alarm system, gentle alarm clock, treadmill, dog trainer, cat tail grabber
- RFID door lock, vaccine nanobot, human exam taker, super hero



 $Environment \implies sensations, actions$



Peter Stone

 ${\sf Environment} \Longrightarrow {\sf sensations}, {\sf actions}$

• fully observable vs. partially observable (accessible)



- fully observable vs. partially observable (accessible)
- single-agent vs. multiagent



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- single-agent vs. multiagent
- deterministic vs. non-deterministic



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- discrete vs. continuous



Environments

 ${\sf Environment} \Longrightarrow {\sf sensations}, {\sf actions}$

- fully observable vs. partially observable (accessible)
- single-agent vs. multiagent
- deterministic vs. non-deterministic
- episodic vs. sequential
- static vs. dynamic
- discrete vs. continuous
- known vs. unknown



An Example



• You, as a class, act as a learning agent



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- Actions: Wave, Stand, Clap



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- Observations: colors, reward



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- Goal: Find an optimal *policy*



- You, as a class, act as a learning agent
- Actions: Wave, Stand, Clap
- Observations: colors, reward
- Goal: Find an optimal *policy*
 - Way of selecting actions that gets you the most reward



How did you do it?



- What is your policy?
- What does the world look like?



Knowns:



Knowns:

- $\mathcal{O} = \{\text{Blue}, \text{Red}, \text{Green}, \text{Black}, \ldots\}$
- Rewards in \mathbb{R}
- $\mathcal{A} = \{Wave, Clap, Stand\}$

 $o_0, a_0, r_0, o_1, a_1, r_1, o_2, \ldots$



Knowns:

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- S = 4x3 grid
- $\mathcal{R}: \mathcal{S} \times \mathcal{A} \mapsto \mathbb{R}$
- $\mathcal{P} = \mathcal{S} \mapsto \mathcal{O}$
- $\mathcal{T}: \mathcal{S} \times \mathcal{A} \mapsto \mathcal{S}$



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$o_i = \mathcal{P}(s_i)$



Knowns:

- $\mathcal{O} = \{\text{Blue}, \text{Red}, \text{Green}, \text{Black}, \ldots\}$
- Rewards in ${\sf I\!R}$
- $\mathcal{A} = \{Wave, Clap, Stand\}$

 $o_0, a_0, r_0, o_1, a_1, r_1, o_2, \ldots$

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- $\mathcal{R}: \mathcal{S} \times \mathcal{A} \mapsto \mathbb{R}$
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 $o_i = \mathcal{P}(s_i)$ $r_i = \mathcal{R}(s_i, a_i)$



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• Speak loudly



- Speak loudly
- Name, year, major



- Speak loudly
- Name, year, major
- At least one other thing about yourself



- Textbook readings
- Responses both Monday and Wednesday
- Python tutorial due

