CS378 Autonomous Multiagent Systems Spring 2005

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Week 7b: Thursday, March 3rd

Good Afternoon, Colleagues

Are there any questions?



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- How does the Roomba work?
- Examples of randomization leading to specialization



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- How does the Roomba work?
- Examples of randomization leading to specialization
- Real experiments vs. simulation: pros and cons
- Why does the trail-laying use black markers?





• Surveys





- Surveys
- Faculty hiring talks start next week: T/R @ 11am



- An application to real robots
- Trails marked with a pen



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 - Future options(?): odor, fluorescence



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Task Allocation :

- Also on real robots
- How many is too many?



•



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 - Each item has a key and a rank
 - Goal: keep the ranks in ascending order of the keys



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 - Goal: dead ants should all be piled in the same place
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- ... Do network routing
 - build routing table mapping destinations to links at each node
 - Goal: minimal transit time for packets



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 - Randomized algorithm (packets sent probabilistically)



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 - Rules: move randomly, drop if you have 3
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- Missionaries and Cannibals An optimization problem
- Character animation (Reynolds, Star Wars)



Continue ML crash course

- Genetic algorithms/programming
- Neural networks
- Reinforcement learning



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- How does "altruism" arise?
- What does this mean about agent-based systems?
 - Should we create self-interested ants?
 - Or do we need to give them a global objective function?

