CS394R Reinforcement Learning: Theory and Practice Fall 2007

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Good Afternoon Colleagues

Are there any questions?

Logistics

How are the final projects coming?

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- Actions: Settings of the 4 or 5 controls
- Goal: Hover

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 - Collect a small amount of human expert data
 - Use that to train a 1-step model (simulator)
 - Determine the optimal policy in the simulator
 - Fly it!

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 - General question: is policy good or lucky?
 - Use same random samples for evaluation of each policy
- How does he do policy optimization?
 - greedy hillclimbing over few parameters (the NNs)!
- Could the approach be used to invert the helicopter? Or is it easier just to hover?
- Can it generalize to adverse conditions?
- Where's the power? Is it an easy problem or a powerful approach?

Robot Soccer paper

• Why I selected it...