CS394R Reinforcement Learning: Theory and Practice

Peter Stone

Department of Computer Science The University of Texas at Austin

BE a reinforcement learner



• You, as a class, act as a learning agent



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- Actions: Wave, Stand, Clap



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- Actions: Wave, Stand, Clap
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- Goal: Find an optimal *policy*
 - Way of selecting actions that gets you the most reward

How did you do it?



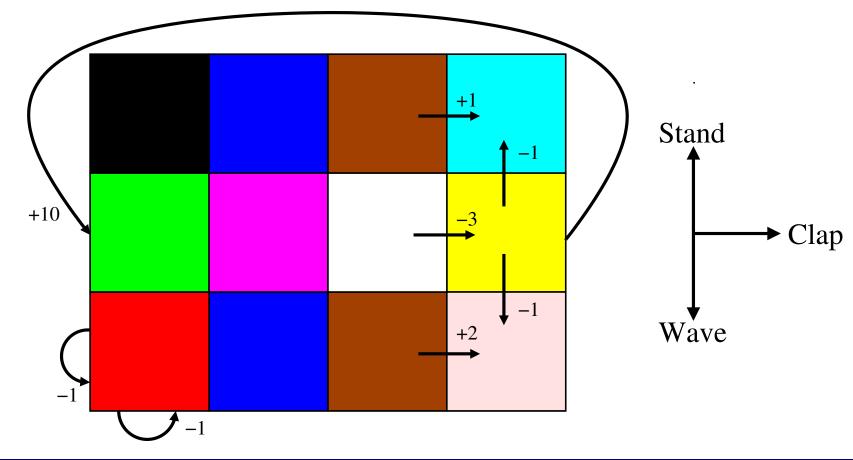
How did you do it?

- What is your policy?
- What does the world look like?



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- $\mathcal{R}: \mathcal{S} \times \mathcal{A} \mapsto \mathbb{R}$
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 $r_i = \mathcal{R}(s_i, a_i)$

$o_i = \mathcal{T}(s_i)$

$$s_{i+1} = \mathcal{P}(s_i, a_i)$$

UT Austin Learning Agents Research Group

• Reinforcement Learning theory (start)

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- Reinforcement Learning in practice (end)



The Big Picture





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 $\bullet \ \mathsf{AI} \longrightarrow \mathsf{ML}$



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Supervised learning: learn from labeled examples Unsupervised learning: cluster unlabeled examples

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- Book focusses on a particular class of approaches

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 - State representation, reward function given
 - Focus on policy algorithms, theoretical analyses

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• Available on-line



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- Read Chapter 2 (and 1 if you haven't)



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